

# **Operation Manual**

Fieldbus system PROFIBUS DP compatible PRODUCT NAME

> EX600-SPR\* EX600-DX\* EX600-DY\* EX600-AX\* EX600-ED\* MODEL/ Series

**SMC** Corporation

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### **Safety Instructions**

These safety instructions are intended to prevent hazardous situations and/or equipment damage. These instructions indicate the level of potential hazard with the labels of "Caution," "Warning" or "Danger.". They are all important notes for safety and must be followed in addition to International standards (ISO/IEC), Japan Industrial Standards (JIS)<sup>\*1)</sup> and other safety regulations<sup>\*2)</sup>.

- \*1) ISO 4414: Pneumatic fluid power - General rules relating to systems.
  - ISO 4413: Hydraulic fluid power - General rules relating to systems.
  - IEC 60204-1: Safety of machinery -Electrical equipment of machines. (Part 1: General requirements)
  - ISO 10218-1992: Manipulating industrial robots -Safety.
  - JIS B 8370: General rules for pneumatic equipment.
  - JIS B 8361: General rules for hydraulic equipment.
  - JIS B 9960-1: Safety of machinery Electrical equipment of machines. (Part 1: General requirements)
  - JIS B 8433-1993: Manipulating industrial robots Safety. etc.
- \*2) Labor Safety and Sanitation Law, etc.

Caution : Operator error could result in injury or equipment damage.
 Warning : Operator error could result in serious injury or loss of life.
 Danger : In extreme conditions, there is a possibility of serious injury or loss of life.

# Warning

1. The compatibility of the product is the responsibility of the person who designs the equipment or decides its specifications.

Since the product specified here is used under various operating conditions, its compatibility with specific equipment must be decided by the person who designs the equipment or decides its specifications based on necessary analysis and test results. The expected performance and safety assurance of the equipment will be the responsibility of the person who has determined its compatibility with the product. This person should also continuously review all specifications of the product referring to its latest catalog information, with a view to giving due consideration to any possibility of equipment failure when configuring the equipment.

- 2. Only personnel with appropriate training should operate machinery and equipment. The product specified here may become unsafe if handled incorrectly. The assembly, operation and maintenance of machines or equipment including our products must be performed by an operator who is appropriately trained and experienced.
- 3. Do not service or attempt to remove product and machinery/equipment until safety is confirmed.
- 1. The inspection and maintenance of machinery/equipment should only be performed after measures to prevent falling or runaway of the driven objects have been confirmed.
- 2. When the product is to be removed, confirm that the safety measures as mentioned above are implemented and the power from any appropriate source is cut, and read and understand the specific product precautions of all relevant products carefully.
- 3. Before machinery/equipment is restarted, take measures to prevent unexpected operation and malfunction.
- 4. Contact SMC beforehand and take special consideration of safety measures if the product is to be used in any of the following conditions.
  - 1. Conditions and environments outside of the given specifications, or use outdoors or in a place exposed to direct sunlight.
- 2. Installation on equipment in conjunction with atomic energy, railways, air navigation, space, shipping, vehicles, military, medical treatment, combustion and recreation, or equipment in contact with food and beverages, emergency stop circuits, clutch and brake circuits in press applications, safety equipment or other applications unsuitable for the standard specifications described in the product catalog.
- 3. An application which could have negative effects on people, property, or animals requiring special safety analysis.
- 4. Use in an interlock circuit, which requires the provision of double interlock for possible failure by using a mechanical protective function, and periodical checks to confirm proper operation.



# Caution Caution I. The product is provided for use in manufacturing industries. The product herein described is basically provided for peaceful use in manufacturing industries. If considering using the product in other industries consult SMC beforehand and exchange specifications

or a contract if necessary.

If anything is unclear, contact your nearest sales branch.

#### Limited warranty and Disclaimer/Compliance Requirements

The product used is subject to the following "Limited warranty and Disclaimer" and "Compliance Requirements".

Read and accept them before using the product.

#### Limited warranty and Disclaimer

- 1. The warranty period of the product is 1 year in service or 1.5 years after the product is delivered.<sup>\*3)</sup> Also, the product may have specified durability, running distance or replacement parts. Please consult your nearest sales branch.
- For any failure or damage reported within the warranty period which is clearly our responsibility, a replacement product or necessary parts will be provided. This limited warranty applies only to our product independently, and not to any other damage
- incurred due to the failure of the product.
- 3. Prior to using SMC products, please read and understand the warranty terms and disclaimers noted in the specified catalog for the particular products.
  - \*3) Vacuum pads are excluded from this 1 year warranty.
    - A vacuum pad is a consumable part, so it is warranted for a year after it is delivered.
  - Also, even within the warranty period, the wear of a product due to the use of the vacuum pad or failure due to the deterioration of rubber material are not covered by the limited warranty.

#### **Compliance Requirements**

When the product is exported, strictly follow the laws required by the Ministry of Economy, Trade and Industry (Foreign Exchange and Foreign Trade Control Law).



### Operator

- This operation manual has been written for those who have knowledge of machinery and apparatus that use pneumatic equipment and have full knowledge of assembly, operation and maintenance of such equipment.
- Please read this operation manual carefully and understand it before assembling, operating or providing maintenance.

# **Warning**

♦ Do not disassemble, modify (including change of printed circuit board) or repair this product. Injury or failure can result.

- ♦ Do not perform operation or setting with wet hands.
- There is a risk of electric shock.

Do not operate the product beyond the specification range.
 Do not apply the product to flammable gas or liquid or the gas or liquid harmful to human body.
 Otherwise it causes fire, malfunction, or damage to the system.
 Please confirm the specifications before use.

•Do not operate the product in an environment where flammable or explosive gas may be present.

Fire, explosion or corrosion can result.

The product is not designed to be explosion proof.

• The following instructions must be followed when using the product in an interlocking circuit:

- Provide multiple interlocking using another system such as mechanical protection
- Check the product regularly to ensure proper operation Otherwise malfunction can cause an accident.

• The following instructions must be followed while performing maintenance work:

• Turn off the power supply

• Stop the air supply, exhaust the residual pressure and verify that the air is released to atmosphere before performing maintenance work

Otherwise it can cause injury.

# **A**Caution

♦When handling, assembling and replacing the unit:

- When handling the unit, do not touch any sharp metal parts of the connector and plug.
- When disassembling the unit, do not strike the product forcefully.
  - The connection parts are firmly joined with seals.
- When joining units, take care not to get your fingers trapped between units.
- Perform a proper functional check after completing maintenance work.
   Stop operation if any abnormality is observed or if the product is not working properly.
   Safety cannot be assured due to unexpected malfunction.

Provide grounding to assure the safety and noise resistance of the fieldbus system. Individual grounding should be provided close to the product with a short cable.

# NOTE

- Follow the instructions given below when handling the fieldbus system. Otherwise, the system may be damaged and may fail.
- The instructions on selection (installation, wiring, operating environment, adjustment, operation and maintenance) described below must also be followed.

#### **Product specifications**

- Use the following UL recognized direct-current (DC) power supply.
  - (1) Limited voltage current circuit in accordance with UL508
    - A circuit whose power is supplied by secondary coil of an isolating transformer that meets the following conditions
    - Maximum voltage (with no load) : less than 30 Vrms (42.4 Vpeak)
    - Maximum current : (1) less than 8A (including when short circuited)
      - (2) limited by circuit protector (such as a fuse) with the following ratings

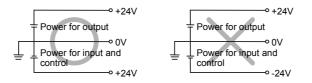
| No load voltage (Vpeak) | Max. current rating (A) |
|-------------------------|-------------------------|
| 0 ~ 20 [V]              | 5.0                     |
| Above 20 to 30 [V]      | 100 / peak voltage      |

(2) A circuit using max. 30 Vrms or less (Class-2 circuit), whose power is supplied by Class-2 power supply unit in accordance with UL1310 or by Class-2 power supply unit in accordance with UL1585

• Operate the fieldbus system within the specified voltage.

Operation with a voltage outside of the specifications could cause malfunction or damage to the system.The reference for the power supply of the SI unit is 0 V for both the output and control power supplies of

the SI unit.



• Do not mount in a location where the product will be used as a foothold.

The unit may be damaged if excessive force is applied by stepping or climbing onto it.



- Reserve sufficient space for maintenance around the product
- Be sure to reserve sufficient space for maintenance when designing the layout of the system.
- Do not remove any nameplates or labels. This can lead to incorrect maintenance, or misreading of the operation manual, which could cause damage or malfunction to the unit. It may also result in non-conformity to safety standards.
- Be careful regarding the inrush current generated when the power is supplied.
- Depending on the connected load, an initial charging current may cause an over current protective function resulting in malfunction of the system.

#### Precautions for handling Installation

- Do not drop, hit or apply excessive shock to the unit. Otherwise the unit could be damaged, resulting in failure.
- Tighten screws to the specified tightening torque.
   Excessive tightening torque can break the screws.
   IP67 protection cannot be guaranteed if the screws a
- IP67 protection cannot be guaranteed if the screws are not tightened to the specified torque.
- When lifting a large size solenoid valve manifold unit, take care to avoid causing stress to the valve connection joint

The connection parts of the unit may be damaged.

Because the unit may be heavy, carrying and installation should be performed by more than one operator to avoid strain or injury.

#### Wiring (including plugging in/out of connector)

- Do not bend the cables or apply excessive force by pulling or placing heavy loads on them.
- Bending or tensile stress could cause the cables to break.
- Connect wires and cables correctly. Incorrect wiring could break the fieldbus system.
- Do not connect wires while the power is supplied.

This can damage components and also cause undisirable behaviour

- Do not lay wires and cables together with power or high-voltage cables in the same wiring route. Otherwise the wires to the fieldbus system could be affected by noise or induced surge voltage from power lines or high-voltage cables, causing malfunction. Route the wires to the SI Unit and each I/O device to a wire duct or in a protective tube other than those for power lines or high-voltage cables
- Verify the insulation of wiring.
   Poor insulation (interference with other circuits, poor insulation between terminals, etc.) can introduce excessive voltage or current to the SI Unit or each I/O device causing damage.
- Separate the power line for solenoid valves from the power line for input and control unit. Otherwise wires can be affected by noise or induced surge voltage, causing malfunction.
- Take appropriate measures against noise, such as using a noise filter, when the fieldbus system is incorporated into equipment. Otherwise noise can cause malfunction.

#### **Operating environment**

- Select the proper type of protection according to the environment of operation.
  - IP65/67 protection is achieved when the following conditions are met.
    - (1). The units are connected properly with communication line connector and power cable M12 connector at both ends,
    - (2) Suitable mounting of each unit and manifold valve.
    - (3) Be sure to mount a seal cap on any unused connectors.
      - If using in an environment that is exposed to water splashes, please take measures such as using a cover.



• Take sufficient shielding measures if the unit is installed in any of the locations described below. Insufficient measures could cause malfunction or failure.

Verify the effectiveness of the measures after incorporation of the unit into the equipment.

- (1) A place where noise is generated due to static electricity
- (2) A place where electric field strength is high
- (3) A place where there is radioactive irradiation
- (4) A place near a power line
- Do not use in an environment exposed to oil or chemicals.
- Using the product in an environment exposed to any type of oil or chemicals, such as coolants and cleaning fluids, may adversely affect the unit, causing failure or malfunction reducing the life of the product.
- Do not use in an environment exposed to corrosive gases or liquids. The unit may be damaged, leading to malfunction.
- Do not use the unit near to a place where electrical surges are generated. Internal circuit elements of the fieldbus system can deteriorate or break if equipment generating a large surge (electromagnetic lifter, high frequency induction furnace, motor, etc.) is located near the fieldbus system. Provide surge prevention measures, and avoid interference.
- Use the fieldbus system equipped with a surge absorber if a surge-generating load such as a solenoid valve is driven directly.
- Direct drive of a load generating surge voltage can damage the fieldbus system.
- The product does not have resistance against lightning surges required for CE marking, so please take measures against lightning surge on the equipment side.
- Make sure foreign matter such as dust and piping waste does not get inside the product. This may cause failure or malfunction.
- Do not expose the fieldbus system to vibration or impact. Otherwise failure or malfunction could be caused.
- Do not use in an environment that is subject to a temperature cycle. If it is subjected to a temperature cycle outside of normal temperature changes, this may adversely affect the internal parts of the unit.
- Do not use in a location directly exposed to sunlight. If the product is located in such a position, arrange a suitable cover to protect the unit. Direct exposure to sunlight may cause failure or malfunction.
- Keep within the specified ambient temperature range. Otherwise malfunction could be caused. Do not use the fieldbus system in a place where temperature changes suddenly, even within the specified range.
- Do not expose the fieldbus system to heat radiation from a heat source located nearby. Malfunction could be caused.

#### Adjustment and Operation

- Set the switches using a small screwdriver, etc.. When operating the switches, do not touch parts other than the related parts. This may lead to failure due to component damage or short-circuit.
- Perform setting appropriate to the operating conditions. Inappropriate settings can cause defective operation.
- Please refer to page20-23 of this document for the settings of each switch.
- Please refer to the PLC manufacturer's manual for details of programming and addresses. For the PLC protocol and programming refer to the relevant manufacturer's documentation.

#### **Maintenance and Checks**

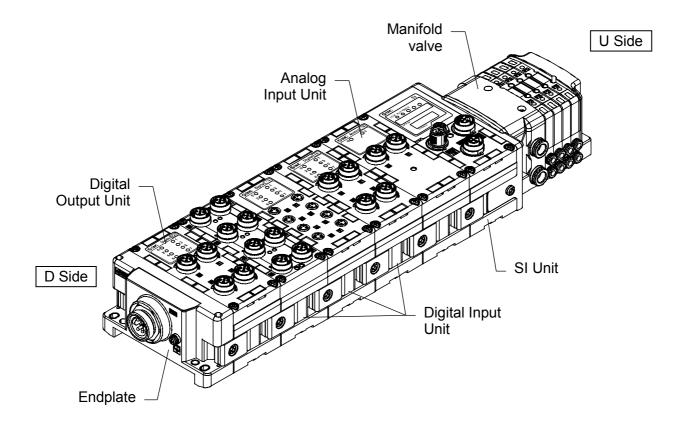
- Before performing maintenance work, turn off the power supply, stop the supply of air, exhaust the compressed air from inside the piping, and verify that the air is released to atmosphere. Otherwise, there is a risk of unexpected malfunction of the system components.
- Perform maintenance and checks regularly. Otherwise unexpected malfunction of components could occur due to a malfunction of the whole unit.
- Perform appropriate functional checks. Stop operation if any abnormality is observed or if the device does not work properly. Otherwise an unexpected malfunction of the unit or components could occur.
- Do not use solvents such as benzene, thinner, etc. to clean the fieldbus system. They could damage the surface of the body and erase the indication markings on the body. Use a soft cloth to remove stains. For heavy stains, use a cloth soaked in diluted neutral detergent and fully squeezed, then wipe again with a dry cloth.

### **Product Outline**

#### System configuration

The EX600 range of units can be connected to various types of Fieldbus to realize the reduction of I/O device wiring and the distributed control system. The unit communicates with the Fieldbus through the SI unit. One SI unit can be connected with manifold valves with up to 32 points and I/O units with maximum 10 points.

All wiring between devices use cables with connectors at both ends and the system is compliant to IP67 protection.



- SI unit: Performs fieldbus communication and solenoid valve manifold ON/OFF output.
- Digital Input unit: For connecting sensors with switch output capability. PNP and NPN types are available.
- Digital Output unit: For connecting output equipment such as solenoid valves, lamps, buzzers, etc. PNP and NPN types are available.
- Analog Input unit: For connecting sensors with analog output capability.
- Endplate: Connected at EX600 Manifold's D side, incorporating the power supply connection.
- Solenoid valve manifold: An assembly of solenoid valves. One connector is used as the electric connection to all connected valves.



#### Glossary

| No. | Term                         | Definition   |
|-----|------------------------------|--|
| А   | Address<br>(Station Address) | Number allocated to identify each unit connected on PROFIBUS DP network. Address number is not permitted to be duplicated.   |
| С   | Communication speed          | Data receive and transmit speed used by the fieldbus. This depends on master equipment (PLC etc.), the unit used is bps (bit per second).  |
| С   | Current consumption          | The amount of current required by each unit in order to operate.   |
| D   | Diagnosis<br>Information     | Diagnosis information that composed of standard diagnosis information of PROFIBUS DP and EX600 diagnosis information.  |
| D   | DIN rail                     | Metal rail in accordance with DIN standard.  |
| D   | D Side                       | T The DOWN side of the manifold, where EX600 Endplate is connected   |
| F   | FAIL SAFE<br>Function        | When PLC (DP master) is at clear mode, it sends data packet of output data with data length ="0". As a result the slave will be set to a defined state (Hold/Clear/Force ON).        |
| F   | FE                           | Functional Earth.  |
| F   | Fieldbus                     | Type of communication system between a PLC and factory equipment (such as measuring instruments or machines), in which data is exchanged by digital communication.                   |
| F   | FREEZE Function              | Function which synchronizes input data of SI unit with FREEZE Command from PLC (DP master).  |
| G   | GSD file                     | General Station Description file. This is a file which describes the product characteristics for configuration with PROFIBUS DP system.  |
| н   | Handheld Terminal<br>(H.T.)  | A unit to connect with the SI unit PCI connection, for parameter adjustment, to monitor all input and output signal status, and for Forced input/output selection.                   |
| Ι   | ID No.                       | 16 bit number which is assigned by PNO to identify the product   |
| I   | Idle                         | Condition when SI unit (PROFIBUS DP) receives FAIL SAFE command.<br>Using parameter setting, output can be set to CLEAR/HOLD/Force ON.   |
| I   | Input points                 | Number of points that which can receive information from input equipment. (Sensor and switch, etc.)  |
| М   | Manifold                     | An assembly with many openings for receiving and distributing fluid or gas.  |
| N   | NPN output                   | Output that switches a load through an NPN transistor. The +ve side of the load is connected to a common +ve. For this reason, NPN output is often referred to as "common positive". |
| Ν   | NPN input                    | Input that receives data from sensor with an NPN output signal.  |
| 0   | Open circuit detection       | Diagnosis function which detects open circuit, caused by broken or disconnected wiring to the input/output equipment.  |
| 0   | Output Points                | Number of points of output equipment (Solenoid Valve, lamp, motor starter, etc.) which can be operated.  |

| No. | Term                        | Definition  |  |  |
|-----|-----------------------------|---|--|--|
| Р   | PLC                         | Programmable Logic Controller. A Controller which performs sequential control using programs of logical, order and arithmetic operation, etc.   |  |  |
| Р   | PNP output                  | Output that switches a load through a PNP transistor. The –ve side of the load is connected to the 0V common return. For this reason, PNP output is often referred to as "common negative". |  |  |
| Р   | PNP input                   | Input that receives data from sensor with PNP output signal.  |  |  |
|     | PROFIBUS DP                 | Fieldbus that Siemens, Bosch, and ABB, etc. jointly developed in Germany  |  |  |
| Р   |                             | in 1980's. PNO (PROFIBUS Nutzerorganisation e.V) is started in order to   |  |  |
|     |                             | spreads the PROFIBUS.   |  |  |
| Р   | Protection Class<br>(IP□□)  | International Protection Rating. A Standard related to protection against foreign objects into electrical enclosures. (Hand,wire, dust, and water, etc.)                                    |  |  |
| S   | Short circuit detection     | Function that detect if output or power supply positive line is short circuited with GND, thus over current state has occurred.   |  |  |
| S   | Short circuit<br>protection | Internal circuit protection to prevent damage by over current caused by power supply positive line being short circuit with GND   |  |  |
| S   | SI unit                     | Serial Interface Unit. A unit for connection with a PLC, to and perform input/output data communication.  |  |  |
| S   | SYNC Function               | Function that synchronizes output data of SI unit with SYNC command from a PLC (DP master).   |  |  |
| Т   | Terminating resistance      | When connecting device to the fieldbus, resistance must be installed on both ends of wiring system. This prevents signal reflection, and maintains data integrity.                          |  |  |
| U   | U Side                      | The UP side of the manifold, where solenoid valve manifold is connected.  |  |  |

### Assembly

Composing the unit as a manifold.

