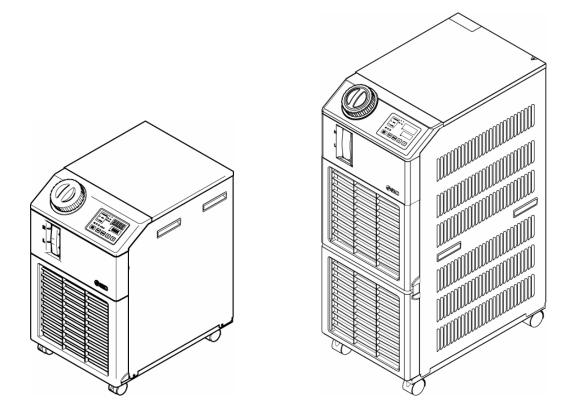




# **Operation Manual** Communication function

#### **Thermo chiller**

Air-Cooled refrigerated type HRS012-A\*-10-\* HRS018-A\*-10-\* HRS012-A\*-20-\* HRS018-A\*-20-\* HRS024-A\*-20-\* HRS050-A\*-20-\* Water-Cooled refrigerated type HRS012-W\*-10-\* HRS018-W\*-10-\* HRS012-W\*-20-\* HRS018-W\*-20-\* HRS024-W\*-20-\* HRS024-W\*-20-\*



Keep this manual available whenever necessary

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#### To the users

Thank you for purchasing SMC's Thermo chiller (hereinafter referred to as the "product").

For safety and long life of the product, be sure to read this operation manual (hereinafter referred to as the "manual") and clearly understand the contents.

- Be sure to read and follow all instructions noted with "Warning" or "Caution" in this manual.
- This manual is intended to explain the installation and operation of the product. Only people who understand the basic operation of the product through this manual or who performs installation and operation of or have basic knowledge about industrial machines are allowed to work on the product.
- This manual and other documents attached to the product do not constitute a contract, and will not affect any existing agreements or commitments.
- It is strictly prohibited to copy this manual entirely or partially for the use by the third party without prior permission from SMC.

Note: This manual is subject to possible change without prior notice.

# **SMC** Corporation

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# Chapter 1 Read before using

The communication of this device consists of contact input/output communication and serial communication.

MODBUS communication and simple communication protocol can be selected as the serial communication protocol. Depending on the customer's specification, communication can be changed to contact input/output communication or serial communication.

Table 1-1 Communication method						
Contact input/ou	tput communication	This product is equipped with a terminal which runs/stops the product by remote control and a terminal which can pick up alarm signals. The terminals can be changed depending on the customer's application.				
	MODBUS standard protocol	Serial communication (RS-485/RS232C) enables remote control of run/start of the product, temperature setting, and details of product condition and alarm condition can be obtained.				
Serial communication	Simple communication protocol	Serial communication (RS-485/RS232C) enables remote control of temperature setting. This protocol complies with SMC thermo-cooler HRG, HRGC series. (We recommend using the MODBUS protocol if you are unfamiliar with using the communication function.) There are two ways to start and stop by simple communication protocol. The customer can choose between operation using the Operation display panel (simple communication protocol 1) and remote control using the contact input (simple communication protocol 2).				

#### ●If using contact input/output communication, refer to chapter 2.

If using serial communication MODBUS, refer to chapter 3 for serial communication specifications first, then refer to chapter 4 for protocol specifications.

●If using simple communication protocol for serial communication, refer to chapter 3 for serial communication specifications first, then refer to chapter 5 for protocol specifications.

## **1.1** Communication mode and operation method

LOCAL, DIO and SERIAL are available as the communication modes. Table 1.1-1 explains the communication modes. The default setting is LOCAL.

The operation method depends on the communication mode. Table 1.1-2 shows how the communication mode and method of operation are related.

The operation of the product functions depends on the communication mode. Table 1.1-3 shows how the communication mode and functions of this product are related.

