Air Gripper with Finger Changer Function

Ø8

RoHS)

Automatic tool changer unit for robots

The wiring and piping are bundled together in the body of the air gripper (robot side).

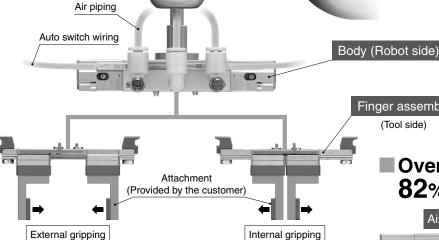
Improves electric contact during tool changes, reduces air leakage due to defective piping connections, etc.

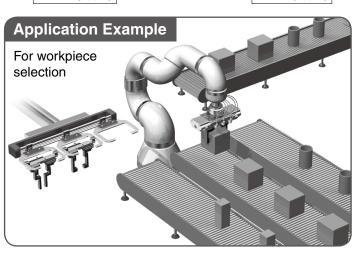
■ Various workpieces can be handled by a single robot.

Increased productivity due to reduced attachment replacement and positioning work

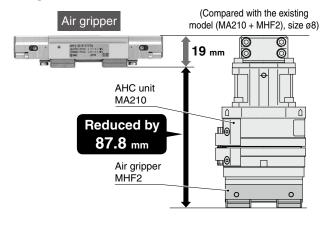


Finger assembly (Tool side)





Overall length: Reduced by **82%** or more



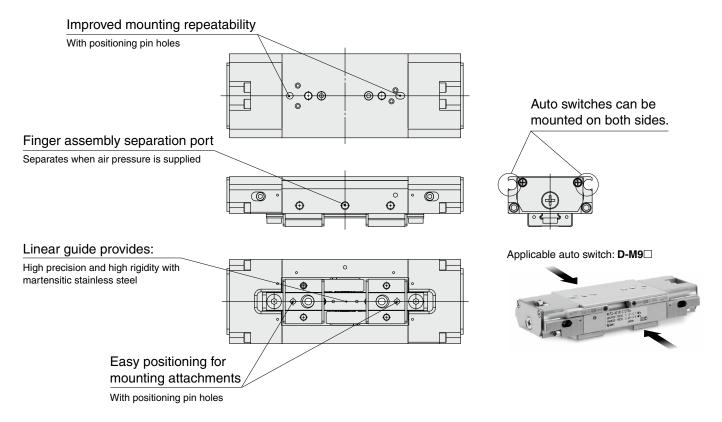
■ Weight: Reduced by **69**% or more $(485 \, q \rightarrow 150 \, q)$

(Compared with the existing model (MA210 + MHF2), size Ø8)

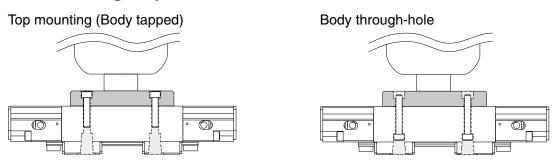


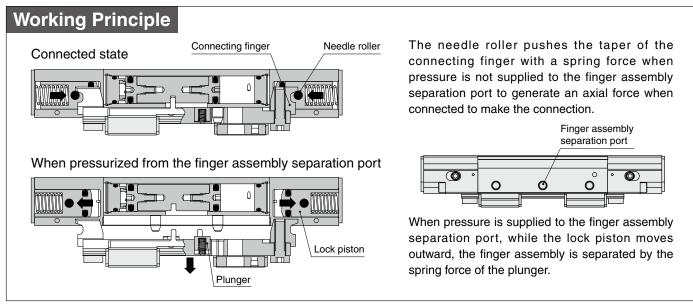
MHF2-X7076A

Configured for improved function and easier maintenance

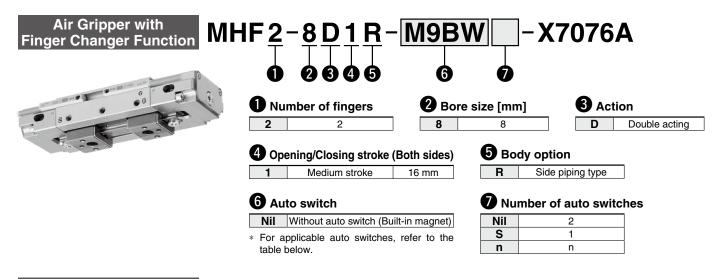


■ Mounting is possible from 2 directions.





How to Order



Finger assembly MHF-A 08 02-1-X7076A Bore size [mm] Opening/Closing stroke (Both sides) Medium stroke Med

Applicable Auto Switches/Refer to the Web Catalog for further information on auto switches.

