

Operation Manual

Fieldbus system PROFIBUS DP compatible PRODUCT NAME

> EX600-SPR* EX600-DX* EX600-DY* EX600-AX* EX600-ED* MODEL/ Series

SMC Corporation

Table of Contents

Safety Instructions	2
Product Outline	9
Assembly	12
Mounting and Installation	14
SI Unit	
How to order	18
Name and Function of Parts	18
Mounting and Installation	19
Setting and Adjustment	20
Error Display	24
Specifications	26
Digital Input Unit	
How to order	28
Name and Function of Parts	28
Mounting and Installation	30
Error Display	32
Specifications	33
Digital Output Unit	
How to order	37
Name and Function of Parts	37
Mounting and Installation	38
Error Display	39
Specifications	40
Analog Input Unit	
How to order	42
Name and Function of Parts	42
Mounting and Installation	43
Error Display	44
Specifications	45
Endplate	
How to order	51
Name and Function of Parts	51
Mounting and Installation	52
Troubleshooting	55
Parameter Setting	
Hard ware configuration	70
Diagnostics	77
Accessory	84

Safety Instructions

These safety instructions are intended to prevent hazardous situations and/or equipment damage. These instructions indicate the level of potential hazard with the labels of "Caution," "Warning" or "Danger.". They are all important notes for safety and must be followed in addition to International standards (ISO/IEC), Japan Industrial Standards (JIS)^{*1)} and other safety regulations^{*2)}.

- *1) ISO 4414: Pneumatic fluid power - General rules relating to systems.
 - ISO 4413: Hydraulic fluid power - General rules relating to systems.
 - IEC 60204-1: Safety of machinery -Electrical equipment of machines. (Part 1: General requirements)
 - ISO 10218-1992: Manipulating industrial robots -Safety.
 - JIS B 8370: General rules for pneumatic equipment.
 - JIS B 8361: General rules for hydraulic equipment.
 - JIS B 9960-1: Safety of machinery Electrical equipment of machines. (Part 1: General requirements)
 - JIS B 8433-1993: Manipulating industrial robots Safety. etc.
- *2) Labor Safety and Sanitation Law, etc.

Caution : Operator error could result in injury or equipment damage.
 Warning : Operator error could result in serious injury or loss of life.
 Danger : In extreme conditions, there is a possibility of serious injury or loss of life.

Warning

1. The compatibility of the product is the responsibility of the person who designs the equipment or decides its specifications.

Since the product specified here is used under various operating conditions, its compatibility with specific equipment must be decided by the person who designs the equipment or decides its specifications based on necessary analysis and test results. The expected performance and safety assurance of the equipment will be the responsibility of the person who has determined its compatibility with the product. This person should also continuously review all specifications of the product referring to its latest catalog information, with a view to giving due consideration to any possibility of equipment failure when configuring the equipment.

- 2. Only personnel with appropriate training should operate machinery and equipment. The product specified here may become unsafe if handled incorrectly. The assembly, operation and maintenance of machines or equipment including our products must be performed by an operator who is appropriately trained and experienced.
- 3. Do not service or attempt to remove product and machinery/equipment until safety is confirmed.
- 1. The inspection and maintenance of machinery/equipment should only be performed after measures to prevent falling or runaway of the driven objects have been confirmed.
- 2. When the product is to be removed, confirm that the safety measures as mentioned above are implemented and the power from any appropriate source is cut, and read and understand the specific product precautions of all relevant products carefully.
- 3. Before machinery/equipment is restarted, take measures to prevent unexpected operation and malfunction.
- 4. Contact SMC beforehand and take special consideration of safety measures if the product is to be used in any of the following conditions.
 - 1. Conditions and environments outside of the given specifications, or use outdoors or in a place exposed to direct sunlight.
- 2. Installation on equipment in conjunction with atomic energy, railways, air navigation, space, shipping, vehicles, military, medical treatment, combustion and recreation, or equipment in contact with food and beverages, emergency stop circuits, clutch and brake circuits in press applications, safety equipment or other applications unsuitable for the standard specifications described in the product catalog.
- 3. An application which could have negative effects on people, property, or animals requiring special safety analysis.
- 4. Use in an interlock circuit, which requires the provision of double interlock for possible failure by using a mechanical protective function, and periodical checks to confirm proper operation.



Caution Caution I. The product is provided for use in manufacturing industries. The product herein described is basically provided for peaceful use in manufacturing industries. If considering using the product in other industries consult SMC beforehand and exchange specifications

or a contract if necessary.

If anything is unclear, contact your nearest sales branch.

Limited warranty and Disclaimer/Compliance Requirements

The product used is subject to the following "Limited warranty and Disclaimer" and "Compliance Requirements".

Read and accept them before using the product.

Limited warranty and Disclaimer

- 1. The warranty period of the product is 1 year in service or 1.5 years after the product is delivered.^{*3)} Also, the product may have specified durability, running distance or replacement parts. Please consult your nearest sales branch.
- For any failure or damage reported within the warranty period which is clearly our responsibility, a replacement product or necessary parts will be provided. This limited warranty applies only to our product independently, and not to any other damage
- incurred due to the failure of the product.
- 3. Prior to using SMC products, please read and understand the warranty terms and disclaimers noted in the specified catalog for the particular products.
 - *3) Vacuum pads are excluded from this 1 year warranty.
 - A vacuum pad is a consumable part, so it is warranted for a year after it is delivered.
 - Also, even within the warranty period, the wear of a product due to the use of the vacuum pad or failure due to the deterioration of rubber material are not covered by the limited warranty.

Compliance Requirements

When the product is exported, strictly follow the laws required by the Ministry of Economy, Trade and Industry (Foreign Exchange and Foreign Trade Control Law).



Operator

- This operation manual has been written for those who have knowledge of machinery and apparatus that use pneumatic equipment and have full knowledge of assembly, operation and maintenance of such equipment.
- Please read this operation manual carefully and understand it before assembling, operating or providing maintenance.

Warning

♦ Do not disassemble, modify (including change of printed circuit board) or repair this product. Injury or failure can result.

- ♦ Do not perform operation or setting with wet hands.
- There is a risk of electric shock.

Do not operate the product beyond the specification range.
 Do not apply the product to flammable gas or liquid or the gas or liquid harmful to human body.
 Otherwise it causes fire, malfunction, or damage to the system.
 Please confirm the specifications before use.

•Do not operate the product in an environment where flammable or explosive gas may be present.

Fire, explosion or corrosion can result.

The product is not designed to be explosion proof.

• The following instructions must be followed when using the product in an interlocking circuit:

- Provide multiple interlocking using another system such as mechanical protection
- Check the product regularly to ensure proper operation Otherwise malfunction can cause an accident.

• The following instructions must be followed while performing maintenance work:

• Turn off the power supply

• Stop the air supply, exhaust the residual pressure and verify that the air is released to atmosphere before performing maintenance work

Otherwise it can cause injury.

ACaution

♦When handling, assembling and replacing the unit:

- When handling the unit, do not touch any sharp metal parts of the connector and plug.
- When disassembling the unit, do not strike the product forcefully.
 - The connection parts are firmly joined with seals.
- When joining units, take care not to get your fingers trapped between units.
- Perform a proper functional check after completing maintenance work.
 Stop operation if any abnormality is observed or if the product is not working properly.
 Safety cannot be assured due to unexpected malfunction.

Provide grounding to assure the safety and noise resistance of the fieldbus system. Individual grounding should be provided close to the product with a short cable.

NOTE

- Follow the instructions given below when handling the fieldbus system. Otherwise, the system may be damaged and may fail.
- The instructions on selection (installation, wiring, operating environment, adjustment, operation and maintenance) described below must also be followed.

Product specifications

- Use the following UL recognized direct-current (DC) power supply.
 - (1) Limited voltage current circuit in accordance with UL508
 - A circuit whose power is supplied by secondary coil of an isolating transformer that meets the following conditions
 - Maximum voltage (with no load) : less than 30 Vrms (42.4 Vpeak)
 - Maximum current : (1) less than 8A (including when short circuited)
 - (2) limited by circuit protector (such as a fuse) with the following ratings

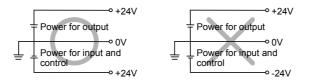
No load voltage (Vpeak)	Max. current rating (A)
0 ~ 20 [V]	5.0
Above 20 to 30 [V]	100 / peak voltage

(2) A circuit using max. 30 Vrms or less (Class-2 circuit), whose power is supplied by Class-2 power supply unit in accordance with UL1310 or by Class-2 power supply unit in accordance with UL1585

• Operate the fieldbus system within the specified voltage.

Operation with a voltage outside of the specifications could cause malfunction or damage to the system.The reference for the power supply of the SI unit is 0 V for both the output and control power supplies of

the SI unit.



• Do not mount in a location where the product will be used as a foothold.

The unit may be damaged if excessive force is applied by stepping or climbing onto it.



- Reserve sufficient space for maintenance around the product
- Be sure to reserve sufficient space for maintenance when designing the layout of the system.
- Do not remove any nameplates or labels. This can lead to incorrect maintenance, or misreading of the operation manual, which could cause damage or malfunction to the unit. It may also result in non-conformity to safety standards.
- Be careful regarding the inrush current generated when the power is supplied.
- Depending on the connected load, an initial charging current may cause an over current protective function resulting in malfunction of the system.

Precautions for handling Installation

- Do not drop, hit or apply excessive shock to the unit. Otherwise the unit could be damaged, resulting in failure.
- Tighten screws to the specified tightening torque.
 Excessive tightening torque can break the screws.
 IP67 protection cannot be guaranteed if the screws a
- IP67 protection cannot be guaranteed if the screws are not tightened to the specified torque.
- When lifting a large size solenoid valve manifold unit, take care to avoid causing stress to the valve connection joint

The connection parts of the unit may be damaged.

Because the unit may be heavy, carrying and installation should be performed by more than one operator to avoid strain or injury.

Wiring (including plugging in/out of connector)

- Do not bend the cables or apply excessive force by pulling or placing heavy loads on them.
- Bending or tensile stress could cause the cables to break.
- Connect wires and cables correctly. Incorrect wiring could break the fieldbus system.
- Do not connect wires while the power is supplied.

This can damage components and also cause undisirable behaviour

- Do not lay wires and cables together with power or high-voltage cables in the same wiring route. Otherwise the wires to the fieldbus system could be affected by noise or induced surge voltage from power lines or high-voltage cables, causing malfunction. Route the wires to the SI Unit and each I/O device to a wire duct or in a protective tube other than those for power lines or high-voltage cables
- Verify the insulation of wiring.
 Poor insulation (interference with other circuits, poor insulation between terminals, etc.) can introduce excessive voltage or current to the SI Unit or each I/O device causing damage.
- Separate the power line for solenoid valves from the power line for input and control unit. Otherwise wires can be affected by noise or induced surge voltage, causing malfunction.
- Take appropriate measures against noise, such as using a noise filter, when the fieldbus system is incorporated into equipment. Otherwise noise can cause malfunction.

Operating environment

- Select the proper type of protection according to the environment of operation.
 - IP65/67 protection is achieved when the following conditions are met.
 - (1). The units are connected properly with communication line connector and power cable M12 connector at both ends,
 - (2) Suitable mounting of each unit and manifold valve.
 - (3) Be sure to mount a seal cap on any unused connectors.
 - If using in an environment that is exposed to water splashes, please take measures such as using a cover.



• Take sufficient shielding measures if the unit is installed in any of the locations described below. Insufficient measures could cause malfunction or failure.

Verify the effectiveness of the measures after incorporation of the unit into the equipment.

- (1) A place where noise is generated due to static electricity
- (2) A place where electric field strength is high
- (3) A place where there is radioactive irradiation
- (4) A place near a power line
- Do not use in an environment exposed to oil or chemicals.
- Using the product in an environment exposed to any type of oil or chemicals, such as coolants and cleaning fluids, may adversely affect the unit, causing failure or malfunction reducing the life of the product.
- Do not use in an environment exposed to corrosive gases or liquids. The unit may be damaged, leading to malfunction.
- Do not use the unit near to a place where electrical surges are generated. Internal circuit elements of the fieldbus system can deteriorate or break if equipment generating a large surge (electromagnetic lifter, high frequency induction furnace, motor, etc.) is located near the fieldbus system. Provide surge prevention measures, and avoid interference.
- Use the fieldbus system equipped with a surge absorber if a surge-generating load such as a solenoid valve is driven directly.
- Direct drive of a load generating surge voltage can damage the fieldbus system.
- The product does not have resistance against lightning surges required for CE marking, so please take measures against lightning surge on the equipment side.
- Make sure foreign matter such as dust and piping waste does not get inside the product. This may cause failure or malfunction.
- Do not expose the fieldbus system to vibration or impact. Otherwise failure or malfunction could be caused.
- Do not use in an environment that is subject to a temperature cycle. If it is subjected to a temperature cycle outside of normal temperature changes, this may adversely affect the internal parts of the unit.
- Do not use in a location directly exposed to sunlight. If the product is located in such a position, arrange a suitable cover to protect the unit. Direct exposure to sunlight may cause failure or malfunction.
- Keep within the specified ambient temperature range. Otherwise malfunction could be caused. Do not use the fieldbus system in a place where temperature changes suddenly, even within the specified range.
- Do not expose the fieldbus system to heat radiation from a heat source located nearby. Malfunction could be caused.

Adjustment and Operation

- Set the switches using a small screwdriver, etc.. When operating the switches, do not touch parts other than the related parts. This may lead to failure due to component damage or short-circuit.
- Perform setting appropriate to the operating conditions. Inappropriate settings can cause defective operation.
- Please refer to page20-23 of this document for the settings of each switch.
- Please refer to the PLC manufacturer's manual for details of programming and addresses. For the PLC protocol and programming refer to the relevant manufacturer's documentation.

Maintenance and Checks

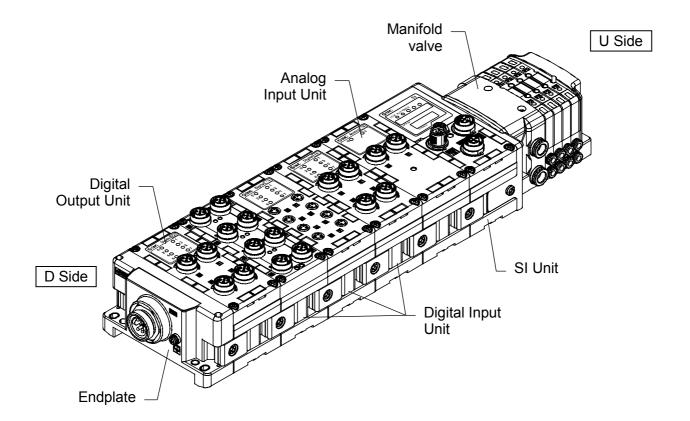
- Before performing maintenance work, turn off the power supply, stop the supply of air, exhaust the compressed air from inside the piping, and verify that the air is released to atmosphere. Otherwise, there is a risk of unexpected malfunction of the system components.
- Perform maintenance and checks regularly. Otherwise unexpected malfunction of components could occur due to a malfunction of the whole unit.
- Perform appropriate functional checks. Stop operation if any abnormality is observed or if the device does not work properly. Otherwise an unexpected malfunction of the unit or components could occur.
- Do not use solvents such as benzene, thinner, etc. to clean the fieldbus system. They could damage the surface of the body and erase the indication markings on the body. Use a soft cloth to remove stains. For heavy stains, use a cloth soaked in diluted neutral detergent and fully squeezed, then wipe again with a dry cloth.