Table 1.1-1 Communication modes

Communication mode	e Explanation			
LOCAL	Mode allowing the product to be operated by the operation panel.			
	Mode allowing the product to be operated by the contact input/output communication. When the communication mode is "DIO", operation mode automatically becomes "DIO REMOTE". "DIO REMOTE" and "DIO LOCAL" can be selected by DIO communication signal.			
DIO	DIO REMOTE : Contact input/output communication takes control of the operation of the product. The [REMOTE] lamp on the operation panel turns on.			
	DIO LOCAL : Operation control of the product is the same as that of LOCAL. The [REMOTE] lamp on the operation panel turns off.			
SERIAL	Mode allowing the product to be operated by serial communication. MODBUS/ simple communication protocol can be selected.			

Table 1.1-2 Communication mode and operation

		C	010	SERIAL		
	LOCAL	DIO LOCAL	DIO REMOTE	MODBUS	Simple communication protocol pattern	
					1	2
Run/Stop control with operation display panel	0	0	×	×	0	×
Circulating fluid discharge temperature setting control with operation display panel	0	0	0	×	>	<
Except above with operation display panel	0	Ó	Ó	0	(	)
Condition reading with operation display panel	0	0	0	0	C	)
Run/Stop operation by contact input/output communication	×	×	0	×	×	0
Condition reading by contact input/output communication	0	0	0	0	(	C
Reading of the external switch	0	O*1	O*1	0	0	O*1
Run/Stop operation by serial communication.	×	×	×	0	>	<
Circulating fluid discharge temperature setting control by serial communication.	×	×	×	0	(	C
Condition reading by serial communication.	0	0	0	0	(	)

\*1: Only one external switch can be installed.

 Table 1.1-3
 Communication mode and product functions

		C	DIO	SERIAL		
	LOCAL	DIO	DIO REMOTE	MODBUS	Simple communication protocol pattern	
					1	2
Run timer	0	0	×	×	0	×
Stop timer	0	0	×	×	0	×
Recovery from power failure	0	0	×	×	0	×
Anti-freezing	0	0	0	0	0	0
Pump accumulated operating time reset	0	0	×	×	0	×

1.1 Communication mode and operation method

## 1.2 Communication port

The communication port at the back of the product is used for communication. Fig 1.2-1, Fig 1.2-2 shows the location of the communication port.

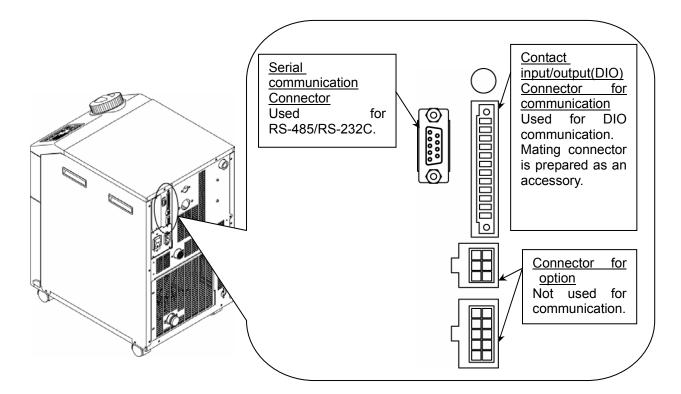
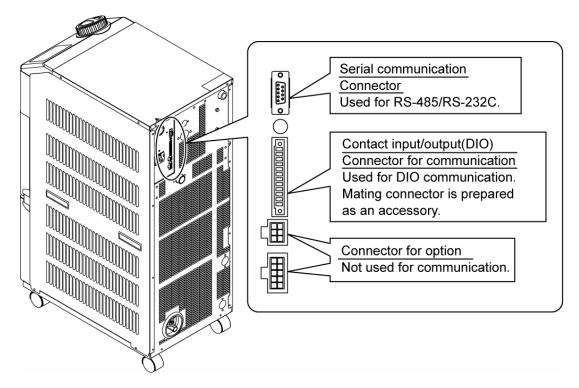


Fig 1.2-1 Communication port (HRS012-\*\*-\*-\*, HRS018-\*\*-\*-\*, HRS024-\*\*-20-\*)





## 1.3 Key operations

Fig 1.3-1 "Key operation (1/2)" and

Fig 1.3-2 "Key operation (2/2)" show the operation of keys of the thermo-chiller. This manual explains the "Communication setting menu".