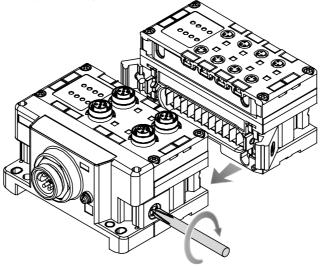
\*: If the unit was purchased as a manifold, the work described in this section is not necessary.

#### Note

Be sure to turn off the power when carrying out the work to compose the unit as a manifold.

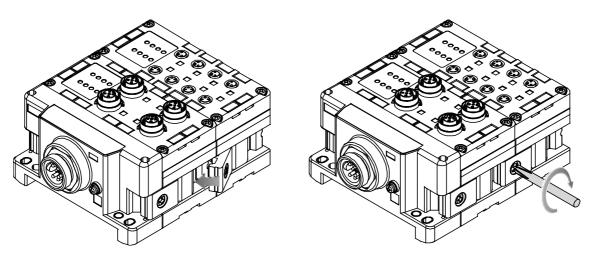
#### (1) Connect the unit to the end plate

Digital input unit/digital output unit/Analog unit can be connected in any order. Tighten the bracket of the joint using Tightening torque 1.5 to 1.6 N•m.



#### (2) Add more units

Up to 10 units (including the SI unit) can be connected to one manifold.



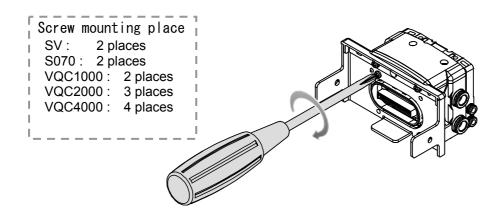
#### (3)Connecting SI unit

After connecting the necessary units, connect the SI unit. Connecting method is the same as above.



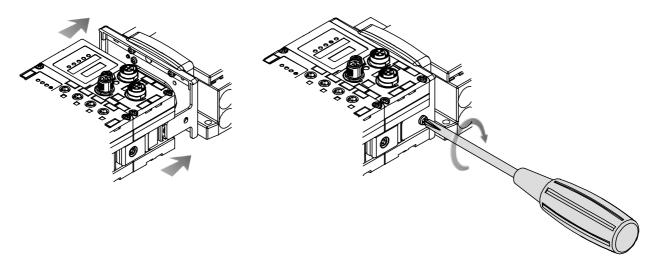
#### (4) Mounting the valve plate

Mount the valve plate to the manifold solenoid valve using the valve set screws. Apply 0.6 to 0.7N•m tightening torque to the screws.



(5) Connect the SI unit and the manifold solenoid valve.

Insert the valve plate to the valve plate set groove on the side of SI unit. Then, tighten it with the valve plate set screws to fix the plate. Tightening torque for set screws 0.7 to 0.8N•m.



#### Note:

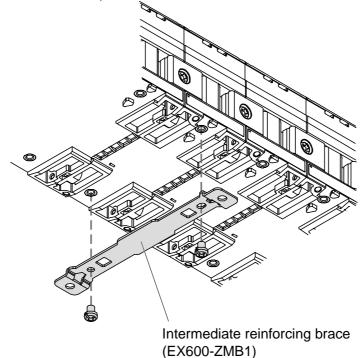
Please do not connect the unit while the power supply is active. It will cause equipment damage.

# **Mounting and Installation**

#### Installation method

#### (1) Direct mounting

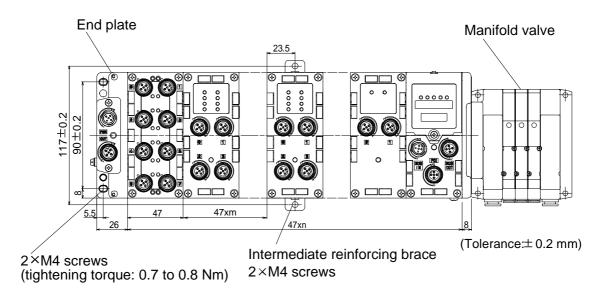
When joining six or more units, fix the middle part of the complete EX600 unit with an intermediate reinforcing brace (EX600-ZMB1) before mounting (Refer to the figure below.) using 2xM4 screws (Tightening torque: 0.7 to 0.8 N•m)



Fix and tighten the end plates at one end of the unit as shown in the figure below.

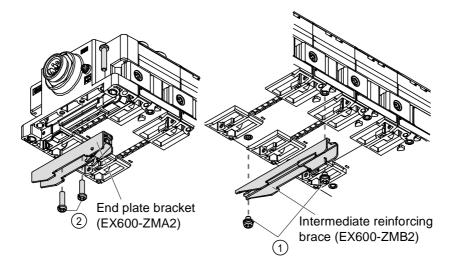
(Tightening torque: 0.7 to 0.8 N•m)

Fix the end plate at the valve side while referring to the operation manual of the corresponding manifold valve.



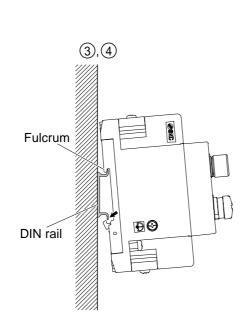
#### (2) DIN rail mounting

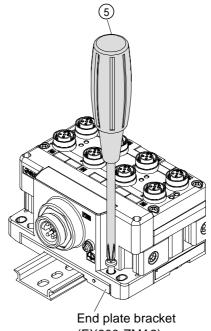
- (i) When joining six or more units, fix the middle part of the complete EX600 unit with an intermediate reinforcing brace (EX600-ZMB2) before mounting, using 2xM4 screws (Tightening torque: 0.7 to 0.8 N•m)
- (ii) Mount the end plate bracket (EX600-ZMA2) to the end plate at the opposite end to the valves, using 2xM4 screws (Tightening torque: 0.7 to 0.8 N•m)



- (iii) Hook the DIN rail mounting groove to the DIN rail. (See the figure below.)
- (iv) Press the manifold using its side hooked to the DIN rail as a fulcrum until the manifold is locked.
- (v) Fix the manifold by tightening the DIN rail fixing screws of the EX600-ZMA2.
  - (Tightening torque: 0.7 to 0.8 Nm)

The tightening torque at the valve side depends on the valve type.



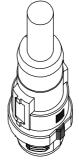


#### • Wiring

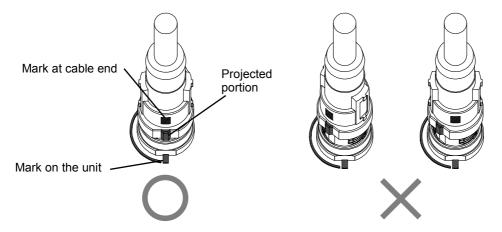
The M12 connector can be mated with a SPEEDCON connector or standard M12 connector.

(1) Set the projected portion of the cable connector metal ring (plug / socket) to the mark.



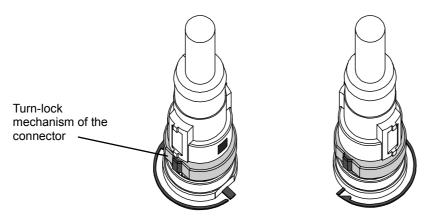


(2) Push the connector straight to insert it into the receptacle of the unit. If inserted without aligning the mark, the connector will not mate with the receptacle.



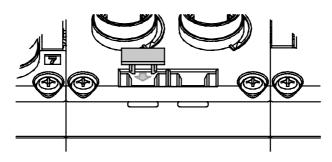
(3) Turn the connector clockwise. It stops when turned 1/4 turn.Turn it further. When the connector is turned 1/2 turn from the original position, the projected portion is set at the diagonal position to the mark and the turn is completed.

Check that the connector is securely locked.

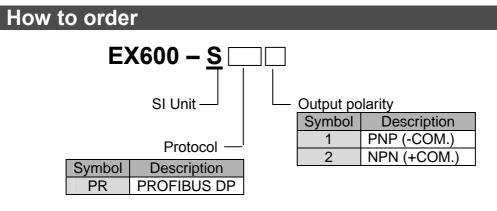


If the connector is turned excessively, it will become difficult to remove.

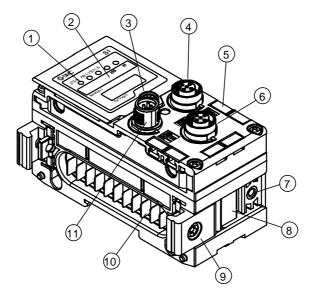
• Mounting the marker Mount the marker (EX600-ZT1) into the marker groove as required.



#### SI Unit



# Name and Function of the Parts



| No. | Name  | Description                                 |
|-----|---|---|
| 1   | Status indication LED   | Indicates the unit status                   |
| 2   | Indication cover  | Open to gain access to the Setting switches |
| 3   | Indication cover set screw  | Loosen to open the cover                    |
| 4   | Connector(BUS OUT)  | Connector for FieldBus output               |
| 5   | Marker groove Groove to mount an indication marker                                  |   |
| 6   | Connector (H.T.)  | Connector to connect handheld terminal      |
| 7   | Valve plate mounting hole Holes for fixing the valve plate                          |   |
| 8   | Valve plate mounting groove Groove for mounting the valve plate                     |   |
| 9   | Joint bracket Bracket used to secure the adjacent unit                              |   |
| 10  | Connector for unit (Plug) Conveys the signals and power supply to the adjacent unit |   |
| 11  | Connector (BUS IN) Connector for FieldBus input                                     |   |

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**SMC** 

Display indicator and description



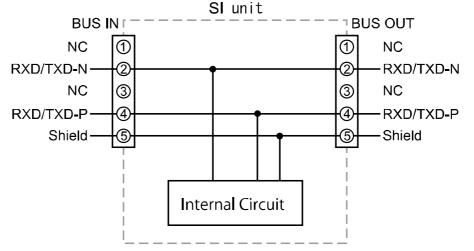
| Indicator | Description                                     |  |  |  |  |
|-----------|---|--|--|--|--|
| ST(M)     | Unit diagnostics status                         |  |  |  |  |
| PWR       | Displays the power supply voltage status of the |  |  |  |  |
|           | power supply for control and input              |  |  |  |  |
| PWR(V)    | Displays the power supply voltage status of the |  |  |  |  |
| FVIC(V)   | power supply for output                         |  |  |  |  |
| SF        | System fault                                    |  |  |  |  |
| BF        | Bus fault                                       |  |  |  |  |
|           |   |  |  |  |  |

### **Mounting and Installation**

Connector Pin Assignment

|         | Oimedia     | Configuration |               |  |
|---------|-------------|---------------|---------------|--|
| Pin No. | Signal name | BUS IN        | BUS OUT       |  |
| 1       | NC          | 2 _ 1         | 1 7 2         |  |
| 2       | RXD/TXD-N   |               |               |  |
| 3       | NC          | (50)          | (5 <b>0</b> ) |  |
| 4       | RXD/TXD-P   |               |               |  |
| 5       | Shield      | 5 — 4         | 4 3           |  |

The branch connection is arranged in the EX600-SPR1/2 as illustrated on the circuit below. When connecting other PROFIBUS DP products, connect using the BUS OUT connector, to increase the number of PROFIBUS DP Slave stations.



#### Note

Be sure to place a seal cap on any unused connectors. Placing the seal cap appropriately enables the unit to achieve IP67 protection.

**SMC** 

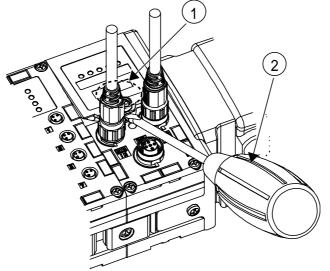
#### Transmission distance

For communication wiring, PROFIBUS DP compatible shielded twisted pair cable must be used. The longest permissible cable length depends on transmission speed and type of cable used. The table below gives data for when type A cable is used.

| Communication<br>speed [kbps] | 9.6 | 19.2 | 45.45 | 93.75 | 187.5 | 500 | 1500 | 3000 | 6000 | 12000 |
|-------------------------------|-----|------|-------|-------|-------|-----|------|------|------|-------|
| Cable length [m]              | 12  | 00   | 10    | 00    | 4(    | 00  | 20   | 00   | 1(   | 00    |

### **Setting and Adjustment**

- Setting procedure
- (1) Loosen the screw of the switch protection cover (indicated with an arrow).
- (2) Open the cover with a flat blade screwdriver.



(3) Perform the switch settings referring to the following pages.

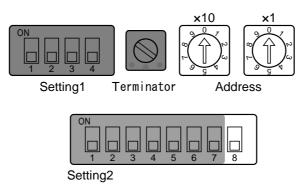
Set the switches with a small point precision screwdriver.

(4) After setting the switches close the switch protection cover and tighten the screw in the reverse order to the above. (Tightening torque: 0.3 to 0.4 Nm)

#### Note

- When adjusting the switch, make sure not to touch other parts other than the setting switch. Failure can be caused by damaged parts or short circuit.
- Be sure to perform the switch settings with the power turned OFF.
- All switches are set to OFF or 0 when delivered (Factory setting). Perform the switch settings before use.
- When any foreign matter or water droplets are observed near the switch protection cover, wipe them off before opening the cover.

oAddress setting switch

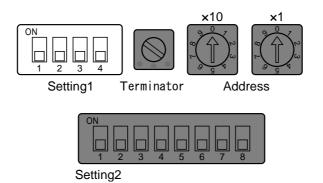


Address Setting switch (x10): To set PROFIBUS DP Node Address Tens digit. Address Setting switch (x1): To set PROFIBUS DP Node Address Units digit. Setting2 (No.8) switch: To set PROFIBUS DP Node Address Hundreds digit.

| Address Setting |        |       |                    |  |  |
|-----------------|--------|-------|--------------------|--|--|
| Setting2        | Addres | ss SW |                    |  |  |
| No.8            | ×10    | ×1    | Node Address       |  |  |
| OFF             | 0      | 0     | 0(Factory default) |  |  |
|                 | 0      | 1     | 1                  |  |  |
|                 | 0      | 2     | 2                  |  |  |
|                 | ł      | 2     | 2                  |  |  |
|                 | 9      | 8     | 98                 |  |  |
|                 | 9      | 9     | 99                 |  |  |
| ON              | 0      | 0     | 100                |  |  |
|                 | 0      | 1     | 101                |  |  |
|                 | 2      | 2     | 2                  |  |  |
|                 | 2      | 6     | 126                |  |  |

Note) If the address is set to 0 or number greater than 126, an error will result and "SF" and "BF" LED's will flash.

Setting1 switch



#### V\_SEL switch: A function to select the number of points occupied by valve outputs. Select the output points (size) occupied by the SI unit.

| Setting1 |      | Description                                  | SI unit Output data size |  |  |
|----------|------|--|--------------------------|--|--|
| No.1     | No.2 | Description                                  | Si unit Output data size |  |  |
| OFF      | OFF  | Occupied bit for valve output<br>is 32       | 4byte(Factory default)   |  |  |
| OFF      | ON   | Occupied bit for valve output<br>is 24       | 3byte                    |  |  |
| ON       | OFF  | Occupied bit for valve output<br>is 26 2byte |                          |  |  |
| ON       | ON   | Occupied bit for valve output<br>is 8 1byte  |                          |  |  |

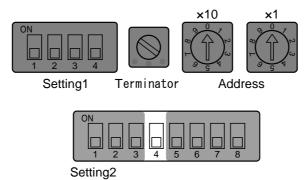
Note) Please set the number of occupied valve points to more than the connected number of valves.

#### Baud Rate switch: Switches to set the baud rate of internal communication.

| Set  | ting1 | Description            |  |  |
|------|-------|------------------------|--|--|
| No3. | No.4  | Description            |  |  |
| OFF  | OFF   | 1Mbps(factory setting) |  |  |
| OFF  | ON    | 500kbps                |  |  |
| ON   | OFF   | 250kbps                |  |  |
| ON   | ON    | 125kbps                |  |  |
|      |       |                        |  |  |

Note) 500, 250 & 125kbps settings are for future extension. Please use 1 Mbps (factory default setting).

Setting2 switch

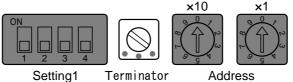


HOLD/CLR Switch : When a fieldbus communication error occurs or the communication idle state, all output can be set to Hold or Clear.

#### Active/inactive of this switch can be set with Parameter. (Refer to page 60)

| Setting2<br>No.4 | Description   |
|------------------|---|
| OFF              | All outputs are cleared "0" when a communication error occurs.<br>(Factory setting) |
| ON               | All outputs are held when a communication error occurs                              |

Terminator switch



Setting1 Terminator



Setting2

Terminator switch: Set the Terminator resistance of the PROFIBUS communication line

| Terminator setting                 |  |                          |
|------------------------------------|--|--------------------------|
|                                    |  |                          |
| Terminator<br>resistance<br>fitted | No terminator<br>resistance<br>(Factory default) | No terminator resistance |

#### Note

- When this unit is connected at the end of the PROFIBUS DP line, make sure to set to [Terminator Resistance fitted]
- The size of terminator resistance depends on the specification of the cable used. This terminator resistance value is fitted to suit type A cable.