	Special function	Electrical entry	Indicator light	Wiring (Output)	Load voltage			Auto switch model		Lead wire length [m]				Dua suinad	Annlinable	
Туре					DC		AC	Perpendicular	In-line	0.5	1	3	5	Pre-wired connector	Applicable load	
										(Nil)	(M)	(L)	(Z)		106	ioau
Solid state auto switch	_		Yes	3-wire (NPN)	12 5 V,1 12 5 V,1	5 V,12 V	1	M9NV	M9N	•	•	•	0	0	IC	Relay,
				3-wire (PNP)				M9PV	M9P	•	•	•	0	0	circuit	
				2-wire		12 V		M9BV	M9B	•	•	•	0	0	_	
	Diagnostic			3-wire (NPN)		5 V,12 V		M9NWV	M9NW	•	•	•	0	0	IC	
	indication			3-wire (PNP)				M9PWV	M9PW	•	•	•	0	0	circuit	
	(2-color indicator)			2-wire		12 V		M9BWV	M9BW	•	•		0	0	_	
	Water resistant (2-color indicator)			3-wire (NPN)		5 V.12 V		M9NAV*1	M9NA*1	0	0	•	0	0	IC	
				3-wire (PNP)		5 v, 12 v		M9PAV*1	M9PA*1	0	0	•	0	0	circuit	
				2-wire		12 V		M9BAV*1	M9BA*1	0	0	•	0	0	_	

- *1 Water-resistant type auto switches can be mounted on the above models, but SMC cannot guarantee water resistance.
- * Auto switches marked with "O" are produced upon receipt of order.

Specifications



Bore size [mm]		8					
Fluid		Air					
Action	Gripper unit	Double acting					
ACTION	Changer unit	Single acting (Normally connected)					
Operating pressure	Gripper unit	0.15 to 0.7					
[MPa]	Changer unit	0.45 to 0.6					
Ambient temperature	[°C]	-10 to 60					
Axial force when conn	ected (Theoretical value) [N]	98					
Finger position	Position of fingers when fully open	4.3					
holding force [N]*1	Position of fingers when not fully open	0.6					
Gripping force per finge	er at 0.5 MPa (Effective value) [N]	19					
Opening/Closing strol	ce (Both sides) [mm]	16					
Max. operating freque	ncy [c.p.m]	120					
Lubricant		Non-lube					
Weight [g]		150 (Finger assembly: 38)					

^{*1} The theoretical holding force (reference value) which fixes the finger position when the finger assembly is separated

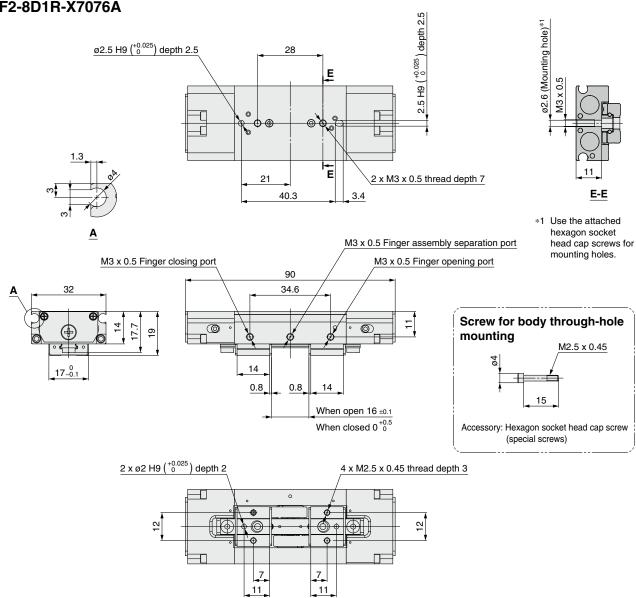


MHF2-X7076A

Dimensions

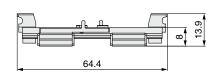


Air Gripper with Finger Changer Function MHF2-8D1R-X7076A



Finger assembly MHF-A08021-X7076A







MHF2-X7076A Specific Product Precautions

Be sure to read this before handling the products.

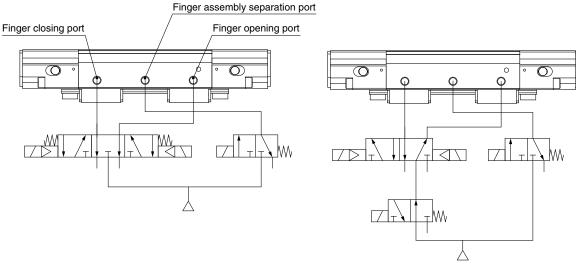
Handling

⚠ Caution

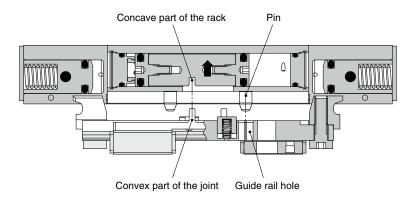
1. While pressure is being supplied to the finger opening/closing ports, the finger assembly may be difficult to separate.

Use the exhaust center solenoid valve or 3-port solenoid valve together to separate the finger assembly after the pressure from the finger opening/closing ports has been released.

Recommended Circuit Examples



- 2. It is recommended that the finger assembly be separated while the fingers are in a fully open state.
 - (If the finger assembly is separated while the fingers are not in a fully open state, the force to fix the finger position will be reduced.)
- 3. When connecting, align the guide rail holes and pins (2 locations), and confirm that the convex part of each joint is aligned with the concave part of the rack. Then, tightly connect the body and guide rail.



Connection Method

4. If the separated state is not maintained, such as when the fingers or piston are operated while the finger assembly is separated, the pieces will no longer be able to connect as is.

Align the convex part of each joint and the concave part of the rack to make the connection.