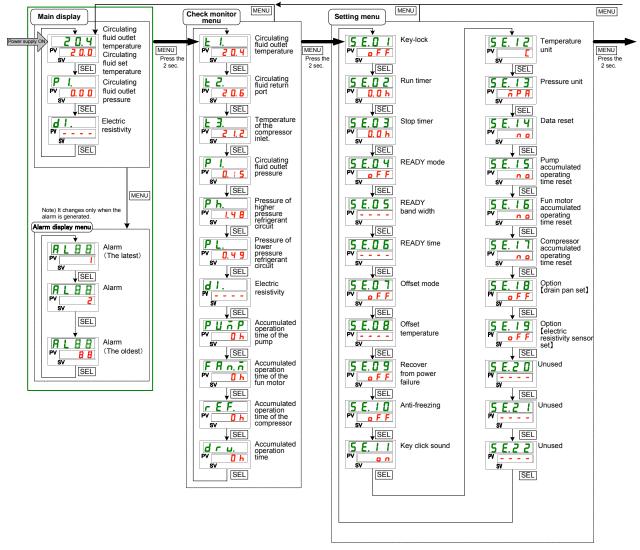


Fig 1.3-1 Key operation (1/2)

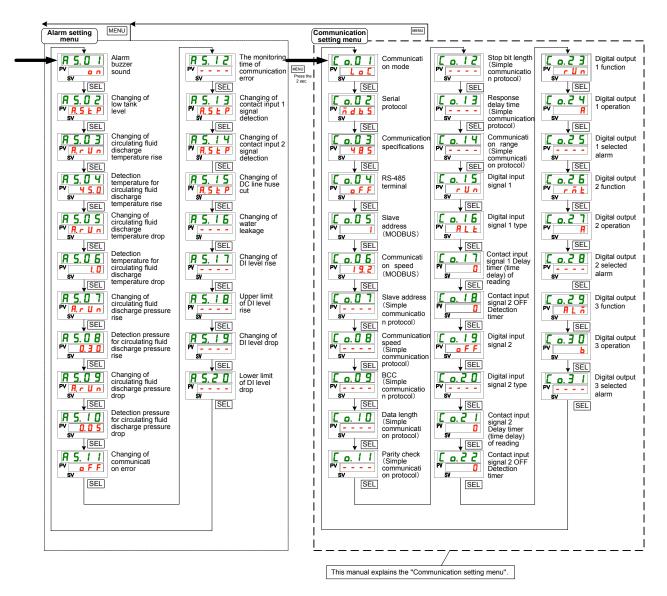


Fig 1.3-2 Key operation (2/2)

## 1.4 Parameters

Table 1.4-1 "Parameters" explains the parameters of the  $\$   $\$  fcommunication setting menu1 .