# Error display

#### SI unit common status

| LED status       | Descriptions  |  |  |
|------------------|---|--|--|
| ST(M) PWR PWR(V) | Power supply for control and input is OFF.  |  |  |
| ST(M) PWR PWR(V) | Unit is operating normally.   |  |  |
| ST(M) PWR PWR(V) | Component failure inside the SI unit.<br>When ST (M) indicator is red, stop using the product and contact SMC.  |  |  |
| ST(M) PWR PWR(V) | Valve is in short-circuit or open-circuit status. Replace the valve.<br>Valve ON/OFF counter exceeds setting value.<br>(When Open/Short-circuit detection mode is ON) |  |  |
| ST(N) PWR PWR(V) | Communication error between units.<br>Check the connection between units.   |  |  |
| ST(M) PWR PWR(V) | Error diagnostic detected the error of a unit other than the SI unit.   |  |  |
| ST(M) PWR PWR(V) | Abnormal power voltage for control/input devices.<br>Check the power supply and adjust or replace it.   |  |  |
| ST(M) PWR PWR(V) |   |  |  |
| O OF             | O OFF   Red Light ON  Green Light ON  Green Light ON  |  |  |
| - Flas           | shing Red Flashing Red and Green alternately (1 second frequency)   |  |  |
| - Flas           | shing Green   |  |  |

#### **PROFIBUS DP**

| LED status          | Descriptions  |  |  |
|---------------------|---|--|--|
| X(V) SF BF          | Normal status with established communication with DP master, or unit power is in OFF status.  |  |  |
| R(V) SF BF          | SI unit recognized the communication speed but DP master address setting is wrong.<br>Check the address and correct it.   |  |  |
| X(V) SF BF          | <ul> <li>Any one of the following:</li> <li>♦ No connection between DP master and SI unit.</li> <li>♦ SI unit cannot recognize the communication speed.</li> <li>♦ DP master failure or SI unit failure.</li> </ul> |  |  |
| R(V) SF BF          | Communication established between DP master and SI unit, but with diagnostic error.   |  |  |
| R(V) SF BF          | Discrepancy between DP master setting and device configuration data.<br>Check the setting and correct it.   |  |  |
| ≷(V) SF BF<br>) ● ● | SI unit address set to "0" or above "126".<br>Check the address and correct it.   |  |  |
| 0 0                 | ○ OFF ● Red Light ON - Flashing Red   |  |  |

Red Light ON

- Flashing Red

# Specifications

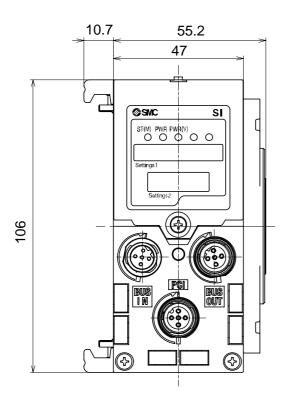
#### Specifications

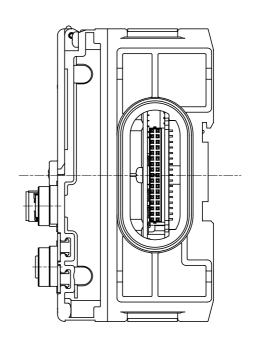
| Model   |  | EX600-SPR1   | EX600-SPR2                    |
|---|--|--|-------------------------------|
|   | Fieldbus   | PROFIBUS DP<br>(DP-V0)   |                               |
| ion   | Device type  | DP slave   |                               |
| Communication   | Communication speed                                      | 9.6/19.2/45.45/93.75/<br>187.5/500kbps<br>1.5/3/6/12Mbps   |                               |
| ပိ  | Configuration file                                       | GSD (SMC   | A1411.gsd)                    |
|   | I/O occupation area<br>(Inputs/Outputs)                  | (512 points/512 points) max  |                               |
| Term  | inal Resistance  | Internally implement   | ed(For type A cable)          |
| Internal Current Consumption<br>(Power supply for Control and<br>Input) |  | Less than 80mA   |                               |
|   | Output method  | PNP (-COM.)  | NPN (+COM.)                   |
| nt  | Output channel   | 32 channels (8/16/24/32 channels selectable)   |                               |
| Valve output  | Connected load   | Solenoid valve with lamp and circuit of protection of surge voltage of DC24V 1.5W (SMC)  |                               |
| alve  | Supply voltage   | DC24V +10/-5%  |                               |
| >   | Output for com. error                                    | HOLD/CLEA  | R/ Force ON                   |
|   | Protective function                                      | Short-circui   | it protective                 |
|   | Enclosure  | IP67(manifold assembly)  |                               |
|   | Operating temp. range                                    | -10~   | 50°C                          |
| ntal<br>e   | Departing humidity range 35~85% RH (no dew condensation) |  | ew condensation)              |
| ivironment<br>resistance  | Withstand voltage  |  | n external terminals and FE   |
| ron<br>sist   | Insulation resistance                                    |  | een external terminals and FE |
| Environmental<br>resistance   | Vibration resistance                                     | 10~57Hz with constant amplitude of 0.75mm p-p<br>57-150Hz with constant acceleration of 49m/s <sup>2</sup><br>for 2 hours in each direction of X, Y and Z direction (during de-energizing) |                               |
|   | Impact resistance  | 147m/s <sup>2</sup> 3 times in each direction of X, Y and Z (during de-energizing)   |                               |
| Stand   | dard   | CE marking, UL recognition (CSA)   |                               |
| Weig  | ht   | 300 g  |                               |

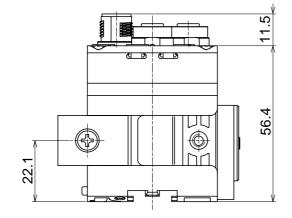
#### PROFIBUS DP function.

| Model number          | EX600-SPR1 | EX600-SPR2 |
|-----------------------|------------|------------|
| Address setting range | 1~125      |            |
| FREEZE Function       | Supported  |            |
| SYNC Function         | Supported  |            |
| FAIL SAFE Function    | Supported  |            |
| ID Number             | 1411(Hex)  |            |

Outline Dimensions







#### **Digital input unit**

# How to order

# EX600 – <u>DX</u>

Digital input

| Input polarity —   |     |  |
|--------------------|-----|--|
| Symbol Description |     |  |
| Р                  | PNP |  |
| Ν                  | NPN |  |

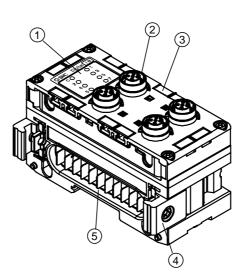
- Connector and input points and open circuit detection

| Symbol | Connector     | Input<br>points | Open circuit detection |
|--------|---------------|-----------------|------------------------|
| В      | 4 x M12(5Pin) | 8 points        | No                     |
| С      | 8 x M8(3Pin)  | 8 points        | No                     |
| C1     | 8 x M8(3Pin)  | 8 points        | Yes                    |
| D      | 8 x M12(5Pin) | 16 points       | No                     |

Note: Input equipment with 4 pin M12 connector can also be connected to M12 (5pin) connector.

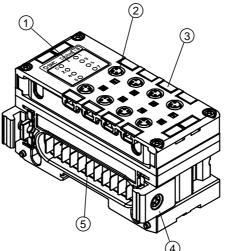
### Name and Function of the Parts

EX600-DX\*B



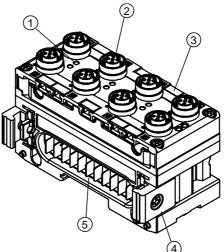
| No. | Name                      | Description   |  |
|-----|---------------------------|---|--|
| 1   | Status indication LED     | Indicates the unit status.<br>(Refer to the chapter "Troubleshooting" for the detailed display contents.) |  |
| 2   | Connector(Input)          | Connector for digital inputs.<br>(M12, 5pin, socket : SPEEDCON)   |  |
| 3   | Marker groove             | Groove to mount an indication marker.   |  |
| 4   | Joint bracket             | Joint bracket to join the adjacent unit, fixed with attached screws.                                      |  |
| 5   | Connector for unit (plug) | Conveys the signals and power supplies to the adjacent unit.  |  |

### EX600-DX\*C\*



|     |                           | 4   |
|-----|---------------------------|---|
| No. | Name                      | Description   |
| 1   | Status indication LED     | Indicates the unit status.<br>(Refer to the chapter "Troubleshooting" for the detailed display contents.) |
| 2   | Connector(Input)          | Connector for digital inputs. (M8, 3pin, socket)  |
| 3   | Marker groove             | Groove to mount an indication marker.   |
| 4   | Joint bracket             | Joint bracket to join the adjacent unit, fixed with attached screws.                                      |
| 5   | Connector for unit (plug) | Conveys the signals and power supplies to the adjacent unit.  |

#### EX600-DX\*D



| No. | Name                      | Description   |
|-----|---------------------------|---|
| 1   | Status indication LED     | Indicates the unit status.<br>(Refer to the chapter "Troubleshooting" for the detailed display contents.) |
| 2   | Connector(Input)          | Connector for digital inputs. (M12, 5pin, socket : SPEEDCON)  |
| 3   | Marker groove             | Groove to mount an indication marker.   |
| 4   | Joint bracket             | Joint bracket to join the adjacent unit, fixed with attached screws.                                      |
| 5   | Connector for unit (plug) | Conveys the signals and power supplies to the adjacent unit.  |
|     |                           |   |

# **Mounting and Installation**

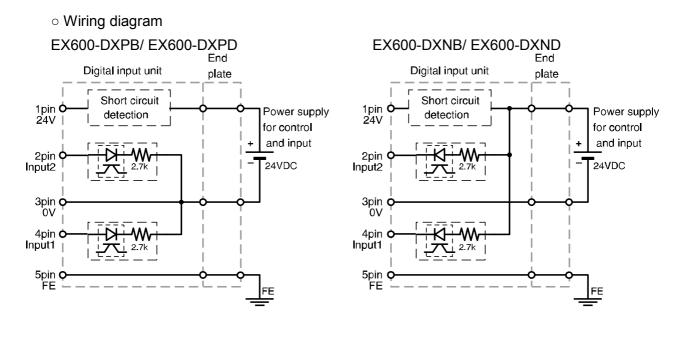
#### Pin assignment and wiring diagram

#### (1) EX600-DX\*B/EX600-DX\*D

oConnector's Pin assignment

|         | <u> </u>                 |               |
|---------|--------------------------|---------------|
| Pin No. | Signal name              | Configuration |
| 1       | 24V(for control / input) | 1 < 2         |
| 2       | Input2                   |               |
| 3       | 0V(for control / input)  | (5 <b>0</b> ) |
| 4       | Input1                   |               |
| 5       | FE                       | 4 3           |

Note: Input equipment with M12 (4 pin)connector can also be connected to M12 (5pin) connector.



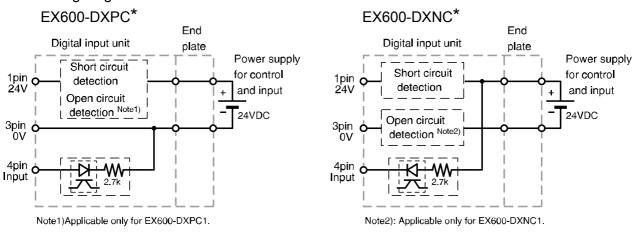
#### Note

Be sure to place a seal cap on any unused connectors. Using the appropriate seal cap enables the unit to achieve IP67 protection.

#### (2) EX600-DX\*C\*

| <ul> <li>Connector's pin assignment</li> </ul> |                          |               |
|--|--------------------------|---------------|
| Pin No.  | Signal name              | Configuration |
| 1  | 24V(for control / input) |               |
| 3  | 0V(for control / input)  |               |
| 4  | Input1                   | 4             |

• Wiring diagram



#### Note

Be sure to place a seal cap on any unused connectors. Using the appropriate seal cap enables the unit to achieve IP67 protection.

#### Handling care.

Please note the following points when using Open Circuit Detection function.

- Open Circuit Detection setting can only be carried out using a Handheld Terminal. Setting can not be carried out using a PLC.
- When 2-wire sensor is used, sensor which has current leakage during OFF status is less than 0.5mA (contact sensor, etc.) will not be detected. Please use sensor which has current leakage of 0.5mA or more during OFF status.
- When 3-wire sensor is used, sensor that has current consumption of less than 0.5mA will not be detected, and also open circuit (wire breakage) at input signal line will not be detected

# Error display

Status indication LED displays power supply status and communication status. These can be checked according to the following:-

| LED status  | Descriptions  |
|---|---|
| O<br>OFF  | Power supply for control and input is OFF, or input device is OFF.  |
| Green Light ON  | Input device is ON.   |
| Flashing Red  | Either of the following:<br>(1) Input device ON/OFF count has exceeded the set value.<br>(2) Input device not connected (for open circuit detection type only). |
| All LED Flashing<br>Red and Green<br>alternately                    | Component failure inside the digital input unit.<br>Stop using the product and contact SMC.   |
| 0 • 1<br>Red Light ON<br>(Both adjacent LED's<br>are ON)            | <b>without Open Circuit Detection&gt;</b> Short circuit in power line of either input device "0" or "1". Check which input device has caused the short circuit. |
| 0 • 1<br>Red Light ON<br>(Either one<br>of adjacent<br>LED's is ON) | <pre><with circuit="" detection="" open=""> Short circuit in power line of input device indicated.</with></pre>   |

# Specifications

#### Specifications

| • 3                      | pecificatio   | ns           |  |         |                       |                       |                                     |              |  |  |  |  |
|--------------------------|---|--------------|--|---------|-----------------------|-----------------------|-------------------------------------|--------------|--|--|--|--|
|                          | Model   |              |  |         | EX600-DXPC            |                       |                                     |              |  |  |  |  |
|                          | Input type  |              | PNP  | NPN     | PNP                   | NPN                   | PNP                                 | NPN          |  |  |  |  |
|                          | Input conn  | ector        | M12(5Pin)s   |         | M8(3Pir               |                       |                                     | socket Note1 |  |  |  |  |
|                          | Input channels                                      |              | 8channels<br>(2channels/Connector)   |         | 8chai<br>(1 channels) |                       | 16channels<br>(2channels/Connector) |              |  |  |  |  |
|                          | Sensor<br>voltage                                   | supplied     | 24VDC(Supplied from the power supply for control and inputs )  |         |                       |                       |                                     |              |  |  |  |  |
|                          | Maximum sensor supplied voltage                     |              | r 0.5A/Connector<br>2A/unit  |         | 0.25A/Co<br>2A/       |                       | 0.5A/Connector<br>2A/unit           |              |  |  |  |  |
| ion                      | Protection  |              | Short circuit protection   |         |                       |                       |                                     |              |  |  |  |  |
| cat                      | Input resist  | tance        | 2.7 kΩ   |         |                       |                       |                                     |              |  |  |  |  |
| cifi                     | Rated inpu  | t current    |  |         | 9 mA o                | or less               |                                     |              |  |  |  |  |
| Input Specifications     | ON voltage<br>/ON curren                            |              | 17 V or more/ 5 mA or more<br>(At NPN input, between the pin for input terminal and for sensor supplied voltage of +24 V)<br>(At PNP input, between the pin for input terminal and for sensor supplied voltage of 0 V) |         |                       |                       |                                     |              |  |  |  |  |
|                          | OFF voltage/OFF<br>current                          |              | 5 V or less/ 1 mA or less<br>(At NPN input, between the pin for input terminal and for sensor supplied voltage of +24 V)<br>(At PNP input, between the pin for input terminal and for sensor supplied voltage of 0 V)  |         |                       |                       |                                     |              |  |  |  |  |
|                          | Open  | Open 2 wires |  | -       | 0.5mA/P               | oint <sup>Note2</sup> | —                                   |              |  |  |  |  |
|                          | circuit<br>detection<br>current<br><sub>Note2</sub> | 3 wires      | _  | -       | 0.5mA/Con             |                       | _                                   |              |  |  |  |  |
| Cur                      | rent consur   | nption       | 50mA (   | or less | 55mA                  | or less               | 70mA or less                        |              |  |  |  |  |
|                          | icator  |              | Green LED on (Input is ON)<br>Red LED on (when short circuit detected at sensor's power supply)<br>Red LED flashing (ON/OFF counter exceeded/ open circuit detected <sup>Note2</sup> )                                 |         |                       |                       |                                     |              |  |  |  |  |
|                          | Enclosure   |              | IP67(manifold assembly)  |         |                       |                       |                                     |              |  |  |  |  |
| ance                     | Operating temp.<br>range                            |              | -10~50°C   |         |                       |                       |                                     |              |  |  |  |  |
| esiste                   | Operating hur<br>range                              | midity       | 35~85%RH (no dew condensation)   |         |                       |                       |                                     |              |  |  |  |  |
|                          | Withstand   | voltage      | AC500V for 1 min. between external terminals and FE  |         |                       |                       |                                     |              |  |  |  |  |
| lenta                    | Insulation re                                       | sistance     | DC500V, 10M $\Omega$ or more between external terminals and FE   |         |                       |                       |                                     |              |  |  |  |  |
| Environmental resistance | Vibration resistance                                |              | 10~57Hz with constant amplitude of 0.75mm p-p<br>57-150Hz with constant acceleration of 49m/s <sup>2</sup><br>for 2 hours in each direction of X, Y and Z direction (during de-energizing)                             |         |                       |                       |                                     |              |  |  |  |  |
|                          | Impact resi   | istance      | 147m/s <sup>2</sup> 3 times in each direction of X, Y and Z (during de-energizing)   |         |                       |                       |                                     |              |  |  |  |  |
| Sta                      | ndard   |              | CE marking, UL recognition (CSA)   |         |                       |                       |                                     |              |  |  |  |  |
|                          | ight  |              | 30   |         | 27                    |                       |                                     | 10g          |  |  |  |  |
|                          | <u> </u>  | connector    | can be connected   | 0       |                       | - 3                   | . v                                 | - 3          |  |  |  |  |

Note 1 : M12(4 pin)connector can be connected.

Note 2 : Applicable only for unit with Open circuit detection function.

