

# **Operation Manual**

Fieldbus system DeviceNet<sup>TM</sup> compatible PRODUCT NAME

> EX600-SDN\* EX600 –DX\* EX600 –DY\* EX600 –AX\* MODEL/ Series

**SMC** Corporation

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### **Safety Instructions**

These safety instructions are intended to prevent hazardous situations and/or equipment damage. These instructions indicate the level of potential hazard with the labels of "Caution," "Warning" or "Danger.". They are all important notes for safety and must be followed in addition to International standards (ISO/IEC), Japan Industrial Standards (JIS)<sup>\*1)</sup> and other safety regulations<sup>\*2)</sup>.

- \*1) ISO 4414: Pneumatic fluid power - General rules relating to systems.
  - ISO 4413: Hydraulic fluid power - General rules relating to systems.
  - IEC 60204-1: Safety of machinery -Electrical equipment of machines. (Part 1: General requirements)
  - ISO 10218-1992: Manipulating industrial robots -Safety.
  - JIS B 8370: General rules for pneumatic equipment.
  - JIS B 8361: General rules for hydraulic equipment.
  - JIS B 9960-1: Safety of machinery Electrical equipment of machines. (Part 1: General requirements)
  - JIS B 8433-1993: Manipulating industrial robots Safety. etc.
- \*2) Labor Safety and Sanitation Law, etc.

Caution : Operator error could result in injury or equipment damage.
 Warning : Operator error could result in serious injury or loss of life.
 Danger : In extreme conditions, there is a possibility of serious injury or loss of life.

## Warning

1. The compatibility of the product is the responsibility of the person who designs the equipment or decides its specifications.

Since the product specified here is used under various operating conditions, its compatibility with specific equipment must be decided by the person who designs the equipment or decides its specifications based on necessary analysis and test results. The expected performance and safety assurance of the equipment will be the responsibility of the person who has determined its compatibility with the product. This person should also continuously review all specifications of the product referring to its latest catalog information, with a view to giving due consideration to any possibility of equipment failure when configuring the equipment.

- **2.** Only personnel with appropriate training should operate machinery and equipment. The product specified here may become unsafe if handled incorrectly. The assembly, operation and maintenance of machines or equipment including our products must be performed by an operator who is appropriately trained and experienced.
- 3. Do not service or attempt to remove product and machinery/equipment until safety is confirmed.
- 1. The inspection and maintenance of machinery/equipment should only be performed after measures to prevent falling or runaway of the driven objects have been confirmed.
- 2. When the product is to be removed, confirm that the safety measures as mentioned above are implemented and the power from any appropriate source is cut, and read and understand the specific product precautions of all relevant products carefully.
- 3. Before machinery/equipment is restarted, take measures to prevent unexpected operation and malfunction.
- 4. Contact SMC beforehand and take special consideration of safety measures if the product is to be used in any of the following conditions.
  - 1. Conditions and environments outside of the given specifications, or use outdoors or in a place exposed to direct sunlight.
- 2. Installation on equipment in conjunction with atomic energy, railways, air navigation, space, shipping, vehicles, military, medical treatment, combustion and recreation, or equipment in contact with food and beverages, emergency stop circuits, clutch and brake circuits in press applications, safety equipment or other applications unsuitable for the standard specifications described in the product catalog.
- 3. An application which could have negative effects on people, property, or animals requiring special safety analysis.
- 4. Use in an interlock circuit, which requires the provision of double interlock for possible failure by using a mechanical protective function, and periodical checks to confirm proper operation.



## 

1. The product is provided for use in manufacturing industries.

The product herein described is basically provided for peaceful use in manufacturing industries. If considering using the product in other industries, consult SMC beforehand and exchange specifications or a contract if necessary.

If anything is unclear, contact your nearest sales branch.

### Limited warranty and Disclaimer/Compliance Requirements

The product used is subject to the following "Limited warranty and Disclaimer" and "Compliance Requirements".

Read and accept them before using the product.

### Limited warranty and Disclaimer

- 1. The warranty period of the product is 1 year in service or 1.5 years after the product is delivered.<sup>\*3)</sup> Also, the product may have specified durability, running distance or replacement parts. Consult your nearest sales branch.
- 2. For any failure or damage reported within the warranty period which is clearly our responsibility, a replacement product or necessary parts will be provided.

This limited warranty applies only to our product independently, and not to any other damage incurred due to the failure of the product.

- 3. Prior to using SMC products, Read and understand the warranty terms and disclaimers noted in the specified catalog for the particular products.
  - \*3) Vacuum pads are excluded from this 1 year warranty.
    - A vacuum pad is a consumable part, so it is warranted for a year after it is delivered.
  - Also, even within the warranty period, the wear of a product due to the use of the vacuum pad or failure due to the deterioration of rubber material are not covered by the limited warranty.

### **Compliance Requirements**

When the product is exported, strictly follow the laws required by the Ministry of Economy, Trade and Industry (Foreign Exchange and Foreign Trade Control Law).



### Operator

- This operation manual has been written for those who have knowledge of machinery and apparatus that use pneumatic equipment and have full knowledge of assembly, operation and maintenance of such equipment.
- •Read this operation manual carefully and understand it before assembling, operating or providing maintenance.

## Warning

♦ Do not disassemble, modify (including change of printed circuit board) or repair this product. Injury or failure can result.

- Do not perform operation or setting with wet hands.
- There is a risk of electric shock.

Do not operate the product beyond the specification range.
 Do not apply the product to flammable gas or liquid or the gas or liquid harmful to human body.
 Otherwise it causes fire, malfunction, or damage to the system.
 Confirm the specifications before use.

•Do not operate the product in an environment where flammable or explosive gas may be present.

Fire, explosion or corrosion can result.

The product is not designed to be explosion proof.

• The following instructions must be followed when using the product in an interlocking circuit:

- Provide multiple interlocking using another system such as mechanical protection
- Check the product regularly to ensure proper operation Otherwise malfunction can cause an accident.

• The following instructions must be followed while performing maintenance work:

• Turn off the power supply

• Stop the air supply, exhaust the residual pressure and verify that the air is released to atmosphere before performing maintenance work

Otherwise it can cause injury.

## **A**Caution

♦When handling, assembling and replacing the unit:

- When handling the unit, do not touch any sharp metal parts of the connector and plug.
- When disassembling the unit, do not strike the product forcefully.
  - The connection parts are firmly joined with seals.
- When joining units, take care not to get your fingers trapped between units.
- Perform a proper functional check after completing maintenance work.
   Stop operation if any abnormality is observed or if the product is not working properly.
   Safety cannot be assured due to unexpected malfunction.

Provide grounding to assure the safety and noise resistance of the Fieldbus system. Individual grounding should be provided close to the product with a short cable.

### NOTE

- Follow the instructions given below when handling the Fieldbus system. Otherwise, the system may be damaged and may fail.
- The instructions on selection (installation, wiring, operating environment, adjustment, operation and maintenance) described below must also be followed.

### **Product specifications**

- Use the following UL recognized direct-current power supply.
  - (1) Limited voltage current circuit in accordance with UL508
    - A circuit whose power is supplied by secondary coil of an insulating transformer that meets the following conditions
    - Maximum voltage (with no load) : less than 30 Vrms (42.4 Vpeak)
    - Maximum current : (1) less than 8A (including when short circuited)
      - (2) limited by circuit protector (such as a fuse) with the following ratings

No load voltage (Vpeak)	Max. current rating (A)
0 ~ 20 [V]	5.0
Above 20 to 30 [V]	100 / peak voltage

- (2) A circuit using max. 30 Vrms or less (Class-2 circuit), whose power is supplied by Class-2 power supply unit in accordance with UL1310 or by Class-2 power supply unit in accordance with UL1585
- Operate the Fieldbus system with the specified voltage. Operation with a voltage outside of the specifications could cause malfunction or damage to the system.

• The reference for the power supply of the SI unit is 0 V for both the output and control power supplies of the SI unit.



• Do not mount in a location that will be used as a foothold.

The unit may be damaged if excessive force is applied by stepping or climbing onto it.



• Reserve sufficient space for maintenance Be sure to reserve sufficient space for maintenance when designing layout of the system.

• Do not remove any nameplates or labels. This can lead to incorrect maintenance, or misreading of the operation manual, which could cause damage or malfunction to the unit.

It may also result in non-conformity to safety standards.

- Be careful regarding the inrush current generated when the power is supplied.
- Depending on the connected load, an initial charging current may cause an over current protective function resulting in malfunction of the system.

#### Precautions for handling Installation

- Do not drop, hit or apply excessive shock to the unit. Otherwise the unit could be damaged, resulting in failure.
- Tighten screws to the specified tightening torque.
   Excessive tightening torque can break the screws.
   IP67 protection cannot be guaranteed if the screws are not tightened to the specified torque.
- When lifting a large size solenoid valve manifold unit, take care to avoid causing stress to the valve connection joint

The connection parts of the unit may be damaged.

Because the unit may be heavy, carrying and installation should be performed by more than one operator to avoid strain or injury.

### Wiring (including plugging in/out of connector)

- Do not bend the cables or apply excessive force by pulling or placing heavy loads on them. Bending or tensile stress could cause the cables to break.
- Connect wires and cables correctly. Incorrect wiring could break the Fieldbus system.

• Do not connect wires while the power is supplied.

This can damage components and also cause undisired behaviour

- Do not lay wires and cables together with power or high-voltage cables in the same wiring route. Otherwise the wires to the Fieldbus system could be affected by noise or induced surge voltage from power lines or high-voltage cables, causing malfunction. Route the wires to the SI Unit and each I/O device to a wire duct or in a protective tube other than those for power lines or high-voltage cables
- Verify the insulation of wiring.
   Poor insulation (interference with other circuits, poor insulation between terminals, etc.) can introduce excessive voltage or current to the SI Unit or each I/O device causing damage.
- Separate the power line for solenoid valves from the power line for input and control unit. Otherwise wires can be affected by noise or induced surge voltage, causing malfunction.
- Take appropriate measures against noise, such as using a noise filter, when the Fieldbus system is incorporated into equipment. Otherwise noise can cause malfunction.

### **Operating environment**

- Select the proper type of protection according to the environment of operation.
  - IP65/67 protection is achieved when the following conditions are met.
    - (1). The units are connected properly with communication line connector and power cable M12 connector at both ends,
    - (2) Suitable mounting of each unit and manifold valve.
  - (3) Be sure to mount a seal cap on any unused connectors.
    - If using in an environment that is exposed to water splashes, please take measures such as using a cover.

• Take sufficient shielding measures if the unit is installed in any of the locations described below. Insufficient measures could cause malfunction or failure.

Verify the effectiveness of the measures after incorporation of the unit into the equipment.

- (1) A place where noise is generated due to static electricity
- (2) A place where electric field strength is high
- (3) A place where there is radioactive irradiation
- (4) A place near a power line
- Do not use in an environment exposed to oil or chemicals.
- Using the product in an environment exposed to any type of oil or chemicals, such as coolants and cleaning fluids, may adversely affect the unit, causing failure or malfunction reducing the life of the product.
- Do not use in an environment exposed to corrosive gases or liquids. The unit may be damaged, leading to malfunction.
- Do not use the unit near to a place where electrical surges are generated. Internal circuit elements of the Fieldbus system can deteriorate or break if equipment generating a large surge (electromagnetic lifter, high frequency induction furnace, motor, etc.) is located near the Fieldbus system. Provide surge prevention measures, and avoid interference.
- Use the Fieldbus system equipped with a surge absorber if a surge-generating load such as a solenoid valve is driven directly.
- Direct drive of a load generating surge voltage can damage the Fieldbus system.
- The product does not have resistance against lightning surges required for CE marking, so please take measures against lightning surge on the equipment side.
- Make sure foreign matter such as dust and piping waste does not get inside the product. This may cause failure or malfunction.
- Do not expose the Fieldbus system to vibration or impact. Otherwise failure or malfunction could be caused.
- Do not use in an environment that is subject to a temperature cycle. If it is subjected to a temperature cycle outside of normal temperature changes, this may adversely affect the internal parts of the unit.
- Do not use in a location directly exposed to sunlight. If the product is located in such a position, arrange a suitable cover to protect the unit. Direct exposure to sunlight may cause failure or malfunction.
- Keep within the specified ambient temperature range. Otherwise malfunction could be caused. Do not use the Fieldbus system in a place where temperature changes suddenly, even within the specified range.
- Do not expose the Fieldbus system to heat radiation from a heat source located nearby. Malfunction could be caused.