Product Outline

System configuration

The EX600 range of units can be connected to various types of Fieldbus to realize the reduction of I/O device wiring and the distributed control system. The unit communicates with the Fieldbus through the SI unit. One SI unit can be connected with manifold valves with up to 32 points and I/O units with maximum 10 points.

All wiring between devices use cables with connectors at both ends and the system is compliant to IP67 protection.



- SI unit: Performs fieldbus communication and solenoid valve manifold ON/OFF output.
- Digital Input unit: For connecting sensors with switch output capability. PNP and NPN types are available.
- Digital Output unit: For connecting output equipment such as solenoid valves, lamps, buzzers, etc. PNP and NPN types are available.
- Analog Input unit: For connecting sensors with analog output capability.
- Endplate: Connected at EX600 Manifold's D side, incorporating the power supply connection.
- Solenoid valve manifold: An assembly of solenoid valves. One connector is used as the electric connection to all connected valves.



Glossary

No.	Term	Definition
А	Address (Station Address)	Number allocated to identify each unit connected on PROFIBUS DP network. Address number is not permitted to be duplicated.
С	Communication speed	Data receive and transmit speed used by the fieldbus. This depends on master equipment (PLC etc.), the unit used is bps (bit per second).
С	Current consumption	The amount of current required by each unit in order to operate.
D	Diagnosis Information	Diagnosis information that composed of standard diagnosis information of PROFIBUS DP and EX600 diagnosis information.
D	DIN rail	Metal rail in accordance with DIN standard.
D	D Side	T The DOWN side of the manifold, where EX600 Endplate is connected
F	FAIL SAFE Function	When PLC (DP master) is at clear mode, it sends data packet of output data with data length ="0". As a result the slave will be set to a defined state (Hold/Clear/Force ON).
F	FE	Functional Earth.
F	Fieldbus	Type of communication system between a PLC and factory equipment (such as measuring instruments or machines), in which data is exchanged by digital communication.
F	FREEZE Function	Function which synchronizes input data of SI unit with FREEZE Command from PLC (DP master).
G	GSD file	General Station Description file. This is a file which describes the product characteristics for configuration with PROFIBUS DP system.
н	Handheld Terminal (H.T.)	A unit to connect with the SI unit PCI connection, for parameter adjustment, to monitor all input and output signal status, and for Forced input/output selection.
Ι	ID No.	16 bit number which is assigned by PNO to identify the product
I	Idle	Condition when SI unit (PROFIBUS DP) receives FAIL SAFE command. Using parameter setting, output can be set to CLEAR/HOLD/Force ON.
I	Input points	Number of points that which can receive information from input equipment. (Sensor and switch, etc.)
М	Manifold	An assembly with many openings for receiving and distributing fluid or gas.
N	NPN output	Output that switches a load through an NPN transistor. The +ve side of the load is connected to a common +ve. For this reason, NPN output is often referred to as "common positive".
Ν	NPN input	Input that receives data from sensor with an NPN output signal.
0	Open circuit detection	Diagnosis function which detects open circuit, caused by broken or disconnected wiring to the input/output equipment.
0	Output Points	Number of points of output equipment (Solenoid Valve, lamp, motor starter, etc.) which can be operated.

No.	Term	Definition		
Р	PLC	Programmable Logic Controller. A Controller which performs sequential control using programs of logical, order and arithmetic operation, etc.		
Р	PNP output	Output that switches a load through a PNP transistor. The –ve side of the load is connected to the 0V common return. For this reason, PNP output is often referred to as "common negative".		
Р	PNP input	Input that receives data from sensor with PNP output signal.		
	PROFIBUS DP	Fieldbus that Siemens, Bosch, and ABB, etc. jointly developed in Germany		
Р		in 1980's. PNO (PROFIBUS Nutzerorganisation e.V) is started in order to		
		spreads the PROFIBUS.		
Р	Protection Class (IP□□)	International Protection Rating. A Standard related to protection against foreign objects into electrical enclosures. (Hand,wire, dust, and water, etc.)		
S	Short circuit detection	Function that detect if output or power supply positive line is short circuited with GND, thus over current state has occurred.		
S	Short circuit protection	Internal circuit protection to prevent damage by over current caused by power supply positive line being short circuit with GND		
S	SI unit	Serial Interface Unit. A unit for connection with a PLC, to and perform input/output data communication.		
S	SYNC Function	Function that synchronizes output data of SI unit with SYNC command from a PLC (DP master).		
Т	Terminating resistance	When connecting device to the fieldbus, resistance must be installed on both ends of wiring system. This prevents signal reflection, and maintains data integrity.		
U	U Side	The UP side of the manifold, where solenoid valve manifold is connected.		

Assembly

Composing the unit as a manifold.

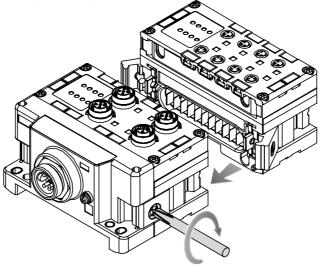
*: If the unit was purchased as a manifold, the work described in this section is not necessary.

Note

Be sure to turn off the power when carrying out the work to compose the unit as a manifold.

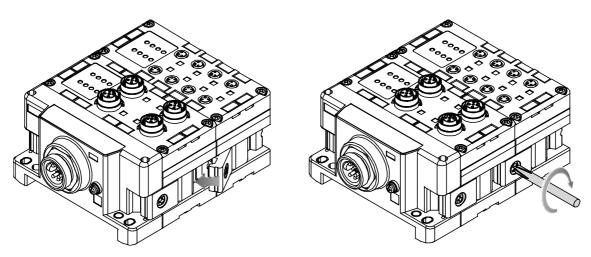
(1) Connect the unit to the end plate

Digital input unit/digital output unit/Analog unit can be connected in any order. Tighten the bracket of the joint using Tightening torque 1.5 to 1.6 N•m.



(2) Add more units

Up to 10 units (including the SI unit) can be connected to one manifold.



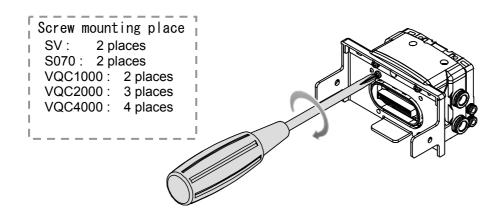
(3)Connecting SI unit

After connecting the necessary units, connect the SI unit. Connecting method is the same as above.



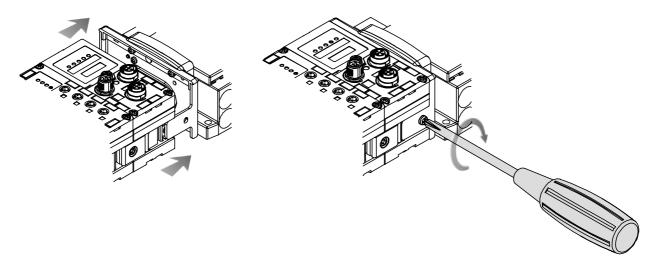
(4) Mounting the valve plate

Mount the valve plate to the manifold solenoid valve using the valve set screws. Apply 0.6 to 0.7N•m tightening torque to the screws.



(5) Connect the SI unit and the manifold solenoid valve.

Insert the valve plate to the valve plate set groove on the side of SI unit. Then, tighten it with the valve plate set screws to fix the plate. Tightening torque for set screws 0.7 to 0.8N•m.



Note:

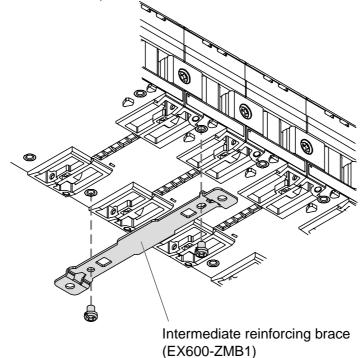
Please do not connect the unit while the power supply is active. It will cause equipment damage.

Mounting and Installation

Installation method

(1) Direct mounting

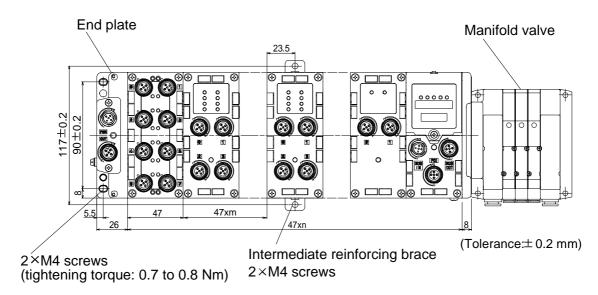
When joining six or more units, fix the middle part of the complete EX600 unit with an intermediate reinforcing brace (EX600-ZMB1) before mounting (Refer to the figure below.) using 2xM4 screws (Tightening torque: 0.7 to 0.8 N•m)



Fix and tighten the end plates at one end of the unit as shown in the figure below.

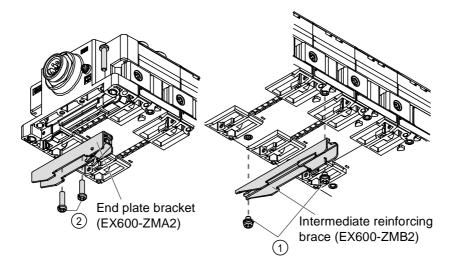
(Tightening torque: 0.7 to 0.8 N•m)

Fix the end plate at the valve side while referring to the operation manual of the corresponding manifold valve.



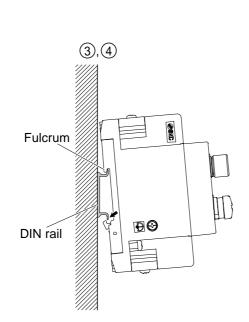
(2) DIN rail mounting

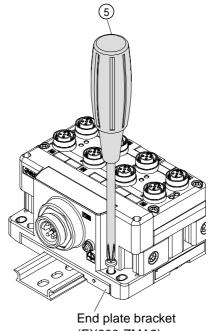
- (i) When joining six or more units, fix the middle part of the complete EX600 unit with an intermediate reinforcing brace (EX600-ZMB2) before mounting, using 2xM4 screws (Tightening torque: 0.7 to 0.8 N•m)
- (ii) Mount the end plate bracket (EX600-ZMA2) to the end plate at the opposite end to the valves, using 2xM4 screws (Tightening torque: 0.7 to 0.8 N•m)



- (iii) Hook the DIN rail mounting groove to the DIN rail. (See the figure below.)
- (iv) Press the manifold using its side hooked to the DIN rail as a fulcrum until the manifold is locked.
- (v) Fix the manifold by tightening the DIN rail fixing screws of the EX600-ZMA2.
 - (Tightening torque: 0.7 to 0.8 Nm)

The tightening torque at the valve side depends on the valve type.



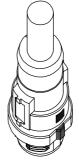


• Wiring

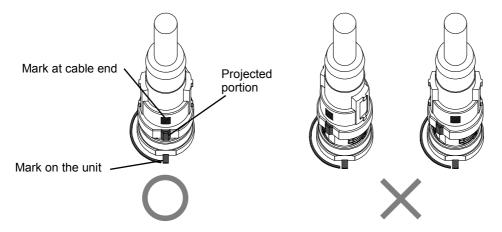
The M12 connector can be mated with a SPEEDCON connector or standard M12 connector.

(1) Set the projected portion of the cable connector metal ring (plug / socket) to the mark.



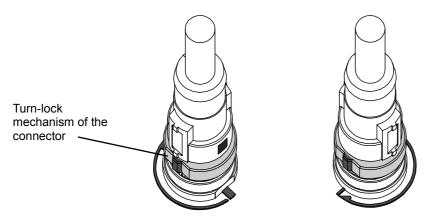


(2) Push the connector straight to insert it into the receptacle of the unit. If inserted without aligning the mark, the connector will not mate with the receptacle.



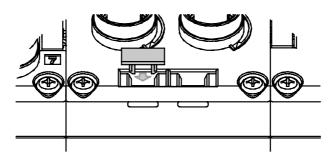
(3) Turn the connector clockwise. It stops when turned 1/4 turn.Turn it further. When the connector is turned 1/2 turn from the original position, the projected portion is set at the diagonal position to the mark and the turn is completed.

Check that the connector is securely locked.

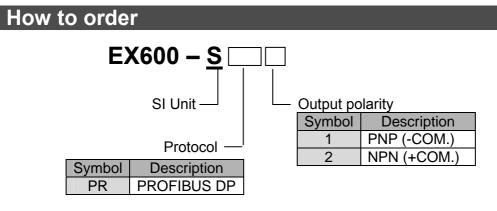


If the connector is turned excessively, it will become difficult to remove.

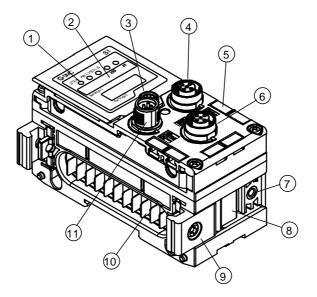
• Mounting the marker Mount the marker (EX600-ZT1) into the marker groove as required.



SI Unit



Name and Function of the Parts



No.	Name	Description
1	Status indication LED	Indicates the unit status
2	Indication cover	Open to gain access to the Setting switches
3	Indication cover set screw	Loosen to open the cover
4	Connector(BUS OUT)	Connector for FieldBus output
5	Marker groove Groove to mount an indication marker	
6	Connector (H.T.)	Connector to connect handheld terminal
7	Valve plate mounting hole Holes for fixing the valve plate	
8	Valve plate mounting groove Groove for mounting the valve plate	
9	Joint bracket Bracket used to secure the adjacent unit	
10	Connector for unit (Plug) Conveys the signals and power supply to the adjacent unit	
11	Connector (BUS IN) Connector for FieldBus input	

-18-

SMC

Display indicator and description



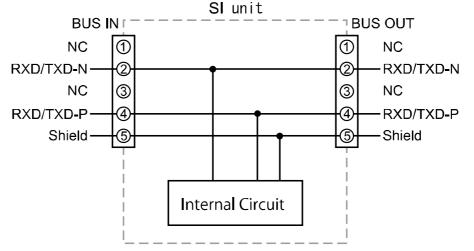
Indicator	Description				
ST(M)	Unit diagnostics status				
PWR	Displays the power supply voltage status of the				
	power supply for control and input				
PWR(V)	Displays the power supply voltage status of the				
FVIC(V)	power supply for output				
SF	System fault				
BF	Bus fault				

Mounting and Installation

Connector Pin Assignment

	Oimedia	Configuration		
Pin No.	Signal name	BUS IN	BUS OUT	
1	NC	2 _ 1	1 7 2	
2	RXD/TXD-N			
3	NC	(50)	(5 0)	
4	RXD/TXD-P			
5	Shield	5 — 4	4 3	

The branch connection is arranged in the EX600-SPR1/2 as illustrated on the circuit below. When connecting other PROFIBUS DP products, connect using the BUS OUT connector, to increase the number of PROFIBUS DP Slave stations.