Digital Input data The table shows the relation between the connector position and the input data allocation.

| connector<br>position |       |       | 00    | 00    | 00    |  |  |  |  |
|-----------------------|-------|-------|-------|-------|-------|--|--|--|--|
| connector №           |       | 0     | 1     | 2     | 3     |  |  |  |  |
| input                 | Pin 2 | Bit 1 | Bit 3 | Bit 5 | Bit 7 |  |  |  |  |
| signal                | Pin 4 | Bit 0 | Bit 2 | Bit 4 | Bit 6 |  |  |  |  |

• Table for input signal (EX600-DX\*B)

#### • Table for input signal (EX600-DX\*D)

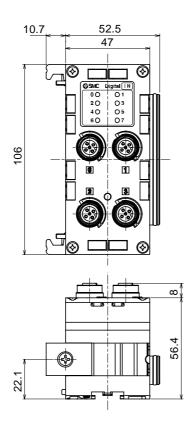
| connector<br>position |       | 00000<br>0000 |       |       |       |       |        |        |        |
|-----------------------|-------|---------------|-------|-------|-------|-------|--------|--------|--------|
| connector №           |       | 0             | 1     | 2     | 3     | 4     | 5      | 6      | 7      |
| input                 | Pin 2 | Bit 1         | Bit 3 | Bit 5 | Bit 7 | Bit 9 | Bit 11 | Bit 13 | Bit 15 |
| signal                | Pin 4 | Bit 0         | Bit 2 | Bit 4 | Bit 6 | Bit 8 | Bit 10 | Bit 12 | Bit 14 |

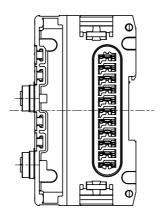
• Table for input signal (EX600-DX\*C\*)

|                       |       |       |       | /     | -     |       |       |       |       |
|-----------------------|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| connector<br>position |       | 0000  | 0000  | 0000  | 0000  | 0000  | 0000  | 0000  | 0000  |
| connector №           |       | 0     | 1     | 2     | 3     | 4     | 5     | 6     | 7     |
| input<br>signal       | Pin 4 | Bit 0 | Bit 1 | Bit 2 | Bit 3 | Bit 4 | Bit 5 | Bit 6 | Bit 7 |

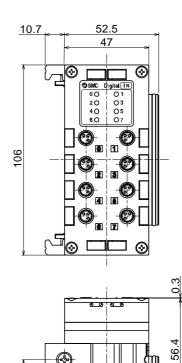
Outline Dimensions

EX600-DX\*B



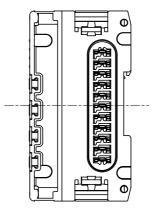


EX600-DX\*C\*



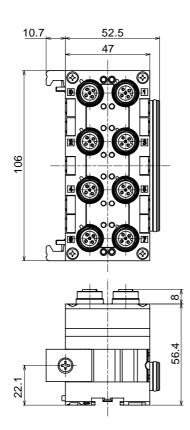
d

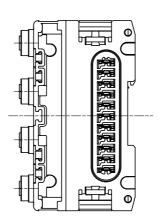
22.1



-35-**SMC** 

## EX600-DX\*D







### **Digital Output unit**

# How to order

# EX600 – <u>DY</u> 🖵 🖵

Digital Output -

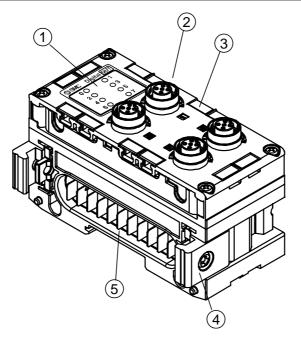
| ( | Output specification |     |  |
|---|----------------------|-----|--|
|   | Symbol Description   |     |  |
|   | Р                    | PNP |  |
|   | Ν                    | NPN |  |

### - Connector and number of channel

| Symbol | Connector     | Output channels |
|--------|---------------|-----------------|
| В      | 4 x M12(5Pin) | 8 channels      |

Note : output equipment with 4 pin M12 connector can also be connected to M12 (5pin) connector。

# Name and Function of the Parts



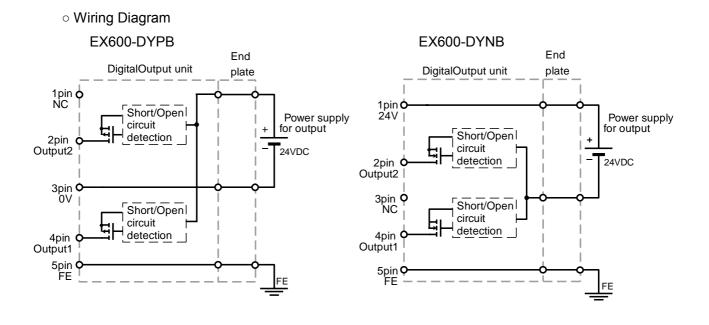
| No. | Name                      | Description   |  |
|-----|---------------------------|---|--|
| 1   | Status indication LED     | Indicates the unit status.<br>(Refer to the chapter "Troubleshooting" for the detailed display contents.) |  |
| 2   | Connector(Input)          | Connector for digital outputs. (M12, 5pin, socket : SPEEDCON)   |  |
| 3   | Marker groove             | Groove to mount an indication marker.   |  |
| 4   | Joint bracket             | Joint bracket to join the adjacent unit, fixed with attached screws.                                      |  |
| 5   | Connector for unit (plug) | Conveys the signals and power supplies to the adjacent unit.  |  |

# **Mounting and Installation**

Connector's pin assignment and wiring diagram
 Connector's pin assignment

| Din No  | Signal                | Configuration   |                     |  |  |
|---------|-----------------------|-----------------|---------------------|--|--|
| Pin No. | EX600-DYPB EX600-DYNB |                 |                     |  |  |
| 1       | NC                    | 24V(For Output) | $1 \land \land 2$   |  |  |
| 2       | Output2               | Output2         |                     |  |  |
| 3       | 0V(for Output)        | NC              | (5 <b>0</b> )       |  |  |
| 4       | Output1               | Output1         | $\bigvee$ $\bigvee$ |  |  |
| 5       | FE                    | FE              | 4 ) 3               |  |  |

Note : output equipment with 4 pin M12 connector can also be connected to M12 (5pin) connector



#### Note

Be sure to place a seal cap on any unused connectors. Using the appropriate seal cap enables the unit to achieve IP67 protection.

#### Handling care.

Please note the following points when using Open Circuit Detection function.

- Open Circuit Detection setting can only be carried out using a Handheld Terminal. Setting can not be carried out at the PLC.
- This function detects open circuit only when the output is OFF. Therefore if output is turned ON, open circuit can not be detected

# Error display

Status indication LED (see figure to the right) displays power supply status and communication status. These can be checked according to the following:-

| LED status                                       | Descriptions  |
|--|---|
| O<br>OFF   | Power supply for control and input is OFF, or output device is OFF.   |
| Green Light ON                                   | Output device is ON.  |
| Red Light ON                                     | Output is short circuited.  |
|  | Either of the following:<br>Output device contact operations count has exceeded the set value.<br>Output device is not connected. |
| All LED Flashing<br>Red and Green<br>alternately | Component failure inside the digital output unit.<br>Stop using the product and contact SMC.                                      |

# Specifications

#### Specifications

| cincations               |  |  |  |
|--------------------------|--|--|--|
| el                       | EX600-DYPB   | EX600-DYNB   |  |
| Output style             | PNP  | NPN  |  |
| Output connector         | M12(5Pin),9  | Socket Note1   |  |
| Output channel           | 8 channels (2 channels/connector)  |  |  |
| Rated load voltage       | 24VDC(Supplied from Power supply for output)   |  |  |
| Max. load current        | 0.5A/1 channel 2A/unit   |  |  |
| Protection               | Short circuit protection   |  |  |
| ent consumption          | 50mA   | or less  |  |
| lay                      | Green LED on (during output is ON)<br>Red LED flashing (ON/OFF counter is  |  |  |
| Enclosure                | IP67(manifold assembly)  |  |  |
| Operating temp. range    | -10~50°C   |  |  |
| Operating humidity range | 35~85%RH (no dew condensation)   |  |  |
| Withstand voltage        | AC500V for 1 min. betweer  | n external terminals and FE  |  |
| Insulation resistance    | DC500V, 10MΩ or more betwe   | en external terminals and FE   |  |
| Vibration resistance     | 10~57Hz with constant amplitude of 0.75mm p-p<br>57-150Hz with constant acceleration of 49m/s <sup>2</sup><br>for 2 hours in each direction of X, Y and Z direction (during de-energiz   |  |  |
| Impact resistance        | 147m/s <sup>2</sup> 3 times in each direction of X, Y and Z (during de-energizing  |  |  |
| dard                     | CE marking, UL recognition (CSA)   |  |  |
| ght                      | 30   | 0g   |  |
|                          | el<br>Output style<br>Output connector<br>Output channel<br>Rated load voltage<br>Max. load current<br>Protection<br>ent consumption<br>lay<br>Enclosure<br>Operating temp. range<br>Operating humidity range<br>Withstand voltage<br>Insulation resistance<br>Vibration resistance<br>Impact resistance<br>dard | elEX600-DYPBOutput stylePNPOutput connectorM12(5Pin),Output channel8 channels (2 chaRated load voltage24VDC(Supplied from FMax. load current0.5A/1 channProtectionShort circuient consumption50mAlayGreen LED on (during output is ON)Red LED flashing (ON/OFF counter isEnclosureIP67(manifolOperating temp. range-10~Operating humidity range35~85%RH (no deWithstand voltageAC500V for 1 min. betweerInsulation resistanceDC500V, 10MΩ or more betweenVibration resistance10~57Hz with constant a<br>57-150Hz with constant a<br>for 2 hours in each direction of X, Y aImpact resistance147m/s² 3 times in each direction of<br>CE marking, UL r |  |

Note1 : M12 (4 pin) connector can also be connected.

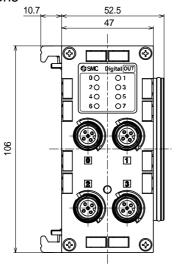
### •Digital Output data

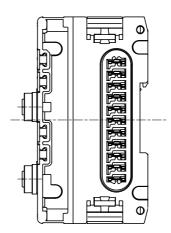
The table shows the relation between the connector position and the output data allocation.

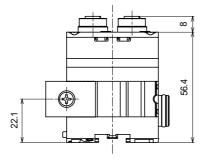
| connecto<br>position | r     | 000   |       | 0<br>0<br>0 |       |
|----------------------|-------|-------|-------|-------------|-------|
| connecto             | r Nº  | 0     | 1     | 2           | 3     |
| output               | Pin 2 | Bit 1 | Bit 3 | Bit 5       | Bit 7 |
| signal               | Pin 4 | Bit 0 | Bit 2 | Bit 4       | Bit 6 |

•Table for output signal (EX600-DY\*B)

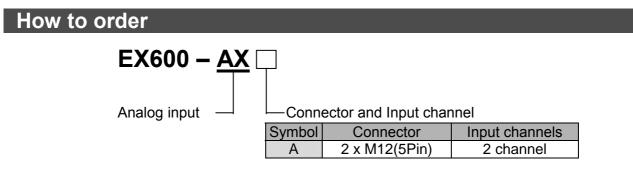
Outline Dimensions



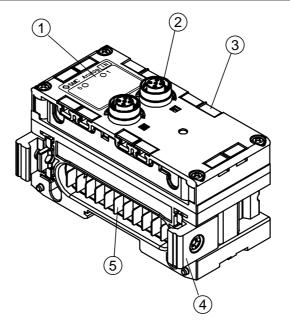




### Analog Input Unit



# Name and Function of the Parts



| No. | Name                      | Description  |  |
|-----|---------------------------|--|--|
| 1   | Status indication LED     | Indicates the unit status.<br>(Refer to the chapter "Troubleshooting" for the detailed<br>display contents.) |  |
| 2   | Connector(Input)          | Connector for digital inputs.<br>(M12, 5pin, socket : SPEEDCON)  |  |
| 3   | Marker groove             | Groove to mount an indication marker.  |  |
| 4   | Joint bracket             | Joint bracket to join the adjacent unit, fixed with attached screws.   |  |
| 5   | Connector for unit (plug) | Conveys the signals and power supplies to the adjacent unit.   |  |

-42-

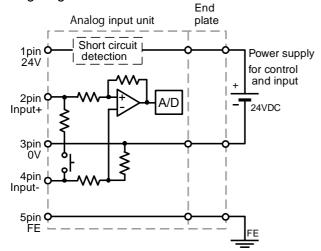
# **Mounting and Installation**

### •Pin Assignment and wiring diagram

#### Pin assignment

| Pin No | Signal name            | Configuration |  |
|--------|------------------------|---------------|--|
| 1      | 24V(For Control/Input) | 1002          |  |
| 2      | Input+                 |               |  |
| 3      | 0V(For Control/input)  | (5 <b>0</b> ) |  |
| 4      | Input-                 |               |  |
| 5      | FE                     | 4 - 3         |  |

#### • Wiring diagram



Input impedance Voltage input type: 100kΩ Current input type: 50Ω

#### Note

Be sure to place a seal cap on any unused connectors. Using the appropriate seal cap enables the unit to achieve IP67 protection.

#### Handling care

Please note the following points when wiring the Analogue input unit and sensor.

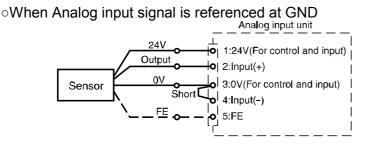
The EX600 Analogue Input operates using a differential input specification, therefore pin No.4 (input -) becomes the reference and pin No.2 (input +) carries the signal data.

This means that, if pin No.4 is not connected, the signal input cannot be correctly input.

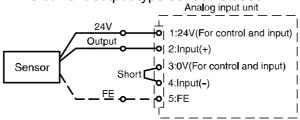
Therefore externally connect pin No.3 and pin No.4 together when a differential output sensor is not used.



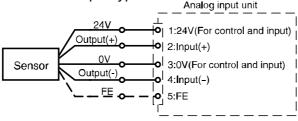
·Sensor and wiring example is shown below



oWhen 2-wire current output type sensor is used.



oWhen differential output type sensor is used



# **Error display**

Status indication LED displays power supply status and communication status. These can be checked according to the following:-

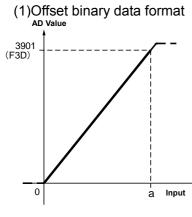
| LED status                                    | Descriptions   |
|---|--|
| O<br>OFF                                      | Power supply for control and input is OFF.   |
| Green Light ON                                | Operating normally.  |
| Red Light ON                                  | Power supply for input devices is short circuited.   |
| Flashing Red                                  | Upper or lower limit is detected for the following items:<br>(1) Range<br>(2)Measurement value(User setting) |
| All LED Flashing Red<br>and Green alternately | Component failure inside the analog input unit.<br>Stop using the product and contact SMC.                   |

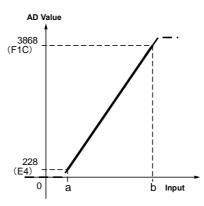
# Specifications

### Specifications

| <ul> <li>Specifications</li> </ul>                        |                     |   |                                 |  |
|---|---------------------|---|---------------------------------|--|
| Model   |                     | EX600-AXA   |                                 |  |
| Input type  |                     | Voltage input   | Current input                   |  |
| Input connec  | tor                 | M12(5Pin), Socket   |                                 |  |
| Input channe  | ls                  | 2channel(1channel/Connector)  |                                 |  |
| Sensor suppl  | ied voltage         | DC24V (Supplied from power  | r supply for control and input) |  |
|   | nsor supplied       | 0.5A/channel  |                                 |  |
| Protection  |                     | Short circui  | t protection                    |  |
| voltage<br>Protection<br>Input signal<br>range            | 12bit<br>Resolution | 0 ~ 10V<br>1 ~ 5V<br>0 ~ 5V   | 0 ~ 20mA<br>4 ~ 20mA            |  |
| orrange   | 16bit<br>Resolution | -10V ~ 10V (factory default setting)<br>-5V~5V  | -20mA ~ 20mA                    |  |
| Max. input s  | signal              | ±15V  | ±40mA                           |  |
| Input imped   | ance                | 100kΩ   | 50Ω                             |  |
| Linearity   |                     | ±0.05%F.S or less   |                                 |  |
| Repeatabilit  | у                   | ±0.15%F.S. or less  |                                 |  |
| Absolute ac   | curacy              | ±0.5%F.S. or less   | ±0.6%F.S. or less               |  |
| Current consump   | otion               | 70mA  |                                 |  |
| Display   |                     | Green LED on (when input is ON)<br>Red LED on (Short circuit at sensor power supply)<br>Red LED flashing (analog input exceeds measurement range or user<br>setting range)                    |                                 |  |
| Enclosure   |                     | IP67(manifold assembly)   |                                 |  |
| Operating temp  | o. range            | -10~50°C  |                                 |  |
| 🕡 Operating humic   | lity range          | 35~85%RH (no dew condensation)  |                                 |  |
| G Withstand vo  | <u> </u>            | AC500V for 1 min. between external terminals and FE   |                                 |  |
| E B Insulation resis                                      | tance               | DC500V, 10M $\Omega$ or more between external terminals and FE  |                                 |  |
| Withstand vo<br>Unsulation resister<br>Vibration resister | stance              | 10~57Hz with constant amplitude of 0.75mm p-p<br>57-150Hz with constant acceleration of 49m/s <sup>2</sup><br>for 2 hours in each direction of X, Y and Z direction (during<br>de-energizing) |                                 |  |
| Impact resist   | ance                | 147m/s <sup>2</sup> 3 times in each direction of X, Y and Z (during de-energizing)  |                                 |  |
| Standard  |                     | CE marking, UL recognition (CSA)  |                                 |  |
| Weight 290g   |                     |   | 0g                              |  |

### Analog characteristics





| Input signal range | а    |
|--------------------|------|
| 0 ~ 10V            | 10V  |
| 0 ~ 5V             | 5V   |
| 0 ~ 20mA           | 20mA |

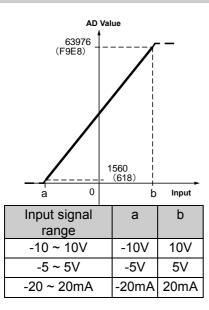
| Input signal range | а   | b    |
|--------------------|-----|------|
| 1 ~ 5V             | 1V  | 5V   |
| 4 ~ 20mA           | 4mA | 20mA |

Regarding AD value

In the above graph, 2 AD values are explained as below. 3901: AD value [decimal value] (F3D): Offset Binary type [hexadecimal value]

| Data | Form | at |    |     |    |          |   |   |   |   |   |   |   |   |     |
|------|------|----|----|-----|----|----------|---|---|---|---|---|---|---|---|-----|
| 15   | 14   | 13 | 12 | 11  | 10 | 9        | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0   |
| 0    | 0    | 0  | 0  | MSB |    | AD value |   |   |   |   |   |   |   | l | LSB |

| AD va       | alue    | 0 ~ 10V | 1 ~ 5V      | 0~5V  | 0 ~ 20mA | 4 ~ 20mA |
|-------------|---------|---------|-------------|-------|----------|----------|
| Hexadecimal | Decimal |         | Voltage [V] |       | Curre    | nt[mA]   |
| 0FFF        | 4095    | 10.5    | 5.25        | 5.25  | 21       | 21       |
| 0F3D        | 3901    | 10      | -           | 5     | 20       | -        |
| 0F1C        | 3868    | -       | 5           | -     | -        | 20       |
| 0800        | 2048    | 5.25    | 3           | 2.625 | 10.5     | 12       |
| 00E4        | 228     | -       | 1           | -     | -        | 4        |
| 0000        | 0       | 0       | 0.75        | 0     | 0        | 3        |

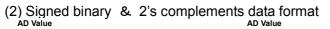


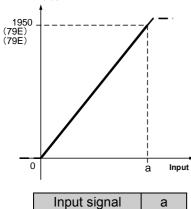
#### Data format

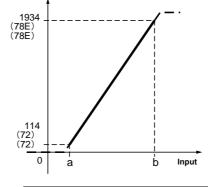
| Data lonnat  |    |    |    |    |    |   |   |   |   |     |   |   |   |   |   |
|--------------|----|----|----|----|----|---|---|---|---|-----|---|---|---|---|---|
| 15           | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5   | 4 | 3 | 2 | 1 | 0 |
| MSB AD value |    |    |    |    |    |   |   |   |   | LSB |   |   |   |   |   |

| AD v        | alue    | -10V ~ 10V | -5 ~ 5V | -20mA ~ 20mA |
|-------------|---------|------------|---------|--------------|
| Hexadecimal | Decimal | Volta      | ge [V]  | Current [mA] |
| FFFF        | 65535   | 10.5       | 5.25    | 21           |
| F9E8        | 63976   | 10         | 5       | 20           |
| BCF4        | 48372   | 5          | 2.5     | 10           |
| 8000        | 32768   | 0          | 0       | 0            |
| 430C        | 17164   | -5         | -2.5    | -10          |
| 0618        | 1560    | -10        | -5      | -20          |
| 0000        | 0       | -10.5      | -5.25   | -21          |









| Input signal | а    | Input |
|--------------|------|-------|
| range        |      | rar   |
| 0 ~ 10V      | 10V  | 1 ~   |
| 0 ~ 5V       | 5V   | 4 ~ 2 |
| 0 ~ 20mA     | 20mA |       |

| o a          | D   | Input |
|--------------|-----|-------|
| Input signal | а   | b     |
| range        |     |       |
| 1 ~ 5V       | 1V  | 5V    |
| 4 ~ 20mA     | 4mA | 20mA  |