#### Adjustment and Operation

- Set the switches using a small screwdriver, etc.. When operating the switches, do not touch parts other than the related parts. This may lead to failure due to component damage or short-circuit.
- Perform setting appropriate to the operating conditions. Inappropriate settings can cause defective operation.
- Please refer to page19-23 of this document for the settings of each switch.
- Refer to the PLC manufacturer's manual for details of programming and addresses. For the PLC protocol and programming refer to the relevant manufacturer's documentation.

#### **Maintenance and Checks**

- Before performing maintenance work, turn off the power supply, stop the supply of air, exhaust the compressed air from inside the piping, and verify that the air is released to atmosphere. Otherwise, there is a risk of unexpected malfunction of the system components.
- Perform maintenance and checks regularly.
   Otherwise unexpected malfunction of components could occur due to a malfunction of the whole unit.
- Perform appropriate functional checks. Stop operation if any abnormality is observed or if the device does not work properly. Otherwise an unexpected malfunction of the unit or components could occur.
- Do not use solvents such as benzene, thinner, etc. to clean the Fieldbus system. They could damage the surface of the body and erase the indication markings on the body. Use a soft cloth to remove stains. For heavy stains, use a cloth soaked in diluted neutral detergent and fully squeezed, then wipe again with a dry cloth.

### **Product Outline**

### System configuration

The EX600 range of units can be connected to various types of Fieldbus to realize the reduction of I/O device wiring and the distributed control system. The unit communicates with the Fieldbus through the SI unit. One SI unit can be connected with manifold valves with up to 32 points and I/O units with maximum 10 points.

All wiring between devices use cables with connectors at both ends and the system is compliant to IP67 protection.



- SI unit: Performs Fieldbus communication and solenoid valve manifold ON/OFF output.
- Digital Input unit: For connecting sensors with switch output capability. PNP and NPN types are available.
- Digital Output unit: For connecting output equipment such as solenoid valves, lamps, buzzers, etc. PNP and NPN types are available.
- Analog Input unit: For connecting sensors with analog output capability.
- End plate: Connected at EX600 Manifold's D side, incorporating the power supply connection.
- Solenoid valve manifold: An assembly of solenoid valves. One connector is used as the electric connection to all connected valves.



### Glossary

No.	Term	Definition	
		Open Fieldbus for factory automation. Developed by Rockwell Automation. Currently	
D	DeviceNet	headquartered in America, and expansion to Europe Japan and China	
D	DIN rail Metal rail in accordance with DIN standard.		
D	D Side	Term used to express the side where EX600 End plate is connected when it is assembled	
		as a manifold.	
_		Settable attribute information of a device (each parameter's object address, etc.) stored	
	EDS	on external disk.	
F	FE	Functional Earth.	
м		Abbreviation for Media-Access-Control Identifier. Node addresses identifier for the DeviceNet	
		Output that switches a load through an NPN transistor. The +ve side of the load is	
N	NPN output	connected to a common +ve. For this reason, NPN output is often referred to as "common	
		nositive"	
N	NPN input	Input that receives data from sensor with an NPN output signal.	
		Programmable Logic Controller, A Controller which performs sequential control using	
Р	PLC	programs of logical order and arithmetic operation, etc.	
		Output that switches a load through a PNP transistor. The -ve side of the load is connected	
Р		to the 0V common return. For this reason, PNP output is often referred to as "common	
•		negative"	
Р	PNP input	Input that receives data from sensor with PNP output signal	
		The LIP side of the manifold, where solenoid valve manifold is connected	
		Expression for PLC operation state For details Refer to manuals of each PLC maker	
I	Idle	Depending on which PLC is used; the Idle state might not be available.	
	<b>T</b>	When connecting device to the Fieldbus, resistance must be installed on both ends of	
Т	lerminating resistance	wiring system. This prevents signal reflection, and maintains data integrity.	
0		Number of points of output equipment (Solenoid Valve, lamp, motor starter, etc.) which can	
0	Output Points	be operated.	
С	Current consumption	The amount of current required by each unit in order to operate.	
_		Function that detect if output or power supply positive line is short circuited with GND, thus	
S	Short circuit detection	over current state has occurred.	
0		Internal circuit protection to prevent damage by over current caused by power supply	
5	Short circuit protection	positive line being short circuited with GND	
0		Diagnostic function which detects open circuit, caused by broken or disconnected wiring to	
0	Open circuit detection	the input/output equipment.	
		Data receive and transmit speed used by the Fieldbus. This depends on master equipment	
С	Communication speed	(PLC etc.), the unit used is bps (bit per second).	
	la a stata	Number of points that which can receive information from input equipment. (Sensor and	
1	input points	switch, etc.)	
	Handheld Terminal	A unit to connect with the SI unit PCI connection, for parameter adjustment, to monitor all	
н	(H.T.)	input and output signal status, and for Forced input/output selection.	
_	Fieldhue	Type of communication system between a PLC and factory equipment (such as measuring	
	Fieldbus	instruments or machines), in which data is exchanged by digital communication.	
	Protection Class (IP□□)	International Protection Rating. A Standard related to protection against foreign objects into	
Р		electrical enclosures. (Hand,wire, dust, and water, etc.)	
Μ	Manifold	An assembly with many openings for receiving and distributing fluid or gas.	

### Assembly

Composing the unit as a manifold.

\*: If the unit was purchased as a manifold, the work described in this section is not necessary.

### Note

Be sure to turn off the power when carrying out the work to compose the unit as a manifold.

#### (1) Connect the unit to the End plate

Digital input unit/digital output unit/Analog unit can be connected in any order.. Tighten the bracket of the joint using Tightening torque 1.5 to  $1.6 \text{ N} \cdot \text{m}$ .



#### (2) Add more units

Up to 10 units (including the SI unit) can be connected to one manifold.



### (3)Connecting SI unit

After connecting the necessary units, connect the SI unit. Connecting method is the same as above.

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#### (4) Mounting the valve plate

Mount the valve plate to the manifold solenoid valve using the valve set screws. Apply 0.6 to 0.7N•m tightening torque to the screws.



(5) Connect the SI unit and the manifold solenoid valve.

Insert the valve plate to the valve plate set groove on the side of SI unit. Then, tighten it with the valve plate set screws to fix the plate. Tightening torque for set screws 0.7 to 0.8N•m.



### Note:

Please do not connect the unit while the power supply is active. It will cause equipment damage.

### **Mounting and Installation**

### Installation method

### (1) Direct mounting

When joining six or more units, fix the middle part of the complete EX600 unit with an intermediate reinforcing brace (EX600-ZMB1) before mounting (Refer to the figure below.) using 2 M4 screws (Tightening torque: 0.7 to 0.8 N•m)



Fix and tighten the End plates at one end of the unit as shown in the figure below.

(Tightening torque: 0.7 to 0.8 N•m)

Fix the End plate at the valve side while referring to the operation manual of the corresponding manifold valve.



#### (2) DIN rail mounting

- (i) When joining six or more units, fix the middle part of the complete EX600 unit with an intermediate reinforcing brace (EX600-ZMB2) before mounting, using 2xM4 screws (Tightening torque: 0.7 to 0.8 N•m)
- (ii) Mount the End plate bracket (EX600-ZMA2) to the End plate, using 2xM4 screws (Tightening torque: 0.7 to 0.8 N•m)



- (iii) Hook the DIN rail mounting groove to the DIN rail. (See the figure below.)
- (iv) Press the manifold using its side hooked to the DIN rail as a fulcrum until the manifold is locked.
- (v) Fix the manifold by tightening the DIN rail fixing screws of the EX600-ZMA2.

### (Tightening torque: 0.7 to 0.8 Nm)

The tightening torque at the valve side depends on the valve type.





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#### • Wiring

The M12 connector can be mated with a SPEEDCON connector orstandard M12 connector.

(1) Set the projected portion of the cable connector metal ring (plug / socket) to the mark.





(2) Push the connector straight to insert it into the receptacle of the unit. If inserted without aligning the mark, the connector will not mate with the receptacle.



(3) Turn the connector clockwise. It stops when turned 1/4 turn.Turn it further. When the connector is turned 1/2 turn from the original position, the projected portion is set at the diagonal position to the mark and the turn is completed.

Check that the connector is securely locked.



If the connector is turned excessively, it will become difficult to remove.

• Mounting the marker Mount the marker (EX600-ZT1) into the marker groove as required.



### SI Unit



### Name and Function of the Parts



No.	Name	Description
1	Status indication LED	Indicates the unit status
2	Indication cover	Open to gain access to the Setting switches
3	Indication cover set screw	Loosen to open the cover
4	Connector(BUS OUT)	Connector for Fieldbus output
5	Marker groove	Groove to mount an indication marker
6	Connector (H.T.)	Connector to connect handheld terminal
7	Valve plate mounting hole	Holes for fixing the valve plate
8	Valve plate mounting groove	Groove for mounting the valve plate
9	Joint bracket	Bracket used to secure the adjacent unit
10	Connector for unit (Plug)	Conveys the signals and power supply to the adjacent unit
11	Connector (BUS IN)	Connector for Fieldbus input

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• Display indicator and description



Indicator	Description
ST(M)	Unit diagnostics status
PWR	Displays the power supply voltage status of the
	power supply for control and input
PWR(V)	Displays the power supply voltage status of the
	power supply for output
MS	Module Status
NS	Network Status

### **Mounting and Installation**

Connector Pin Assignment

Din na		configuration		
Pin no	signal name	BUS IN	BUS OUT	
1	DRAIN	2 1	$1 \land \land^2$	
2	V+		<u>`0 0`</u>	
3	V-	(50)	(5 <b>0</b> )	
4	CAN_H			
5	CAN_L	3 <b>4</b>	4 3	

EX600-SDN1/2 internally implements the branch connection as illustrated on the circuit below. When extending the network, connect using the BUS OUT connector, to increase the number of DeviceNet<sup>™</sup> slave stations.



### Note

Be sure to place a seal cap on any unused connectors.
Placing the seal cap appropriately enables the unit to achieve IP67 protection.
Be sure to connect a termination resister at both ends of the DeviceNet<sup>™</sup> trunk line.

### Setting and Adjustment

#### Setting procedure

- (1) Loosen the screw of the switch protection cover (indicated with an arrow).
- (2) Open the cover with a flat blade screwdriver.



(3) Perform the switch settings referring to the following pages.

Set the switches with a small point precision screwdriver.

(4) After setting the switches close the switch protection cover and tighten the screw in the reverse order to the above. (Tightening torque: 0.3 to 0.4 Nm)

### Note

- When adjusting the switch, make sure not to touch other parts other than the setting switch. Failure can be caused by damaged parts or short circuit.
- Be sure to perform the switch settings with the power turned OFF.
- All switches are set to OFF or 0 when delivered (Factory setting). Perform the switch settings before use.
- When any foreign matter or water droplets are observed near the switch protection cover, wipe them off before opening the cover.

### Address setting switch/ Data Rate setting switch

The switch settings become effective when power is introduced to the unit.



Address setting switch Data Rate setting switch :Set DeviceNet<sup>™</sup> node address. :Set DeviceNet<sup>™</sup> communication speed.

Address Setting

Address SW			
×10	×1	Node Address	
0	0	0(Factory default setting)	
0	1	1	
0	2	2	
2	ł	2	
6	2	62	
6	3	63	
6	4		
ł	ł	PGM <sup>Note)</sup>	
9	9		

#### Data Rate setting

Data Rate SW	Communication speed
0	125kbps (factory default
	setting)
1	250kbps
2	500kbps
3~9	PGM Note)

Note) if set to PGM, Communication speed is set through DeviceNet<sup>™</sup> network.

It is necessary to set HW/SW switch to ON. ( refer to page 22 ).



### $\circ$ Setting1 switch

When introducing power supply, switch setting will become effective.



V\_SEL switch: A function to select the number of points occupied by valve outputs. Select the output points (size) occupied by the SI unit.