Note

Be sure to place a seal cap on any unused connectors. Placing the seal cap appropriately enables the unit to achieve IP67 protection.

SMC

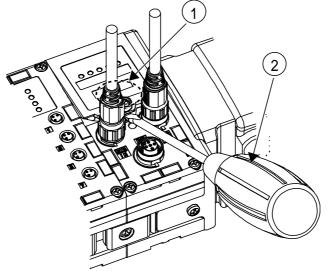
Transmission distance

For communication wiring, PROFIBUS DP compatible shielded twisted pair cable must be used. The longest permissible cable length depends on transmission speed and type of cable used. The table below gives data for when type A cable is used.

Communication speed [kbps]	9.6	19.2	45.45	93.75	187.5	500	1500	3000	6000	12000
Cable length [m]	12	00	10	00	4(00	20	00	1(00

Setting and Adjustment

- Setting procedure
- (1) Loosen the screw of the switch protection cover (indicated with an arrow).
- (2) Open the cover with a flat blade screwdriver.



(3) Perform the switch settings referring to the following pages.

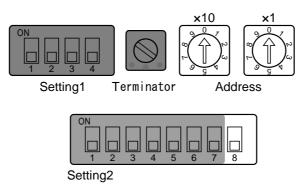
Set the switches with a small point precision screwdriver.

(4) After setting the switches close the switch protection cover and tighten the screw in the reverse order to the above. (Tightening torque: 0.3 to 0.4 Nm)

Note

- When adjusting the switch, make sure not to touch other parts other than the setting switch. Failure can be caused by damaged parts or short circuit.
- Be sure to perform the switch settings with the power turned OFF.
- All switches are set to OFF or 0 when delivered (Factory setting). Perform the switch settings before use.
- When any foreign matter or water droplets are observed near the switch protection cover, wipe them off before opening the cover.

oAddress setting switch

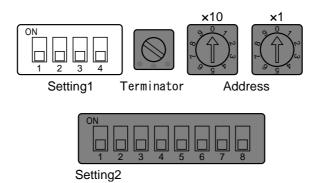


Address Setting switch (x10): To set PROFIBUS DP Node Address Tens digit. Address Setting switch (x1): To set PROFIBUS DP Node Address Units digit. Setting2 (No.8) switch: To set PROFIBUS DP Node Address Hundreds digit.

Address Setting					
Setting2	Addres	ss SW			
No.8	×10	×1	Node Address		
OFF	0	0	0(Factory default)		
	0	1	1		
	0	2	2		
	ł	2	2		
	9	8	98		
	9	9	99		
ON	0	0	100		
	0	1	101		
	2	2	2		
	2	6	126		

Note) If the address is set to 0 or number greater than 126, an error will result and "SF" and "BF" LED's will flash.

Setting1 switch



V_SEL switch: A function to select the number of points occupied by valve outputs. Select the output points (size) occupied by the SI unit.

Setting1		Description	SI unit Output data size		
No.1	No.2	Description	Si unit Output data size		
OFF	OFF	Occupied bit for valve output is 32	4byte(Factory default)		
OFF	ON	Occupied bit for valve output is 24	3byte		
ON	OFF	Occupied bit for valve output is 26 2byte			
ON	ON	Occupied bit for valve output is 8 1byte			

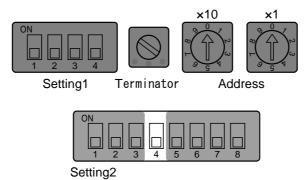
Note) Please set the number of occupied valve points to more than the connected number of valves.

Baud Rate switch: Switches to set the baud rate of internal communication.

Set	ting1	Description		
No3.	No.4	Description		
OFF	OFF	1Mbps(factory setting)		
OFF	ON	500kbps		
ON	OFF	250kbps		
ON	ON	125kbps		

Note) 500, 250 & 125kbps settings are for future extension. Please use 1 Mbps (factory default setting).

Setting2 switch

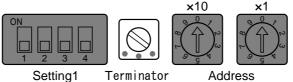


HOLD/CLR Switch : When a fieldbus communication error occurs or the communication idle state, all output can be set to Hold or Clear.

Active/inactive of this switch can be set with Parameter. (Refer to page 60)

Setting2 No.4	Description
OFF	All outputs are cleared "0" when a communication error occurs. (Factory setting)
ON	All outputs are held when a communication error occurs

Terminator switch



Setting1 Terminator



Setting2

Terminator switch: Set the Terminator resistance of the PROFIBUS communication line

Terminator setting		
Terminator resistance fitted	No terminator resistance (Factory default)	No terminator resistance

Note

- When this unit is connected at the end of the PROFIBUS DP line, make sure to set to [Terminator Resistance fitted]
- The size of terminator resistance depends on the specification of the cable used. This terminator resistance value is fitted to suit type A cable.

Error display

SI unit common status

LED status	Descriptions		
ST(M) PWR PWR(V)	Power supply for control and input is OFF.		
ST(M) PWR PWR(V)	Unit is operating normally.		
ST(M) PWR PWR(V)	Component failure inside the SI unit. When ST (M) indicator is red, stop using the product and contact SMC.		
ST(M) PWR PWR(V)	Valve is in short-circuit or open-circuit status. Replace the valve. Valve ON/OFF counter exceeds setting value. (When Open/Short-circuit detection mode is ON)		
ST(N) PWR PWR(V)	Communication error between units. Check the connection between units.		
ST(M) PWR PWR(V)	Error diagnostic detected the error of a unit other than the SI unit.		
ST(M) PWR PWR(V)	Abnormal power voltage for control/input devices. Check the power supply and adjust or replace it.		
ST(M) PWR PWR(V)			
O OF	O OFF Red Light ON Green Light ON Green Light ON		
- Flas	shing Red Flashing Red and Green alternately (1 second frequency)		
- Flas	shing Green		

PROFIBUS DP

LED status	Descriptions		
X(V) SF BF	Normal status with established communication with DP master, or unit power is in OFF status.		
R(V) SF BF	SI unit recognized the communication speed but DP master address setting is wrong. Check the address and correct it.		
X(V) SF BF	 Any one of the following: ♦ No connection between DP master and SI unit. ♦ SI unit cannot recognize the communication speed. ♦ DP master failure or SI unit failure. 		
R(V) SF BF	Communication established between DP master and SI unit, but with diagnostic error.		
R(V) SF BF	Discrepancy between DP master setting and device configuration data. Check the setting and correct it.		
≷(V) SF BF) ● ●	SI unit address set to "0" or above "126". Check the address and correct it.		
0 0	○ OFF ● Red Light ON - Flashing Red		

Red Light ON

- Flashing Red

Specifications

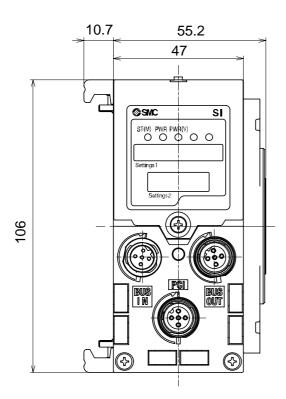
Specifications

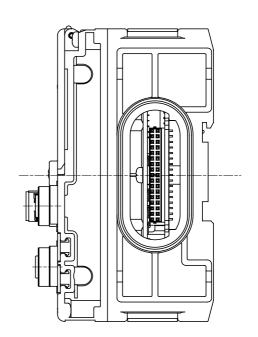
Model		EX600-SPR1	EX600-SPR2
	Fieldbus	PROFIBUS DP (DP-V0)	
ion	Device type	DP slave	
Communication	Communication speed	9.6/19.2/45.45/93.75/ 187.5/500kbps 1.5/3/6/12Mbps	
ပိ	Configuration file	GSD (SMC	A1411.gsd)
	I/O occupation area (Inputs/Outputs)	(512 points/512 points) max	
Term	inal Resistance	Internally implement	ed(For type A cable)
Internal Current Consumption (Power supply for Control and Input)		Less than 80mA	
	Output method	PNP (-COM.)	NPN (+COM.)
nt	Output channel	32 channels (8/16/24/32 channels selectable)	
Valve output	Connected load	Solenoid valve with lamp and circuit of protection of surge voltage of DC24V 1.5W (SMC)	
alve	Supply voltage	DC24V +10/-5%	
>	Output for com. error	HOLD/CLEA	R/ Force ON
	Protective function	Short-circui	it protective
	Enclosure	IP67(manifold assembly)	
	Operating temp. range	-10~	50°C
ntal e	Departing humidity range 35~85% RH (no dew condensation)		ew condensation)
ivironment resistance	Withstand voltage		n external terminals and FE
ron sist	Insulation resistance		een external terminals and FE
Environmental resistance	Vibration resistance	10~57Hz with constant amplitude of 0.75mm p-p 57-150Hz with constant acceleration of 49m/s ² for 2 hours in each direction of X, Y and Z direction (during de-energizing)	
	Impact resistance	147m/s ² 3 times in each direction of X, Y and Z (during de-energizing)	
Stand	dard	CE marking, UL recognition (CSA)	
Weig	ht	300 g	

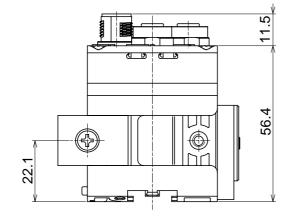
PROFIBUS DP function.

Model number	EX600-SPR1	EX600-SPR2
Address setting range	1~125	
FREEZE Function	Supported	
SYNC Function	Supported	
FAIL SAFE Function	Supported	
ID Number	1411(Hex)	

Outline Dimensions







Digital input unit

How to order

EX600 – <u>DX</u>

Digital input

Input polarity —		
Symbol Description		
Р	PNP	
Ν	NPN	

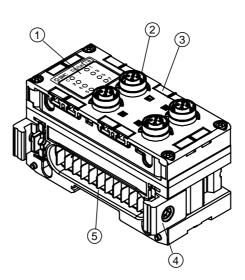
- Connector and input points and open circuit detection

Symbol	Connector	Input points	Open circuit detection
В	4 x M12(5Pin)	8 points	No
С	8 x M8(3Pin)	8 points	No
C1	8 x M8(3Pin)	8 points	Yes
D	8 x M12(5Pin)	16 points	No

Note: Input equipment with 4 pin M12 connector can also be connected to M12 (5pin) connector.

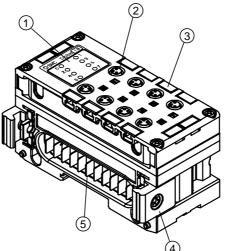
Name and Function of the Parts

EX600-DX*B



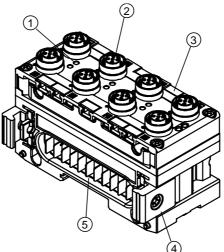
No.	Name	Description	
1	Status indication LED	Indicates the unit status. (Refer to the chapter "Troubleshooting" for the detailed display contents.)	
2	Connector(Input)	Connector for digital inputs. (M12, 5pin, socket : SPEEDCON)	
3	Marker groove	Groove to mount an indication marker.	
4	Joint bracket	Joint bracket to join the adjacent unit, fixed with attached screws.	
5	Connector for unit (plug)	Conveys the signals and power supplies to the adjacent unit.	

EX600-DX*C*



		4
No.	Name	Description
1	Status indication LED	Indicates the unit status. (Refer to the chapter "Troubleshooting" for the detailed display contents.)
2	Connector(Input)	Connector for digital inputs. (M8, 3pin, socket)
3	Marker groove	Groove to mount an indication marker.
4	Joint bracket	Joint bracket to join the adjacent unit, fixed with attached screws.
5	Connector for unit (plug)	Conveys the signals and power supplies to the adjacent unit.

EX600-DX*D



No.	Name	Description
1	Status indication LED	Indicates the unit status. (Refer to the chapter "Troubleshooting" for the detailed display contents.)
2	Connector(Input)	Connector for digital inputs. (M12, 5pin, socket : SPEEDCON)
3	Marker groove	Groove to mount an indication marker.
4	Joint bracket	Joint bracket to join the adjacent unit, fixed with attached screws.
5	Connector for unit (plug)	Conveys the signals and power supplies to the adjacent unit.

Mounting and Installation

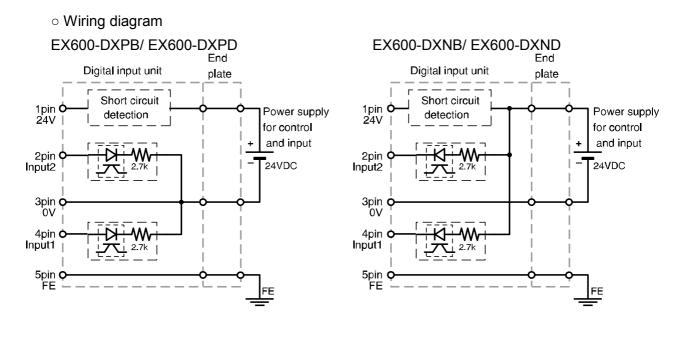
Pin assignment and wiring diagram

(1) EX600-DX*B/EX600-DX*D

oConnector's Pin assignment

	<u> </u>	
Pin No.	Signal name	Configuration
1	24V(for control / input)	1 < 2
2	Input2	
3	0V(for control / input)	(5 0)
4	Input1	
5	FE	4 3

Note: Input equipment with M12 (4 pin)connector can also be connected to M12 (5pin) connector.



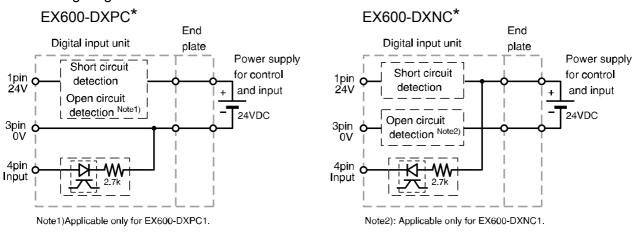
Note

Be sure to place a seal cap on any unused connectors. Using the appropriate seal cap enables the unit to achieve IP67 protection.

(2) EX600-DX*C*

 Connector's pin assignment 		
Pin No.	Signal name	Configuration
1	24V(for control / input)	
3	0V(for control / input)	
4	Input1	4

• Wiring diagram



Note

Be sure to place a seal cap on any unused connectors. Using the appropriate seal cap enables the unit to achieve IP67 protection.

Handling care.

Please note the following points when using Open Circuit Detection function.