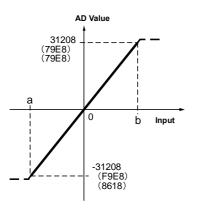
#### Regarding AD value

In the above graph, 2 AD values are explained as below. -31208: AD value [decimal value] (F9E8): Sign & Magnitude [Hexadecimal value] (8618): 2's complements [Hexadecimal value]

Data format

| Data |    |    |    |    |     |   |   |   |    |       |   |   |   |   |     |
|------|----|----|----|----|-----|---|---|---|----|-------|---|---|---|---|-----|
| 15   | 14 | 13 | 12 | 11 | 10  | 9 | 8 | 7 | 6  | 5     | 4 | 3 | 2 | 1 | 0   |
| 0    | 0  | 0  | 0  | 0  | MSB | - |   |   | AD | value |   |   |   |   | LSB |

| AD va       | alue    | 0 ~ 10V | 1V ~ 5V     | 0 ~ 5V | 0 ~ 20mA | 4 ~ 20mA     |  |  |  |
|-------------|---------|---------|-------------|--------|----------|--------------|--|--|--|
| Hexadecimal | Decimal |         | Voltage [V] |        | Currer   | Current [mA] |  |  |  |
| 07FF        | 2047    | 10.5    | 5.25        | 5.25   | 21       | 21           |  |  |  |
| 079E        | 1950    | 10      | -           | 5      | 20       | -            |  |  |  |
| 078E        | 1934    | -       | 5           | -      | -        | 20           |  |  |  |
| 0400        | 1024    | 5.25    | 3           | 2.625  | 10.5     | 12           |  |  |  |
| 0072        | 114     | -       | 1           | -      | -        | 4            |  |  |  |
| 0000        | 0       | 0       | 0.75        | 0      | 0        | 3            |  |  |  |



| Input signal range | а     | b    |
|--------------------|-------|------|
| -10 ~ 10V          | -10V  | 10V  |
| -5 ~ 5V            | -5V   | 5V   |
| -20 ~ 20mA         | -20mA | 20mA |

#### Data format

| 15   | 14  | 13 | 12 | 11 | 10 | 9 | 8  | 7     | 6        | 5 | 4 | 3 | 2 | 1 | 0   |
|------|-----|----|----|----|----|---|----|-------|----------|---|---|---|---|---|-----|
| Sign | MSB | •  |    |    |    |   | AD | value | <b>;</b> |   |   |   |   |   | LSB |

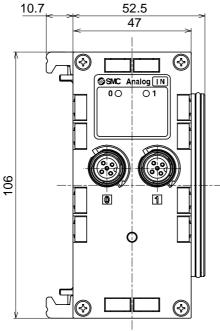
### Signed Binary

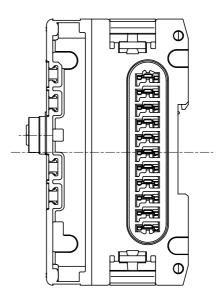
| AD \        | /alue   | -10V ~ 10V | -5V ~ 5V | -20mA ~ 20mA |
|-------------|---------|------------|----------|--------------|
| Hexadecimal | Decimal | Voltag     | ge [V]   | Current [mA] |
| 7FFF        | 32767   | 10.5*      | 5.25     | 21           |
| 79E8        | 31208   | 10         | 5        | 20           |
| 3CF4        | 15604   | 5          | 2.5      | 10           |
| 0000        | 0       | 0          | 0        | 0            |
| BCF4        | -15604  | -5         | -2.5     | -10          |
| F9E8        | -31208  | -10        | -5       | -20          |
| FFFF        | -32767  | -10.5      | -5.25    | -21          |

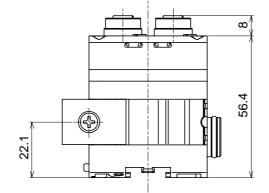
### 2's complements

| AD value    |         | -10V ~ 10V | -5V ~ 5V | -20mA ~ 20mA |
|-------------|---------|------------|----------|--------------|
| Hexadecimal | Decimal | Volta      | ge [V]   | Current [mA] |
| 7FFF        | 32767   | 10.5       | 5.25     | 21           |
| 79E8        | 31208   | 10         | 5        | 20           |
| 3CF4        | 15604   | 5          | 2.5      | 10           |
| 0000        | 0       | 0          | 0        | 0            |
| C30C        | -15604  | -5         | -2.5     | -10          |
| 8618        | -31208  | -10        | -5       | -20          |
| 8000        | -32767  | -10.5      | -5.25    | -21          |

Outline Dimensions



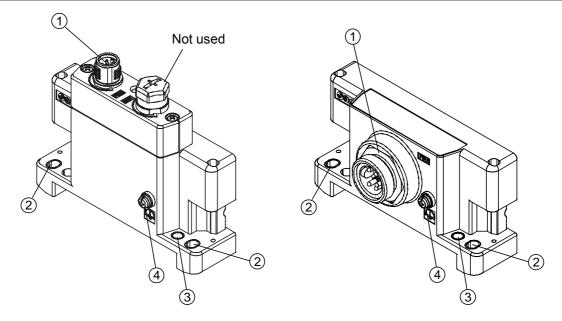




### End plate

| How to              | o orde  | r                 |       |              |                                       |
|---------------------|---------|-------------------|-------|--------------|---------------------------------------|
|                     | E       | X600 – ED 🗌       | ] — [ |              |                                       |
| End plate at D side |         |                   |       | iting method |                                       |
|                     |         |                   |       | Symbol       | Mounting method                       |
|                     |         | Connector —       |       | None         | No DIN rail mounting plate            |
| 1                   | Cumphal |                   |       | 2            | With DIN rail mounting plate          |
|                     | Symbol  | Connector         |       |              | • • • • • • • • • • • • • • • • • • • |
|                     | 2       | M12(5Pin)         |       |              |                                       |
|                     | 3       | 7/8inch Connector |       |              |                                       |
|                     |         |                   |       |              |                                       |

# Name and Function of the Parts



| No. | Name                            | Description                    |
|-----|---------------------------------|--------------------------------|
| 1   | Power connector                 | Connector for power input      |
| 2   | Fixing hole for direct mounting | Holes used for direct mounting |
| 3   | DIN rail fixing hole            | Holes used to fix DIN rail     |
| 4   | FE terminal                     | FE terminal to earth.          |

# **Mounting and Installation**

### Connector's pin assignment

### (1) EX600-ED2

| /       |                          |               |
|---------|--------------------------|---------------|
| Pin No. | Signal name              | Configuration |
| 1       | 24V(for Output)          | 2 - 1         |
| 2       | 0V(for Output)           |               |
| 3       | 24V(for control / input) | (50)          |
| 4       | 0V(for control / input)  |               |
| 5       | FE                       | 3 🗨 4         |

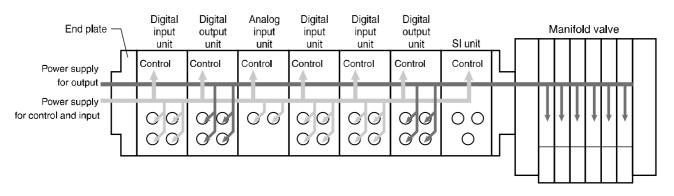
#### (2) EX600-ED3

| Pin No. | Signal name              | Configuration |
|---------|--------------------------|---------------|
| 1       | 0V(for Output)           |               |
| 2       | 0V(for control / input)  |               |
| 3       | FE                       |               |
| 4       | 24V(for control / input) |               |
| 5       | 24V(for Output)          |               |

### Regarding the 2 types of power supply

This product has 2 power supplies, and it is divided as follows.

- Power supply for control and input: supplying power for control of each unit's power supply for control and also for equipment connected to Digital input unit and Analog input unit.
- Power supply for output: supplying power for equipment connected to digital output unit, and also power supply for solenoid valve manifold.

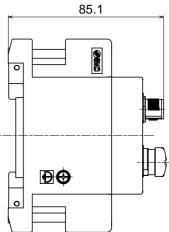


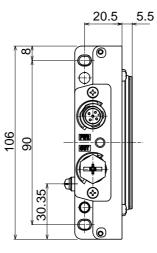
# Specifications

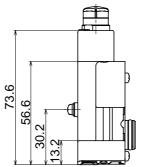
### Specifications

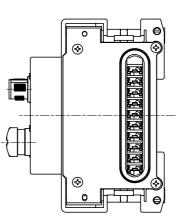
| Mod           | el   | EX600-ED2  | EX600-ED3                     |  |  |
|---------------|--|--|-------------------------------|--|--|
|               | Power connector  | M12(5Pin) Plug   | 7/8inch(5Pin) Plug            |  |  |
| Input         | Control, input power supply  | 24VDC±10%<br>Maximum 2 A   | 24VDC±10%<br>Maximum 8 A      |  |  |
|               | Output power supply  | 24VDC +10%/-5%<br>Maximum 2 A  | 24VDC +10%/-5%<br>Maximum 8 A |  |  |
|               | Enclosure  | IP67(manifold assembly)  |                               |  |  |
|               | Operating temp. range  | -10~50°C   |                               |  |  |
| Ital          | Operating humidity range   | 35~85%RH (no dew condensation)   |                               |  |  |
| ner           | Withstand voltage  | AC500V for 1 min. between external terminals and FE                                |                               |  |  |
| onr           | Insulation resistance  | DC500V, 10M $\Omega$ or more between external terminals and FE                     |                               |  |  |
| Environmental | Vibration resistance<br>10~57Hz with constant amplitude of 0.75mm p-p<br>57-150Hz with constant acceleration of 49m/s <sup>2</sup><br>for 2 hours in each direction of X, Y and Z direction (durin<br>de-energizing) |  |                               |  |  |
|               | Impact resistance  | 147m/s <sup>2</sup> 3 times in each direction of X, Y and Z (during de-energizing) |                               |  |  |
| Star          | ndard  | CE marking, UL recognition (CSA)   |                               |  |  |
| Wei           | ght  | 170g   | 175g                          |  |  |

- Outline Dimensions
- (1) EX600-ED2

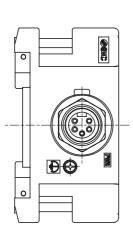


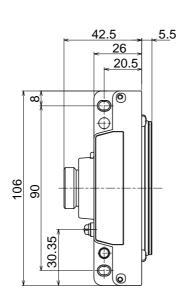


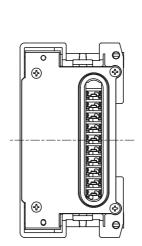


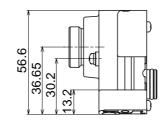


### (2) EX600-ED3











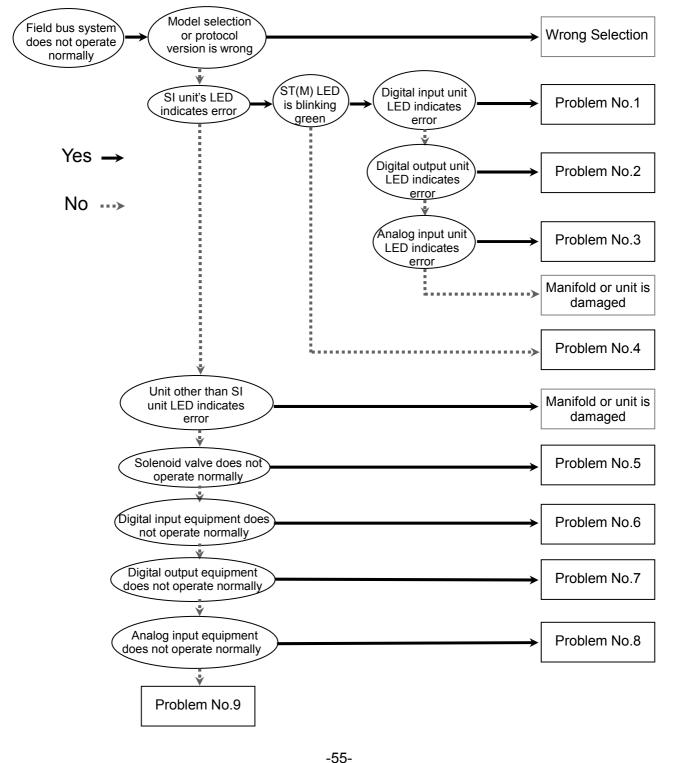
## Troubleshooting

Please refer to the following troubleshooting flowchart if errors occur on the fieldbus system.

Error status is also reflected by the parameter settings of fieldbus system.

When trouble occurs, please give appropriate counter measure after referring to the troubleshooting and the parameter setting.

If cause of the problem cannot be confirmed, it is possible that the equipment may have failed. When failure of fieldbus system equipment occurs, it is also possible that the error caused by the system requirements. If that is the case, please consider the counter-measures accordingly



**∂SMC** 

### Trouble counter measure method

| Problem<br>No. | LED indication                            | Problem  | Investigation Method   | Counter-measure  |
|----------------|---|--|--|--|
|                | Flashing Red<br>(Diagnostic is<br>active) | Cause can be either:<br>1) Sensor's ON/OFF counter<br>exceeds setting value<br>2) Open circuit is detected on<br>input sensor or cable.<br>(for Open Circuit Detection<br>type only) | Confirm cause 1) or 2) by<br>PLC or H.T. Refer to details<br>of system diagnosis data.   | <ol> <li>Reset the counter, change<br/>the setting or disable the<br/>diagnostic through<br/>parameter setting.</li> <li>Confirm if there are loose<br/>connector and wire<br/>breakage. Moreover,<br/>please confirm if<br/>applicable sensor is used.</li> </ol>   |
| 1              | Red<br>(Diagnostic is<br>active)          | Diagnosis error<br>(Sensor power supply is short<br>circuited)   | [No open circuit detection]<br>Either of two adjacent<br>sensor connections is short<br>circuited (2x LED's will be<br>ON).<br>[With open circuit detection]<br>The sensor connection is<br>short circuited (LED is ON). | Check the wiring of the<br>sensor connection which has<br>the short circuit, or confirm<br>whether the cable and the<br>sensor are operating<br>correctly.   |
|                | All LED flashing<br>Green and Red         | Unit has failed  | -  | Stop operation and contact<br>SMC sales office   |
|                | Flashing Red<br>(Diagnostic is<br>active) | Cause can be either:<br>1) Output device ON/OFF<br>counter exceeds setting<br>value<br>2) Open circuit is detected on<br>output device or cable.                                     | Confirm cause 1) or 2) by<br>PLC or H.T. Refer to details<br>of system diagnosis data.   | <ol> <li>Reset the counter, change<br/>the setting or disable the<br/>diagnostics through<br/>parameter setting.</li> <li>Confirm if there are loose<br/>connections or broken<br/>wires.</li> </ol>   |
| 2              | Red<br>(Diagnostic is<br>active)          | Diagnosis error<br>(output equipment is short<br>circuited)  | The output connection is short circuited (LED is ON).  | Check the wiring, or confirm<br>whether the output<br>equipment is operating<br>correctly  |
|                | All LED flashing<br>Green and Red         | Unit has failed  |  | Stop operation and contact<br>SMC sales office   |
| 3              | Flashing Red<br>(Diagnosis is<br>active)  | Diagnosis error<br>(Upper/lower range limit<br>exceeded)   | <ol> <li>Confirm if the sensor<br/>output exceeds the<br/>upper/lower<br/>measurement limits.</li> <li>Confirm whether sensor<br/>output exceeds user<br/>setting upper/lower<br/>range.</li> </ol>                      | <ol> <li>Please adjust sensor<br/>output so that it is inside<br/>the measurement range, or<br/>adjust setting range or turn<br/>off over/under range<br/>detection.</li> <li>Please adjust sensor<br/>output so that it is Inside<br/>the user setting value, or<br/>adjust user setting value or<br/>turn off user set value<br/>upper/lower limit detection.</li> </ol> |
|                | Red<br>(Diagnostic is<br>active)          | Diagnosis error<br>(Short circuit is detected on<br>the sensor power supply).  | Confirm if short circuit<br>occurs at the sensor or<br>cable   | Confirm if sensor and cable are operating correctly.   |
|                | All LED Flashing green and red            | Unit has failed  | -  | Please stop operation and<br>please contact our sales<br>office  |

| Problem<br>No. | LED indication                                     | Problem  | Investigation Method  | Counter-measure   |
|----------------|--|--|---|---|
| 110.           | ST(M): Off   | Power supply for control/input is OFF  | Confirm if power supply<br>for control/input is<br>connected.   | Re-connect power supply for control/input   |
|                | ST(M): Red   | SI unit has failed   | -   | Stop operation and contact SMC sales office.  |
|                | ST(M): Flashing<br>red<br>(Diagnosis is<br>active) | Diagnosis error (SI unit )<br>1) Valve short circuited<br>2) Broken wire at valve<br>3) Valve ON/OFF counter<br>exceeds setting value. | Confirm through PLC or<br>handheld terminal. For<br>details, please refer to the<br>System Diagnosis<br>information.  | For 1) and 2): valve is<br>broken. Please replace valve<br>and confirm operation.<br>3) Reset counter value,<br>change setting value or<br>disable the diagnostic through<br>parameter setting. |
|                | ST(M): Flashing green and red                      | Communication error<br>between SI unit and I/O<br>unit   | Confirm if the connection between units is not loose.   | f the error does not recover,<br>stop operation and contact<br>SMC sales office   |
|                | PWR: Red<br>(Diagnostic is<br>active)              | The power supply voltage level for control and input is not normal   | Confirm the power supply voltage level.   | Supply DC24V±10% to the power supply for control and input.   |
| 4              | PWR(V): Red<br>(Diagnostic is<br>active)           | The power supply voltage<br>level for output is not<br>normal  | Confirm the used power supply voltage level.  | Supply DC24V+10/-5% to the power supply for output.   |
|                | SF: Off<br>BF: Flashing Red                        | Address Setting fault  | Confirm if SI Unit address<br>is consistent with address<br>at DP master.   | Set the correct address.  |
|                | SF: Off<br>BF: Red                                 | PROFIBUS DP<br>communication fault   | <ol> <li>Confirm if</li> <li>communication speed</li> <li>and wiring length are</li> <li>compatible.</li> <li>Confirm if terminating</li> <li>resistance is connected</li> <li>appropriately at both</li> <li>ends of network.</li> <li>Confirm if</li> <li>communication wiring is</li> <li>close to any noise</li> <li>source.</li> </ol> | Wire based on the<br>PROFIBUS specification.<br>Moreover, separate wire for<br>the communication line and<br>the noise source.  |
|                | SF: Red<br>BF: Off<br>(Diagnosis is<br>active)     | Diagnosis Error<br>(Between PLC and Unit)  | Confirm each unit's LED display.  | Perform counter measure<br>according to each unit LED<br>display.   |
|                | SF: Red<br>BF: Flashing Red                        | Configuration is<br>inconsistent   | Confirm PLC<br>Configuration setting.   | Match the PLC configuration setting with the actual unit configuration.   |
|                | SF: Red<br>BF: Red                                 | Address setting fault  | Confirm if SI Unit address is "0" or above "126".   | Set SI Unit address to be between 1 and 125.  |