Setting1		Description	SI unit Output data sizo	
No.1	No.2	Description		
OFF	OFF	Occupied bit for valve output is 32	4byte(Factory default)	
OFF	ON	Occupied bit for valve output is 24	3byte	
ON	OFF	Occupied bit for valve output is 16	2byte	
ON	ON	Occupied bit for valve output is 8	1byte	

Note) Change to the occupied valve point setting to more than the connected number of valves.

Baud Rate switch: Switches to set the baud rate of internal communication.

Setting1		Description	
No3.	No.4	Description	
OFF	OFF	1Mbps(factory setting)	
OFF	ON	500kbps	
ON	OFF	250kbps	
ON	ON	125kbps	

Note) 500, 250 & 125kbps settings are for future extension. Please use 1 Mbps (factory default setting).

### Setting2 switch

When introducing power supply, switch setting will become effective.



### Diagnostics switches: Mapping of diagnostic data to input data

Sett	ing2	Mode	Description Status size to b	Status size to be set
No.1	No.2	Mode		to the input
OFF	OFF	0	Input data only (factory setting)	0 byte
OFF	ON	1	Input data + System diagnostics	4 byte
ON	OFF	2	Input data + System diagnostics + Unit diagnostics (max.10 units)	6 byte
ON	ON	3 Note1)	Input data + System diagnostics + Unit diagnostics (max.64 units)	12 byte

Note 1)Mode 3 is used for future extended functions. Currently it is not used.

HOLD/CLEAR switch: Switch to set Hold/Clear of output at Fieldbus communication error or during idling. This setting can be made invalid (over-ridden) by the parameter (refer to page 64.)

Setting2 No.3	Description
OFF	Clears the output at Fieldbus communication error or during idling. (factory setting)
ON	Hold the output at Fieldbus communication error or during idling.

HW/SW switch: Fieldbus Address and Data Rate can be set through switch settings or from the

1 20:		
Setting2 No.4	Description	
OFF	Enables the Address and Data Rate switches (Factory Setting)	
ON	Disables the Address and Data Rate switches. PLC now controls the Address and Data Rate. (Note 1)	

Note1) In addition, when setting trough PLC, it is necessary to set Address or Data Rate switch to PGM.

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Manifold configuration memory switch : When the manifold configuration memory switch is set ON and the power supply is switched ON, the system will compare the stored configuration with the manifold configuration. If the configuration is different, diagnostic error will be generated.

Setting2 No.5	Description
OFF	Normal operation mode (factory default setting)
ON	Manifold configuration memory mode

Storing of the manifold configuration.

When powering up the unit with the switch set to ON, the manifold configuration will be stored into non-volatile memory. The user should then power down the unit and turn OFF the switch before re-powering.

Comparison of the manifold configuration.

When powering up the unit with the switch set to OFF, the manifold configuration is compared with the last stored configuration. Diagnostic errors are produced if the configurations are not the same.

## Error display

### SI unit common status

LED status	Descriptions	
ST(M) PWR PWR(V)	Power supply for control and input is OFF.	
ST(M) PWR PWR(V)	Unit is operating normally.	
ST(M) PWR PWR(V)	Component failure inside the SI unit. When ST (M) indicator is red, stop using the product and contact SMC.	
ST(M) PWR PWR(V)	Valve is in short-circuit or open-circuit status. Replace the valve. Valve ON/OFF counter exceeds setting value. (When Open/Short-circuit detection mode is ON)	
ST(N) PWR PWR(V)	Communication error between units or configuration memory error. Check the connection between units, or unit configuration.	
ST(M) PWR PWR(V)	Error diagnostic detected the error of a unit other than the SI unit.	
ST(M) PWR PWR(V)	Abnormal power voltage for control/input devices. Check the power supply and adjust or replace it.	
ST(M) PWR PWR(V)	Abnormal power voltage for valve/output devices. Check the power supply and adjust or replace it.	
OFF Red Light ON Green Light ON		
- <b>X</b> - Fla	shing Red Flashing Red and Green alternately (1 second frequency)	
- Flas	shing Green	

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LED status	Descriptions	
R(V) MS NS	Power supply for control and input is OFF.	
R(V) MS NS	Normal communication	
3(V) MS NS	<ul> <li>Check for Node Address duplication.</li> <li>Communication does not operate normally<sub>o</sub></li> </ul>	
R(V) MS NS	Connection cannot be established.	
R(V) MS NS	An internal element within the SI unit has been damaged. Stop operation and contact our sales branch.	
R(V) MS NS	<ul> <li>Critical communication error. (After ensuring compliance with the items below, Restart.)</li> <li>Confirm or fix the node address is set correctly.</li> <li>Check that the communication speed of the PLC and the slave unit are the same.</li> <li>Check that the cable length is within the specification.</li> <li>Check the integrity of the wiring (cable and connections).</li> <li>Check the specified terminators have been used</li> </ul>	
	<ul> <li>Non-critical communication error. (After checking compliance with the list below, Restart).</li> <li>Check that the communication speed of the PLC and the slave are the same.</li> <li>Check that the cable length is within the specification.</li> <li>Check the integrity of the wiring (cable and connections).</li> <li>Check the specified terminators have been used.</li> </ul>	
3(V) MS NS ) (V) MS NB ) (V) MS NB )	Unit is carrying out self diagnostics at power on.	
	OFF     Red Light ON     Green Light ON       Flashing Red     Flashing Red and Green alternately     Flashing Green	

## Specifications

### Specifications

Model		EX600-SDN1	EX600-SDN2	
	Fieldbus	DeviceNet <sup>™</sup> Volume1(Edition2.1) Volume3(Edition1.1)		
	Device type	Group2 Only Server		
nication	Communication speed	125/250/500kbps		
nm	Configuration file	EDS	S file	
Com	I/O occupation area (Inputs/Outputs)	Max (512 points/512 points )		
	Corresponding message	Duplicate MAC ID Check Message Group 2 Only Unconnected Explicit Message Explicit Message (Group 2) Poll I/O Message (Predefined M/S Connection set)		
Communication power supply for DeviceNet <sup>™</sup>		DC11V~25V		
Internal Current Consumption (Power supply for Control and Input)		Less than 55mA		
	Output method	PNP(-COM)	NPN(+COM)	
Ħ	Output channel	32 channels (8/16/24/32 channels selectable)		
e outp	Connected load	Solenoid valve with lamp and circuit of protection of surge voltage of DC24V 1.5W (SMC)		
alve	Supply voltage	DC24V +10/-5%		
Š	Output for com. error	HOLD/CLEAR/ Force ON		
	Protective function	Short-circuit protection		
	Enclosure	IP67(manifold assembly)		
_	Operating temp. range	-10~50°C		
nta e	Operating humidity range	35~85%RH (no dew condensation)		
Environmei resistanc	Withstand voltage	AC500V for 1 min. between external terminals and FE		
	Insulation resistance	DC500V, 10M $\Omega$ or more between external terminals and FE		
	Vibration resistance	10~57Hz with constant amplitude of 0.75mm p-p 57-150Hz with constant acceleration of 49m/s <sup>2</sup> for 2 hours in each direction of X, Y and Z direction (during de-energizing)		
	Impact resistance	147m/s <sup>2</sup> 3 times in each direction c	f X, Y and Z (during de-energizing)	
Stan	dard	CE marking, UL recognition (CSA)		
Weight		300 g		

Outline Dimensions









### **Digital input unit**

## How to order

# EX600 – <u>DX</u>

Digital input

Input polarity —		
Symbol Description		
Р	PNP	
N	NPN	

- Connector and input points and open circuit detection

Symbol	Connector	Input	Open circuit
- ,		points	detection
В	4 x M12(5Pin)	8 points	No
C	8 x M8(3Pin)	8 points	No
C1	8 x M8(3Pin)	8 points	Yes
D	8 x M12(5Pin)	16 points	No

Note: Input equipment with M12 (4 pin) connector can also be connected to M12 (5 pin) connector.

### Name and Function of the Parts

EX600-DX\*B



No.	Name	Description	
1	Status indication LED	Indicates the unit status. (Refer to the chapter "Troubleshooting" for the detailed display contents.)	
2	Connector(Input)	Connector for digital inputs. (M12, 5pin, socket : SPEEDCON)	
3	Marker groove	Groove to mount an indication marker.	
4	Joint bracket	Joint bracket to join the adjacent unit, fixed with attached screws.	
5	Connector for unit (plug)	Conveys the signals and power supplies to the adjacent unit.	

### EX600-DX\*C\*



No.	Name	Description	
1	Status indication LED	Indicates the unit status. (Refer to the chapter "Troubleshooting" for the detailed display contents.)	
2	Connector(Input)	Connector for digital inputs. (M8, 3pin, socket)	
3	Marker groove	Groove to mount an indication marker.	
4	Joint bracket	Joint bracket to join the adjacent unit, fixed with attached screws.	
5	Connector for unit (plug)	Conveys the signals and power supplies to the adjacent unit.	

### EX600-DX\*D



-	-	
No.	Name	Description
1	Status indication LED	Indicates the unit status. (Refer to the chapter "Troubleshooting" for the detailed display contents.)
2	Connector(Input)	Connector for digital inputs. (M12, 5pin, socket : SPEEDCON)
3	Marker groove	Groove to mount an indication marker.
4	Joint bracket	Joint bracket to join the adjacent unit, fixed with attached screws.
5	Connector for unit (plug)	Conveys the signals and power supplies to the adjacent unit.

### **Mounting and Installation**

### · Pin assignment and wiring diagram

- (1) EX600-DX\*B/EX600-DX\*D
  - •Connector's Pin assignment

Pin No.	Signal name	Configuration
1	24V(for control / input)	1002
2	Input2	
3	0V(for control / input)	(5 <b>0</b> )
4	Input1	
5	FE	4 - 3

Note: Input equipment with M12 (4 pin) connector can also be connected to M12 (5 pin) connector.



#### Note

Be sure to place a seal cap on any unused connectors. Using the appropriate seal cap enables the unit to achieve IP67 protection.

### (2) EX600-DX\*C\*

Connector's pin assignment			
Pin No.	Signal name	Configuration	
1	24V(for control / input)	1002	
3	0V(for control / input)		
4	Input1	4	

• Wiring diagram



#### Note

Be sure to place a seal cap on any unused connectors. Using the appropriate seal cap enables the unit to achieve IP67 protection.

#### Handling care.

Please note the following points when using Open Circuit Detection function.

- Open Circuit Detection setting can only be carried out using a Handheld Terminal. Setting can not be carried out using a PLC.
- When 2-wire sensor is used, sensor which has current leakage during OFF status is less than 0.5mA (contact sensor, etc.) will not be detected. Please use sensor which has current leakage of 0.5mA or more during OFF status.
- When 3-wire sensor is used, sensor that has current consumption of less than 0.5mA will not be detected, and also open circuit (wire breakage) at input signal line will not be detected

## Error display

Status indication LED displays power supply status and communication status. These can be checked according to the following:-

LED status	Descriptions					
O OFF	Power supply for control and input is OFF, or input device is OFF.					
Green Light ON	Input device is ON.					
Flashing Red	Either of the following: 1) Input device ON/OFF count has exceeded the set value. 2) Input device not connected (for open circuit detection type only).					
All LED Flashing Red and Green alternately	Component failure inside the digital input unit. Stop using the product and contact SMC.					
0 • 1 Red Light ON (Both adjacent LED's are ON)	<b>without Open Circuit Detection&gt;</b> Short circuit in power line of either input device "0" or "1". Check which input device has caused the short circuit.					
0 • 1 Red Light ON (Either one of adjacent LED's is ON)	<b>with Open Circuit Detection&gt;</b> Short circuit in power line of input device indicated.					