- Open Circuit Detection setting can only be carried out using a Handheld Terminal. Setting can not be carried out using a PLC.
- When 2-wire sensor is used, sensor which has current leakage during OFF status is less than 0.5mA (contact sensor, etc.) will not be detected. Please use sensor which has current leakage of 0.5mA or more during OFF status.
- When 3-wire sensor is used, sensor that has current consumption of less than 0.5mA will not be detected, and also open circuit (wire breakage) at input signal line will not be detected

Error display

Status indication LED displays power supply status and communication status. These can be checked according to the following:-

LED status	Descriptions
O OFF	Power supply for control and input is OFF, or input device is OFF.
Green Light ON	Input device is ON.
Flashing Red	Either of the following: (1) Input device ON/OFF count has exceeded the set value. (2) Input device not connected (for open circuit detection type only).
All LED Flashing Red and Green alternately	Component failure inside the digital input unit. Stop using the product and contact SMC.
0 • 1 Red Light ON (Both adjacent LED's are ON)	without Open Circuit Detection> Short circuit in power line of either input device "0" or "1". Check which input device has caused the short circuit.
0 • 1 Red Light ON (Either one of adjacent LED's is ON)	<pre><with circuit="" detection="" open=""> Short circuit in power line of input device indicated.</with></pre>

Specifications

Specifications

• 3	pecificatio	ns										
	Model				EX600-DXPC							
	Input type		PNP	NPN	PNP	NPN	PNP	NPN				
	Input conn	ector	M12(5Pin)s		M8(3Pir			socket Note1				
	Input channels		8channels (2channels/Connector)		8chai (1 channels)		16channels (2channels/Connector)					
	Sensor voltage	supplied	24VDC(Supplied from the power supply for control and inputs)									
	Maximum sensor supplied voltage		r 0.5A/Connector 2A/unit		0.25A/Co 2A/		0.5A/Connector 2A/unit					
ion	Protection		Short circuit protection									
cat	Input resist	tance	2.7 kΩ									
cifi	Rated inpu	t current			9 mA o	or less						
Input Specifications	ON voltage /ON curren		17 V or more/ 5 mA or more (At NPN input, between the pin for input terminal and for sensor supplied voltage of +24 V) (At PNP input, between the pin for input terminal and for sensor supplied voltage of 0 V)									
	OFF voltage/OFF current		5 V or less/ 1 mA or less (At NPN input, between the pin for input terminal and for sensor supplied voltage of +24 V) (At PNP input, between the pin for input terminal and for sensor supplied voltage of 0 V)									
	Open	Open 2 wires		-	0.5mA/P	oint ^{Note2}	—					
	circuit detection current _{Note2}	3 wires	_	-	0.5mA/Con		_					
Cur	rent consur	nption	50mA (or less	55mA	or less	70mA or less					
	icator		Green LED on (Input is ON) Red LED on (when short circuit detected at sensor's power supply) Red LED flashing (ON/OFF counter exceeded/ open circuit detected ^{Note2})									
	Enclosure		IP67(manifold assembly)									
ance	Operating temp. range		-10~50°C									
esiste	Operating hur range	midity	35~85%RH (no dew condensation)									
	Withstand	voltage	AC500V for 1 min. between external terminals and FE									
lenta	Insulation re	sistance	DC500V, 10M Ω or more between external terminals and FE									
Environmental resistance	Vibration resistance		10~57Hz with constant amplitude of 0.75mm p-p 57-150Hz with constant acceleration of 49m/s ² for 2 hours in each direction of X, Y and Z direction (during de-energizing)									
	Impact resi	istance	147m/s ² 3 times in each direction of X, Y and Z (during de-energizing)									
Sta	ndard		CE marking, UL recognition (CSA)									
	ight		30		27			10g				
	<u> </u>	connector	can be connected	0		- 3	. v	- 3				

Note 1 : M12(4 pin)connector can be connected.

Note 2 : Applicable only for unit with Open circuit detection function.

Digital Input data The table shows the relation between the connector position and the input data allocation.

connector position			00	00	00				
connector №		0	1	2	3				
input	Pin 2	Bit 1	Bit 3	Bit 5	Bit 7				
signal	Pin 4	Bit 0	Bit 2	Bit 4	Bit 6				

• Table for input signal (EX600-DX*B)

• Table for input signal (EX600-DX*D)

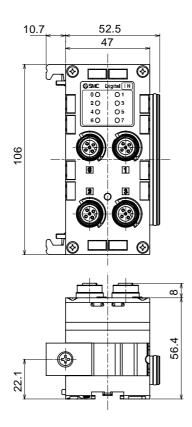
connector position		00000 0000							
connector №		0	1	2	3	4	5	6	7
input	Pin 2	Bit 1	Bit 3	Bit 5	Bit 7	Bit 9	Bit 11	Bit 13	Bit 15
signal	Pin 4	Bit 0	Bit 2	Bit 4	Bit 6	Bit 8	Bit 10	Bit 12	Bit 14

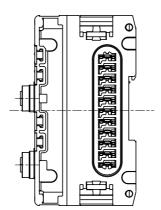
• Table for input signal (EX600-DX*C*)

				/	-				
connector position		0000	0000	0000	0000	0000	0000	0000	0000
connector №		0	1	2	3	4	5	6	7
input signal	Pin 4	Bit 0	Bit 1	Bit 2	Bit 3	Bit 4	Bit 5	Bit 6	Bit 7

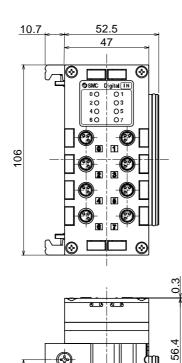
Outline Dimensions

EX600-DX*B



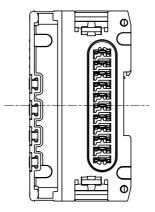


EX600-DX*C*



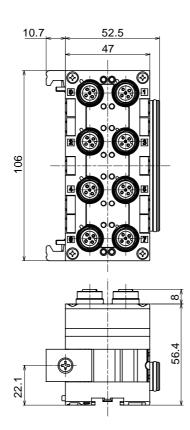
d

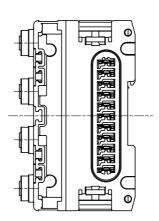
22.1



-35-**SMC**

EX600-DX*D







Digital Output unit

How to order

EX600 – <u>DY</u> 🖵 🖵

Digital Output -

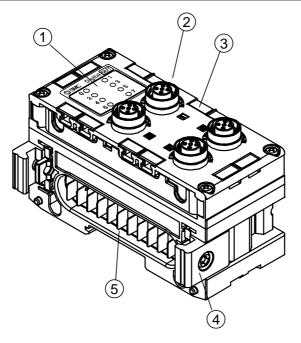
(Output specification		
	Symbol Description		
	Р	PNP	
	Ν	NPN	

- Connector and number of channel

Symbol	Connector	Output channels
В	4 x M12(5Pin)	8 channels

Note : output equipment with 4 pin M12 connector can also be connected to M12 (5pin) connector。

Name and Function of the Parts



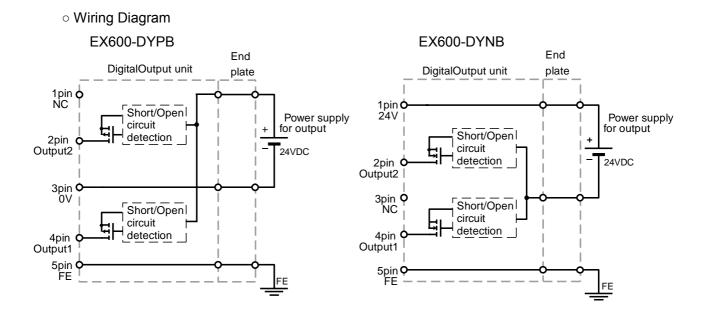
No.	Name	Description	
1	Status indication LED	Indicates the unit status. (Refer to the chapter "Troubleshooting" for the detailed display contents.)	
2	Connector(Input)	Connector for digital outputs. (M12, 5pin, socket : SPEEDCON)	
3	Marker groove	Groove to mount an indication marker.	
4	Joint bracket	Joint bracket to join the adjacent unit, fixed with attached screws.	
5	Connector for unit (plug)	Conveys the signals and power supplies to the adjacent unit.	

Mounting and Installation

Connector's pin assignment and wiring diagram
 Connector's pin assignment

Din No	Signal	Configuration			
Pin No.	EX600-DYPB EX600-DYNB				
1	NC	24V(For Output)	$1 \land \land 2$		
2	Output2	Output2			
3	0V(for Output)	NC	(5 0)		
4	Output1	Output1	\bigvee \bigvee		
5	FE	FE	4) 3		

Note : output equipment with 4 pin M12 connector can also be connected to M12 (5pin) connector



Note

Be sure to place a seal cap on any unused connectors. Using the appropriate seal cap enables the unit to achieve IP67 protection.

Handling care.

Please note the following points when using Open Circuit Detection function.

- Open Circuit Detection setting can only be carried out using a Handheld Terminal. Setting can not be carried out at the PLC.
- This function detects open circuit only when the output is OFF. Therefore if output is turned ON, open circuit can not be detected

Error display

Status indication LED (see figure to the right) displays power supply status and communication status. These can be checked according to the following:-

LED status	Descriptions
O OFF	Power supply for control and input is OFF, or output device is OFF.
Green Light ON	Output device is ON.
Red Light ON	Output is short circuited.
	Either of the following: Output device contact operations count has exceeded the set value. Output device is not connected.
All LED Flashing Red and Green alternately	Component failure inside the digital output unit. Stop using the product and contact SMC.

Specifications

Specifications

cincations			
el	EX600-DYPB	EX600-DYNB	
Output style	PNP	NPN	
Output connector	M12(5Pin),9	Socket Note1	
Output channel	8 channels (2 channels/connector)		
Rated load voltage	24VDC(Supplied from Power supply for output)		
Max. load current	0.5A/1 channel 2A/unit		
Protection	Short circuit protection		
ent consumption	50mA	or less	
lay	Green LED on (during output is ON) Red LED flashing (ON/OFF counter is		
Enclosure	IP67(manifold assembly)		
Operating temp. range	-10~50°C		
Operating humidity range	35~85%RH (no dew condensation)		
Withstand voltage	AC500V for 1 min. betweer	n external terminals and FE	
Insulation resistance	DC500V, 10MΩ or more betwe	en external terminals and FE	
Vibration resistance	10~57Hz with constant amplitude of 0.75mm p-p 57-150Hz with constant acceleration of 49m/s ² for 2 hours in each direction of X, Y and Z direction (during de-energiz		
Impact resistance	147m/s ² 3 times in each direction of X, Y and Z (during de-energizing		
dard	CE marking, UL recognition (CSA)		
ght	30	0g	
	el Output style Output connector Output channel Rated load voltage Max. load current Protection ent consumption lay Enclosure Operating temp. range Operating humidity range Withstand voltage Insulation resistance Vibration resistance Impact resistance dard	elEX600-DYPBOutput stylePNPOutput connectorM12(5Pin),Output channel8 channels (2 chaRated load voltage24VDC(Supplied from FMax. load current0.5A/1 channProtectionShort circuient consumption50mAlayGreen LED on (during output is ON)Red LED flashing (ON/OFF counter isEnclosureIP67(manifolOperating temp. range-10~Operating humidity range35~85%RH (no deWithstand voltageAC500V for 1 min. betweerInsulation resistanceDC500V, 10MΩ or more betweenVibration resistance10~57Hz with constant a 57-150Hz with constant a for 2 hours in each direction of X, Y aImpact resistance147m/s² 3 times in each direction of CE marking, UL r	

Note1 : M12 (4 pin) connector can also be connected.

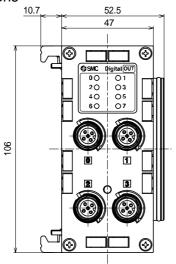
•Digital Output data

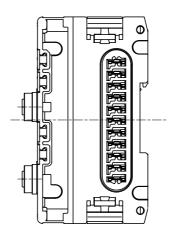
The table shows the relation between the connector position and the output data allocation.

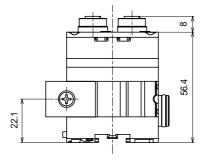
connecto position	r	000		0 0 0	
connecto	r Nº	0	1	2	3
output	Pin 2	Bit 1	Bit 3	Bit 5	Bit 7
signal	Pin 4	Bit 0	Bit 2	Bit 4	Bit 6

•Table for output signal (EX600-DY*B)

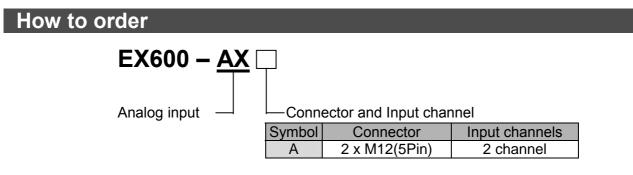
Outline Dimensions



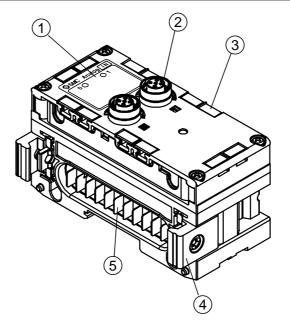




Analog Input Unit



Name and Function of the Parts



No.	Name	Description	
1	Status indication LED	Indicates the unit status. (Refer to the chapter "Troubleshooting" for the detailed display contents.)	
2	Connector(Input)	Connector for digital inputs. (M12, 5pin, socket : SPEEDCON)	
3	Marker groove	Groove to mount an indication marker.	
4	Joint bracket	Joint bracket to join the adjacent unit, fixed with attached screws.	
5	Connector for unit (plug)	Conveys the signals and power supplies to the adjacent unit.	

-42-

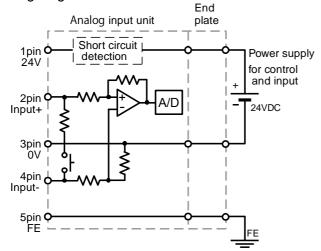
Mounting and Installation

•Pin Assignment and wiring diagram

Pin assignment

Pin No	Signal name	Configuration	
1	24V(For Control/Input)	1002	
2	Input+		
3	0V(For Control/input)	(5 0)	
4	Input-		
5	FE	4 - 3	

• Wiring diagram



Input impedance Voltage input type: 100kΩ Current input type: 50Ω

Note

Be sure to place a seal cap on any unused connectors. Using the appropriate seal cap enables the unit to achieve IP67 protection.

Handling care

Please note the following points when wiring the Analogue input unit and sensor.

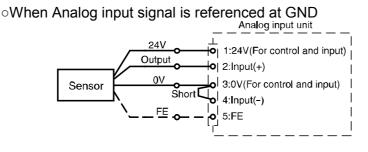
The EX600 Analogue Input operates using a differential input specification, therefore pin No.4 (input -) becomes the reference and pin No.2 (input +) carries the signal data.

This means that, if pin No.4 is not connected, the signal input cannot be correctly input.

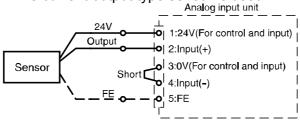
Therefore externally connect pin No.3 and pin No.4 together when a differential output sensor is not used.



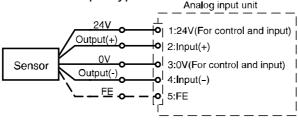
·Sensor and wiring example is shown below



oWhen 2-wire current output type sensor is used.



oWhen differential output type sensor is used



Error display

Status indication LED displays power supply status and communication status. These can be checked according to the following:-

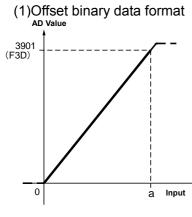
LED status	Descriptions
O OFF	Power supply for control and input is OFF.
Green Light ON	Operating normally.
Red Light ON	Power supply for input devices is short circuited.
Flashing Red	Upper or lower limit is detected for the following items: (1) Range (2)Measurement value(User setting)
All LED Flashing Red and Green alternately	Component failure inside the analog input unit. Stop using the product and contact SMC.