| Problem<br>No. | LED indication   | Problem   | Investigation Method  | Counter-measure  |
|----------------|--|---|---|--|
|                |  | Valve output setting for<br>occupied points is less<br>than the number of<br>connected valves | Confirm the V_SEL switch<br>setting in the SI unit is set to<br>more than the actual connected<br>valves.   | Set the SI unit switch settings<br>to an occupation points count<br>greater than the number of<br>valves used. |
|                |  | Program does not operate normally.  | Confirm if ladder program at<br>PLC Is correct  | Same as left   |
|                |  | Power supply for output<br>is defective   |   | Supply DC24V +10/-5% to the<br>power supply for output from<br>the end plate unit                              |
| 5              | Solenoid valve<br>does not operate<br>normally             | Connection between SI<br>Unit and solenoid valve<br>manifold is defective                     | Confirm the connection between<br>the SI Unit and solenoid valve<br>manifold (Connector pin not<br>bent, etc.)  | Connect the SI Unit to the<br>solenoid valve Manifold<br>correctly   |
|                | normany  | SI Unit output type is not<br>compatible with the<br>solenoid valves                          | Confirm that the SI Unit and<br>solenoid valves are compatible:<br>EX600-SPR1 (PNP Output)<br>- Negative common type valve<br>EX600-SPR2 (NPN Output)<br>- Positive common type valve | Replace the SI Unit or the solenoid valve so that the correct combination is used                              |
|                |  | Defective SI Unit   | Replace the SI Unit and confirm the operation   | Replace the SI Unit.   |
|                |  | Defective solenoid valve  | Replace the solenoid valve and confirm the operation  | If the problem continues, refer<br>to the solenoid valve operation<br>manual.                                  |
|                |  | Input type is not<br>compatible   | Confirm if input unit specification<br>(PNP or NPN) and connected<br>input equipment specification<br>are compatible  | Replace input unit or input<br>equipment so that it become<br>the correct combination                          |
| 0              | Digital input<br>equipment does<br>not operate<br>normally | Power supply for control and input is defective   | Check the status of power supply for control and input  | Supply DC24V ±10% to the<br>power supply for control and<br>input from the end plate                           |
|                |  | Wiring or connection is defective   | Confirm connection and wiring between input equipment and digital input unit.   | Make corrections to the wiring<br>between input equipment and<br>digital input unit and continue<br>operation  |
|                |  | Digital input unit is defective   | Confirm the digital input unit  | Replace the digital input unit   |
|                |  | Defective input<br>equipment  | Replace the input equipment and confirm the operation.  | If the problem continues, refer<br>to the input equipment<br>operation manual.                                 |

| Problem<br>No. | LED indication                                       | Problem   | Investigation Method   | Counter-measure   |
|----------------|--|---|--|---|
|                |  | Output type is not compatible                         | Confirm if output unit specification (PNP<br>or NPN) and connected load specification<br>are compatible. | Replace the output unit or<br>load to give the correct<br>combination   |
|                |  | Program does<br>not operate<br>normally               | Confirm if the ladder program at the PLC Is correct  | Correct the ladder program at the PLC   |
| 7              | Digital output<br>equipment does                     | Power supply for<br>output is<br>defective            | Check the status of the power supply for output  | Supply DC24V +10/-5% to the<br>power supply for output from<br>the end plate  |
|                | not operate<br>normally                              | Wiring and<br>connection is<br>defective              | Confirm connection between the output equipment and digital output unit.                                 | Make corrections to the wiring<br>between the output<br>equipment and digital output<br>unit and continue operation |
|                |  | Digital output unit<br>is defective                   | Confirm the digital output unit.   | Replace the digital output unit.  |
|                |  | Output<br>equipment is<br>defective                   | Replace the output equipment and confirm the operation.  | If the problem continues, refer<br>to the output equipment<br>operation manual.                                     |
|                | Analog input<br>sensor does not<br>operate normally  | Power supply for<br>control and input<br>is defective | Check the status of the power supply for<br>control and input  | Supply DC24V±10% to the<br>power supply for control and<br>input from the end plate                                 |
|                |  | Input signal<br>range setting is<br>not compatible    | Confirm the connected sensor specification   | Set the input signal range to suit the sensor specification.  |
| 0              |  | Analog data<br>format is not<br>compatible            | Confirm the data format setting of the<br>Analog input unit.   | Set the data format of the<br>Analog input unit to suit the<br>application/program.                                 |
| 8              |  | Wiring and<br>connection is<br>defective              | Confirm the connection between the input sensor and Analog input unit                                    | Correct the wiring between<br>the input sensor and Analog<br>input unit   |
|                |  | Analog Input Unit<br>is defective                     | Check the Analog input unit and confirm the operation  | Replace the Analog input unit and confirm the operation   |
|                |  | Defective sensor                                      | Replace the sensor and confirm the operation.  | If the problem continues, refer<br>to the sensor operation<br>manual.   |
| 9              | Other peripheral<br>units do not<br>operate normally | Defective<br>peripheral units                         | Confirm that the program at PLC is correct.  | For further details, refer to the relevant manuals of each peripheral unit.   |

# **Parameter Setting**

The EX600 has parameters settings for the system, unit and also each unit's channel, which can be set through PLC or Handheld Terminal.

There are no priorities in setting the parameter. The most recent setting will be reflected on the unit.

### Caution

The following notes apply to Parameter setting, which can be changed from both PLC and Handheld Terminal (H.T.)

If a parameter is changed using the H.T., the parameter setting content in the PLC will not be changed. This means that, if the parameter is changed by the H.T., when the PROFIBUS communication is disconnected and then reconnected again, the parameter settings will revert to the settings saved in the PLC.

When setting parameters which can be set from both the PLC or H.T., it is recommended that the setting is made from the PLC.

## **Parameter Definition**

#### System parameter

| No | Parameter<br>Name               | Contents   |
|----|---------------------------------|--|
| 1  | Diagnosis<br>Mode               | Change memory mapping of extended diagnostic data. There are 4 types of diagnostic: [No Diagnostic], [System Diagnostic], [Unit Diagnostic], [Channel Diagnostic]. Please refer to (Page 76) for the memory map information.   |
| 2  | Hold/Clear<br>Setting<br>Method | Select setting method of output state during communication fault or<br>communication idle state, either with the unit's setting switches or using a<br>HHT. When using an HHT, each channel's output state can be set to<br>Hold/Clear/Force ON. However, when using setting switches, the entire<br>system's output state can be set. |

### **SI Unit Parameter**

| No | Parameter<br>Name                                     | Contents   |
|----|---|--|
| 1  | Power Supply<br>Voltage<br>Monitor<br>(Control/Input) | When power supply voltage for control/input goes above 26V or falls below 21V, a diagnostic error will be generated.   |
| 2  | Power Supply<br>Voltage<br>Monitor<br>(Output)        | When power supply voltage for output goes above 26V or falls below 20V, a diagnostic error will be generated.  |
| 3  | Short Circuit<br>Detection                            | If short circuit or over current occurs when the valve output is ON, diagnostic error will be generated.   |
| 4  | Restart after short circuit                           | When a short circuit at the valve has been removed, the short circuit detection error diagnostic can be set to automatically reset (error will automatically be cleared) or manual reset (error will not be cleared until power supply is reset)   |
| 5  | Open Circuit<br>Detection                             | If an open circuit is detected during Valve Output OFF, a diagnostic error will be generated. This setting can be made for each channel.   |
| 6  | Output setting<br>during<br>communication<br>fault    | At the time of communication fault, each channel's Valve Output can<br>be set to Hold, Clear or Force ON setting. This function will only be<br>activated when the Hold/Clear setting method at the system<br>configuration is set to Handheld.  |
| 7  | Output setting<br>during<br>communication<br>idle     | At the time when the communication is idle, each channel's Valve<br>Output can be set to Hold, Clear or Force ON setting. This function will<br>only be activated when Hold/Clear setting method at the system<br>configuration is set to Handheld.  |
| 8  | Channel<br>ON/OFF<br>Counter                          | The number of times the valve is ON/OFF is recorded for each channel.<br>There is a set value for each channel, and it is possible to generate a diagnostic error when the set value is reached.<br>However, recording the number of ON/OFF is done in 30 second intervals (30 seconds per channel) from CH0 to the channels which have valve outputs.<br>If the power supply for control and input is turned OFF, the last recorded value for each channel will become valid. |

| No.                         | Parameter<br>Name  | Contents   |  |
|-----------------------------|--|--|--|
| 1                           | Short circuit detection  | If a short circuit or over current occurs at the sensor power supply, a diagnostic error will be generated.  |  |
| 2                           | Open Circuit<br>Detection<br>(Only available<br>for Open<br>Circuit<br>Detection Unit) | <ul> <li>If an open circuit is detected at the input sensor, a diagnostic error will be generated. There is a setting available for each channel.</li> <li>Please note the following:</li> <li>1) When a 2-wire type sensor is used, during OFF state, a leak current of less than 0.5mA will not be detected. A sensor with a leak current of 0.5mA or more (in the OFF state) must be used.</li> <li>2) When a 3-wire type sensor is used, if the sensor has a current consumption of less than 0.5mA, an open circuit may not be detected.</li> </ul> |  |
| 3                           | Inrush current<br>filter   | When an input equipment with high capacitance is connected, at the time power is supplied, over current will be detected.<br>If the inrush current filter is active, during the first 100msec after power is supplied, over current will not be detected.  |  |
| 4                           | Input filtering<br>time  | A change of signal faster than the input filtering time will be disregarded.   |  |
| 5                           | Input extension An Input signal will be extended to the time set by this parameter. I  |  |  |
| 6 Channel On/Off<br>Counter |  | The number of times the input is ON/OFF is recorded for each channel.<br>There is a set value for each channel, and it is possible to generate a<br>diagnostic error when the set value is reached.<br>However, the counter value is recorded every one hour.<br>If the power supply for control and input is turned OFF, data that has<br>not been recorded will be cleared.  |  |

#### **Digital Input Unit Parameter**

| No | Parameter<br>Name                                  | Contents   |  |  |  |
|----|--|--|--|--|--|
| 1  | Short Circuit<br>Detection                         | f a short circuit or over-current occurs at the output's load, a<br>diagnostic error will be generated.  |  |  |  |
| 2  | Restart after<br>Short Circuit                     | When a short circuit at the output has been removed, the short circuid detection error diagnostic can be set to automatically reset (error will automatically be cleared) or manual reset (error will not be cleared until power supply is reset)  |  |  |  |
| 3  | Open Circuit<br>Detection                          | If an open circuit is detected when the output is in the OFF state, a diagnostic error will be generated. This setting can be made for each channel.   |  |  |  |
| 4  | Output Setting<br>during<br>communication<br>fault | At the time of communication fault, each channel's output can be a to Hold, Clear or Force ON setting. This function will only be activat when the Hold/Clear setting method at the system configuration is a to Handheld.   |  |  |  |
| 5  | Output Setting<br>during<br>communication<br>idle  | At the time when the communication is idle, each channel's output can<br>be set to Hold, Clear or Force ON setting. This function will only be<br>activated when the Hold/Clear Setting method at the system<br>configuration is set to Handheld.  |  |  |  |
| 6  | Channel On/Off<br>Counter                          | The number of times the output is ON/OFF is recorded for each channel.<br>There is a set value for each channel, and it is possible to generate a<br>diagnostic error when the set value is reached.<br>However, the counter value is recorded every one hour.<br>If the power supply for control and input is turned OFF, data that has<br>not been recorded will be cleared. |  |  |  |

## Analog Input Unit Parameter

| No | Parameter<br>Name  | Contents  |  |  |  |  |  |  |
|----|--|---|--|--|--|--|--|--|
| 1  | Short Circuit<br>Detection   | If a short circuit or over-current occurs at the sensor power supply, diagnostic error will be generated.                         |  |  |  |  |  |  |
| 2  | Analog input<br>measurement<br>range   | Selection of Analog Input Range. The settable measurement ranges are: 010V, 15V, 05V, -10V+10V, -5V+5V, 020mA, 420mA, -20mA+20mA. |  |  |  |  |  |  |
| 3  | Analog data<br>format  |   |  |  |  |  |  |  |
| 4  | 4 Analog<br>averaging filter Selection of analog averaging filter. The sampling cycle is a<br>seconds. Selectable values are: No filter, 2 Average (average b<br>the last 2 input values), 4 Average, and 8 Average. |   |  |  |  |  |  |  |
| 5  | Range Upper<br>Limit Error   | If the input signal exceeds the upper limit value of the input range (0.5%), a diagnostic error will be generated.                |  |  |  |  |  |  |
| 6  | Range Lower<br>Limit Error   | If the input signal exceeds the lower limit value of the input range (0.5%), a diagnostic error will be generated.                |  |  |  |  |  |  |
| 7  | If the input signal exceeds the upper limit value of the user settable   |   |  |  |  |  |  |  |
| 8  | If the input signal exceeds the lower limit value of the user settable range   |   |  |  |  |  |  |  |

# Parameter's Factory Default Setting

### **System Parameter**

| No | Parameter<br>Name                  | Setting                                 | Contente  | Setting | Default | Setting<br>Method |            |
|----|------------------------------------|---|---|---------|---------|-------------------|------------|
| NO | No (GSD Valu<br>Parameter)         |   | Contents  | Level   | setting | By<br>PLC         | By<br>H.T. |
|    | Diagnostic<br>mode (Diag.<br>mode) | No diag.                                | No Diagnostic data                                    | System  |         |                   |            |
|    |                                    | Device<br>diag.                         | System diagnostic<br>data only                        |         |         |                   |            |
| 1  | 1 Device<br>+Module<br>Diag.       |   | System and unit diagnostic data                       |         |         | 0                 | 0          |
|    |                                    | Device[<br>+Module<br>+Channel<br>diag. | System, unit and channel diagnostic data              |         | 0       |                   |            |
| 2  | Hold/Clear<br>Setting Method       | Switch                                  | Hold/Clear Setting is made at SI Unit setting switch. | Sustam  | 0       | 0                 | 0          |
|    | (Hold/Clear)                       | Handheld                                | Hold/Clear Setting<br>is made at Handheld Terminal    | System  |         | 0                 | 0          |

### SI Unit Parameter

| Parameter<br>No No Name |   | Setting   |   |          | Default                   | Set<br>Met |         |           |            |
|-------------------------|---|---|---|----------|---------------------------|------------|---------|-----------|------------|
| NO                      | (GSD<br>Parameter)                            | Value   |   |          | Contents Setting<br>Level |            | setting | By<br>PLC | By<br>H.T. |
| 1                       | Power supply voltage for control and          | Enable monitoring of power<br>Enable supply voltage for control and<br>input. |   | Unit     | 0                         | 0          | Ο       |           |            |
|                         | input monitor<br>(Pwr control<br>monitor)     | Disable   | Disable monitoring of power<br>supply voltage for control and<br>input.                                       |          |                           |            |         |           |            |
| 2                       | Power supply<br>voltage for<br>output monitor | Enable  | Enable monitoring of power<br>supply voltage for output   | Unit     | 0                         | Ο          | 0       |           |            |
| 2                       | (Pwr output<br>monitor)                       | Disable   | Disable monitoring of power<br>supply voltage for output  | Onit     |                           | 0          | U       |           |            |
| 3                       | Short Circuit<br>Detection                    | Enable  | Enable valve short circuit detection  | Unit     | 0                         | 0          | 0       |           |            |
|                         | (Monitor short<br>circuit)                    | Disable   | Disable valve short circuit detection   | Onic     |                           | 0          | 0       |           |            |
|                         | Restart after short circuit                   | Auto  | After short circuit has been<br>removed, the error will be<br>cleared automatically.                          |          | 0                         | Ο          |         |           |            |
| 4                       | (Restart after<br>short circuit)              | Manual  | After short circuit has been<br>removed, the error will not be<br>cleared until the power supply is<br>reset. | Unit     |                           |            | 0       |           |            |
| 5                       | Open Circuit<br>Detection                     | Enable  | Enable valve open circuit detection   | Channel  |                           | x          | 0       |           |            |
| Ŭ                       | (OC_Mon)                                      | Disable   | Disable valve open circuit detection  | ondriner | 0                         |            | 0       |           |            |
|                         | Output setting                                | Clear   | During communication fault, clear valve output.   |          | 0                         |            |         |           |            |
| 6                       | during<br>communication<br>fault.             |   | During communication fault, hold valve output.  | Channel  |                           | х          | Ο       |           |            |
|                         | (Fault_MD)                                    | ForceOn   | During communication fault, turn ON valve output.   |          |                           |            |         |           |            |
|                         | Output setting                                | Clear   | During communication idle, clear valve output.  |          | 0                         |            |         |           |            |
| 7                       | during<br>communication<br>idle               | Hold  | During communication idle, hold valve output.   | Channel  |                           | Х          | Ο       |           |            |
|                         | (Idle_MD)                                     | ForceOn   | During communication idle, turn ON valve output.  |          |                           |            |         |           |            |
|                         | Valve ON/OFF                                  | Enable  | If valve's ON/OFF counter<br>exceeds the setting value, a<br>diagnostic error will be<br>generated.           |          |                           |            |         |           |            |
| 8                       | counter<br>(Counter)                          | Disable   | Diagnostic error will not be generated  | Channel  | 0                         | Х          | 0       |           |            |
|                         |   | Val   | Set maximum counter value.<br>Settable values are (1~65000) x<br>1000 times                                   |          | 65000                     |            |         |           |            |