## Specifications

### Specifications

Model		EX600-DXPB	EX600-DXNB	EX600-DXPC	EX600-DXNC	EX600-DXPD	EX600-DXND			
	Input type		PNP	NPN	PNP	NPN	PNP	NPN		
	nput connector		M12(5Pin)socket Note1		M8(3Pir	M8(3Pin)socket		socket Note1		
	Input chan		8channels		8chai	nnels	16cha	annels		
	input chan	input channels		Connector)	(1 channels	/Connector)	(2channels	/Connector)		
	Sensor voltage	supplied	24VDC(Supplied from the power supply for control and inputs)							
	Maximum	sensor	0.5A/Co	nnector	0.25A/Co	onnector	0.5A/Co	onnector		
s	supplied vo	oltage	2A/	unit	2A/	unit	2A/	unit		
ion	Protection				Short circui	t protection				
cat	Input resist	ance			2.7	kΩ				
cific	Rated inpu	t current			9 mA o	or less				
nput Spe	ON voltage /ON current		17 V or more/ 5 mA or more (At NPN input, between the pin for input terminal and for sensor supplied voltage of +24 V) (At PNP input, between the pin for input terminal and for sensor supplied voltage of 0 V)							
_					5 V or less/ <sup>2</sup>	1 mA or less				
	Current	aye/OFF	(At NPN input	, between the p	oin for input termi	inal and for sens	or supplied vol	age of +24 V)		
	Current		(At PNP inpu	it, between the	pin for input tern	ninal and for sen	sor supplied vo	ltage of 0 V)		
	Open	2 wires	_	-	0.5mA/P	oint <sup>Note2</sup>	-	_		
	circuit									
	detection current	3 wires	-	-	0.5mA/Con	nector Note2	-			
Current consumption		50mA	orless	55mA	or less	70mA	or less			
			Green   ED on /Input is ON)							
Indiantor			Red LED on (when short circuit detected at sensor's power supply)							
ma	Cator		Red I FC	) flashing (ON	/OFF counter e	exceeded/ one	n circuit detec	ted <sup>Note2</sup> )		
	Enclosure				IP67 (manifol	d assembly)				
UC#		mp.	-10~50°C							
stal	Operating hur	nidity								
esi	rance	i noncy	35~85%RH (no dew condensation)							
alre	Withstand	voltage	AC500V for 1 min. between external terminals and FE							
enta	Insulation re	sistance	DC500V, 10M $\Omega$ or more between external terminals and FE							
ш			10~57Hz with constant amplitude of 0 75mm p-p							
iro	Vibration resistance		57-150 Hz with constant acceleration of 49m/s <sup>2</sup>							
Env			for 2 hours in each direction of X, Y and Z direction (during de-energizing)							
	Impact resi	stance	147m/s <sup>2</sup> 3 times in each direction of X, Y and Z (during de-energizing)							
Standard			CE marking, UL recognition (CSA)							
Weight			30	Эg	27	5g	34	.0g		

Note 1 : M12(4 pin)connector can be connected.

Note 2 : Applicable only for unit with Open circuit detection function.



• **Digital Input data** The table shows the relation between the connector position and the input data allocation.

•Table for input signal (EX600-DX\*B)

connector position		000		000	000	
connector №		0	1	2	3	
input	Pin 2	Bit 1	Bit 3	Bit 5	Bit 7	
signal	gnal Pin 4 Bit 0		Bit 2	Bit 4	Bit 6	

### • Table for input signal (EX600-DX\*D)

connector position		0000	00000	00000	00000	00000	00000		
connector №		0	1	2	3	4	5	6	7
input	Pin 2	Bit 1	Bit 3	Bit 5	Bit 7	Bit 9	Bit 11	Bit 13	Bit 15
signal	Pin 4	Bit 0	Bit 2	Bit 4	Bit 6	Bit 8	Bit 10	Bit 12	Bit 14

#### • Table for input signal (EX600-DX\*C\*)

connecto position	r	0000	0000	00000	0000	00000	0000	0000	0000
connecto	r Nº	0	1	2	3	4	5	6	7
input signal	Pin 4	Bit 0	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7

Outline Dimensions

EX600-DX\*B





EX600-DX\*C\*







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## EX600-DX\*D





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**SMC** 

## **Digital Output unit**



## Name and Function of the Parts



No.	Name	Description							
1	Status indication LED	Indicates the unit status. (Refer to the chapter "Troubleshooting" for the detailed display contents.)							
2	Connector(Output)	Connector for digital outputs. (M12, 5 pin, socket : SPEEDCON)							
3	Marker groove	Groove to mount an indication marker.							
4	Joint bracket	Joint bracket to join the adjacent unit, fixed with attached screws.							
5	Connector for unit (plug)	Conveys the signals and power supplies to the adjacent unit.							

## **Mounting and Installation**

Connector's pin assignment and wiring diagram
 Connector's pin assignment

Din No	Signal	Configuration							
PIN NO.	EX600-DYPB	Conliguration							
1	NC	24V(For Output)	1 < < 2						
2	Output 2 Output 2								
3	0V(for Output)	0V(for Output) NC							
4	Output 1	Output 1							
5	FE	FE	4 3						

Note : output equipment with M12 (4 pin) connector can also be connected to M12 (5 pin) connector



#### Note

Be sure to place a seal cap on any unused connectors. Using the appropriate seal cap enables the unit to achieve IP67 protection.

#### Handling care.

Please note the following points when using Open Circuit Detection function.

- Open Circuit Detection setting can only be carried out using a Handheld Terminal. Setting can not be carried out at the PLC.
- This function detects open circuit only when the output is OFF. Therefore if output is turned ON, open circuit can not be detected

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# Error display

Status indication LED (see figure to the right) displays power supply status and communication status. These can be checked according to the following:-

LED status	Descriptions
O OFF	Power supply for control and input is OFF, or output device is OFF.
Green Light ON	Output device is ON.
Red Light ON	Output is short circuited.
Flashing Red	Either of the following: Output device contact operations count has exceeded the set value. Output device is not connected.
All LED Flashing Red and Green alternately	Component failure inside the digital output unit. Stop using the product and contact SMC.

# **Specifications**

#### Specifications

Mod	el	EX600-DYPB	EX600-DYNB				
_	Output style	PNP	NPN				
Output Specificatior	Output connector	M12(5 Pin),Socket <sup>Note1</sup>					
	Output channel	8 channels (2 channels/connector)					
	Rated load voltage	24VDC(Supplied from F	Power supply for output)				
	Max. load current	0.5A/1 chann	el 2A/unit				
	Protection	Short circui	t protection				
Curr	ent consumption	50mA	or less				
Display		Green LED on (during output is ON)	Red LED on (short circuit at load)				
		Red LED flashing (ON/OFF counter is exceeded, or open circuit detected)					
	Enclosure	IP67(Manifold Assembly)					
	Operating temp. range	-10~50°C					
tal	Operating humidity range	35~85%RH (no dew condensation)					
ner	Withstand voltage	AC500V for 1 min. between external terminals and FE					
nm star	Insulation resistance	DC500V, 10M $\Omega$ or more between external terminals and FE					
viro esis		10~57Hz with constant amplitude of 0.75mm p-p					
E	Vibration resistance	57~150Hz with constan	t acceleration of 49m/s <sup>2</sup>				
		for 2 hours in each direction of X, Y and Z direction (during de-energizing)					
	Impact resistance	147m/s <sup>2</sup> 3 times in each direction of X, Y and Z (during de-energizing)					
Stan	dard	CE marking, UL recognition (CSA)					
Weig	ght	300g					

Note1 : M12 (4 pin) connector can also be connected.

## Digital Output data

The table shows the relation between the connector position and the output data allocation.

connecto position	r	0 0 0 0				
connector №		0	1	2	3	
output Pin 2		Bit 1	Bit 3	Bit 5	Bit 7	
signal Pin 4		Bit 0	Bit 2	Bit 4	Bit 6	

•Table for output signal (EX600-DY\*B)

### Outline Dimensions









## Analog Input Unit



# Name and Function of the Parts



No.	Name	Description					
1	Status indication LED	Indicates the unit status. (Refer to the chapter "Troubleshooting" for the detailed display contents.)					
2	Connector(Input)	Connector for digital inputs. (M12, 5 pin, socket : SPEEDCON)					
3	Marker groove	Groove to mount an indication marker.					
4	Joint bracket	Joint bracket to join the adjacent unit, fixed with attached screws.					
5	Connector for unit (plug)	Conveys the signals and power supplies to the adjacent unit.					

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## **Mounting and Installation**

#### Pin Assignment and wiring diagram

#### Pin assignment

Pin No	Signal name	Configuration
1	24V(For Control/Input)	1002
2	Input+	
3	0V(For Control/input)	(5 <b>0</b> )
4	Input-	
5	FE	4

#### • Wiring diagram



Input impedance Voltage input type: 100kΩ Current input type: 50Ω

#### Note

Be sure to place a seal cap on any unused connectors. Using the appropriate seal cap enables the unit to achieve IP67 protection.

#### Handling care

Please note the following points when wiring the Analogue input unit and sensor.

The EX600 Analogue Input operates using a differential input specification, therefore pin No.4 (input -) becomes the reference and pin No.2 (input +) carries the signal data.

This means that, if pin No.4 is not connected, the signal input cannot be correctly input.

Therefore externally connect pin No.3 and pin No.4 together when a differential output sensor is not used.

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- sensor and wiring example is shown below



•When 2-wire current output type sensor is used.



oWhen differential output type sensor is used



## **Error display**

Status indication LED displays power supply status and communication status. These can be checked according to the following:-

LED status	Descriptions
O OFF	Power supply for control and input is OFF.
Green Light ON	Operating normally.
Red Light ON	Power supply for input devices is short circuited.
Flashing Red	Upper or lower limit is detected for the following items: (1) Range (2)Measurement value(User setting)
All LED Flashing Red and Green alternately	Component failure inside the analog input unit. Stop using the product and contact SMC.

# Specifications

### Specifications

Model			EX600-AXA					
	Input type		Voltage input Current input					
	Input connecto	or	M12(5Pin), Socket					
ations	Input channels	;	2channel(1channel/Connector)					
	Sensor supplie	ed voltage	DC24V (Supplied from power supply for control and input)					
	Maximum sensivoltage	sor supplied	0.5A/channel					
	Protection		Short circuit protect	ction circuit built in				
Specifica	Input signal	12bit Resolution	0 ~ 10V 1 ~ 5V 0 ~ 5V	0 ~ 20mA 4 ~ 20mA				
Input \$	range	16bit Resolution	-10V ~ 10V (factory default setting) -5V~5V	-20mA ~ 20mA				
	Max. input sig	gnal	±15V	±40mA				
	Input impeda	nce	100kΩ	50Ω				
	Linearity		±0.05%F.S or less					
	Repeatability		±0.15%F.S. or less					
	Absolute acc	uracy	±0.5%F.S. or less	±0.6%F.S. or less				
Cur	rent consumpt	ion	70mA or less					
Display			Green LED on (when input is ON) Red LED on (Short circuit at sensor power supply) Red LED flashing (analog input exceeds measurement range or user setting range)					
	Enclosure		IP67(Manifold Assembly)					
	Operating temp.	range	-10~50°C					
<u>a</u>	Operating humidity	yrange	35~85%RH (no dew condensation)					
ent	Withstand volt	age	AC500V for 1 min. between external terminals and FE					
nm	Insulation resista	ance	DC500V, 10M $\Omega$ or more between external terminals and FE					
Enviro resis	Vibration resis	tance	10~57Hz with constant amplitude of 0.75mm p-p 57~150Hz with constant acceleration of 49m/s <sup>2</sup> for 2 hours in each direction of X, Y and Z direction (during de-energizing)					
	Impact resista	nce	147m/s <sup>2</sup> 3 times in each direction of X, Y and Z (during de-energizing)					
Stan	dard		CE marking, UL recognition (CSA)					
Weight			290g					

## Analog characteristics





Input signal range	а
0 ~ 10V	10V
0 ~ 5V	5V
0 ~ 20mA	20mA

Input signal range	а	b
1 ~ 5V	1V	5V
4 ~ 20mA	4mA	20mA

Regarding AD value

In the above graph, 2 AD values are explained as below. 3901: AD value [decimal value] (F3D): Offset Binary type [hexadecimal value]

Data	Form	at													
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
0	0	0	0	MSB				AD va	alue						LSB

AD va	alue	0 ~ 10V	1 ~ 5V	0 ~ 5V	0 ~ 20mA	4 ~ 20mA
Hexadecimal	Decimal		Voltage [V]	Current[mA]		
0FFF	4095	10.5	5.25	5.25	21	21
0F3D	3901	10	-	5	20	-
0F1C	3868	-	5	-	-	20
0800	2048	5.25	3	2.625	10.5	12
00E4	228	-	1	-	-	4
0000	0	0	0.75	0	0	3