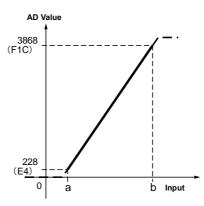
Specifications

Specifications

 Specifications 				
Model		EX600-AXA		
Input type		Voltage input	Current input	
Input connec	tor	M12(5Pin), Socket		
Input channe	ls	2channel(1channel/Connector)		
Sensor suppl	ied voltage	DC24V (Supplied from power	r supply for control and input)	
	nsor supplied	0.5A/channel		
Protection		Short circui	t protection	
voltage Protection Input signal range	12bit Resolution	0 ~ 10V 1 ~ 5V 0 ~ 5V	0 ~ 20mA 4 ~ 20mA	
orrange	16bit Resolution	-10V ~ 10V (factory default setting) -5V~5V	-20mA ~ 20mA	
Max. input s	signal	±15V	±40mA	
Input imped	ance	100kΩ	50Ω	
Linearity		±0.05%F.S or less		
Repeatabilit	у	±0.15%F.S. or less		
Absolute ac	curacy	±0.5%F.S. or less	±0.6%F.S. or less	
Current consump	otion	70mA		
Display		Green LED on (when input is ON) Red LED on (Short circuit at sensor power supply) Red LED flashing (analog input exceeds measurement range or user setting range)		
Enclosure		IP67(manifold assembly)		
Operating temp	o. range	-10~50°C		
🕡 Operating humic	lity range	35~85%RH (no dew condensation)		
G Withstand vo	<u> </u>	AC500V for 1 min. between external terminals and FE		
E B Insulation resis	tance	DC500V, 10M Ω or more between external terminals and FE		
Withstand vo Unsulation resister Vibration resister	stance	10~57Hz with constant amplitude of 0.75mm p-p 57-150Hz with constant acceleration of 49m/s ² for 2 hours in each direction of X, Y and Z direction (during de-energizing)		
Impact resist	ance	147m/s ² 3 times in each direction of X, Y and Z (during de-energizing)		
Standard		CE marking, UL recognition (CSA)		
Weight 290g			0g	

Analog characteristics





Input signal range	а
0 ~ 10V	10V
0 ~ 5V	5V
0 ~ 20mA	20mA

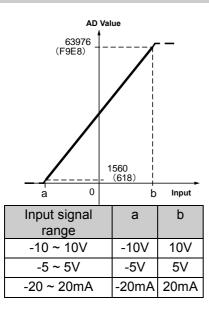
Input signal range	а	b
1 ~ 5V	1V	5V
4 ~ 20mA	4mA	20mA

Regarding AD value

In the above graph, 2 AD values are explained as below. 3901: AD value [decimal value] (F3D): Offset Binary type [hexadecimal value]

Data	Form	at													
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
0	0	0	0	MSB		AD value								l	LSB

AD va	alue	0 ~ 10V	1 ~ 5V	0~5V	0 ~ 20mA	4 ~ 20mA
Hexadecimal	Decimal		Voltage [V]		Curre	nt[mA]
0FFF	4095	10.5	5.25	5.25	21	21
0F3D	3901	10	-	5	20	-
0F1C	3868	-	5	-	-	20
0800	2048	5.25	3	2.625	10.5	12
00E4	228	-	1	-	-	4
0000	0	0	0.75	0	0	3

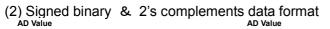


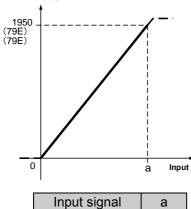
Data format

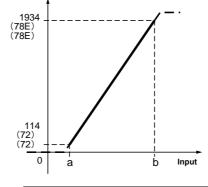
Data lonnat															
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
MSB AD value										LSB					

AD v	alue	-10V ~ 10V	-5 ~ 5V	-20mA ~ 20mA
Hexadecimal	Decimal	Volta	ge [V]	Current [mA]
FFFF	65535	10.5	5.25	21
F9E8	63976	10	5	20
BCF4	48372	5	2.5	10
8000	32768	0	0	0
430C	17164	-5	-2.5	-10
0618	1560	-10	-5	-20
0000	0	-10.5	-5.25	-21









Input signal	а	Input
range		rar
0 ~ 10V	10V	1 ~
0 ~ 5V	5V	4 ~ 2
0 ~ 20mA	20mA	

o a	D	Input
Input signal	а	b
range		
1 ~ 5V	1V	5V
4 ~ 20mA	4mA	20mA

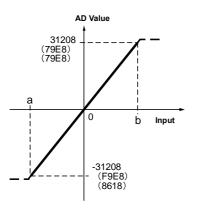
Regarding AD value

In the above graph, 2 AD values are explained as below. -31208: AD value [decimal value] (F9E8): Sign & Magnitude [Hexadecimal value] (8618): 2's complements [Hexadecimal value]

Data format

Data															
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
0	0	0	0	0	MSB	-			AD	value					LSB

AD va	alue	0 ~ 10V	1V ~ 5V	0 ~ 5V	0 ~ 20mA	4 ~ 20mA			
Hexadecimal	Decimal		Voltage [V]		Currer	Current [mA]			
07FF	2047	10.5	5.25	5.25	21	21			
079E	1950	10	-	5	20	-			
078E	1934	-	5	-	-	20			
0400	1024	5.25	3	2.625	10.5	12			
0072	114	-	1	-	-	4			
0000	0	0	0.75	0	0	3			



Input signal range	а	b
-10 ~ 10V	-10V	10V
-5 ~ 5V	-5V	5V
-20 ~ 20mA	-20mA	20mA

Data format

15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Sign	MSB	•					AD	value	;						LSB

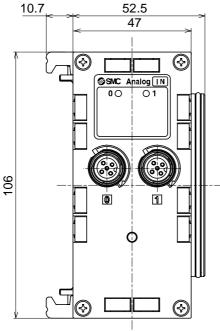
Signed Binary

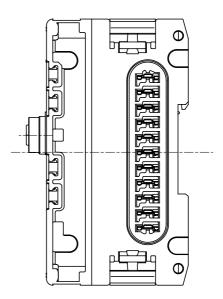
AD \	/alue	-10V ~ 10V	-5V ~ 5V	-20mA ~ 20mA
Hexadecimal	Decimal	Voltag	ge [V]	Current [mA]
7FFF	32767	10.5*	5.25	21
79E8	31208	10	5	20
3CF4	15604	5	2.5	10
0000	0	0	0	0
BCF4	-15604	-5	-2.5	-10
F9E8	-31208	-10	-5	-20
FFFF	-32767	-10.5	-5.25	-21

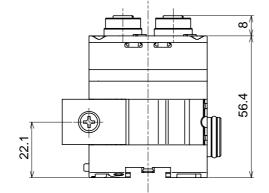
2's complements

AD value		-10V ~ 10V	-5V ~ 5V	-20mA ~ 20mA
Hexadecimal	Decimal	Volta	ge [V]	Current [mA]
7FFF	32767	10.5	5.25	21
79E8	31208	10	5	20
3CF4	15604	5	2.5	10
0000	0	0	0	0
C30C	-15604	-5	-2.5	-10
8618	-31208	-10	-5	-20
8000	-32767	-10.5	-5.25	-21

Outline Dimensions



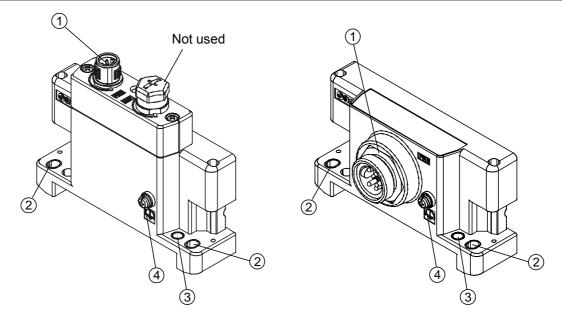




End plate

How to	o orde	r			
	E	X600 – ED 🗌] — [
End plate at D side				iting method	
				Symbol	Mounting method
		Connector —		None	No DIN rail mounting plate
1	Cumphal			2	With DIN rail mounting plate
	Symbol	Connector			• • • • • • • • • • • • • • • • • • •
	2	M12(5Pin)			
	3	7/8inch Connector			

Name and Function of the Parts



No.	Name	Description
1	Power connector	Connector for power input
2	Fixing hole for direct mounting	Holes used for direct mounting
3	DIN rail fixing hole	Holes used to fix DIN rail
4	FE terminal	FE terminal to earth.

Mounting and Installation

Connector's pin assignment

(1) EX600-ED2

/		
Pin No.	Signal name	Configuration
1	24V(for Output)	2 - 1
2	0V(for Output)	
3	24V(for control / input)	(50)
4	0V(for control / input)	
5	FE	3 🗨 4

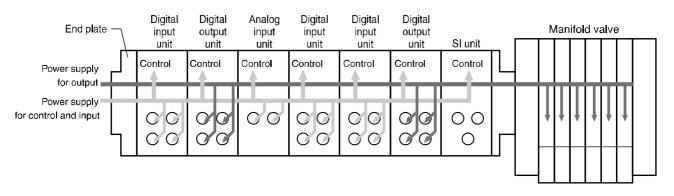
(2) EX600-ED3

Pin No.	Signal name	Configuration
1	0V(for Output)	
2	0V(for control / input)	
3	FE	
4	24V(for control / input)	
5	24V(for Output)	

Regarding the 2 types of power supply

This product has 2 power supplies, and it is divided as follows.

- Power supply for control and input: supplying power for control of each unit's power supply for control and also for equipment connected to Digital input unit and Analog input unit.
- Power supply for output: supplying power for equipment connected to digital output unit, and also power supply for solenoid valve manifold.

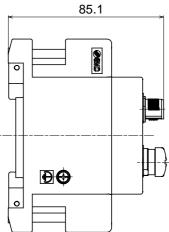


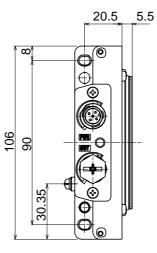
Specifications

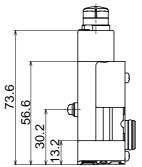
Specifications

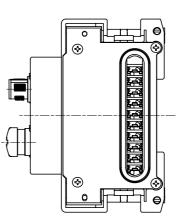
Mod	el	EX600-ED2	EX600-ED3		
	Power connector	M12(5Pin) Plug	7/8inch(5Pin) Plug		
Input	Control, input power supply	24VDC±10% Maximum 2 A	24VDC±10% Maximum 8 A		
	Output power supply	24VDC +10%/-5% Maximum 2 A	24VDC +10%/-5% Maximum 8 A		
	Enclosure	IP67(manifold assembly)			
	Operating temp. range	-10~50°C			
Ital	Operating humidity range	35~85%RH (no dew condensation)			
ner	Withstand voltage	AC500V for 1 min. between external terminals and FE			
onr	Insulation resistance	DC500V, 10M Ω or more between external terminals and FE			
Environmental	Vibration resistance 10~57Hz with constant amplitude of 0.75mm p-p 57-150Hz with constant acceleration of 49m/s ² for 2 hours in each direction of X, Y and Z direction (durin de-energizing)				
	Impact resistance	147m/s ² 3 times in each direction of X, Y and Z (during de-energizing)			
Star	ndard	CE marking, UL recognition (CSA)			
Wei	ght	170g	175g		

- Outline Dimensions
- (1) EX600-ED2

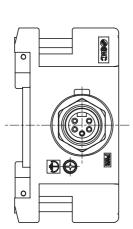


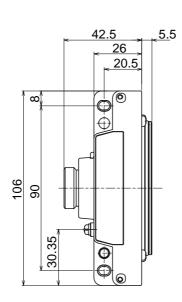


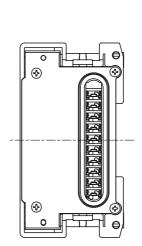


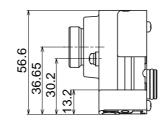


(2) EX600-ED3











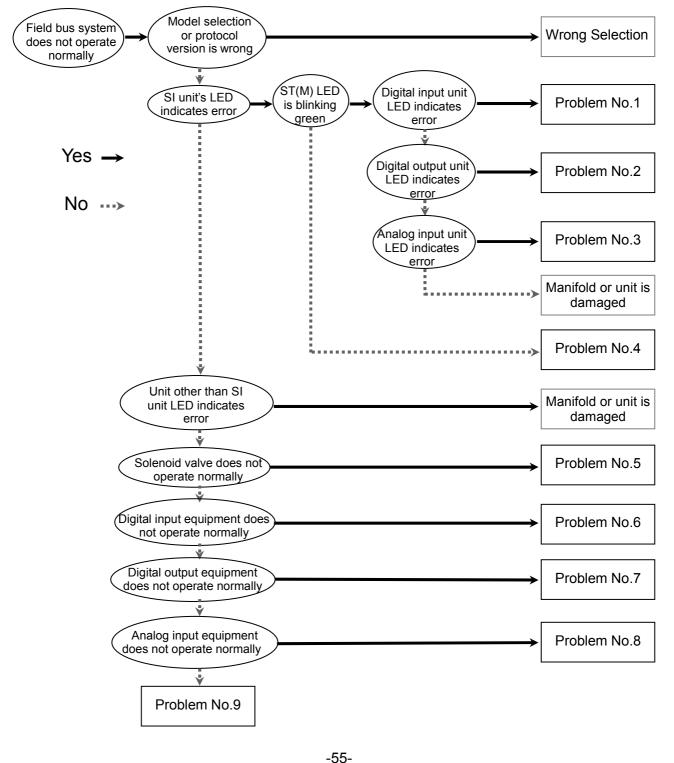
Troubleshooting

Please refer to the following troubleshooting flowchart if errors occur on the fieldbus system.

Error status is also reflected by the parameter settings of fieldbus system.

When trouble occurs, please give appropriate counter measure after referring to the troubleshooting and the parameter setting.