			Ia	ble 1.4-1 Parameters		
Display			Item	Initial value	Reference	Category
				(Default setting)	page	0,
	0		inction mode		2.4	
[ 0.0 ]	00	mmun	ication mode	LOC	4.3	
		1			5.3 4.3	
<u> </u>		Seria	I protocol	MDBS	4.3 5.3	
		Com	munication		4.3	
<u> </u>			ifications	485	5.3	
	~				4.3	
<u>Co.04</u>	Ser	RS-4	85 terminal	OFF	5.3	
[ 0.05	ial c	Мо	Slave address	1		
C o. 0 6	Serial communication	db us	Communication speed	19.2	4.3	
[ 0.0]	nu		Slave address	1		
[ 0.08	nic	Simple communication protocol	Communication speed	9.6		
[ 0.09	atio	, mc	BCC	ON		
<u>[ o. 10</u>	n	Sin Not	Data length	8BIT	5.0	
[ o.		inic	Parity check	NON	5.3	
E o. 12		oläti	Stop bit length	2BIT		
[ 0. ] ]		on	Response delay time	0		
E o. 14			Communication range	RW		
E o. 15			act input signal 1	RUN		Communication
<u> </u>			act input signal 1 type	ALT		setting menu
[0.17]			act input signal 1 delay	0		
	0		(time delay) of reading		-	
[ 0. 18	Contact input/output		act input signal 1 OFF ction timer	0		
[ o. 19	ac		act input signal 2	OFF		
[ 0.20	in		act input signal 2 type	ALT		
	put		act input signal 2 delay	0		
[ 0.2 ]	ίο		(time delay) of reading	0		
[ 0.22	ıtpu		act input signal 2 OFF	0	2.4	
	tcc		ction timer act output 1 function	RUN		
<u>[ o.23</u> [ o.24	commur		act output 1 operation	A	-	
<u> </u>	mu		cted for contact output 1	AL.01	-	
<u> </u>	nic		act output 2 function	RMT		
<u> </u>	nication		act output 2 operation	A		
[ 0.28	n		cted for contact output 2.	AL.01		
[ 0.2 9			act output 3 function	ALM		
<u> </u>			act output 3 operation	B		
			cted for contact output 3	AL.01		
[ 0. ] ]		26160		AL.UI		

# Chapter 2 Contact input/output communication

The device is equipped with a terminal which runs/stops the product. It is also equipped with a terminal which picks up operation signals, alarm signals and setting condition.

The device starts contact input/output communication according to the setting of the operation display panel. Contact input/output communication can be customized by changing the settings. Table 2-1 "Customizable content" shows the contents which can be changed by the operation display panel.

Table 2-1	Customizable	content

Signal	Can be changed
Contact input/output signal (2pcs.)	Signal configuration (Alternate/Momentary)
Contact input/output signal (3pcs.)	Type of signal, signal operation ( N.O type / N.C type )

## 2.1 Precautions for communication

#### 2.1.1 Precautions wiring communication

OCommunication wiring

A communication cable that connects the product and customer system is not included with the product. Please prepare a cable, referring to 2.3 "Terminal block explanation (The connector is included.) In order to avoid malfunction, do not connect to any place other than those shown in 2.3 "Terminal block explanation.

OPower supply

To use the power of the product, the total load current must be 500mA or less.

If the load is 500mA or more, the internal fuse is cut to protect the product and the alarm [AL21 DC line fuse cut] is generated. Refer to the "Installation / Operation" of the operation manual for alarms.

Optional parts needs to be adjusted so that the total load is 500mA or less referring the table below.

Table 2-1-1	Current consumption of optional parts

No.	Name	Part NO	Current consumption
1	Drain pan set(with water leakage sensor)	HRS-WL001	25mA
2	Drain pan set(with water leakage sensor)	HRS-WL002	25mA
3	Electric resistivity sensor set	HRS-DI001	100mA

#### 2.1.2 **Precautions after wiring and before communication**

OCheck or set the communication mode by the operation display panel.

Communication mode shall be DIO.

Other modes can perform reading, but only DIO mode can perform writing.

## 2.2 Communication specification

		ltem	Specification
Connector	type (for	this product)	MC 1,5/12-GF-3,5
Contact	input	Insulation system	Photo coupler
signal		Rated input voltage	DC24V
		Used input voltage	DC 21.6V to 26.4V
		Rated input current	5mA TYP
		Input signal	4.7kΩ
Contact	output	Rated load voltage	AC48V or less/DC30V or less
signal		Maximum load current	AC/DC 500mA (Resistance load)
Output vol	tage		DC24V±10% 0.5A MAX