#### Data format

Data															
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
MSB	MSB AD value								LSB						

AD v	/alue	-10V ~ 10V	-5 ~ 5V	-20mA ~ 20mA
Hexadecimal	Decimal	Voltag	ge [V]	Current [mA]
FFFF	65535	10.5	5.25	21
F9E8	63976	10	5	20
BCF4	48372	5	2.5	10
8000	32768	0	0	0
430C	17164	-5	-2.5	-10
0618	1560	-10	-5	-20
0000	0	-10.5	-5.25	-21







Input signal	а	b
range		
1 ~ 5V	1V	5V
4 ~ 20mA	4mA	20mA

#### Regarding AD value

0~10V

0~5V

0~20mA

In the above graph, 2 AD values are explained as below. -31208: AD value [decimal value] (F9E8): Sign & Magnitude [Hexadecimal value] (8618): 2's complements [Hexadecimal value]

10V

5V

20mA

Data format

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
0	0	0	0	0	MSB				AD	value					LSB

AD va	alue	0 ~ 10V	1V ~ 5V	0 ~ 5V	0 ~ 20mA	4 ~ 20mA
Hexadecimal	Decimal		Voltage [V]	Current [mA]		
07FF	2047	10.5	5.25	5.25	21	21
079E	1950	10	-	5	20	-
078E	1934	-	5	-	-	20
0400	1024	5.25	3	2.625	10.5	12
0072	114	-	1	-	-	4
0000	0	0	0.75	0	0	3



Input signal range	а	b
-10 ~ 10V	-10V	10V
-5 ~ 5V	-5V	5V
-20 ~ 20mA	-20mA	20mA

#### Data format

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Sign	MSB						AD	) value	<b>;</b>						LSB

### Signed Binary

AD v	/alue	-10V~10V	-5V~5V	-20mA~20mA
Hexadecimal	Decimal	Voltage [V]		Current [mA]
7FFF	32767	10.5*	5.25	21
79E8	31208	10	5	20
3CF4	15604	5	2.5	10
0000	0	0	0	0
BCF4	-15604	-5	-2.5	-10
F9E8	-31208	-10	-5	-20
FFFF	-32767	-10.5	-5.25	-21

### 2's complements

AD value		-10V~10V	-5V~5V	-20mA~20mA
Hexadecimal	Decimal	Volta	ge [V]	Current [mA]
7FFF	32767	10.5	5.25	21
79E8	31208	10	5	20
3CF4	15604	5	2.5	10
0000	0	0	0	0
C30C	-15604	-5	-2.5	-10
8618	-31208	-10	-5	-20
8000	-32767	-10.5	-5.25	-21

Outline Dimensions







**SMC** 

### End plate



# Name and Function of the Parts



No.	Name	Description
1	Power connector	Connector for power input
2	Fixing hole for direct mounting	Holes used for direct mounting
3	DIN rail fixing hole	Holes used to fix DIN rail
4	FE terminal	FE terminal to earth.

# **Mounting and Installation**

### Connector's pin assignment

### (1) EX600-ED2

Pin No.	Signal name	Configuration
1	24V(for Output)	2 7 1
2	0V(for Output)	
3	24V(for control / input)	(50)
4	0V(for control / input)	
5	FE	3 🗨 4

#### (2) EX600-ED3

Pin No.	Signal name	Configuration
1	0V(for Output)	
2	0V(for control / input)	
3	FE	
4	24V(for control / input)	
5	24V(for Output)	

### Regarding the 2 types of power supply

This product has 2 power supplies, and it is divided as follows.

- Power supply for control and input: supplying power for control of each unit's power supply for control and also for equipment connected to Digital input unit and Analog input unit.
- Power supply for output: supplying power for equipment connected to digital output unit, and also power supply for solenoid valve manifold.



# Specifications

### Specifications

Mod	el	EX600-ED2 EX600-ED3			
	Power connector	M12(5Pin) Plug	7/8inch(5Pin) Plug		
Input	Control, input power supply	24VDC±10% Maximum 2 A	24VDC±10% Maximum 8 A		
	Output power supply	24VDC +10%/-5% Maximum 2 A	24VDC +10%/-5% Maximum 8 A		
	Enclosure	IP67(manifold assembly)			
	Operating temp. range	-10~50°C			
ıtal	Operating humidity range	35~85%RH (no d	ew condensation)		
ner	Withstand voltage	AC500V for 1 min. between external terminals and FE			
JUO	Insulation resistance	DC500V, 10M $\Omega$ or more between external terminals and FE			
Envir	Vibration resistance	10~57Hz with constant amplitude of 0.75mm p-p 57-150Hz with constant acceleration of 49m/s <sup>2</sup> for 2 hours in each direction of X, Y and Z direction (during de-energizing)			
	Impact resistance	147m/s <sup>2</sup> 3 times in each direction o	f X, Y and Z (during de-energizing)		
Star	ndard	CE marking, UL recognition (CSA)			
Wei	ght	170g 175g			

- Outline Dimensions
- (1) EX600-ED2









## (2) EX600-ED3









## Troubleshooting

Refer to the following troubleshooting flowchart if errors occur on the Fieldbus system.

Error status is also reflected by the parameter settings of the Fieldbus system.

When problems occur, please take appropriate counter-measures after referring to the troubleshooting and the parameter settings.

If the cause of the problem cannot be confirmed, it is possible that the equipment may have failed. When failure of Fieldbus system equipment occurs, it is also possible that the error is caused by the system requirements. If that is the case, Consider the counter-measures accordingly.



### Trouble counter measure method

Problem No.	LED indication	Problem	Investigation Method	Counter-measure
	Flashing Red (Diagnostic is active) Cause can be either: 1) Sensor's ON/OFF counter exceeds setting value 2) Open circuit is detected on input sensor or cable. (for Open Circuit Detection type only)		Confirm cause 1) or 2) by PLC or H.T. Refer to details of system diagnosis data.	<ol> <li>Reset the counter, change the setting or disable the diagnostic through parameter setting.</li> <li>Confirm if there are loose connector and wire breakage. Moreover, please confirm if applicable sensor is used.</li> </ol>
1	Red Diagnosis error (Diagnostic is (Sensor power supply is short active) circuited)		[No open circuit detection] Either of two adjacent sensor connections is short circuited (2x LED's will be ON). [With open circuit detection] The sensor connection is short circuited (LED is ON).	Check the wiring of the sensor connection which has the short circuit, or confirm whether the cable and the sensor are operating correctly.
	All LED flashing Green and Red	Unit has failed	-	Stop operation and contact SMC sales office
	Flashing Red (Diagnostic is active)	Cause can be either: 1) Output device ON/OFF counter exceeds setting value 2) Open circuit is detected on output device or cable.	Confirm cause 1) or 2) by PLC or H.T. Refer to details of system diagnosis data.	<ol> <li>Reset the counter, change the setting or disable the diagnostics through parameter setting.</li> <li>Confirm if there are loose connections or broken wires.</li> </ol>
-	Red (Diagnostic is active)	Diagnosis error (output equipment is short circuited)	The output connection is short circuited (LED is ON).	Check the wiring, or confirm whether the output equipment is operating correctly
	All LED flashing Green and Red	Unit has failed	-	Stop operation and contact SMC sales office
3	Flashing Red (Diagnosis is active)	Diagnosis error (Upper/lower range limit exceeded)	<ol> <li>Confirm if the sensor output exceeds the upper/lower measurement limits.</li> <li>Confirm whether sensor output exceeds user setting upper/lower range.</li> </ol>	<ol> <li>Please adjust sensor output so that it is inside the measurement range, or adjust setting range or turn off over/under range detection.</li> <li>Please adjust sensor output so that it is Inside the user setting value, or adjust user setting value or turn off user set value upper/lower limit detection.</li> </ol>
	Red (Diagnostic is active)	Diagnosis error (Short circuit is detected on the sensor power supply).	Confirm if short circuit occurs at the sensor or cable	Confirm if sensor and cable are operating correctly.
	All LED Flashing green and red	Unit has failed	_	Please stop operation and please contact our sales office

Problem No.	LED indication	Problem	Investigation Method	Counter-measure
	ST(M): Off	Power supply for control/input is OFF	Confirm if power supply for control/input is connected.	Re-connect power supply for control/input
	ST(M): Red	SI unit has failed	-	Stop operation and contact SMC sales office.
	ST(M): Flashing red (Diagnosis is active)	Diagnosis error (SI unit) 1) Valve short circuited 2) Broken wire at valve 3) Valve ON/OFF counter exceeds setting value.	Confirm through PLC or handheld terminal. For details, please refer to the System Diagnosis information.	<ul> <li>For 1) and 2): valve is broken.</li> <li>Please replace valve and confirm operation.</li> <li>3) Reset counter value, change setting value or disable the diagnostic through parameter setting.</li> </ul>
	ST(M): Flashing green and red	<ol> <li>Communication error between SI unit and I/O unit</li> <li>Manifold configuration error</li> </ol>	<ol> <li>Confirm if the connection between units is not loose.</li> <li>Confirm unit's order of connection</li> </ol>	<ol> <li>If the error does not recover, stop operation and contact SMC sales office</li> <li>Connect the unit according to the saved configuration, re-register new manifold configuration or turn off manifold configuration memory function</li> </ol>
	PWR: Red (Diagnostic is active)	The power supply voltage level for control and input is not normal	Confirm the power supply voltage level.	Supply DC24V±10% to the power supply for control and input.
	PWR(V): Red (Diagnostic is active)	The power supply voltage level for output is not normal	Confirm the used power supply voltage level.	Supply DC24V+10/-5% to the power supply for output.
	MS : Green NS : Off	-Checking duplicated node address -Communication fault	Confirm the following. -Node address. -Communication speed used by PLC and slave are the same.	After setting the following, resume operation. -Node address -PLC/unit communication speed
4	MS : Green NS : Flashing green	Device is online, but communication cannot be established	<ul> <li>Confirm the following.</li> <li>1) PLC is operating normally</li> <li>2) If the scanlist is used on the network, confirm that slave is correctly registered on the scanlist.</li> </ul>	<ol> <li>Operate PLC correctly. (For details, Refer to each PLC's operation manual)</li> <li>Perform scanlist registration correctly.</li> </ol>
	MS : Red NS : Off	SI unit is defective	-	Stop operation and contact our sales branch.
	MS : Green NS : Red	Critical DeviceNet communication error	<ul> <li>Confirm the following</li> <li>1) Confirm or fix node address.</li> <li>2) Communication speed of PLC and slave are the same.</li> <li>3) Cable length is appropriate.</li> <li>4) No wire breakage or loose connection on the cable.</li> <li>5) Appropriate termination resistance is used.</li> <li>6) Communication line is noise protected.</li> </ul>	<ul> <li>After setting the the following, Resume operation <ol> <li>Node address</li> <li>PLC/Unit communication speed</li> <li>Appropriate cable length is connected</li> <li>Cable integrity is good (no wire breakage).</li> <li>Appropriate terminal resistance is connected.</li> <li>Communication line is protected from noise.</li> </ol></li></ul>
	MS : Green NS : Flashing Red	Non critical DeviceNet communication error	<ul> <li>Confirm the following</li> <li>1) Communication speed of PLC and slave are the same.</li> <li>2) Cable length is appropriate.</li> <li>3) No wire breakage or loose connection on the cable.</li> <li>4) Appropriate termination resistance is used.</li> <li>5) Communication line is noise protected.</li> </ul>	<ul> <li>After setting the the following, Resume operation <ol> <li>PLC/Unit communication</li> <li>PLC/Unit communication</li> <li>Appropriate cable length is connected</li> </ol> </li> <li>Cable integrity is good (no wire breakage).</li> <li>Appropriate terminal resistance is connected.</li> <li>Communication line is protected from noise.</li> </ul>



Problem No.	LED indication	LED indication Problem Inve		Counter-measure
		Valve output setting for occupied points is less than the number of connected valves	Confirm the V_SEL switch setting in the SI unit is set to more than the actual connected valves.	Set the SI unit switch settings to an occupation points count greater than the number of valves used.
		Program does not operate normally.	Confirm if ladder program at PLC Is correct	Same as left
		Power supply for output is defective	Check the status of the power supply for output	Supply DC24V +10/-5% to the power supply for output from the end plate unit
5	Solenoid valve does not operate normally	Connection between SI Unit and solenoid valve manifold is defective	Confirm the connection between the SI Unit and solenoid valve manifold (Connector pin not bent, etc.)	Connect the SI Unit to the solenoid valve Manifold correctly
		SI Unit output type is not compatible with the solenoid valves	Confirm that the SI Unit and solenoid valves are compatible: EX600-SDN1 (PNP Output) - Negative common type valve EX600-SDN2 (NPN Output) - Positive common type valve	Replace the SI Unit or the solenoid valve so that the correct combination is used
		Defective SI Unit	Replace the SI Unit and confirm the operation	Replace the SI Unit.
		Defective solenoid valve	Replace the solenoid valve and confirm the operation	If the problem continues, refer to the solenoid valve operation manual.
		Input type is not compatible	Confirm if input unit specification (PNP or NPN) and connected input equipment specification are compatible	Replace input unit or input equipment so that it become the correct combination
	Digital input	Power supply for control and input is defective	Check the status of power supply for control and input	Supply DC24V ±10% to the power supply for control and input from the end plate
6	equipment does not operate normally	Wiring or connection is defective	Confirm connection and wiring between input equipment and digital input unit.	Make corrections to the wiring between input equipment and digital input unit and continue operation
		Digital input unit is defective	Confirm the digital input unit	Replace the digital input unit
		Defective input equipment	Replace the input equipment and confirm the operation.	If the problem continues, refer to the input equipment operation manual.