### **Digital Input Unit Parameter**

| (GSD<br>Parameter)<br>Short circuit<br>detection<br>(Monitor short<br>circuit)<br>Open circuit<br>detection | Setting<br>Value<br>Enable<br>Disable<br>Enable  | Contents<br>Enable sensor's power supply<br>short circuit detection<br>Disable sensor's power supply   | Setting<br>Level<br>Unit   | setting<br>O   | By<br>PLC<br>O   | By<br>H.T.<br>O   |
|---|--|--|--|--|--|---|
| detection<br>(Monitor short<br>circuit)<br>Open circuit<br>detection  | Disable  | short circuit detection<br>Disable sensor's power supply   | Unit   | 0  | 0  | 0   |
| circuit)<br>Open circuit<br>detection   |  |  |  |  |  |   |
| detection   | Enable   | short circuit detection  |  |  |  |   |
|   |  | Enable input sensor open<br>circuit detection  | Channel  |  | Х  | 0   |
| (Monitor open<br>circuit) Note 1)   | Disable  | Disable input sensor open<br>circuit detection   |  | 0  |  |   |
| Inrush current<br>Filter  | Enable   | Enable inrush current filter   | Unit   | 0  | 0  | 0   |
| (Inrush current filter)   | Disable  | Disable inrush current filter  |  |  |  |   |
| Input Filtering<br>time<br>(Input filtering<br>time)  | 0.1/1/10/<br>20<br>msec  | 20   |  | 1msec  | 0  | 0   |
| Input<br>extension time<br>(Input<br>extension<br>time)   | 1/15/100<br>/200<br>msec   | 00 time  |  | 15<br>msec   | 0  | 0   |
| Input Sensor's<br>ON/OFF<br>(Counter)   | Enable   | If input sensor's ON/OFF<br>counter exceeds setting value,<br>diagnostic error will be<br>generated.   | Channel  |  | х  | 0   |
|   | Disabl<br>e  | Diagnostic error will not be generated   |  | 0  |  |   |
|   | Val  | Set maximum counter value.<br>Settable setting value are<br>(1~65000) x 1000 times   |  | 65000  |  |   |
|   | (Monitor open<br>circuit) <sup>Note 1)</sup><br>Inrush current<br>Filter<br>(Inrush current<br>filter)<br>Input Filtering<br>time<br>(Input filtering<br>time)<br>Input<br>extension time<br>(Input<br>extension<br>time)<br>Input Sensor's<br>ON/OFF<br>(Counter) | (Monitor open<br>circuit) Note 1)DisableInrush current<br>Filter<br>(Inrush current<br>filter)EnableInput surrent<br>filter)DisableInput Filtering<br>time)0.1/1/10/<br>20<br>msecInput Filtering<br>time)1/15/100<br>/200<br>msecInput<br>extension time<br>time)1/15/100<br>msecInput<br>extension<br>time)1/15/100<br>msecInput<br>extension<br>time)1/15/100<br>msecInput<br>extension<br>time)1/15/100<br>msecInput<br>Sensor's<br>ON/OFF<br>(Counter)Enable<br>Val | (Monitor open<br>circuit)DisableDisable input sensor open<br>circuit detectionInrush current<br>Filter<br>(Inrush current<br>filter)EnableEnable inrush current filterInput surrent<br>filter)DisableDisable inrush current filterInput Filtering<br>time<br>(Input filtering<br>time)0.1/1/10/<br>20<br>msecSet input signal filtering time.Input<br>extension time<br>(Input sensor's ON/OFF<br>(Counter)1/15/100<br>/200<br>msecSet input sensor's ON/OFF<br>counter exceeds setting value,<br>diagnostic error will be<br>generated.DisablDisablDiagnostic error will not be<br>generatedValSet maximum counter value.<br>Settable setting value are<br>(1~65000) x 1000 times | (Monitor open<br>circuit) Note 1)DisableDisable input sensor open<br>circuit detectionUnitInrush current<br>Filter<br>(Inrush current<br>filter)EnableEnable inrush current filterUnitInput Surrent<br>filter)Disable<br>DisableDisable inrush current filterUnitInput Filtering<br>time<br>(Input filtering<br>time)0.1/1/10/<br>20<br>msecSet input signal filtering time.UnitInput<br>extension time<br>(Input<br>extension time)1/15/100<br>/200<br>msecSet input signal's extension<br>timeUnitInput Sensor's<br>ON/OFF<br>(Counter)EnableIf input sensor's ON/OFF<br>counter exceeds setting value,<br>diagnostic error will be<br>generated.ChannelValSet maximum counter value.<br>Settable setting value are<br>(1~65000) x 1000 timesDiagnostic me | (Monitor open<br>circuit) Note 1)DisableDisable input sensor open<br>circuit detectionOInrush current<br>Filter<br>(Inrush current<br>filter)EnableEnable inrush current filterUnitOInput Sensor is<br>(Input sensor is contered)DisableDisable inrush current filterUnitOInput Filtering<br>time)0.1/1/10/<br>20<br>msecSet input signal filtering time.Unit1msecInput Filtering<br>time)0.1/1/10/<br>20<br>msecSet input signal is extension<br>timeUnit1msecInput sensor time<br>(Input extension time)1/15/100<br>/200<br>msecSet input sensor's ON/OFF<br>counter exceeds setting value,<br>diagnostic error will be<br>generated.ChannelOODisableDiagnostic error will not be<br>e<br>ValOOOValSet maximum counter value.<br>Settable setting value areO | (Monitor open<br>circuit) Note 1)DisableDisable input sensor open<br>circuit detectionOInrush current<br>Filter<br>(Inrush current<br>filter)EnableEnable inrush current filterUnitOOInput Siltering<br>time<br>(Input filtering<br>time)DisableDisable inrush current filterUnitOOInput Filtering<br>time<br>(Input filtering<br>time)0.1/1/10/<br>20<br>msecSet input signal filtering time.Unit1msecOInput Sensor time<br>(Input<br>extension time)1/15/100<br>/200<br>msecSet input signal's extension<br>timeUnit15<br>msecOInput Sensor's<br>ON/OFF<br>(Counter)EnableIf input sensor's ON/OFF<br>counter exceeds setting value,<br>diagnostic error will be<br>generated.ChannelXValSet maximum counter value.<br>Settable setting value are<br>(1~65000) x 1000 times65000A |

Note 1) Open Circuit Detection parameter is only available on Digital input unit with open circuit detection (P/N EX600-DXPC1, EX600-DXNC1).

### **Digital Output Unit Parameter**

| No         | Name<br>(GSD  | Setting   | Contents   | Setting | Default | Set<br>Met |            |
|------------|---|---|--|---------|---------|------------|------------|
| Parameter) |   | Value   |  | Level   | setting | By<br>PLC  | By<br>H.T. |
| 1          | Short Circuit<br>Detection                          | Enable  | Enable output short circuit detection  | Unit    | 0       | 0          | Ο          |
|            | (Monitor short<br>circuit)                          | Disable   | Disable output short circuit detection   | Onic    |         | 0          | Ŭ          |
|            | Restart after                                       | Auto  | After short circuit has been<br>removed, the error will be<br>cleared automatically                          | -       | Ο       | Ο          |            |
| 2          | 2 Short Circuit<br>(Restart after<br>short circuit) |   | After short circuit has been<br>removed, the error will not be<br>cleared until the power supply<br>is reset | Unit    | Unit    |            | 0          |
| 3          | Open Circuit<br>Detection                           | Enable  | Enable output open circuit detection   | Channel |         | x          | Ο          |
| 5          | (Monitor pen<br>circuit)                            | Disable   | Disable output open circuit detection  | Channel | 0       |            | U          |
|            | Output setting                                      | Clear   | During communication fault, clear output   |         | 0       |            |            |
| 4          |   |   | During communication fault<br>hold output  | Channel |         | х          | 0          |
|            | (Fault action)                                      | Force<br>On   | During communication fault,<br>turn ON output  |         |         |            |            |
|            | Output setting during                               | Clear   | During communication idle, clear output  |         | 0       |            |            |
| 5          | communication                                       | ommunication Hold   During communication idle, Channe |  | Channel |         | Х          | 0          |
|            | (Idle mode)   | Force<br>On   | During communication idle,<br>turn ON output   |         |         |            |            |
|            | Output<br>ON/OFF<br>counter<br>(Switching           | Enable  | If output ON/OFF counter<br>exceeds the setting value, a<br>diagnostic error will be<br>generated.           |         |         |            |            |
| 6          | counter)  | Disable   | Diagnostic error will not be generated   | Channel | 0       | х          | 0          |
|            |   | Val   | Set the maximum counter<br>value. Settable value are<br>(1~65000) x 1000 times                               |         | 65000   |            |            |

### Analog Input Unit Parameter(1)

| No | Name<br>(GSD                                       |  | Contents  | Setting | Default            |           | ting<br>hod |
|----|--|--|---|---------|--------------------|-----------|-------------|
| NU | Parameter)   | Setting Value  |   | Level   | setting            | By<br>PLC | By<br>H.T.  |
| 1  | Short Circuit<br>Detection                         | Enable   | Enable sensor<br>power supply short<br>circuit detection  | Unit    | 0                  | 0         | 0           |
|    | (Monitor short circuit)                            | Disable  | Disable sensor<br>power supply short<br>circuit detection   |         |                    | 0         |             |
| 2  | Analog Input<br>Range<br>(Ch # Range)              | 010V, 15V、<br>05V,<br>-10V+10V,<br>-5V+5V,<br>020mA,<br>420mA,<br>-20mA+20mA | Select analog input range   | Channel | -10V ~<br>10V      | 0         | 0           |
| 3  | Analog Data<br>Format<br>(Data format)             | Offset Binary,<br>Sign & Magnitude,<br>2s Complement                         | Select analog data<br>format  | Unit    | Offset<br>Binary   | 0         | Ο           |
| 4  | Analog Filter<br>(Ch # Filter)                     | None,<br>2 value average,<br>4 value average,<br>8 value average             | Select analog data<br>filter  | Unit    | 2 value<br>average | 0         | Ο           |
| 5  | Over Range<br>detection<br>(Monitor over<br>range) | Enable   | If the analog input<br>exceeds the<br>maximum allowable<br>input range (0.5%),<br>a diagnostic error<br>will be generated | Unit    | Enable             | 0         | 0           |
|    | range)   | Disable  | Above diagnostic<br>error will not be<br>generated.   |         |                    |           |             |
| 6  | Under Range<br>detection<br>(Monitor under         | Enable   | If the analog input<br>exceeds the<br>minimum allowable<br>input range (0.5%),<br>a diagnostic error<br>will be generated | Unit    | Enable             | 0         | 0           |
|    | range)   | Disable  | Above diagnostic<br>error will not be<br>generated.   |         |                    |           |             |



| Analog Input Unit Parameter (2 | 2) |
|--------------------------------|----|
|--------------------------------|----|

|                               | No Name<br>No (GSD<br>Parameter)         |         |   | Setting | Default               | Setting Method |            |
|-------------------------------|--|---------|---|---------|-----------------------|----------------|------------|
| No                            |  |         | Contents  | Level   | setting               | By<br>PLC      | By<br>H.T. |
| User Setting<br>7 Value Upper |  | Enable  | If the analog input exceeds<br>the upper user setting lower<br>limit, diagnostic error will be<br>generated     | Channal | Disable               | x              | 0          |
|                               | ' Limit Error<br>(Analog upper<br>limit) | Disable | Above diagnostic error will not be generated.   | Channel |                       | ^              | U          |
|                               |  | Val     | Refer to Note1) for possible set value  |         | 10V <sup>Note2)</sup> |                |            |
| 8                             | User Setting<br>Value lower              | Enable  | If the analog input falls below<br>the lower user setting lower<br>limit, diagnostic error will be<br>generated | Channal | Disable               | x              | 0          |
|                               | Limit Error<br>(Analog under             | Disable | Above diagnostic error will not be generated.   | Channel |                       | X              | 0          |
|                               | limit)                                   | Val     | Refer to Note1) for possible set value  |         | 10V                   |                |            |

Note1) User setting value is settable according to the table below.

| Analog input measurement | User setting value set range |                 |  |
|--------------------------|------------------------------|-----------------|--|
| range                    | Upr_Lmt                      | Lwr_Lmt         |  |
| -10 +10V                 | -10.5 ~ +10.45V              | -10.45 ~ +10.5V |  |
| -5V +5V                  | -5.25 ~ +5.22V               | -5.22 ~ +5.25V  |  |
| -20 +20mA                | -21 ~ +20.9mA                | -20.9 ~ +21mA   |  |
| 0 +10V                   | 0 ~ +10.45V                  | 0.05 ~ +10.5V   |  |
| 0 +5V                    | 0 ~ +5.22V                   | 0.02 ~ +5.25V   |  |
| +1 +5V                   | +0.75 ~ +5.22V               | +0.77 ~ +5.25V  |  |
| 0 +20mA                  | 0 ~ +20.9mA                  | 0.1 ~ +21mA     |  |
| +4 +20mA                 | +3 ~ +20.9mA                 | +3.1 ~ +21mA    |  |

Note 2) Factory default setting for Analog input range is -10...+10V When changing the analog input measurement range, please make sure to confirm the set value and set the correct value accordingly.

# Hardware Configuration

This section will explain hardware configuration and implementation and parameter allocation methods for the EX600 Series.

### **GSD File and Symbol File**

GSD file is required to configure the EX600 with a DP Master. The GSD File contains ID number, version, and unit information. Furthermore, a symbol file is necessary for the display microcontroller of the EX600 on the DP Master Software. The GSD File and Symbol File can be downloaded from the URL given below.

- URL : http://www.smcworld.com
- GSD File : SMCA1411.gsd
- Symbol File : EX600\_1N.bmp( standard type)
  - : EX600\_1D.bmp( diagnostic type)
    - : EX600\_1S.bmp( special operating mode)

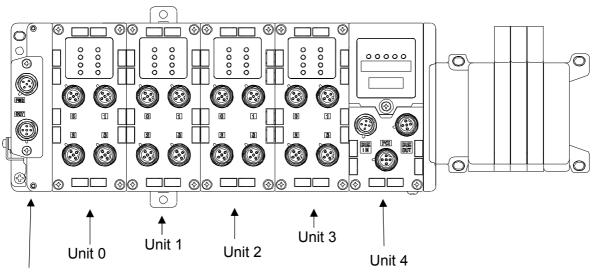
### **Unit Identification**

Each Unit of EX600 Series has a unique identification number.

| Unit Part Number              | Unit Name  | Occupied Byte                  |        | DP ID number |          |
|-------------------------------|--|--------------------------------|--------|--------------|----------|
|                               |  | Input                          | Output | Siemens      | IEC61158 |
| EX600-SPR# (32 Ch)<br>(#:1/2) | SI Unit (32 Ch)  | 0                              | 4      | 32DO         | 23h      |
| EX600-SPR# (24 Ch)<br>(#:1/2) | SI Unit (24 Ch)  | 0                              | 3      | 24DO         | 22h      |
| EX600-SPR# (16 Ch)<br>(#:1/2) | SI Unit (16 Ch)  | 0                              | 2      | 16DO         | 21h      |
| EX600-SPR# (8 Ch)<br>(#:1/2)  | SI Unit (8 Ch)   | 0                              | 1      | 8DO          | 20h      |
| EX600-DX#B<br>(#:P/N)         | Digital Input Unit                                     | 1                              | 0      | 8DI          | 10h      |
| EX600-DX#C<br>(#:P/N)         | Digital Input Unit                                     | 1                              | 0      | 8DI          | 10h      |
| EX600-DX#C1<br>(#:P/N)        | Digital Input Unit<br>(With Open Circuit<br>Detection) | 1                              | 0      | 8DI          | 10h      |
| EX600-DX#D<br>(#:P/N)         | Digital Input Unit                                     | 2                              | 0      | 16DI         | 11h      |
| EX600-DY#B<br>(#:P/N)         | Digital Output Unit                                    | 0                              | 0      | 8DO          | 20h      |
| EX600-AXA<br>( 2channel)      | Analog Input Unit<br>(2 Channel )                      | 4<br>(1 Channel is<br>2 bytes) | 0      | 2AI          | 51h      |

# **Configuration Layout**

The Unit number is sequentially allotted from the End Plate end of the EX600 assembly. The communication with the DP Master will not be established if the layout of the hardware configuration does not match the actual system configuration.



End plate

## **SIEMENS PLC S7 Connection Method**

Below is an explanation of the EX600 Series connection method with a SIEMENS' PLC STEP7™.

## **GSD** File Installation

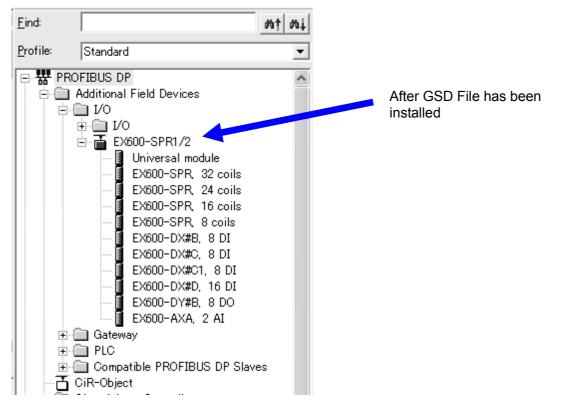
There are 2 methods for installing the EX600-SPR# GSD file:

## Method1: Before starting-up STEP7<sup>™</sup>.

- Copy GSD file to [.../ Siemens / Step7:/ S7data / gsd] folder.
- Copy Symbol file to [.../Siemens / Step7 / S7data / nsbmp] folder.
- After completing the above steps, the EX600-SPR1/2 will automatically be added to the Hardware Catalogue under the STEP7<sup>™</sup> [Hardware Catalogue] [Additional Field Devices / I/O /] Folder.

## Method 2: After STEP7<sup>™</sup> has been started.

- Open [Hardware Configuration] screen.
- Select "Option→Install New GSD… " From the menu bar.
- Select GSD File (SMCA1411.gsd), and click the Open button.
- Copy symbol file to [... / Siemens / STEP7 / S7data / nsbmp] folder.
- After completing the above steps, the EX600-SPR1/2 will automatically be added to the Hardware Catalogue under the STEP7<sup>™</sup> [Hardware Catalogue] [Additional Field Devices / I/O /] Folder..



Screen data used on this document is taken from STEP7™ software by Siemens AG.



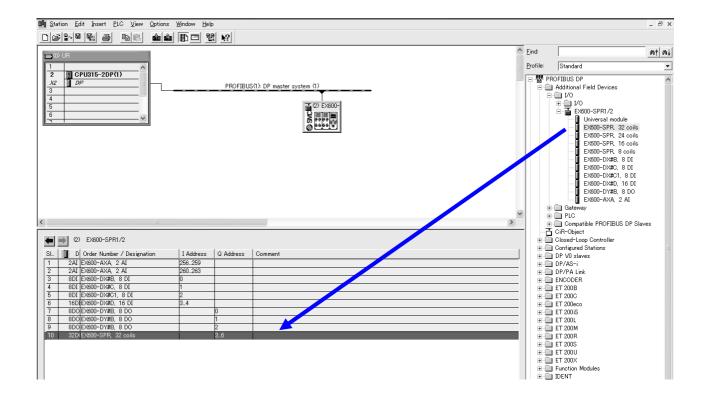
## **Adding Stations**

- Drag and drop EX600-SPR1/2 from the Hardware Catalogue to the station window. "Property-PROFIBUS Interface EX600-SPR1/2" Dialogue Box will be displayed.
- Enter the unit address on the dialogue box. Please make sure that the address entered is the same as the address set, using the SI unit switches.
- Press the OK button to confirm the address setting. EX600-SPR1/2 will be shown on the station window.

| 🕼 Station Edit Insert PLC View Options Window Help  | _ B ×  |
|---|--|
|   |  |
| 🗩 🛈 UR  | Eind: nt nt  |
|   | Profile: Standard  |
| 2         CPU315-2DP(1)           3         PROFIBUS(1): DP master system (1)           4         -           6         - | ■         ■         PROFIBUS DP         ■           ■         ■         Additional Field Devices         ■           ■         □         I/O         ●         □           ■         ■         DS00-SPR12         ■         ■           ■         ■         ■         BS00-SPR12         ■         ■           ■         ■         ■         ■         BS00-SPR12         ■ </td |
|   |  |
| (2) EX600-SPR1/2  |  |
| SL. D Order Number / Designation I Address Q Address Comment  | Configured Stations  |
|   | DP/AS-i  |

## **Adding Units**

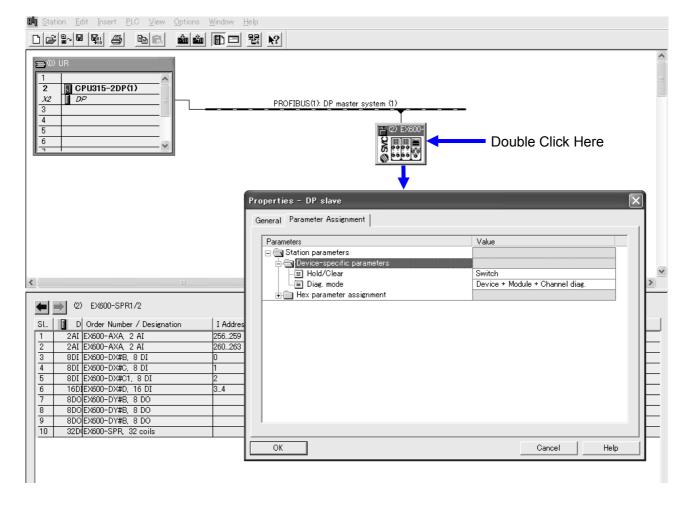
- Select "EX600-SPR1/2" from the station window.
- An empty slot for EX600-SPR1/2 will be displayed on the configuration table, below the station window.
- Drag and drop the connected unit from [Hardware Catalogue] Window to slot 1. Please make sure to add the unit as the real system's order of connecting (i.e Unit 0 at Slot 1).
- Add the other units, according to the connected order, to the configuration table, ending with the SI unit.
- The SI Unit for 32, 24, 16, 8 coils can be selected, please make sure to match the setting with the V\_SEL switch setting in the SI unit.