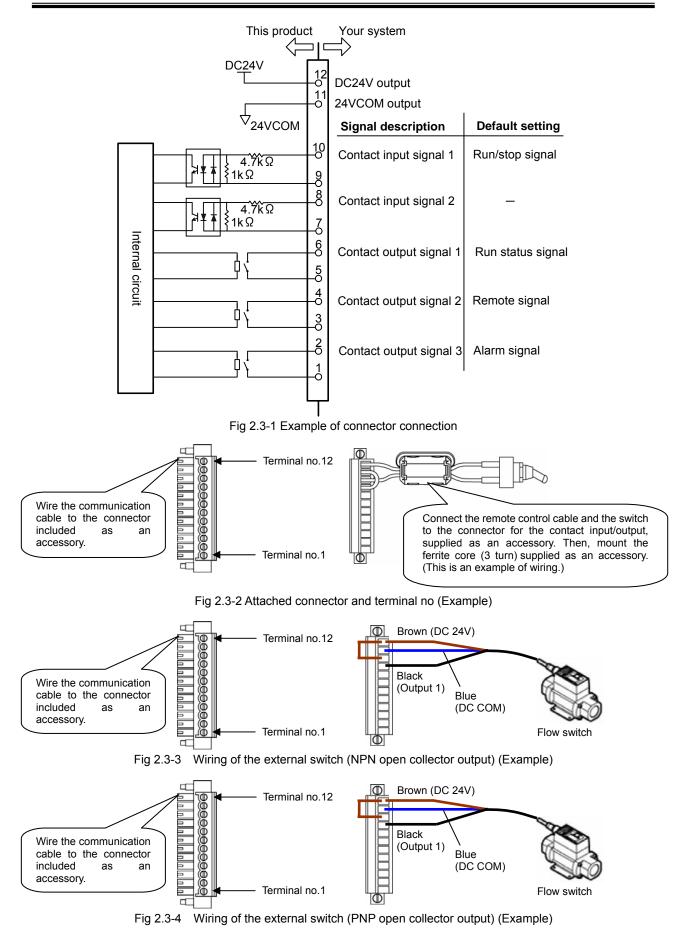
Table 2.2-1 DIO Communication specification

## 2.3 Terminal block explanation

This part explains the terminal block of the contact input/output communication. A communication cable that connects the product and customer system is not included with the product. Prepare a cable, referring to Table 2.3-1 and Fig 2.3-1. Use the connector included as an accessory.

Terminal no	Application	Division	Default setting	Setting available
1	Common of contact output signal 3			
2	Contact output signal 3	Output	Alarm signal (N.C type)	0
3	Common of contact output signal 2			
4	Contact output signal 2	Output	Remote signal (N.O type)	0
5	Common of contact output signal 1			
6	Contact output signal 1	Output	Run status signal (N.O type)	0
7	Common of contact input signal 2			
8	Contact input signal 2	Input	None	0
9	Common of contact input signal 1			
10	Contact input signal 1	Input	Run/stop signal (Alternate)	0
11	24V COM output	Output		
12	DC 24V output	Output		

Table 2.3-1	Terminal explanation
	reminal explanation



2.3 Terminal block explanation

## 2.4 Setting and checking

#### 2.4.1 Setting and checking

The table below explains the setting items of the contact input/output signal and the initial values.