Problem No.	LED indication	Problem	Investigation Method	Counter-measure
		Output type is not compatible	Confirm if output unit specification (PNP or NPN) and connected load specification are compatible.	Replace the output unit or load to give the correct combination
		Program does not operate normally	Confirm if the ladder program at the PLC Is correct	Correct the ladder program at the PLC
7	Digital output equipment does	Power supply for output is defective	Check the status of the power supply for output	Supply DC24V +10/-5% to the power supply for output from the end plate
	not operate normally	Wiring and connection is defective	Confirm connection between the output equipment and digital output unit.	Make corrections to the wiring between the output equipment and digital output unit and continue operation
		Digital output unit is defective	Confirm the digital output unit.	Replace the digital output unit.
		Output equipment is defective	Replace the output equipment and confirm the operation.	If the problem continues, refer to the output equipment operation manual.
	Analog input	Power supply for control and input is defective	Check the status of the power supply for control and input	Supply DC24V±10% to the power supply for control and input from the end plate
		Input signal range setting is not compatible	Confirm the connected sensor specification	Set the input signal range to suit the sensor specification.
0		Analog data format is not compatible	Confirm the data format setting of the Analog input unit.	Set the data format of the Analog input unit to suit the application/program.
0	operate normally	Wiring and connection is defective	Confirm the connection between the input sensor and Analog input unit	Correct the wiring between the input sensor and Analog input unit
		Analog Input Unit is defective	Check the Analog input unit and confirm the operation	Replace the Analog input unit and confirm the operation
		Defective sensor	Replace the sensor and confirm the operation.	If the problem continues, refer to the sensor operation manual.
9	Other peripheral units do not operate normally	Defective peripheral units	Confirm that the program at PLC is correct.	For further details, refer to the relevant manuals of each peripheral unit.

## **Parameter Setting**

The EX600 has parameters settings for the system, unit and also each unit's channel, which can be set through PLC or Handheld Terminal.

There are no priorities in setting the parameter. The most recent setting will be reflected on the unit.

## **Parameter Definition**

### **System Parameter**

No	Parameter Name	Contents
1	Hold/Clear Setting Method	Select setting method of output state during communication fault or communication idle state, either with the unit's setting switches or using a HHT. When using an HHT, each channel's output state can be set to Hold/Clear/Force ON. However, when using setting switches, the entire system's output state can be set.

#### SI Unit Parameter

No	Parameter Name	Contents
1	Power Supply Voltage Monitor (Control/Input)	When power supply voltage for control/input goes above 26V or falls below 21V, a diagnostic error will be generated.
2	Power Supply Voltage Monitor (Output)	When power supply voltage for output goes above 26V or falls below 20V, a diagnostic error will be generated.
3	Short Circuit Detection	If short circuit or over current occurs when the valve output is ON, diagnostic error will be generated.
4	Restart after short circuit	When a short circuit at the valve has been removed, the short circuit detection error diagnostic can be set to automatically reset (error will automatically be cleared) or manual reset (error will not be cleared until power supply is reset)
5	Open Circuit Detection	If an open circuit is detected during Valve Output OFF, a diagnostic error will be generated. This setting can be made for each channel.
6	Output setting during communication fault	At the time of communication fault, each channel's Valve Output can be set to Hold, Clear or Force ON setting. This function will only be activated when the Hold/Clear setting method at the system configuration is set to Handheld.
7	Output setting during communication idle	At the time when the communication is idle, each channel's Valve Output can be set to Hold, Clear or Force ON setting. This function will only be activated when Hold/Clear setting method at the system configuration is set to Handheld.
8	Channel ON/OFF Counter	The number of times the valve is ON/OFF is recorded for each channel. There is a set value for each channel, and it is possible to generate a diagnostic error when the set value is reached. However, recording the number of ON/OFF is done in 30 second intervals (30 seconds per channel) from CH0 to the channels which have valve outputs. If the power supply for control and input is turned OFF, the last recorded value for each channel will become valid.

### **Digital Input Unit Parameter**

No.	Parameter Name	Contents
1	Short circuit detection	If a short circuit or over current occurs at the sensor power supply, a diagnostic error will be generated.
2	Open Circuit Detection (Only available for Open Circuit Detection Unit)	<ul> <li>If an open circuit is detected at the input sensor, a diagnostic error will be generated. There is a setting available for each channel.</li> <li>Please note the following:</li> <li>1) When a 2-wire type sensor is used, during OFF state, a leak current of less than 0.5mA will not be detected. A sensor with a leak current of 0.5mA or more (in the OFF state) must be used.</li> <li>2) When a 3-wire type sensor is used, if the sensor has a current consumption of less than 0.5mA, an open circuit may not be detected.</li> </ul>
3	Inrush current filter	When an input equipment with high capacitance is connected, at the time power is supplied, over current will be detected. If the inrush current filter is active, during the first 100msec after power is supplied, over current will not be detected.
4	Input filtering time	A change of signal faster than the input filtering time will be disregarded.
5	Input extension time	An Input signal will be extended to the time set by this parameter. If the signal is longer than the setting, then this parameter's setting will be disregarded.
6	Channel On/Off Counter	The number of times the input is ON/OFF is recorded for each channel. There is a set value for each channel, and it is possible to generate a diagnostic error when the set value is reached. However, the counter value is recorded every one hour. If the power supply for control and input is turned OFF, data that has not been recorded will be cleared.

### **Digital Output unit**

No	Parameter Name	Contents
1	Short Circuit Detection	If a short circuit or over-current occurs at the output's load, a diagnostic error will be generated.
2	Restart after Short Circuit	When a short circuit at the output has been removed, the short circuit detection error diagnostic can be set to automatically reset (error will automatically be cleared) or manual reset (error will not be cleared until power supply is reset)
3	Open Circuit Detection	If an open circuit is detected when the output is in the OFF state, a diagnostic error will be generated. This setting can be made for each channel.
4	Output Setting during communication fault	At the time of communication fault, each channel's output can be set to Hold, Clear or Force ON setting. This function will only be activated when the Hold/Clear setting method at the system configuration is set to Handheld.
5	Output Setting during communication idle	At the time when the communication is idle, each channel's output can be set to Hold, Clear or Force ON setting. This function will only be activated when the Hold/Clear Setting method at the system configuration is set to Handheld.
6	Channel On/Off Counter	The number of times the output is ON/OFF is recorded for each channel. There is a set value for each channel, and it is possible to generate a diagnostic error when the set value is reached. However, the counter value is recorded every one hour. If the power supply for control and input is turned OFF, data that has not been recorded will be cleared.

### Analog Input Unit Parameter

No	Parameter Name	Contents
1	Short Circuit Detection	If a short circuit or over-current occurs at the sensor power supply, a diagnostic error will be generated.
2	Analog input measurement range	Selection of Analog Input Range. The settable measurement ranges are: 010V, 15V, 05V, -10V+10V, -5V+5V, 020mA, 420mA, -20mA+20mA.
3	Analog data format	Select data format, which is output to the PLC from the Analog Input unit. Available selections are: Offset Binary, Signed Binary, 2's Complements.
4	Analog averaging filter	Selection of analog averaging filter. The sampling cycle is about 2 seconds. Selectable values are: No filter, 2 Average (average between the last 2 input values), 4 Average, and 8 Average.
5	Range Upper Limit Error	If the input signal exceeds the upper limit value of the input range (0.5%), a diagnostic error will be generated.
6	Range Lower Limit Error	If the input signal exceeds the lower limit value of the input range (0.5%), a diagnostic error will be generated.
7	User settable value upper limit	If the input signal exceeds the upper limit value of the user settable range, a diagnostic error will be generated. This setting can be made for each channel.
8	User settable value lower limit	If the input signal exceeds the lower limit value of the user settable range, a diagnostic error will be generated. This setting can be made for each channel.

## Parameter's Factory Default Setting

## System Parameter

No	Parameter Name (EDS Parameter)	Setting Value	Contents	Setting Level	Default Setting	Setting Method	
						By PLC	By H.T.
1	Hold/Clear Setting Method (Hold/Clear )	Switch	Hold/Clear Setting is made at SI Unit setting switch.	O System	0		0
		Handheld	Hold/Clear Setting is made at Handheld Terminal			0	

### **SI Unit Parameter**

	Name	Setting	Setting	Default	Setting Method		
No	Parameter) (EDS Value Contents		Contents	Level	setting	By PLC	By H.T.
1	Power supply voltage monitor for control and	Enable	Enable monitoring of power supply voltage for control and input.	Linit	0	0	0
	input (Pwr control monitor)	Disable	Disable monitoring of power supply voltage for control and input.				
	Power supply voltage monitor	Enable	Enable monitoring of power supply voltage for output	11	0	Ο	
2	for output (Pwr output monitor)	Disable	Disable monitoring of power supply voltage for output	Unit			0
2	Short Circuit Detection	Enable	Enable valve short circuit detection	lloit	0	0	0
3	(Monitor short circuit)	Disable	Disable valve short circuit detection	Unit		0	0
	Restart after short circuit (Restart after short circuit)	Auto	After short circuit has been removed, the error will be cleared automatically.		0	0	0
4		Manual	After short circuit has been removed, the error will not be cleared until the power supply is reset.	Unit			
5	Open Circuit Detection (OC_Mon)	Enable	Enable valve open circuit detection	Channel		×	0
5		Disable	Disable valve open circuit detection	Channel	0		
	Output setting during communication fault. (Fault_MD)	Clear	During communication fault, clear valve output.		0	x	ο
6		Hold	During communication fault, hold valve output.	Channel			
		Force On	During communication fault, turn ON valve output.				
	Output setting during communication idle (Idle_MD)	Clear	During communication idle, clear valve output.		0	x	0
7		Hold	During communication idle, hold valve output.	Channel			
		Force On	During communication idle, turn ON valve output.				
	Valve's ON/OFF counter (Counter)	Enable	If valve's ON/OFF counter exceeds the setting value, a diagnostic error will be generated.			x	0
8		Disable	Diagnostic error will not be generated	Channel	0		
		Val	Set maximum counter value. Settable values are (1~65000) x 1000 times		65000		

### **Digital Input Unit Parameter**

	Parameter Name	Setting	Quality	Settina	Default	Setting Method	
No	(EDS Parameter)	r) Value Contents Lev		Level	setting	By PLC	By H.T.
1	Short circuit detection	Enable	Enable sensor's power supply short circuit detection	Lloit	0	0	0
	(Monitor short circuit)	Disable	Disable sensor's power supply short circuit detection	Unit			
2	Open circuit detection	Enable	Enable input sensor open circuit detection	Channol		x	0
2	(Monitor open circuit) Note 1)	Disable	Disable input sensor open circuit detection	Channel	0		
2	Inrush current Filter	Enable	Enable inrush current filter	Lloit	0	0	0
3	(Inrush current filter)	Disable	Disable inrush current filter	Unit			
4	Input Filtering time (Input filtering time)	0.1/1/10/ 20 msec	Set input signal filtering time.	Unit	1msec	0	0
5	Input extension time (Input extension time)	1/15/100/ 200 msec	Set input signal's extension time	Unit	15 msec	0	0
	Input Sensor's ON/OFF (Counter)	Enable	If input sensor's ON/OFF counter exceeds setting value, diagnostic error will be generated.				
6		Disable	Diagnostic error will not be generated	Channel	0	Х	0
		Val	Set maximum counter value. Settable setting value are (1~65000) x 1000 times		65000		

<sup>Note 1)</sup>Open Circuit Detection parameter is only available on Digital input unit with open circuit detection (P/N EX600-DXPC1, EX600-DXNC1).