If cause of the problem cannot be confirmed, it is possible that the equipment may have failed. When failure of fieldbus system equipment occurs, it is also possible that the error caused by the system requirements. If that is the case, please consider the counter-measures accordingly



∂SMC

Trouble counter measure method

Problem No.	LED indication	Problem	Investigation Method	Counter-measure
	Flashing Red (Diagnostic is active)	Cause can be either: 1) Sensor's ON/OFF counter exceeds setting value 2) Open circuit is detected on input sensor or cable. (for Open Circuit Detection type only)	Confirm cause 1) or 2) by PLC or H.T. Refer to details of system diagnosis data.	 Reset the counter, change the setting or disable the diagnostic through parameter setting. Confirm if there are loose connector and wire breakage. Moreover, please confirm if applicable sensor is used.
1	Red (Diagnostic is active)	Diagnosis error (Sensor power supply is short circuited)	[No open circuit detection] Either of two adjacent sensor connections is short circuited (2x LED's will be ON). [With open circuit detection] The sensor connection is short circuited (LED is ON).	Check the wiring of the sensor connection which has the short circuit, or confirm whether the cable and the sensor are operating correctly.
	All LED flashing Green and Red	Unit has failed	-	Stop operation and contact SMC sales office
	Flashing Red (Diagnostic is active)	Cause can be either: 1) Output device ON/OFF counter exceeds setting value 2) Open circuit is detected on output device or cable.	Confirm cause 1) or 2) by PLC or H.T. Refer to details of system diagnosis data.	 Reset the counter, change the setting or disable the diagnostics through parameter setting. Confirm if there are loose connections or broken wires.
2	Red (Diagnostic is active)	Diagnosis error (output equipment is short circuited)	The output connection is short circuited (LED is ON).	Check the wiring, or confirm whether the output equipment is operating correctly
	All LED flashing Green and Red	Unit has failed		Stop operation and contact SMC sales office
3	Flashing Red (Diagnosis is active)	Diagnosis error (Upper/lower range limit exceeded)	 Confirm if the sensor output exceeds the upper/lower measurement limits. Confirm whether sensor output exceeds user setting upper/lower range. 	 Please adjust sensor output so that it is inside the measurement range, or adjust setting range or turn off over/under range detection. Please adjust sensor output so that it is Inside the user setting value, or adjust user setting value or turn off user set value upper/lower limit detection.
	Red (Diagnostic is active)	Diagnosis error (Short circuit is detected on the sensor power supply).	Confirm if short circuit occurs at the sensor or cable	Confirm if sensor and cable are operating correctly.
	All LED Flashing green and red	Unit has failed	-	Please stop operation and please contact our sales office

Problem No.	LED indication	Problem	Investigation Method	Counter-measure
110.	ST(M): Off	Power supply for control/input is OFF	Confirm if power supply for control/input is connected.	Re-connect power supply for control/input
	ST(M): Red	SI unit has failed	-	Stop operation and contact SMC sales office.
	ST(M): Flashing red (Diagnosis is active)	Diagnosis error (SI unit) 1) Valve short circuited 2) Broken wire at valve 3) Valve ON/OFF counter exceeds setting value.	Confirm through PLC or handheld terminal. For details, please refer to the System Diagnosis information.	For 1) and 2): valve is broken. Please replace valve and confirm operation. 3) Reset counter value, change setting value or disable the diagnostic through parameter setting.
	ST(M): Flashing green and red	Communication error between SI unit and I/O unit	Confirm if the connection between units is not loose.	f the error does not recover, stop operation and contact SMC sales office
	PWR: Red (Diagnostic is active)	The power supply voltage level for control and input is not normal	Confirm the power supply voltage level.	Supply DC24V±10% to the power supply for control and input.
4	PWR(V): Red (Diagnostic is active)	The power supply voltage level for output is not normal	Confirm the used power supply voltage level.	Supply DC24V+10/-5% to the power supply for output.
	SF: Off BF: Flashing Red	Address Setting fault	Confirm if SI Unit address is consistent with address at DP master.	Set the correct address.
	SF: Off BF: Red	PROFIBUS DP communication fault	 Confirm if communication speed and wiring length are compatible. Confirm if terminating resistance is connected appropriately at both ends of network. Confirm if communication wiring is close to any noise source. 	Wire based on the PROFIBUS specification. Moreover, separate wire for the communication line and the noise source.
	SF: Red BF: Off (Diagnosis is active)	Diagnosis Error (Between PLC and Unit)	Confirm each unit's LED display.	Perform counter measure according to each unit LED display.
	SF: Red BF: Flashing Red	Configuration is inconsistent	Confirm PLC Configuration setting.	Match the PLC configuration setting with the actual unit configuration.
	SF: Red BF: Red	Address setting fault	Confirm if SI Unit address is "0" or above "126".	Set SI Unit address to be between 1 and 125.

Problem No.	LED indication	Problem	Investigation Method	Counter-measure
		Valve output setting for occupied points is less than the number of connected valves	Confirm the V_SEL switch setting in the SI unit is set to more than the actual connected valves.	Set the SI unit switch settings to an occupation points count greater than the number of valves used.
		Program does not operate normally.	Confirm if ladder program at PLC Is correct	Same as left
		Power supply for output is defective		Supply DC24V +10/-5% to the power supply for output from the end plate unit
5	Solenoid valve does not operate normally	Connection between SI Unit and solenoid valve manifold is defective	Confirm the connection between the SI Unit and solenoid valve manifold (Connector pin not bent, etc.)	Connect the SI Unit to the solenoid valve Manifold correctly
	normany	SI Unit output type is not compatible with the solenoid valves	Confirm that the SI Unit and solenoid valves are compatible: EX600-SPR1 (PNP Output) - Negative common type valve EX600-SPR2 (NPN Output) - Positive common type valve	Replace the SI Unit or the solenoid valve so that the correct combination is used
		Defective SI Unit	Replace the SI Unit and confirm the operation	Replace the SI Unit.
		Defective solenoid valve	Replace the solenoid valve and confirm the operation	If the problem continues, refer to the solenoid valve operation manual.
		Input type is not compatible	Confirm if input unit specification (PNP or NPN) and connected input equipment specification are compatible	Replace input unit or input equipment so that it become the correct combination
0	Digital input equipment does not operate normally	Power supply for control and input is defective	Check the status of power supply for control and input	Supply DC24V ±10% to the power supply for control and input from the end plate
		Wiring or connection is defective	Confirm connection and wiring between input equipment and digital input unit.	Make corrections to the wiring between input equipment and digital input unit and continue operation
		Digital input unit is defective	Confirm the digital input unit	Replace the digital input unit
		Defective input equipment	Replace the input equipment and confirm the operation.	If the problem continues, refer to the input equipment operation manual.

Problem No.	LED indication	Problem	Investigation Method	Counter-measure
		Output type is not compatible	Confirm if output unit specification (PNP or NPN) and connected load specification are compatible.	Replace the output unit or load to give the correct combination
		Program does not operate normally	Confirm if the ladder program at the PLC Is correct	Correct the ladder program at the PLC
7	Digital output equipment does	Power supply for output is defective	Check the status of the power supply for output	Supply DC24V +10/-5% to the power supply for output from the end plate
	not operate normally	Wiring and connection is defective	Confirm connection between the output equipment and digital output unit.	Make corrections to the wiring between the output equipment and digital output unit and continue operation
		Digital output unit is defective	Confirm the digital output unit.	Replace the digital output unit.
		Output equipment is defective	Replace the output equipment and confirm the operation.	If the problem continues, refer to the output equipment operation manual.
	Analog input sensor does not operate normally	Power supply for control and input is defective	Check the status of the power supply for control and input	Supply DC24V±10% to the power supply for control and input from the end plate
		Input signal range setting is not compatible	Confirm the connected sensor specification	Set the input signal range to suit the sensor specification.
0		Analog data format is not compatible	Confirm the data format setting of the Analog input unit.	Set the data format of the Analog input unit to suit the application/program.
8		Wiring and connection is defective	Confirm the connection between the input sensor and Analog input unit	Correct the wiring between the input sensor and Analog input unit
		Analog Input Unit is defective	Check the Analog input unit and confirm the operation	Replace the Analog input unit and confirm the operation
		Defective sensor	Replace the sensor and confirm the operation.	If the problem continues, refer to the sensor operation manual.
9	Other peripheral units do not operate normally	Defective peripheral units	Confirm that the program at PLC is correct.	For further details, refer to the relevant manuals of each peripheral unit.

Parameter Setting

The EX600 has parameters settings for the system, unit and also each unit's channel, which can be set through PLC or Handheld Terminal.

There are no priorities in setting the parameter. The most recent setting will be reflected on the unit.

Caution

The following notes apply to Parameter setting, which can be changed from both PLC and Handheld Terminal (H.T.)

If a parameter is changed using the H.T., the parameter setting content in the PLC will not be changed. This means that, if the parameter is changed by the H.T., when the PROFIBUS communication is disconnected and then reconnected again, the parameter settings will revert to the settings saved in the PLC.

When setting parameters which can be set from both the PLC or H.T., it is recommended that the setting is made from the PLC.

Parameter Definition

System parameter

No	Parameter Name	Contents
1	Diagnosis Mode	Change memory mapping of extended diagnostic data. There are 4 types of diagnostic: [No Diagnostic], [System Diagnostic], [Unit Diagnostic], [Channel Diagnostic]. Please refer to (Page 76) for the memory map information.
2	Hold/Clear Setting Method	Select setting method of output state during communication fault or communication idle state, either with the unit's setting switches or using a HHT. When using an HHT, each channel's output state can be set to Hold/Clear/Force ON. However, when using setting switches, the entire system's output state can be set.

SI Unit Parameter

No	Parameter Name	Contents
1	Power Supply Voltage Monitor (Control/Input)	When power supply voltage for control/input goes above 26V or falls below 21V, a diagnostic error will be generated.
2	Power Supply Voltage Monitor (Output)	When power supply voltage for output goes above 26V or falls below 20V, a diagnostic error will be generated.
3	Short Circuit Detection	If short circuit or over current occurs when the valve output is ON, diagnostic error will be generated.
4	Restart after short circuit	When a short circuit at the valve has been removed, the short circuit detection error diagnostic can be set to automatically reset (error will automatically be cleared) or manual reset (error will not be cleared until power supply is reset)
5	Open Circuit Detection	If an open circuit is detected during Valve Output OFF, a diagnostic error will be generated. This setting can be made for each channel.
6	Output setting during communication fault	At the time of communication fault, each channel's Valve Output can be set to Hold, Clear or Force ON setting. This function will only be activated when the Hold/Clear setting method at the system configuration is set to Handheld.
7	Output setting during communication idle	At the time when the communication is idle, each channel's Valve Output can be set to Hold, Clear or Force ON setting. This function will only be activated when Hold/Clear setting method at the system configuration is set to Handheld.
8	Channel ON/OFF Counter	The number of times the valve is ON/OFF is recorded for each channel. There is a set value for each channel, and it is possible to generate a diagnostic error when the set value is reached. However, recording the number of ON/OFF is done in 30 second intervals (30 seconds per channel) from CH0 to the channels which have valve outputs. If the power supply for control and input is turned OFF, the last recorded value for each channel will become valid.

No.	Parameter Name	Contents	
1	Short circuit detection	If a short circuit or over current occurs at the sensor power supply, a diagnostic error will be generated.	
2	Open Circuit Detection (Only available for Open Circuit Detection Unit)	 If an open circuit is detected at the input sensor, a diagnostic error will be generated. There is a setting available for each channel. Please note the following: 1) When a 2-wire type sensor is used, during OFF state, a leak current of less than 0.5mA will not be detected. A sensor with a leak current of 0.5mA or more (in the OFF state) must be used. 2) When a 3-wire type sensor is used, if the sensor has a current consumption of less than 0.5mA, an open circuit may not be detected. 	
3	Inrush current filter	When an input equipment with high capacitance is connected, at the time power is supplied, over current will be detected. If the inrush current filter is active, during the first 100msec after power is supplied, over current will not be detected.	
4	Input filtering time	A change of signal faster than the input filtering time will be disregarded.	
5	Input extension An Input signal will be extended to the time set by this parameter. I		
6 Channel On/Off Counter		The number of times the input is ON/OFF is recorded for each channel. There is a set value for each channel, and it is possible to generate a diagnostic error when the set value is reached. However, the counter value is recorded every one hour. If the power supply for control and input is turned OFF, data that has not been recorded will be cleared.	

Digital Input Unit Parameter

No	Parameter Name	Contents			
1	Short Circuit Detection	f a short circuit or over-current occurs at the output's load, a diagnostic error will be generated.			
2	Restart after Short Circuit	When a short circuit at the output has been removed, the short circuid detection error diagnostic can be set to automatically reset (error will automatically be cleared) or manual reset (error will not be cleared until power supply is reset)			
3	Open Circuit Detection	If an open circuit is detected when the output is in the OFF state, a diagnostic error will be generated. This setting can be made for each channel.			
4	Output Setting during communication fault	At the time of communication fault, each channel's output can be a to Hold, Clear or Force ON setting. This function will only be activat when the Hold/Clear setting method at the system configuration is a to Handheld.			
5	Output Setting during communication idle	At the time when the communication is idle, each channel's output can be set to Hold, Clear or Force ON setting. This function will only be activated when the Hold/Clear Setting method at the system configuration is set to Handheld.			
6	Channel On/Off Counter	The number of times the output is ON/OFF is recorded for each channel. There is a set value for each channel, and it is possible to generate a diagnostic error when the set value is reached. However, the counter value is recorded every one hour. If the power supply for control and input is turned OFF, data that has not been recorded will be cleared.			

Analog Input Unit Parameter

No	Parameter Name	Contents						
1	Short Circuit Detection	If a short circuit or over-current occurs at the sensor power supply, diagnostic error will be generated.						
2	Analog input measurement range	Selection of Analog Input Range. The settable measurement ranges are: 010V, 15V, 05V, -10V+10V, -5V+5V, 020mA, 420mA, -20mA+20mA.						
3	Analog data format							
4	4 Analog averaging filter Selection of analog averaging filter. The sampling cycle is a seconds. Selectable values are: No filter, 2 Average (average b the last 2 input values), 4 Average, and 8 Average.							
5	Range Upper Limit Error	If the input signal exceeds the upper limit value of the input range (0.5%), a diagnostic error will be generated.						
6	Range Lower Limit Error	If the input signal exceeds the lower limit value of the input range (0.5%), a diagnostic error will be generated.						
7	If the input signal exceeds the upper limit value of the user settable							
8	If the input signal exceeds the lower limit value of the user settable range							

Parameter's Factory Default Setting

System Parameter

No	Parameter Name	Setting	Contente	Setting	Default	Setting Method	
NO	No (GSD Valu Parameter)		Contents	Level	setting	By PLC	By H.T.
	Diagnostic mode (Diag. mode)	No diag.	No Diagnostic data	System			
		Device diag.	System diagnostic data only				
1	1 Device +Module Diag.		System and unit diagnostic data			0	0
		Device[+Module +Channel diag.	System, unit and channel diagnostic data		0		
2	Hold/Clear Setting Method	Switch	Hold/Clear Setting is made at SI Unit setting switch.	Sustam	0	0	0
	(Hold/Clear)	Handheld	Hold/Clear Setting is made at Handheld Terminal	System		0	0

SI Unit Parameter

Parameter No No Name		Setting			Default	Set Met			
NO	(GSD Parameter)	Value			Contents Setting Level		setting	By PLC	By H.T.
1	Power supply voltage for control and	Enable monitoring of power Enable supply voltage for control and input.		Unit	0	0	Ο		
	input monitor (Pwr control monitor)	Disable	Disable monitoring of power supply voltage for control and input.						
2	Power supply voltage for output monitor	Enable	Enable monitoring of power supply voltage for output	Unit	0	Ο	0		
2	(Pwr output monitor)	Disable	Disable monitoring of power supply voltage for output	Onit		0	U		
3	Short Circuit Detection	Enable	Enable valve short circuit detection	Unit	0	0	0		
	(Monitor short circuit)	Disable	Disable valve short circuit detection	Onic		0	0		
	Restart after short circuit	Auto	After short circuit has been removed, the error will be cleared automatically.		0	Ο			
4	(Restart after short circuit)	Manual	After short circuit has been removed, the error will not be cleared until the power supply is reset.	Unit			0		
5	Open Circuit Detection	Enable	Enable valve open circuit detection	Channel		x	0		
Ŭ	(OC_Mon)	Disable	Disable valve open circuit detection	ondriner	0		0		
	Output setting	Clear	During communication fault, clear valve output.		0				
6	during communication fault.		During communication fault, hold valve output.	Channel		х	Ο		
	(Fault_MD)	ForceOn	During communication fault, turn ON valve output.						
	Output setting	Clear	During communication idle, clear valve output.		0				
7	during communication idle	Hold	During communication idle, hold valve output.	Channel		Х	Ο		
	(Idle_MD)	ForceOn	During communication idle, turn ON valve output.						
	Valve ON/OFF	Enable	If valve's ON/OFF counter exceeds the setting value, a diagnostic error will be generated.						
8	counter (Counter)	Disable	Diagnostic error will not be generated	Channel	0	Х	0		
		Val	Set maximum counter value. Settable values are (1~65000) x 1000 times		65000				