Table 2.4-1List of set communication items

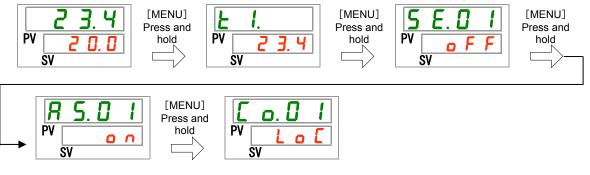
Display	ltem	Contents	Initial value (Default setting)
[ 0.0 ]	Communication mode	Sets communication mode of this product.	LOC
<u>[ o. 15</u>	Contact input signal 1	Setting contact input signal 1 of the contact input/output communication.	RUN
<u>Co. 15</u>	Contact input signal 1 type	Setting input type of contact input signal 1 of the contact input/output communication. [] is displayed when the setting of contact input signal 1 is OFF.	ALT
[0.17]	Contact input signal 1 delay timer of reading	Sets the delay timer of reading of contact input signal 1 of the contact input/output communication. Used when the setting of the contact input signal 1 is SW_A or SW_B.[] is displayed when the setting of the contact input signal 1 is not SW_A or SW_B.	-
[ 0. 18	Contact input signal 1 OFF Detection timer	Sets the OFF detection timer of contact input signal 1 of the contact input/output communication. Used when the setting of the contact input signal 1 is SW_A or SW_B.[] is displayed when the setting of the contact input signal 1 is not SW_A or SW_B.	-
<u>[ o. 19</u>	Contact input signal 2	Setting contact input signal 2 of the contact input/output communication.	OFF
<u>Co.20</u>	Contact input signal 2 type	Setting input type of contact input signal 2 of the contact input/output communication. [] is displayed when the setting of contact input signal 2 is OFF.	ALT
[ 0.2 ]	Contact input signal 2 delay timer of reading	Sets the delay timer of reading of contact input signal 2 of the contact input/output communication. Used when the setting of the contact input signal 2 is SW_A or SW_B.[] is displayed when the setting of the contact input signal 2 is not SW_A or SW_B.	-
[ 0.22	Contact input signal 2 OFF Detection timer	Sets the OFF detection timer of contact input signal 2 of the contact input/output communication. Used when the setting of the contact input signal 2 is SW_A or SW_B.[] is displayed when the setting of the contact input signal 2 is not SW_A or SW_B.	-
[ 0.23	Contact output 1 function	Setting output signal function of contact output 1 of the contact input/output communication.	RUN
[ 0.24	Contact output 1 operation	Setting output signal operation of contact output 1 of the contact input/output communication.	А
[ 0.25	Contact output 1 selected alarm	Setting selected alarm of contact output 1 of the contact input/output communication. [] is displayed when the setting of the output signal of contact output1 is not selected alarm signal.	AL.01
<u> </u>	Contact output 2 function	Setting output signal function of contact output 2 of the contact input/output communication.	RMT
[ 0.27	Contact output 2 operation	Setting output signal operation of contact output 2 of the contact input/output communication.	A
[ 0.28	Contact output 2 selected alarm	Setting selected alarm of contact output 2 of the contact input/output communication. [] is displayed when the setting of the output signal of contact output2 is not selected alarm signal.	AL.01
[ 0.29	Contact output 3 function	Setting output signal function of contact output 3 of the contact input/output communication.	ALM
[ 0.30	Contact output 3 operation	Setting output signal operation of contact output 3 of the contact input/output communication.	В
[ 0.3 ]	Contact output 3 selected alarm	Setting selected alarm of contact output 3 of the contact input/output communication. [] is displayed when the setting of the output signal of contact output3 is not selected alarm signal.	AL.01

#### 2.4.2 Setting and checking

Communication mode Setting and checking

**1.** Press and hold the [MENU] key for 2 sec.

Repeat pressing the key until the setting screen for communication mode [[ . . . . . . . ] appears on the digital display.



**2.** Select [LOC] from the  $[\blacktriangle]$  key , and confirm by pressing "SEL".



Table 2.4-2 List of set values

Set values	Explanation	Initial value (Default setting)
LoE	Sets LOCAL mode.	0
dlo	Sets DIO mode.*1	
SEr	Sets SERIAL mode. *2	

\*1: When the setting of the contact input 1 is "External switch signal", "DIO mode" cannot be set.

\*2: If the serial protocol is "Simple communication protocol 2" and the contact input 1 is "external switch signal" or contact input 2 is "remote signal", "SERIAL mode" cannot be set.

#### CAUTION



If the communication mode is set to [DIO] first while the operating signal is input, the product will start and feed the circulating fluid before the details are set.

For safety, set the communication mode to [DIO] after carrying out the setting below.

Contact input signal1 Setting and checking

**3.** Display the screen of contact input signal 1 by pressing the [SEL] key several times.

The set screen of contact input signal 1 is displayed on the digital display.