#### Digital Output Unit Parameter

No	Parameter Name	Setting	Contonto	Setting	Default	Setting Method	
NO	(EDS Parameter) Value Contents		Contents	Level	setting	By PLC	By H.T.
4	Short Circuit Detection (Monitor short circuit)	Enable	Enable output short circuit detection	Linit	0	0	ο
		Disable	Disable output short circuit detection	Onit			
	Restart after Short Circuit (Restart after short circuit)	Auto	After short circuit has been removed, the error will be cleared automatically		0	0	ο
2		Manual	After short circuit has been removed, the error will not be cleared until the power supply is reset	Unit			
_	Open Circuit Detection (Monitor pen circuit)	Enable	Enable output open circuit detection	Channel		x	Ο
3		Disable	Disable output open circuit detection	Channel	0		
	Output setting during communication fault (Fault action)	Clear	During communication fault, clear output	Channel	0	Х	0
4		Hold	During communication fault hold output				
		Force On	During communication fault, turn ON output				
	Output setting during communication idle (Idle mode)	Clear	During communication idle, clear output	Channel	0	х	Ο
5		Hold	During communication idle, hold output				
		Force On	During communication idle, turn ON output				
	Output ON/OFF counter (Switching counter)	Enable	If output ON/OFF counter exceeds the setting value, a diagnostic error will be generated.			x	0
6		Disable	Diagnostic error will not be generated	Channel	0		
		Val	Set the maximum counter value. Settable value are (1~65000) x 1000 times		65000		

Note1) Depending on which PLC is used, there is a model which does not support Idle Function. If that is the case, this function cannot be used.

## Analog Input Unit Parameter (1)

Nia	Parameter Name		Contonto	Setting	Default	Setting Method	
INO	Parameter)	Setting value	Contents	Level	setting	By PLC	By HT
1	Short Circuit Detection	Enable	Enable sensor power supply short circuit detection	Unit	0	0	0
	circuit)	Disable	power supply short circuit detection				
2	Analog Input Range (Ch # Range)	010V, 15V, 05V, -10V+10V, -5V+5V, 020mA, 420mA, -20mA+20mA	Select analog input range	Channel	-10V~1 0V	0	0
3	Analog Data Format (Data format)	Offset Binary, Sign & Magnitude, 2s Complement	Select analog data format	Unit	Offset Binary	0	0
4	Analog Filter (Ch # Filter)	None, 2 value average 4 value average 8 value average	Select analog data filter	Unit	2 value average	0	0
5	Over Range detection (Monitor over range)	Enable	If the analog input exceeds the maximum allowable input range (0.5%), a diagnostic error will be generated	Unit	Enable	0	0
		Disable	Above diagnostic error will not be generated.				
6	Under Range detection (Monitor under range)	Enable	If the analog input exceeds the minimum allowable input range(0.5%), a diagnostic error will be generated	Unit	Enable	0	0
	Tange)	Disable	Above diagnostic Disable error will not be generated.				
7	User Setting Value Upper Limit Error	Enable	If the analog input exceeds the upper user setting lower limit, diagnostic error will be generated	Channel	Disable	x	0
	(Analog upper limit)	Disable	Above diagnostic error will not be generated.				
		Val	Refer to Note1) for possible set value		10V Note2)		



### Analog Input Unit Parameter (2)

No	No	Parameter Name (EDS Parameter)	Setting Value	Contents	Setting Level	Default setting	Setting Method	
	NU						By PLC	By HT
	8	User Setting Value lower Limit Error (Analog under limit)	Enable	If the analog input falls below the lower user setting lower limit, diagnostic error will be generated	Oheenel	Disable	Y	
			Disable	Above diagnostic error will not be generated.	Channel			0
			Val	Refer to Note1) for possible set value		10V Note2)		

Note1) User setting value is settable according to the table below.

Analog input measurement	User setting value set range			
range	Upr_Lmt	Lwr_Lmt		
-10 +10V	-10.5 ~ +10.45V	-10.45 ~ +10.5V		
-5V +5V	-5.25 ~ +5.22V	-5.22 ~ +5.25V		
-20 +20mA	-21 ~ +20.9mA	-20.9 ~ +21mA		
0 +10V	0 ~ +10.45V	0.05 ~ +10.5V		
0 +5V	0 ~ +5.22V	0.02 ~ +5.25V		
+1 +5V	+0.75 ~ +5.22V	+0.77 ~ +5.25V		
0 +20mA	0 ~ +20.9mA	0.1 ~ +21mA		
+4 +20mA	+3 ~ +20.9mA	+3.1 ~ +21mA		

Note 2) Factory default setting for Analog input range is -10...+10V

When changing the analog input measurement range, please make sure to confirm the set value and set the correct value accordingly.

## Configuration

## EDS file and symbol file

EDS files are necessary to configure the EX600. A symbol file is necessary to display an icon of EX600 on a DeviceNet Configurator. The EDS files and symbol file can be downloaded from the URL shown below.

URL: http://www.smcworld.com

- EDS file: ex600\_sdn1\_v16.eds ex600\_sdn1\_v16.eds
- Symbol file: ex600\_1.ico

## Setting with RSNetWorx for DeviceNet

The following explains how to connect EX600 to a DeviceNet network using RXNetWorx (RSNetWorx for DeviceNet version 5.00.00 is used.)

#### Installing EDS files

Save the files using the EDS Wizard, in the RSNetWorx software.

- 1) Start RSNetWorx for DeviceNet.
- 2) Select Tools/EDS Wizard, and save the EDS files for EX600.



#### 3) They are saved in DeviceNet/Category/Communication Adapter folder or DeviceNet/Vendor/SMC Corporation/Communication Adapter folder in the Hardware window.



### Registeration to the network

Register the of EX600 device to the network.

- 1) Double-click EX600-SDN1.
- 2). EX600-SDN1 is shown on the network.


## Address setting for EX600

Set the address of EX600.

- 1) Double-click EX600-SDN1.
- 2) Input or select the DeviceNet address.

2	) 1)
General     Parameters     I/O Data     EDS File       EX600-SDN1       Name:     EX600-SDN1       Description:	In Zoom Out Hardware Favorites Browse Hardware Favorites Network 1756-DNB/A EX600-SI/N1
Address: 1 Device Identity [Primary] Vendor: SMC Corporation [7] Type: Communication Adapter [12] Device: EX600-SDN1 [124] Catalog: EX600-SDN1 Revision: 1.001	
OK     キャンセル     適用(品)     ヘルプ	1

#### Setting of scanlist

Configure the scanlist so that the unit to be installed is known by the master.

- 1) Double-click the scanner.
- 2) Click the Scanlist tab.
- 3) Move EX600-SDN1 in Available Devices; to Scanlist; by pressing ">" button.



#### I/O parameter setting

Set the I/O parameters for EX600.

- 1) Double-click EX600-SDN1 in Scanlist;.
- 2) The Edit I/O parameters window appears.
- 3) Set the I/O parameters, and press the OK button.

	<u> </u>	2)
📲 1756-DNB/A	?×	
General   Module   Scanlist   Input   Output	ADR Summary	Dut Show Show Browse * Online
Availa <u>b</u> le Devices:	Scanlist:	DNB/A EX60-SDN1
	01, EX600-SDN1	
<		
»		
~		
, √ Auto <u>m</u> ap on Add	v Node A <u>c</u> tive	
Upload from Scanner	Electronic Key:	
Download to Scanner	Edit I/O Parameters : 01, EX600	D-SDN1
Edit I/O Parameters	<u>Strobed:</u>	Change of State / Cyclic:
	Input Size: 🛛 📑 Bytes	C Change of State C Cyclic
OK キャンセル	Use Output Bit:	Inpu <u>t</u> Size: 🛛 🕂 Bytes
	Polled:	Output Size:
	Input Size: 8 - Bytes	Heart <u>b</u> eat Rate: 250 <u></u> msec
	Output Size: 5 🕂 Bytes	<u>A</u> dvanced
	Poll <u>R</u> ate: Every Scan 💌	
	ОК Са	ncel Restore I/O Sizes
		I
		3)

Note) Please leave unticked the "Strobed" and "Change of State / Cyclic" tick boxes. These functions are not supported.

# I/O map

#### Allocated input/ output bytes of each unit type

Linit part po	Abbreviation	Description	Allocated bytes	
Onit part no.	Abbieviation	Description	Input	Output
EX600-SDN# (32 points)		SI Unit (32 points)	0	4
EX600-SDN# (24 points)	ei.	SI Unit (24 points)	0	3
EX600-SDN# (16 points)	51	SI Unit (16 points)	0	2
EX600-SDN# (8 points)		SI Unit (8 points)	0	1
EX600-DX#B		Digital input unit	1	0
EX600-DX#C		Digital input unit	1	0
	DX	Digital input unit	1	0
EX000-DX#C1		(Wire breakage detection)	I	0
EX600-DX#D		Digital input unit	2	0
EX600-DY#B	DY	Digital output unit	0	1
		Analog input unit	4	0
		(2 channels)	(2 bytes per channel)	0

The allocated input/ output bytes for each EX600 unit are shown below.

\* EX600-SDN# can change the allocated output bytes with switch setting.

#### Diagnostics

The following diagnostic data is allocated to the top of the I/O mapping input data by switching No. 1 and No. 2 of the Setting2 switch.

Modo	Switch	setting	Diagnostic data		
woue	No1	No2	Diagnostic data	Daignosis size	
0	OFF	OFF	No diagnostic data	0 byte	
1	OFF	ON	System diagnostic	4 bytes	
2	ON	OFF	System diagnostic + Unit diagnostic (for 10 units)	6 bytes	
3 Note 1)	ON	ON	System diagnostic + Unit diagnostic (for 64 units)	12 bytes	

Note 1) Mode 3 is reserved for future expansion of the system.

Mode 3 should not be used at this time.

Note 2) The channel diagnostics cannot be allocated to the input map. Use the hand-held unit for monitoring.



#### Input / output mapping

The input/ output map of each diagnostic mode is shown with the following unit configuration as an example.

	Unit 0	Unit 1	Unit 2	Unit 3	Unit 4	Unit 5	
	AXA	DY#B	DY#B	DX#B	DX#D	SDN#	
0	Analog Input	Digital Output	Digital Output	Digital Input	Digital Input	SI unit (32 output)	Valve 32 points
	4byte input	1byte output	1byte output	1byte input	2byte input	4byte output	

- Input data: Analog input unit (EX600-AXA) (Unit 0) occupies 4 bytes. Digital input unit (EX600-DX#B) (Unit 3) occupies 1 byte. Digital input unit (EX600-DX#D) (Unit 4) occupies 2 bytes.
- Output data: Digital output unit (EX600-DY#B) (Unit 1) occupies 1 byte. Digital output unit (EX600-DY#B) (Unit 2) occupies 1 byte. SI unit (EX600-SDN#) (Unit 5) occupies 4 bytes.