Digital Input Unit Parameter

(GSD Parameter) Short circuit detection (Monitor short circuit) Open circuit detection	Setting Value Enable Disable Enable	Contents Enable sensor's power supply short circuit detection Disable sensor's power supply	Setting Level Unit	setting O	By PLC O	By H.T. O
detection (Monitor short circuit) Open circuit detection	Disable	short circuit detection Disable sensor's power supply	Unit	0	0	0
circuit) Open circuit detection						
detection	Enable	short circuit detection				
		Enable input sensor open circuit detection	Channel		Х	0
(Monitor open circuit) Note 1)	Disable	Disable input sensor open circuit detection		0		
Inrush current Filter	Enable	Enable inrush current filter	Unit	0	0	0
(Inrush current filter)	Disable	Disable inrush current filter				
Input Filtering time (Input filtering time)	0.1/1/10/ 20 msec	20		1msec	0	0
Input extension time (Input extension time)	1/15/100 /200 msec	00 time		15 msec	0	0
Input Sensor's ON/OFF (Counter)	Enable	If input sensor's ON/OFF counter exceeds setting value, diagnostic error will be generated.	Channel		х	0
	Disabl e	Diagnostic error will not be generated		0		
	Val	Set maximum counter value. Settable setting value are (1~65000) x 1000 times		65000		
	(Monitor open circuit) ^{Note 1)} Inrush current Filter (Inrush current filter) Input Filtering time (Input filtering time) Input extension time (Input extension time) Input Sensor's ON/OFF (Counter)	(Monitor open circuit) Note 1)DisableInrush current Filter (Inrush current filter)EnableInput surrent filter)DisableInput Filtering time)0.1/1/10/ 20 msecInput Filtering time)1/15/100 /200 msecInput extension time time)1/15/100 msecInput extension time)1/15/100 msecInput extension time)1/15/100 msecInput extension time)1/15/100 msecInput Sensor's ON/OFF (Counter)Enable Val	(Monitor open circuit)DisableDisable input sensor open circuit detectionInrush current Filter (Inrush current filter)EnableEnable inrush current filterInput surrent filter)DisableDisable inrush current filterInput Filtering time (Input filtering time)0.1/1/10/ 20 msecSet input signal filtering time.Input extension time (Input sensor's ON/OFF (Counter)1/15/100 /200 msecSet input sensor's ON/OFF counter exceeds setting value, diagnostic error will be generated.DisablDisablDiagnostic error will not be generatedValSet maximum counter value. Settable setting value are (1~65000) x 1000 times	(Monitor open circuit) Note 1)DisableDisable input sensor open circuit detectionUnitInrush current Filter (Inrush current filter)EnableEnable inrush current filterUnitInput Surrent filter)Disable DisableDisable inrush current filterUnitInput Filtering time (Input filtering time)0.1/1/10/ 20 msecSet input signal filtering time.UnitInput extension time (Input extension time)1/15/100 /200 msecSet input signal's extension timeUnitInput Sensor's ON/OFF (Counter)EnableIf input sensor's ON/OFF counter exceeds setting value, diagnostic error will be generated.ChannelValSet maximum counter value. Settable setting value are (1~65000) x 1000 timesDiagnostic me	(Monitor open circuit) Note 1)DisableDisable input sensor open circuit detectionOInrush current Filter (Inrush current filter)EnableEnable inrush current filterUnitOInput Sensor is (Input sensor is contered)DisableDisable inrush current filterUnitOInput Filtering time)0.1/1/10/ 20 msecSet input signal filtering time.Unit1msecInput Filtering time)0.1/1/10/ 20 msecSet input signal is extension timeUnit1msecInput sensor time (Input extension time)1/15/100 /200 msecSet input sensor's ON/OFF counter exceeds setting value, diagnostic error will be generated.ChannelOODisableDiagnostic error will not be e ValOOOValSet maximum counter value. Settable setting value areO	(Monitor open circuit) Note 1)DisableDisable input sensor open circuit detectionOInrush current Filter (Inrush current filter)EnableEnable inrush current filterUnitOOInput Siltering time (Input filtering time)DisableDisable inrush current filterUnitOOInput Filtering time (Input filtering time)0.1/1/10/ 20 msecSet input signal filtering time.Unit1msecOInput Sensor time (Input extension time)1/15/100 /200 msecSet input signal's extension timeUnit15 msecOInput Sensor's ON/OFF (Counter)EnableIf input sensor's ON/OFF counter exceeds setting value, diagnostic error will be generated.ChannelXValSet maximum counter value. Settable setting value are (1~65000) x 1000 times65000A

Note 1) Open Circuit Detection parameter is only available on Digital input unit with open circuit detection (P/N EX600-DXPC1, EX600-DXNC1).

Digital Output Unit Parameter

No	Name (GSD	Setting	Contents	Setting	Default	Set Met	
Parameter)		Value		Level	setting	By PLC	By H.T.
1	Short Circuit Detection	Enable	Enable output short circuit detection	Unit	0	0	Ο
	(Monitor short circuit)	Disable	Disable output short circuit detection	Onic		0	Ŭ
	Restart after	Auto	After short circuit has been removed, the error will be cleared automatically	-	Ο	Ο	
2	2 Short Circuit (Restart after short circuit)		After short circuit has been removed, the error will not be cleared until the power supply is reset	Unit	Unit		0
3	Open Circuit Detection	Enable	Enable output open circuit detection	Channel		x	Ο
5	(Monitor pen circuit)	Disable	Disable output open circuit detection	Channel	0		U
	Output setting	Clear	During communication fault, clear output		0		
4			During communication fault hold output	Channel		х	0
	(Fault action)	Force On	During communication fault, turn ON output				
	Output setting during	Clear	During communication idle, clear output		0		
5	communication	ommunication Hold During communication idle, Channe		Channel		Х	0
	(Idle mode)	Force On	During communication idle, turn ON output				
	Output ON/OFF counter (Switching	Enable	If output ON/OFF counter exceeds the setting value, a diagnostic error will be generated.				
6	counter)	Disable	Diagnostic error will not be generated	Channel	0	х	0
		Val	Set the maximum counter value. Settable value are (1~65000) x 1000 times		65000		

Analog Input Unit Parameter(1)

No	Name (GSD		Contents	Setting	Default		ting hod
NU	Parameter)	Setting Value		Level	setting	By PLC	By H.T.
1	Short Circuit Detection	Enable	Enable sensor power supply short circuit detection	Unit	0	0	0
	(Monitor short circuit)	Disable	Disable sensor power supply short circuit detection			0	
2	Analog Input Range (Ch # Range)	010V, 15V、 05V, -10V+10V, -5V+5V, 020mA, 420mA, -20mA+20mA	Select analog input range	Channel	-10V ~ 10V	0	0
3	Analog Data Format (Data format)	Offset Binary, Sign & Magnitude, 2s Complement	Select analog data format	Unit	Offset Binary	0	Ο
4	Analog Filter (Ch # Filter)	None, 2 value average, 4 value average, 8 value average	Select analog data filter	Unit	2 value average	0	Ο
5	Over Range detection (Monitor over range)	Enable	If the analog input exceeds the maximum allowable input range (0.5%), a diagnostic error will be generated	Unit	Enable	0	0
	range)	Disable	Above diagnostic error will not be generated.				
6	Under Range detection (Monitor under	Enable	If the analog input exceeds the minimum allowable input range (0.5%), a diagnostic error will be generated	Unit	Enable	0	0
	range)	Disable	Above diagnostic error will not be generated.				



Analog Input Unit Parameter (2	2)
--------------------------------	----

	No Name No (GSD Parameter)			Setting	Default	Setting Method	
No			Contents	Level	setting	By PLC	By H.T.
User Setting 7 Value Upper		Enable	If the analog input exceeds the upper user setting lower limit, diagnostic error will be generated	Channal	Disable	x	0
	' Limit Error (Analog upper limit)	Disable	Above diagnostic error will not be generated.	Channel		^	U
		Val	Refer to Note1) for possible set value		10V ^{Note2)}		
8	User Setting Value lower	Enable	If the analog input falls below the lower user setting lower limit, diagnostic error will be generated	Channal	Disable	x	0
	Limit Error (Analog under	Disable	Above diagnostic error will not be generated.	Channel		X	0
	limit)	Val	Refer to Note1) for possible set value		10V		

Note1) User setting value is settable according to the table below.

Analog input measurement	User setting value set range		
range	Upr_Lmt	Lwr_Lmt	
-10 +10V	-10.5 ~ +10.45V	-10.45 ~ +10.5V	
-5V +5V	-5.25 ~ +5.22V	-5.22 ~ +5.25V	
-20 +20mA	-21 ~ +20.9mA	-20.9 ~ +21mA	
0 +10V	0 ~ +10.45V	0.05 ~ +10.5V	
0 +5V	0 ~ +5.22V	0.02 ~ +5.25V	
+1 +5V	+0.75 ~ +5.22V	+0.77 ~ +5.25V	
0 +20mA	0 ~ +20.9mA	0.1 ~ +21mA	
+4 +20mA	+3 ~ +20.9mA	+3.1 ~ +21mA	

Note 2) Factory default setting for Analog input range is -10...+10V When changing the analog input measurement range, please make sure to confirm the set value and set the correct value accordingly.

Hardware Configuration

This section will explain hardware configuration and implementation and parameter allocation methods for the EX600 Series.

GSD File and Symbol File

GSD file is required to configure the EX600 with a DP Master. The GSD File contains ID number, version, and unit information. Furthermore, a symbol file is necessary for the display microcontroller of the EX600 on the DP Master Software. The GSD File and Symbol File can be downloaded from the URL given below.

- URL : http://www.smcworld.com
- GSD File : SMCA1411.gsd
- Symbol File : EX600_1N.bmp(standard type)
 - : EX600_1D.bmp(diagnostic type)
 - : EX600_1S.bmp(special operating mode)

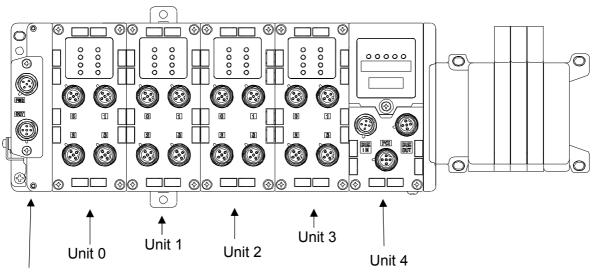
Unit Identification

Each Unit of EX600 Series has a unique identification number.

Unit Part Number	Unit Name	Occupied Byte		DP ID number	
		Input	Output	Siemens	IEC61158
EX600-SPR# (32 Ch) (#:1/2)	SI Unit (32 Ch)	0	4	32DO	23h
EX600-SPR# (24 Ch) (#:1/2)	SI Unit (24 Ch)	0	3	24DO	22h
EX600-SPR# (16 Ch) (#:1/2)	SI Unit (16 Ch)	0	2	16DO	21h
EX600-SPR# (8 Ch) (#:1/2)	SI Unit (8 Ch)	0	1	8DO	20h
EX600-DX#B (#:P/N)	Digital Input Unit	1	0	8DI	10h
EX600-DX#C (#:P/N)	Digital Input Unit	1	0	8DI	10h
EX600-DX#C1 (#:P/N)	Digital Input Unit (With Open Circuit Detection)	1	0	8DI	10h
EX600-DX#D (#:P/N)	Digital Input Unit	2	0	16DI	11h
EX600-DY#B (#:P/N)	Digital Output Unit	0	0	8DO	20h
EX600-AXA (2channel)	Analog Input Unit (2 Channel)	4 (1 Channel is 2 bytes)	0	2AI	51h

Configuration Layout

The Unit number is sequentially allotted from the End Plate end of the EX600 assembly. The communication with the DP Master will not be established if the layout of the hardware configuration does not match the actual system configuration.



End plate

SIEMENS PLC S7 Connection Method

Below is an explanation of the EX600 Series connection method with a SIEMENS' PLC STEP7™.

GSD File Installation

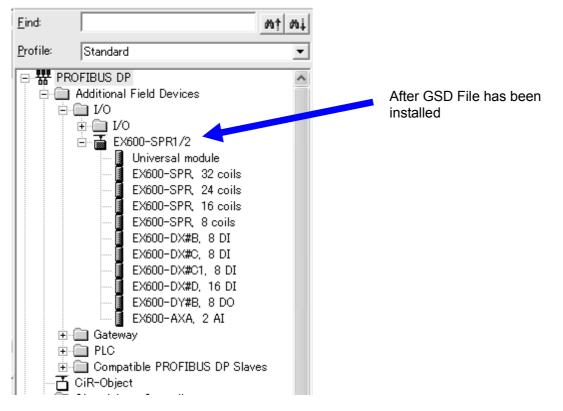
There are 2 methods for installing the EX600-SPR# GSD file:

Method1: Before starting-up STEP7[™].

- Copy GSD file to [.../ Siemens / Step7:/ S7data / gsd] folder.
- Copy Symbol file to [.../Siemens / Step7 / S7data / nsbmp] folder.
- After completing the above steps, the EX600-SPR1/2 will automatically be added to the Hardware Catalogue under the STEP7[™] [Hardware Catalogue] [Additional Field Devices / I/O /] Folder.

Method 2: After STEP7[™] has been started.

- Open [Hardware Configuration] screen.
- Select "Option→Install New GSD… " From the menu bar.
- Select GSD File (SMCA1411.gsd), and click the Open button.
- Copy symbol file to [... / Siemens / STEP7 / S7data / nsbmp] folder.
- After completing the above steps, the EX600-SPR1/2 will automatically be added to the Hardware Catalogue under the STEP7[™] [Hardware Catalogue] [Additional Field Devices / I/O /] Folder..



Screen data used on this document is taken from STEP7™ software by Siemens AG.