4. Select contact input signal 1 from the table below with [▲] key or [▼] key, and confirm by pressing "SEL".

Table 2.4-3	List of set values
-------------	--------------------

Set values	Explanation	Initial value (Default setting)
oFF	Without input signal	
r U n	Input of run/Stop signal	0
5 8 _ R	External switch signal input(N.O. type)*3,*4	
<u>58_</u>	External switch signal input (N.C. type) *3,*4	

\*3: When the setting of the communication mode is "DIO mode", "External switch signal" cannot be set.

\*4: When the setting of the communication mode is "SEIRAL mode" and the protocol setting is "Simplified communication protocol 2", "External switch signal" cannot be set.

Contact input signal 1 type Setting and checking

**5.** Press the [SEL] key once.

The set screen of contact input signal 1 type is displayed on the digital display.



**6.** Select contact input signal 1 type from the table below with [▲] key or [▼] key, and confirm by pressing "SEL".

Table 2.4.4 List of set values

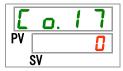
Set values	Explanation	Initial value (Default setting)
	Setting/checking are not available if the setting of contact input signal 1 is OFF.	
ALE	Alternate signal	0
ñŁ	Momentary signal	
ñŁ	Momentary signal <sup>*5</sup>	

\*5: Used when the setting of the contact input 1 is "Operation stop signal input".

Contact input signal 1 delay timer of reading Setting and checking

7. Press the [SEL] key once.

The set screen of the contact input signal 1 delay timer of reading is displayed on the digital display.





Select contact input signal 1 delay timer of reading from the table below with [▲] key or [▼] key, and confirm by pressing "SEL".

	Table 2.4-5 List of set value		
Set value	Explanation	Initial value (Default setting)	
	Setting and checking are not available unless contact input signal 1 is external switch signal input (N.O. type or N.C. type).		
to	Setting of contact input signal 1 delay timer of reading. Set range is 0 to 300 sec.		

Contact input signal 1 OFF detection timer Setting and checking

#### **9.** Press the [SEL] key once.

The set screen of the contact input signal 1 OFF detection timer is displayed on the digital display.



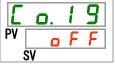
**10.**Select contact input signal 1 OFF detection timer from the table below with [▲] key or [▼] key, and confirm by pressing "SEL".

Set value	Explanation	Initial value (Default setting)
	Setting and checking are not available unless contact input signal 1 is external switch signal input (N.O. type or N.C. type).	
to	Setting of contact input signal 1 OFF detection timer Set range is 0 to 10sec.	

Contact input signal 2 Setting and checking

**11.**Press the [SEL] key once.

The set screen of contact input signal 2 is displayed on the digital display.



**12.**Select contact input signal 2 from the table below with [▲] key or [▼] key, and confirm by pressing "SEL".

Table 2.4-7 List of set values

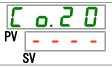
Set values	Explanation	Initial value (Default setting)
oFF	Without input signal	0
r U n	Input of run/stop signal	
5 8 - R	External switch signal input(N.O. type)	
58-6	External switch signal input (N.C. type)	
rñŁ	Remote signal <sup>*6</sup>	

\*6:When the setting of the serial protocol is "Simplified communication protocol 2", "Remote signal" cannot be set.

Contact input signal 2 type Setting and checking

### **13.**Press the [SEL] key once.

The set screen of contact input signal 2 type is displayed on the digital display.



**14.**Select contact input signal 2 type from the table below with [▲] key or [▼] key, and confirm by pressing "SEL".

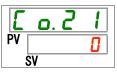
Set values	Explanation	Initial value (Default setting)
	Setting/checking are not available if the setting of contact input signal 2 is OFF.	
RLE	Alternate signal	0
n F	Momentary signal <sup>*7</sup>	

\*7:Can be set when the setting of contact input signal 2 is "Run/Stop signal input" or "Remote signal"

Contact input signal 2 delay timer of reading Setting and checking

**15.**Press the [SEL] key once.

The set screen of contact input signal 2 delay timer of reading is displayed on the digital display.



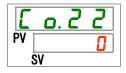
**16.** Select contact input signal 2 delay timer of reading from the table below with [A] key or [V]key, and confirm by pressing "SEL".