#### When Diagnostic Mode 0 is chosen

	Input data	Output data
Byte0	AXA Channel 0	DY#B( Unit1)
Byte1	(Unit 0)	DY#B(Unit 2)
Byte2	AXA Channel 1	
Byte3	(Unit 0)	SDN#
Byte4	DX#B(Unit 3)	
Byte5	DX#D	
Byte6	(Unit 4)	
TOTAL	7byte	6byte

#### When Diagnostic Mode 1 is chosen

	Input data	Output data
Byte0	System diagnostic byte0	DY#B( Unit 1)
Byte1	System diagnostic byte1	DY#B(Unit 2)
Byte2	System diagnostic byte2	
Byte3	System diagnostic byte3	SDN#
Byte4	AXA channel 0	
Byte5	(Unit0)	
Byte6	AXA channel 1	
Byte7		
Byte8	DX#B(Unit 3)	
Byte9	DX#D	
Byte10	(Unit 4)	
TOTAL	11byte	6byte

# When Diagnostic Mode 2 is chosen

	Input data	Output data
Byte0	System diagnostic byte0	DY#B( Unit 1)
Byte1	System diagnostic byte1	DY#B(Unit 2)
Byte2	System diagnostic byte2	
Byte3	System diagnostic byte3	SDN#
Byte4	Unit diagnostic byte0	
Byte5	Unit diagnostic byte1	
Byte6	AXA channel 0	
Byte7	(Unit0)	
Byte8	AXA channel 1	
Byte9	(Unit 0)	
Byte10	DX#B(Unit 3)	
Byte11	DX#D	
Byte12	(Unit 4)	
Total	13byte	6byte

### Details of diagnostic information

Details of the diagnostic information is shown on below list.

#### System diagnostic

1)	S۱)	/stem	diagno	stic	byte0
----	-----	-------	--------	------	-------

Bit	Diagnostic content
0	Analog input falls below user's setting lower limit value
1	Analog input exceeds user's setting upper limit value
2	Analog input falls below measurement range
3	Analog input exceeds measurement range
4	Channel ON/OFF counter exceeds setting value
5	Open circuit error detected
6	Short circuit detected on value output or digital output
7	Short circuit detected on input sensor's power supply

#### 2) System diagnostic byte1

Bit	Diagnostic content
0	Power supply voltage for output is outside operating range
1	Power supply voltage for control and sensor is outside operating range
2	-
3	Connection error on I/O Unit (during operation)
4	Connection error on I/O Unit (at system start up)
5	Manifold configuration error.
6	System error
7	Hardware error

#### 3) System diagnostic byte2

Bit	Diagnostic content
0~7	(Reserved)

#### 4) System diagnostic byte3

Bit	
0	Error detected on Digital Input unit
1	Error detected on Digital Output unit
2	Error detected on Analog Input unit
3	(Reserved)
4	Error detected on Serial interface unit
5	(Reserved)
6	(Reserved)
7	(Reserved)

# Unit diagnostic

## 1) Unit diagnostic byte0

Bit	Diagnostic content			
0	Error detected on Unit 0			
1	Error detected on Unit 1			
2	Error detected on Unit 2			
3	Error detected on Unit 3			
4	Error detected on Unit 4			
5	Error detected on Unit 5			
6	Error detected on Unit 6			
7	Error detected on Unit 7			

#### 2) Unit diagnostic byte1

Bit	Diagnostic content			
0	Error detected on Unit 8			
1	Error detected on Unit 9			
2	(Reserved)			
3	(Reserved)			
4	(Reserved)			
5	(Reserved)			
6	(Reserved)			
7	(Reserved)			

# DeviceNet object

EX600 supports the following Object Class.

Object	Class No	Instance
Identity	01h	1
Message Router	02h	1
DeviceNet	03h	1
Connection	05h	3
Register	07h	2
Acknowledge Handler	2Bh	1
Мар	65h	1
System	66h	1
Generic Unit	67h	64
Digital Input Unit	6Ah	64
Digital Output Unit	6Bh	64
SI Unit	6Ch	64
Analog Input Unit	6Dh	16

## Map Object(65h)

# Map Object Instance Attribute

Attribute ID	Access	Name	Туре	Description / Value
100	Get	Input Data Size	UINT	Length of Input Data
101	Get	Output Data Size	UINT	Length of Output Data

# System Object(66h)

#### Instance Attribute

Attribute ID	Access	Name	Туре	Description / Value		
105	Get	System Status 1	UINT	<ul> <li>Bit0: Power supply voltage monitor for Output</li> <li>Bit1: Power supply voltage monitor for control and input</li> <li>Bit2: (reserved)</li> <li>Bit3: Unit disconnected</li> <li>Bit4: Connection error</li> <li>Bit5: Configuration memory error</li> <li>Bit6: System Error</li> <li>Bit7: Hardware Error</li> <li>Bit8: Analog value falls below user setting lower value</li> <li>Bit9: Analog value exceeds user setting upper value</li> <li>Bit10: Analog value falls below measurement range lower value</li> <li>Bit11: Analog value exceeds measurement range upper value</li> <li>Bit12: ON/OFF counter exceeded</li> <li>Bit13: Open Circuit detection</li> <li>Bit14: Short circuit detected (at output)</li> <li>Bit15: Short circuit detected (at input)</li> </ul>		
106	Get	System Status 2	UINT	Bit0:Digital Input faultBit1:Digital Output faultBit2:Analog Input faultBit3:(reserved)Bit4:SI unit faultBit5:(reserved)Bit6:(reserved)Bit7:(reserved)Bit8:(reserved)Bit9:(reserved)Bit10:(reserved)Bit11:(reserved)Bit12:(reserved)Bit13:(reserved)Bit14:(reserved)Bit15:(reserved)		

Attribute ID	Access	Name	Туре	Description / Value
109	Get	Number of units	USINT	Number of connected units
160	Get	Unit Diagnostics 1	WORD	Bit0:Unit 0 DiagnosticBit1:Unit 1 DiagnosticBit2:Unit 2 DiagnosticBit3:Unit 3 DiagnosticBit4:Unit 4 DiagnosticBit5:Unit 5 DiagnosticBit6:Unit 6 DiagnosticBit7:Unit 7 DiagnosticBit8:Unit 8 DiagnosticBit9:Unit 9 DiagnosticBit10:(reserved)Bit11:(reserved)Bit13:(reserved)Bit14:(reserved)Bit15:(reserved)Bit15:(reserved)
161	Get	Unit Diagnostics 2	WORD	(reserved)
162	Get	Unit Diagnostics 3	WORD	(reserved)
163	Get	Unit Diagnostics 4	WORD	(reserved)
164	Get	Unit Connection 1	WORD	Bit0:Unit 0 ConnectionBit1:Unit 1 ConnectionBit2:Unit 2 ConnectionBit3:Unit 3 ConnectionBit4:Unit 4 ConnectionBit5:Unit 5 ConnectionBit6:Unit 6 ConnectionBit7:Unit 7 ConnectionBit8:Unit 8 ConnectionBit9:Unit 9 ConnectionBit10:(reserved)Bit11:(reserved)Bit12:(reserved)Bit13:(reserved)Bit14:(reserved)Bit15:(reserved)
165	Get	Unit Connection 2	WORD	(reserved)
166	Get	Unit Connection 3	WORD	(reserved)
167	Get	Unit Connection 4	WORD	(reserved)
102	Get/Set	Hold / Clear	BOOL	0 = Switch, 1 = Handheld

# Generic unit Object (67h)

#### **Instance Attribute**

Attribute ID	Access	Name	Туре	Value
102	Get	Unit Type	USINT	
106	Get	Unit Diagnosi	WORD	

# Digital Input Unit Object (6Ah)

#### Instance Attribute

Attribute ID	Access	Name	Туре	Value	
112	Get/Set	Monitoring short circuit	BOOL		0=Disable 1=Enable
120	Get/Set	Inrush current filter	BOOL		1=Active 0=Inactive
164	Get/Set	Input filtering time	WORD		0 = 0.1ms 1 = 1.0ms 2 = 10ms 3 = 20ms
168	Get/Set	Input extension time	WORD		0 = 0.1ms 1 = 15ms 2 = 100ms 3 = 200ms

# Digital Output unit Object(6Bh)

#### Instance Attribute

Attribute ID	Access	Name	Туре	Description	Value
113	Get/Set	Monitor short circuit	BOOL		0=Disable 1=Enable
123	Get/Set	Restart after Short Circuit	BOOL		0=Disable 1=Enable

# SI unit Object (6Ch)

Instance Attribute

Attribute ID	Access	Name	Туре	Description	Value
113	Get/Set	Monitor short circuit	BOOL		0=Disable 1=Enable
123	Get/Set	Restart after short circuit	BOOL		0=Disable 1=Enable
172	Get/Set	Pwr control monitor	BOOL		0=Disable 1=Enable
173	Get/Set	Pwr output monitor	BOOL		0=Disable 1=Enable

# Analog Input unit Object (6Dh)

Attribute ID	Access	Name	Туре	Value	
112	Get/Set	Monitor short circuit	BOOL		0=Disable 1=Enable
116	Get/Set	Monitor over range	BOOL		0=Disable 1=Enable
117	Get/Set	Monitor under range	BOOL		0=Disable 1=Enable
164	Get/Set	Ch 0 input filter	UINT	СНО	0 = None 1 = 2 value average 2 = 4 value average 3 = 8 value average
165	Get/Set	Ch 1 input filter	UINT	CH1	0 = None 1 = 2 value average 2 = 4 value average 3 = 8 value average
168	Get/Set	Ch 0 range	UINT	СНО	0 = -10+10V 1 = -5+5V 2 = -20+20mA 3 = 010V 4 = 05V 5 = 15V 6 = 020mA 7 = 420mA
169	Get/Set	Ch 1 range	UINT	CH1	0 = -10+10V 1 = -5+5V 2 = -20+20mA 3 = 010V 4 = 05V 5 = 15V 6 = 020mA 7 = 420mA
172	Get/Set	Data format	USINT		0=Offset Binary 1=Sign & Magnitude 2=2's complement

Instance Attribute

**SMC** 

## Accessories

Please refer to the catalogue for selecting the accessories.

(1)Valve Plate Used for mounting solenoid valve manifold and SI unit.

EX600-ZMV1

(2)Metal fittings for End plate Metal fittings used with End plate when installed on DIN rail.

EX600-ZMA2

(3)Metal fittings for the intermediate reinforcement Metal fittings used at the intermediate position when more than 6 units are assembled.

EX600-ZMB1	For direct mounting
EX600-ZMB2	For DIN rail mounting

(4)Seal cap (10 pcs included) Please install a seal cap in all unused input/output connectors, to maintain the protective construction of IP67.

EX9-AWES	For M8
EX9-AWTS	For M12

(5)Marker (1 sheet, 88pcs included)

A marker to show input/output equipment signal names and unit addresses, etc. can be inserted for each unit.

EX600-ZT1

(6)Y Junction connector

Connector used to branch off between sensor and input unit.

PCA-1557785 2×M12(3 pin)-M12(5 pin)

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## (7)Assembled type connector

PCA-1558797	Power supply cable 7/8",Plug
PCA-1558807	Power supply cable 7/8",Socket
PCA-1557659	DeviceNet <sup>™</sup> communication cable, Plug
PCA-1557662	DeviceNet <sup>™</sup> communication cable, Socket
PCA-1557730	M8(3 pin),Plug
PCA-1557743	M12(4 pin),Plug ,AWG26~AWG22,SPEEDCON compatible
PCA-1557756	M12(4 pin), Plug , AWG22~AWG18, SPEEDCON compatible

(8)Power supply cable

PCA-1558810	Cable with 7/8" connector, Socket, Straight 2m
PCA-1558823	Cable with 7/8" connector, Socket, Straight 6m
PCA-1558836	Cable with 7/8" connector, Socket, Right angle 2m
PCA-1558849	Cable with 7/8" connector, Socket, Right angle 6m
PCA-1564927	Cable with M12 connector, B Code, Socket, Straight 2m,
	SPEEDCON compatible
PCA-1564930	Cable with M12 connector, B Code ,Socket ,Straight 6m,
	SPEEDCON compatible
PCA-1564943	Cable with M12 connector, B Code, Socket, Right angle 2m,
	SPEEDCON compatible
PCA-1564969	Cable with M12 connector, B Code, Socket, Right angle 6m,
	SPEEDCON compatible

# (9) DeviceNet<sup>™</sup> communication cable

PCA-1557633	Cable with M12 connector cable, A Code, Socket, Straight 5m,
	SPEEDCON compatible
PCA-1557646	Cable with M12 connector, A Code, Plug, Straight 5m,
	SPEEDCON compatible

### (10)Connector extension cable

PCA-1557769	M12(4pin),Straight 3m
PCA-1557772	M8(3pin),Straight 3m

**Revision history** 

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