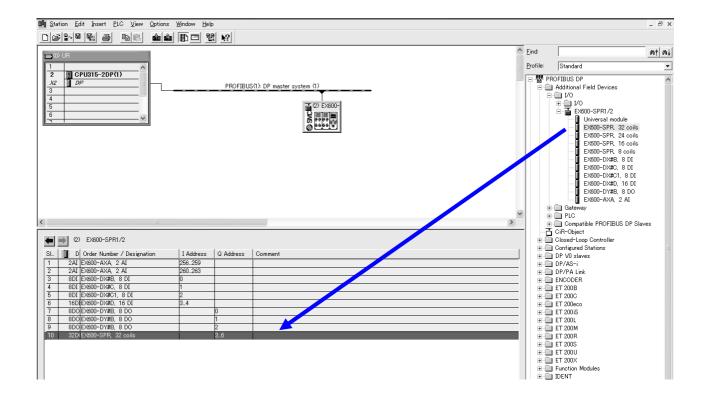
Adding Stations

- Drag and drop EX600-SPR1/2 from the Hardware Catalogue to the station window. "Property-PROFIBUS Interface EX600-SPR1/2" Dialogue Box will be displayed.
- Enter the unit address on the dialogue box. Please make sure that the address entered is the same as the address set, using the SI unit switches.
- Press the OK button to confirm the address setting. EX600-SPR1/2 will be shown on the station window.

🕼 Station Edit Insert PLC View Options Window Help	_ B ×
🗩 🛈 UR	Eind: nt nt
	Profile: Standard
2 CPU315-2DP(1) 3 PROFIBUS(1): DP master system (1) 4 - 6 -	■ ■ PROFIBUS DP ■ ■ ■ Additional Field Devices ■ ■ □ I/O ● □ ■ ■ DS00-SPR12 ■ ■ ■ ■ ■ BS00-SPR12 ■ ■ ■ ■ ■ ■ BS00-SPR12 ■ </td
(2) EX600-SPR1/2	
SL. D Order Number / Designation I Address Q Address Comment	Configured Stations
	DP/AS-i

Adding Units

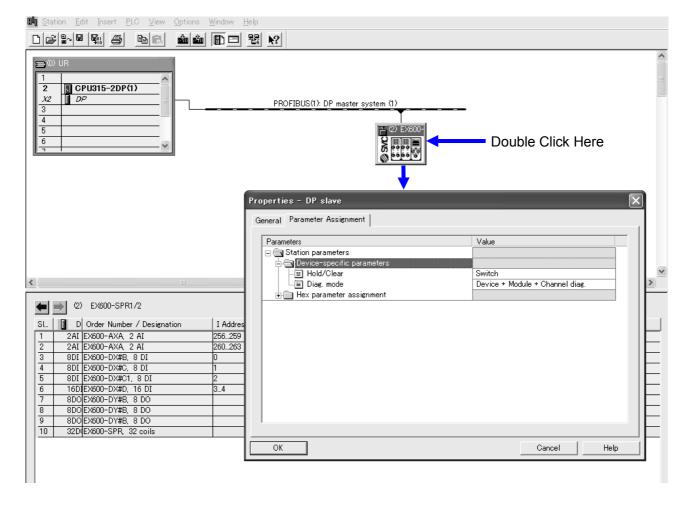
- Select "EX600-SPR1/2" from the station window.
- An empty slot for EX600-SPR1/2 will be displayed on the configuration table, below the station window.
- Drag and drop the connected unit from [Hardware Catalogue] Window to slot 1. Please make sure to add the unit as the real system's order of connecting (i.e Unit 0 at Slot 1).
- Add the other units, according to the connected order, to the configuration table, ending with the SI unit.
- The SI Unit for 32, 24, 16, 8 coils can be selected, please make sure to match the setting with the V_SEL switch setting in the SI unit.



Parameter Setting at PLC

System Parameter Setting

- Double click the "EX600-SPR1/2" symbol on the PROFIBUS: DP master system line. The system properties window will be displayed.
- Select the [Parameter Assignment] tab; the available Parameter setting list will be displayed under [Device-Specific parameters] folder.
- Change the parameter value by clicking on the Value column of the selected parameter.
- Press the OK Button, after the configuration data is downloaded to the PLC, the setting will be completed.



The system parameters given below can be set at the STEP7™.

System Parameter	Setting Value
Hold/Clear	Switch
	Parameter
Diag.mode	No diag.
	Device diag
	Device + Module diag.
	Device + Module + Channel Diag



Unit Parameter Setting

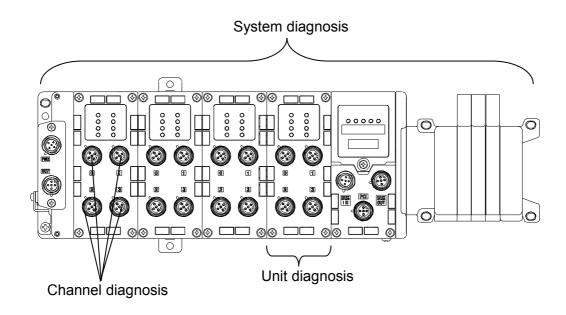
• Double click a unit that you want to set on the configuration table, select [Parameter Assignment] tab. The setting method is the same as described above for system parameter setting.

Address / ID Parameter Assignment	Value
	Value
Parameters Station parameters Station parameters Device-specific parameters	
一国 Monitor short circuit 一国 Restart after short circuit 一国 Pwr control monitor	Enable Auto Enable
	Enable
ОК	Cancel Help

Diagnostic Mode

The diagnostic Mode can be set at Diag. Mode in the system parameter setting.

No.	Diagnostic Mode	Contents
1	No diag.	Provides standard diagnostic data
2	Device diag	Provides standard diagnostic + system diagnostic data
3	Device + Module diag.	Provides standard diagnostic + system diagnostic + unit
		diagnostic data
4	Device + Module + Channel Diag	Provides standard diagnostic + system diagnostic + unit
		diagnostic + channel diagnostic data



Diagnostic Map

Diagnostic	: Map is shown below			
Byte No.	Contents	Diagnostic type		
Byte 0	Station Status 1			
Byte 1	Station Status 2			
Byte 2	Station Status 3	Standard Diagnostic		
Byte 3	Master PROFIBUS Address	data		
Byte 4	Manufacturer ID(MSB : 14h)			
Byte 5	Manufacturer ID(LSB : 11h)			
Byte 6	Header			
Byte 7	System diag.1			
Byte 8	System diag.2			
Byte 9	System diag.3	System Diagnostic		
Byte 10	System diag.4	data		
Byte 11	Reserved			
Byte 18	Reserved			
Byte 19	Header			
Byte 20	Unit 0~7			
Byte 21	Unit 8~9	Unit Diagnostic data		
Byte 22	Reserved			
Byte 27	Reserved			
Byte 28	Unit A			
Byte 29	Channel A			
Byte 30	Diagnostic contents A			
Byte 31	Unit B			
Byte 32	Channel B	Channel Diagnostic		
Byte 33	Diagnostic contents B	data		
Byte 61	Unit L			
Byte 62	Channel L			
Byte 63	Diagnostic contents L			

Standard Diagnostic data

Station Status 1

	7	6	5	4	3	2	1	0	
Byte 0									

Bit No.	Meaning							
0	DP Slave can not be accessed by DP Master							
1	DP Slave is not ready to exchange data							
2	Configuration data transmitted to DP Slave by DP Master does not match with setting of DP Slave.							
3	External diagnostic function can be used							
4	DP Slave does not support the required function							
5	DP Master can not interpret the response of DP Slave							
6	DP Slave type does not correspond to software configuration							
7	Parameter is allocated to DP Slave by different DP Master							

Station Status 2

	7	6	5	4	3	2	1	0
Byte 1		0				1		

Bit No.	Meaning					
0	New Parameter needs to be allocated to the DP slave					
1	A new message was generated					
2	At DP Slave, this bit is always 1)					
3	The response monitor is effective to DP Slave.					
4	DP Slave received FREEZE control command.					
5	DP Slave received the SYNC control command.					
6	(Bit is always 0)					
7	DP Slave is inactive					

Station Status 3

	7	6	5	4	3	2	1	0	
Byte 2		0	0	0	0	0	0	0	
Bit No.				Ν	<i>Meaning</i>				

Bit No.	Meaning
0~6	(Bit is always 0)
7	There are more diagnostic message than DP Slave can store.

Master PROFIBUS Address

Byte 3 shows the PROFIBUS Address of the DP Master.

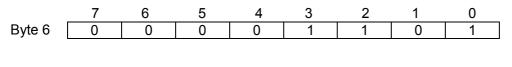
When the address is FFh, the parameter of the DP Slave cannot be changed. For all other address settings, the parameters of the DP Slave can be changed.

Manufacturer ID

The DP Slave manufacturer ID is shown. The EX600-SPR1/2 manufacturer ID is 1411h.

System Diagnostic data

Header



Bit No.	Meaning
0~5	Number of Byte of devices Diagnostic data
6, 7	(Bits are always 0)

System diag.1

-	7	6	5	4	3	2	1	0
Byte 7								

Bit No.	Meaning
0	Analog input falls below user's setting lower limit value
1	Analog input exceeds user's setting upper limit value
2	Analog input falls below lower measurement range
3	Analog input exceeds upper measurement range
4	Channel ON/OFF counter exceeds setting value
5	Open circuit error detected
6	Short circuit detected on valve output or digital output.
7	Short circuit detected on input sensor's power supply

System diag.2 2 1 0 <u>6 5</u> -3 4 Byte 8

Bit No.	Meaning
0	Power supply voltage for output is outside operating range
1	Power supply voltage for control and sensor is outside operating
	range
2	Reserved
3	Connection error on I/O Unit (during operation)
4	Connection error on I/O Unit(at system start up)
5	Reserved
6	System error
7	Hardware error



System d	liag.3								
	7	6	5	4	3	2	1	0	
Byte 9	-	-	-	-	-	-	-	-	
Bit no.					Meaning				
0~7	Rese	erved							
System o	diag.4								
	_	•	_		•	•		•	
	7	6	5	4	3	2	1	0	7
Byte 10	-	-	-		-				
Bit No.					Meaning				
0		r detecte							
1		Error detected on Digital Output unit.							
2	Erro	Error detected on Analog Input unit.							
3		Reserved							
4	Erro	Error detected on SI unit.							
5	Rese	Reserved							
6		erved							
7	Rese	erved							

Unit Standard Diagnostic data

Header

	7	6	5	4	3	2	1	0	
Byte 19	0	1	0	0	1	0	0	1	

Bit No.	Meaning
0~5	Number of byte of unit diagnostic data
6	(Bit is always 1)
7	(Bit is always 0)

Unit 0~	7								
	7	6	5	4	3	2	1	0	
Byte 20									

Bit No.	Meaning
0	Error detected on Unit 0
1	Error detected on Unit 1
2	Error detected on Unit 2
3	Error detected on Unit 3
4	Error detected on Unit 4
5	Error detected on Unit 5
6	Error detected on Unit 6
7	Error detected on Unit 7

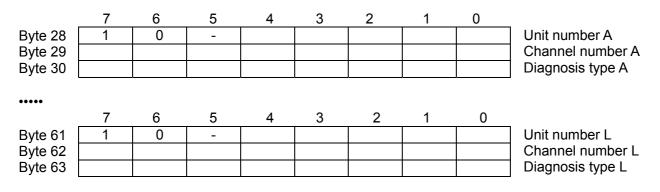
Unit 8~9

	7	6	5	4	3	2	1	0
Byte 21	-	-	-	-	-	-		

Bit No.	Meaning
0	Error detected on Unit 8
1	Error detected on Unit 9
2~7	Reserved

Channel Diagnostic data

Each channel diagnostic data is composed of 3 bytes, with a maximum of 12 errors which can be detected. However, because only one error may output per one unit, when two or more errors are generated by the same unit, the error on the channel with the lowest number will be output.



Unit Number

Bit No.	Meaning
0~4	Displays Unit number 0~9
5	Reserved
6	(Bit is always 0)
7	(Bit is always 1)

Channel Number

Bit no.	Meaning			
0~5	Displays Channel number 0~63			
6, 7	Input / Output Type :			
	00= Reserved、01= Input 、10= Output、11= Input / output			

Diagnostic Type

Bit No.	Meaning
0~4	Error Code
5~7	Channel Type : 001= Bit (Unit other than Analog Input) 101=Word(Analog Input Unit)

Error Code

Error Code (Decimal)	Meaning	Level
0	Reserved	
1	Short Circuit Detection	3
2~5	Reserved	
6	Open circuit Detection	3
7	Analog input exceeds upper measurement range	3
8	Analog input falls below lower measurement range	3
9~15	Reserved	
16	Analog input exceeds user's setting upper limit value	3
17	Analog input falls below user's setting lower limit value	3
18	Channel ON/OFF counter exceeds setting value	3
19~29	Reserved	
30	Connection error on I/O Unit	1
31 ^(Note2)	Hardware error	2

Note1) It becomes the order of the priority level $(1\rightarrow 2\rightarrow 3)$ when an error is detected on the same unit same channel. Note2) The Channel number when an Error is generated is assumed to be 0.

Accessories

Please refer to the catalogue for selecting the accessories.

(1)Valve Plate

Used for mounting solenoid valve manifold and SI unit.

EX600-ZMV1

(2)Metal fittings for Endplate Metal fittings used with endplate when installed on DIN rail.

EX600-ZMA2

(3)Metal fittings for the intermediate reinforcement Metal fittings used at the intermediate position when more than 6 units are assembled.

EX600-ZMB1	For direct mounting
EX600-ZMB2	For DIN rail mounting

(4)Seal cap (10 pcs included)

Please install a seal cap in all unused input/output connectors, to maintain the protective construction of IP67.

EX9-AWES	For M8
EX9-AWTS	For M12

(5)Marker (1 sheet, 88pcs included)

A marker to show input/output equipment signal names and unit addresses, etc. can be inserted for each unit.

EX600-ZT1

(6)Y Junction connector

Connector used to branch off between sensor and input unit.

PCA-1557785 2×M12(3 pin)-M12(5 pin)



(7)Assembled type connector

PCA-1558797	Power supply cable 7/8",Plug	
PCA-1558807	Power supply cable 7/8",Socket	
PCA-1557701	PROFIBUS DP communication cable, Plug	
PCA-1557714	PROFIBUS DP communication cable, Socket	
PCA-1557730	M8(3 pin),Plug	
PCA-1557743	M12(4 pin),Plug ,AWG26~AWG22,SPEEDCON compatible	
PCA-1557756	M12(4 pin),Plug ,AWG22~AWG18,SPEEDCON compatible	

(8)Power supply cable

PCA-1558810	Cable with 7/8" connector, Socket, Straight 2m
PCA-1558823	Cable with 7/8" connector, Socket, Straight 6m
PCA-1558836	Cable with 7/8" connector, Socket, Right angle 2m
PCA-1558849	Cable with 7/8" connector, Socket, Right angle 6m
PCA-1564927	Cable with M12 connector, B Code, Socket, Straight 2m,
	SPEEDCON compatible
PCA-1564930	Cable with M12 connector, B Code ,Socket ,Straight 6m,
	SPEEDCON compatible
PCA-1564943	Cable with M12 connector, B Code, Socket, Right angle 2m,
	SPEEDCON compatible
PCA-1564969	Cable with M12 connector, B Code, Socket, Right angle 6m,
	SPEEDCON compatible

(9)PROFIBUS DP communication cable

PCA-1557688	Cable with M12 connector cable, B Code, Socket, Straight 5m,
	SPEEDCON compatible
PCA-1557691	Cable with M12 connector, B Code, Plug, Straight 5m,
	SPEEDCON compatible

(10)Connector extension cable

PCA-1557769	M12(4pin),Straight 3m
PCA-1557772	M8(3pin),Straight 3m

Revision history

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