## Parameter Setting at PLC

### System Parameter Setting

- Double click the "EX600-SPR1/2" symbol on the PROFIBUS: DP master system line. The system properties window will be displayed.
- Select the [Parameter Assignment] tab; the available Parameter setting list will be displayed under [Device-Specific parameters] folder.
- Change the parameter value by clicking on the Value column of the selected parameter.
- Press the OK Button, after the configuration data is downloaded to the PLC, the setting will be completed.



The system parameters given below can be set at the STEP7™.

| System<br>Parameter | Setting Value                  |
|---------------------|--------------------------------|
| Hold/Clear          | Switch                         |
|                     | Parameter                      |
| Diag.mode           | No diag.                       |
|                     | Device diag                    |
|                     | Device + Module diag.          |
|                     | Device + Module + Channel Diag |



## **Unit Parameter Setting**

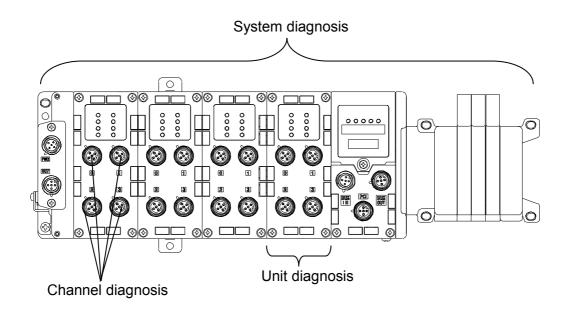
• Double click a unit that you want to set on the configuration table, select [Parameter Assignment] tab. The setting method is the same as described above for system parameter setting.

| Address / ID Parameter Assignment  | Value                    |
|--|--------------------------|
|  | Value                    |
| Parameters  Station parameters  Station parameters  Device-specific parameters       |                          |
| 一国 Monitor short circuit<br>一国 Restart after short circuit<br>一国 Pwr control monitor | Enable<br>Auto<br>Enable |
|  | Enable                   |
|  |                          |
|  |                          |
|  |                          |
| ОК   | Cancel Help              |

# **Diagnostic Mode**

The diagnostic Mode can be set at Diag. Mode in the system parameter setting.

| No. | Diagnostic Mode                | Contents  |
|-----|--------------------------------|---|
| 1   | No diag.                       | Provides standard diagnostic data                       |
| 2   | Device diag                    | Provides standard diagnostic + system diagnostic data   |
| 3   | Device + Module diag.          | Provides standard diagnostic + system diagnostic + unit |
|     |                                | diagnostic data   |
| 4   | Device + Module + Channel Diag | Provides standard diagnostic + system diagnostic + unit |
|     |                                | diagnostic + channel diagnostic data                    |



# **Diagnostic Map**

| Diagnostic | : Map is shown below       |                      |  |  |
|------------|----------------------------|----------------------|--|--|
| Byte No.   | Contents                   | Diagnostic type      |  |  |
| Byte 0     | Station Status 1           |                      |  |  |
| Byte 1     | Station Status 2           |                      |  |  |
| Byte 2     | Station Status 3           | Standard Diagnostic  |  |  |
| Byte 3     | Master PROFIBUS Address    | data                 |  |  |
| Byte 4     | Manufacturer ID(MSB : 14h) |                      |  |  |
| Byte 5     | Manufacturer ID(LSB : 11h) |                      |  |  |
| Byte 6     | Header                     |                      |  |  |
| Byte 7     | System diag.1              |                      |  |  |
| Byte 8     | System diag.2              |                      |  |  |
| Byte 9     | System diag.3              | System Diagnostic    |  |  |
| Byte 10    | System diag.4              | data                 |  |  |
| Byte 11    | Reserved                   |                      |  |  |
|            |                            |                      |  |  |
| Byte 18    | Reserved                   |                      |  |  |
| Byte 19    | Header                     |                      |  |  |
| Byte 20    | Unit 0~7                   |                      |  |  |
| Byte 21    | Unit 8~9                   | Unit Diagnostic data |  |  |
| Byte 22    | Reserved                   |                      |  |  |
|            |                            |                      |  |  |
| Byte 27    | Reserved                   |                      |  |  |
| Byte 28    | Unit A                     |                      |  |  |
| Byte 29    | Channel A                  |                      |  |  |
| Byte 30    | Diagnostic contents A      |                      |  |  |
| Byte 31    | Unit B                     |                      |  |  |
| Byte 32    | Channel B                  | Channel Diagnostic   |  |  |
| Byte 33    | Diagnostic contents B      | data                 |  |  |
|            |                            |                      |  |  |
| Byte 61    | Unit L                     |                      |  |  |
| Byte 62    | Channel L                  |                      |  |  |
| Byte 63    | Diagnostic contents L      |                      |  |  |

## Standard Diagnostic data

#### Station Status 1

|        | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |  |
|--------|---|---|---|---|---|---|---|---|--|
| Byte 0 |   |   |   |   |   |   |   |   |  |

| Bit No. | Meaning  |  |  |  |  |  |  |  |
|---------|--|--|--|--|--|--|--|--|
| 0       | DP Slave can not be accessed by DP Master  |  |  |  |  |  |  |  |
| 1       | DP Slave is not ready to exchange data   |  |  |  |  |  |  |  |
| 2       | Configuration data transmitted to DP Slave by DP Master does not match with setting of DP Slave. |  |  |  |  |  |  |  |
| 3       | External diagnostic function can be used   |  |  |  |  |  |  |  |
| 4       | DP Slave does not support the required function  |  |  |  |  |  |  |  |
| 5       | DP Master can not interpret the response of DP Slave   |  |  |  |  |  |  |  |
| 6       | DP Slave type does not correspond to software configuration                                      |  |  |  |  |  |  |  |
| 7       | Parameter is allocated to DP Slave by different DP Master  |  |  |  |  |  |  |  |

## **Station Status 2**

|        | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|---|---|---|---|---|---|---|
| Byte 1 |   | 0 |   |   |   | 1 |   |   |

| Bit No. | Meaning   |  |  |  |  |  |
|---------|---|--|--|--|--|--|
| 0       | New Parameter needs to be allocated to the DP slave |  |  |  |  |  |
| 1       | A new message was generated                         |  |  |  |  |  |
| 2       | At DP Slave, this bit is always 1)                  |  |  |  |  |  |
| 3       | The response monitor is effective to DP Slave.      |  |  |  |  |  |
| 4       | DP Slave received FREEZE control command.           |  |  |  |  |  |
| 5       | DP Slave received the SYNC control command.         |  |  |  |  |  |
| 6       | (Bit is always 0)                                   |  |  |  |  |  |
| 7       | DP Slave is inactive                                |  |  |  |  |  |

## **Station Status 3**

|         | 7 | 6 | 5 | 4 | 3              | 2 | 1 | 0 |  |
|---------|---|---|---|---|----------------|---|---|---|--|
| Byte 2  |   | 0 | 0 | 0 | 0              | 0 | 0 | 0 |  |
|         |   |   |   |   |                |   |   |   |  |
| Bit No. |   |   |   | Ν | <i>Meaning</i> |   |   |   |  |

| Bit No. | Meaning  |
|---------|--|
| 0~6     | (Bit is always 0)  |
| 7       | There are more diagnostic message than DP Slave can store. |

### Master PROFIBUS Address

Byte 3 shows the PROFIBUS Address of the DP Master.

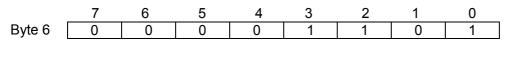
When the address is FFh, the parameter of the DP Slave cannot be changed. For all other address settings, the parameters of the DP Slave can be changed.

#### Manufacturer ID

The DP Slave manufacturer ID is shown. The EX600-SPR1/2 manufacturer ID is 1411h.

## System Diagnostic data

## Header



| Bit No. | Meaning                                   |
|---------|---|
| 0~5     | Number of Byte of devices Diagnostic data |
| 6, 7    | (Bits are always 0)                       |

## System diag.1

| -      | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|--------|---|---|---|---|---|---|---|---|
| Byte 7 |   |   |   |   |   |   |   |   |

| Bit No. | Meaning   |
|---------|---|
| 0       | Analog input falls below user's setting lower limit value |
| 1       | Analog input exceeds user's setting upper limit value     |
| 2       | Analog input falls below lower measurement range          |
| 3       | Analog input exceeds upper measurement range              |
| 4       | Channel ON/OFF counter exceeds setting value              |
| 5       | Open circuit error detected                               |
| 6       | Short circuit detected on valve output or digital output. |
| 7       | Short circuit detected on input sensor's power supply     |

System diag.2 2 1 0 <u>6 5</u> -3 4 Byte 8

| Bit No. | Meaning  |
|---------|--|
| 0       | Power supply voltage for output is outside operating range       |
| 1       | Power supply voltage for control and sensor is outside operating |
|         | range  |
| 2       | Reserved   |
| 3       | Connection error on I/O Unit (during operation)                  |
| 4       | Connection error on I/O Unit(at system start up)                 |
| 5       | Reserved   |
| 6       | System error   |
| 7       | Hardware error   |



| System d | liag.3 |  |   |   |         |   |   |   |   |
|----------|--------|--|---|---|---------|---|---|---|---|
|          | 7      | 6                                      | 5 | 4 | 3       | 2 | 1 | 0 |   |
| Byte 9   | -      | -                                      | - | - | -       | - | - | - |   |
|          |        |  |   |   |         |   |   |   |   |
| Bit no.  |        |  |   |   | Meaning |   |   |   |   |
| 0~7      | Rese   | erved                                  |   |   |         |   |   |   |   |
|          |        |  |   |   |         |   |   |   |   |
|          |        |  |   |   |         |   |   |   |   |
| System o | diag.4 |  |   |   |         |   |   |   |   |
|          | _      | •                                      | _ |   | •       | • |   | • |   |
|          | 7      | 6                                      | 5 | 4 | 3       | 2 | 1 | 0 | 7 |
| Byte 10  | -      | -                                      | - |   | -       |   |   |   |   |
|          |        |  |   |   |         |   |   |   |   |
| Bit No.  |        |  |   |   | Meaning |   |   |   |   |
| 0        |        | r detecte                              |   |   |         |   |   |   |   |
| 1        |        | Error detected on Digital Output unit. |   |   |         |   |   |   |   |
| 2        | Erro   | Error detected on Analog Input unit.   |   |   |         |   |   |   |   |
| 3        |        | Reserved                               |   |   |         |   |   |   |   |
| 4        | Erro   | Error detected on SI unit.             |   |   |         |   |   |   |   |
| 5        | Rese   | Reserved                               |   |   |         |   |   |   |   |
| 6        |        | erved                                  |   |   |         |   |   |   |   |
| 7        | Rese   | erved                                  |   |   |         |   |   |   |   |

# Unit Standard Diagnostic data

Header

|         | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |  |
|---------|---|---|---|---|---|---|---|---|--|
| Byte 19 | 0 | 1 | 0 | 0 | 1 | 0 | 0 | 1 |  |

| Bit No. | Meaning                                |
|---------|--|
| 0~5     | Number of byte of unit diagnostic data |
| 6       | (Bit is always 1)                      |
| 7       | (Bit is always 0)                      |

| Unit 0~ | 7 |   |   |   |   |   |   |   |  |
|---------|---|---|---|---|---|---|---|---|--|
|         | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |  |
| Byte 20 |   |   |   |   |   |   |   |   |  |

| Bit No. | Meaning                  |
|---------|--------------------------|
| 0       | Error detected on Unit 0 |
| 1       | Error detected on Unit 1 |
| 2       | Error detected on Unit 2 |
| 3       | Error detected on Unit 3 |
| 4       | Error detected on Unit 4 |
| 5       | Error detected on Unit 5 |
| 6       | Error detected on Unit 6 |
| 7       | Error detected on Unit 7 |

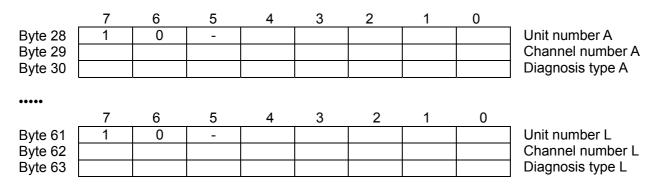
### Unit 8~9

|         | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|---------|---|---|---|---|---|---|---|---|
| Byte 21 | - | - | - | - | - | - |   |   |

| Bit No. | Meaning                  |
|---------|--------------------------|
| 0       | Error detected on Unit 8 |
| 1       | Error detected on Unit 9 |
| 2~7     | Reserved                 |

## **Channel Diagnostic data**

Each channel diagnostic data is composed of 3 bytes, with a maximum of 12 errors which can be detected. However, because only one error may output per one unit, when two or more errors are generated by the same unit, the error on the channel with the lowest number will be output.



## Unit Number

| Bit No. | Meaning                  |
|---------|--------------------------|
| 0~4     | Displays Unit number 0~9 |
| 5       | Reserved                 |
| 6       | (Bit is always 0)        |
| 7       | (Bit is always 1)        |

#### **Channel Number**

| Bit no. | Meaning   |  |  |  |
|---------|---|--|--|--|
| 0~5     | Displays Channel number 0~63                          |  |  |  |
| 6, 7    | Input / Output Type :                                 |  |  |  |
|         | 00= Reserved、01= Input 、10= Output、11= Input / output |  |  |  |

## **Diagnostic Type**

| Bit No. | Meaning   |
|---------|---|
| 0~4     | Error Code  |
| 5~7     | Channel Type :<br>001= Bit (Unit other than Analog Input)<br>101=Word(Analog Input Unit ) |

#### **Error Code**

| Error Code<br>(Decimal) | Meaning   | Level |
|-------------------------|---|-------|
| 0                       | Reserved  |       |
| 1                       | Short Circuit Detection                                   | 3     |
| 2~5                     | Reserved  |       |
| 6                       | Open circuit Detection                                    | 3     |
| 7                       | Analog input exceeds upper measurement range              | 3     |
| 8                       | Analog input falls below lower measurement range          | 3     |
| 9~15                    | Reserved  |       |
| 16                      | Analog input exceeds user's setting upper limit value     | 3     |
| 17                      | Analog input falls below user's setting lower limit value | 3     |
| 18                      | Channel ON/OFF counter exceeds setting value              | 3     |
| 19~29                   | Reserved  |       |
| 30                      | Connection error on I/O Unit                              | 1     |
| 31 <sup>(Note2)</sup>   | Hardware error  | 2     |

Note1) It becomes the order of the priority level  $(1\rightarrow 2\rightarrow 3)$  when an error is detected on the same unit same channel. Note2) The Channel number when an Error is generated is assumed to be 0.

## Accessories

Please refer to the catalogue for selecting the accessories.

(1)Valve Plate

Used for mounting solenoid valve manifold and SI unit.

EX600-ZMV1

(2)Metal fittings for Endplate Metal fittings used with endplate when installed on DIN rail.

EX600-ZMA2

(3)Metal fittings for the intermediate reinforcement Metal fittings used at the intermediate position when more than 6 units are assembled.

| EX600-ZMB1 | For direct mounting   |
|------------|-----------------------|
| EX600-ZMB2 | For DIN rail mounting |

(4)Seal cap (10 pcs included)

Please install a seal cap in all unused input/output connectors, to maintain the protective construction of IP67.

| EX9-AWES | For M8  |
|----------|---------|
| EX9-AWTS | For M12 |

(5)Marker (1 sheet, 88pcs included)

A marker to show input/output equipment signal names and unit addresses, etc. can be inserted for each unit.

EX600-ZT1

(6)Y Junction connector

Connector used to branch off between sensor and input unit.

PCA-1557785 2×M12(3 pin)-M12(5 pin)



## (7)Assembled type connector

| PCA-1558797 | Power supply cable 7/8",Plug                     |  |
|-------------|--|--|
| PCA-1558807 | Power supply cable 7/8",Socket                   |  |
| PCA-1557701 | PROFIBUS DP communication cable, Plug            |  |
| PCA-1557714 | PROFIBUS DP communication cable, Socket          |  |
| PCA-1557730 | M8(3 pin),Plug                                   |  |
| PCA-1557743 | M12(4 pin),Plug ,AWG26~AWG22,SPEEDCON compatible |  |
| PCA-1557756 | M12(4 pin),Plug ,AWG22~AWG18,SPEEDCON compatible |  |

(8)Power supply cable

| PCA-1558810 | Cable with 7/8" connector, Socket, Straight 2m            |
|-------------|---|
| PCA-1558823 | Cable with 7/8" connector, Socket, Straight 6m            |
| PCA-1558836 | Cable with 7/8" connector, Socket, Right angle 2m         |
| PCA-1558849 | Cable with 7/8" connector, Socket, Right angle 6m         |
| PCA-1564927 | Cable with M12 connector, B Code, Socket, Straight 2m,    |
|             | SPEEDCON compatible                                       |
| PCA-1564930 | Cable with M12 connector, B Code ,Socket ,Straight 6m,    |
|             | SPEEDCON compatible                                       |
| PCA-1564943 | Cable with M12 connector, B Code, Socket, Right angle 2m, |
|             | SPEEDCON compatible                                       |
| PCA-1564969 | Cable with M12 connector, B Code, Socket, Right angle 6m, |
|             | SPEEDCON compatible                                       |

## (9)PROFIBUS DP communication cable

| PCA-1557688 | Cable with M12 connector cable, B Code, Socket, Straight 5m, |
|-------------|--|
|             | SPEEDCON compatible  |
| PCA-1557691 | Cable with M12 connector, B Code, Plug, Straight 5m,         |
|             | SPEEDCON compatible  |

## (10)Connector extension cable

| PCA-1557769 | M12(4pin),Straight 3m |
|-------------|-----------------------|
| PCA-1557772 | M8(3pin),Straight 3m  |

Revision history

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