Table 2.4–9 List of set values		
Set values	Explanation	Initial value (Default setting)
to 300	Setting of contact input signal 2 delay timer of reading. Set range is 0 to 300 sec.	

Contact input signal 2 OFF detection timer Setting and checking

**17.**Press the [SEL] key once.

The set screen of contact input signal 2 OFF detection timer is displayed on the digital display.



**18.**Select contact input signal 2 OFF detection timer from the table below with [▲] key or [▼] key, and confirm by pressing "SEL".

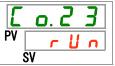
Set values	Explanation	Initial value (Default setting)
	Setting and checking are not available unless contact input singal 2 is external switch signal input(N.O. type or N.C. type).	
to	Setting of contact input signal 2 OFF detection timer. Set range is 0 to 10 sec.	

Table 2.4-10 List of set values

Contact output signal 1 function Setting and checking

**19.**Press the [SEL] key once.

The set screen of contact output signal 1 function is displayed on the digital display.



**20.**Select contact output signal 1 function from the table below with [▲] key or [▼] key, and confirm by pressing "SEL".

Set values	Explanation	Initial value (Default setting)
oFF	Without output signal	
r U n	Signal of operating status is output	0
r ñ Ł	Signal of remote status is output	
r d 4	Signal for completion of preparation (TEMP READY)	
R.SEP	Signal for the status of the operation stop alarm is output	
R.r.U.n	Signal for the status of the operation continue alarm is output	
RLĀ	Signal for the alarm status is output	
R.SEL	Signal for selected alarm status is output	
on.tī	Signal for Run timer set status is output	
oF.Ł n	Signal for Stop timer set status is output	
P.r 5 Ł	Signal for the recovery from power failure is output	
<b>F</b> . <b>P</b> .	Signal for anti-freezing setting is output	
InPl	Pass through signal of contact input signal 1	
1 n P 2	Pass through signal of contact input signal 2	
R.FIL	Signal output during automatic fluid filling	

Table 2.4-11	List of set values

Contact output signal 1 operation Setting and checking

## **21.**Press the [SEL] key once.

The set screen of contact output signal 1 operation is displayed on the digital display.



**22.**Select contact output signal 1 operation from the table below with [▲] key or [▼] key, and confirm by pressing "SEL".

	Table 2.4-12 List of set values	
Set values	Explanation	Initial value (Default setting)
R	N.O type	0
Ь	N.C type	

Contact output 1 selected alarm Setting and checking

**23.**Press the [SEL] key once.

The set screen of digital output 1 selected alarm is displayed on the digital display.



**24.**Select contact output 1 selected alarm from the table below with [▲] key or [▼] key, and confirm by pressing "SEL".

Table 2.4-13 List of set values		
Set values	Explanation	Initial value (Default setting)
	Setting/checking are not available unless the function setting of contact output 1 is selected alarm status signal.	
AL.DI to AL.35	Sets selection alarm. Set range is AL.01 to AL.36.	R L.O I

Contact output 2 function Setting and checking

**25.**Press the [SEL] key once.

The set screen of contact output 2 function is displayed on the digital display.



**26.**Select contact output 2 function from the table below with [▲] key or [▼] key, and confirm by pressing "SEL".

Set values	Explanation	Initial value (Default setting)
oFF	Without output signal	
r U n	Signal of operating status is output	
rñŁ	Signal of remote status is output	0
r d 4	Signal for completion of preparation (TEMP READY)	
R.SEP	Signal for the status of the operation stop alarm is output	
R.r.U.n	Signal for the status of the operation continue alarm is output	
RLĀ	Signal for the alarm status is output	
R.SEL	Signal for selected alarm status is output	
on.tñ	Signal for Run timer set status is output	
oF.E ñ	Signal for Stop timer set status is output	
P.r 5 Ł	Signal for the recovery from power failure is output	
<b>F</b> . <b>P</b> .	Signal for anti-freezing setting is output	
InPl	Pass through signal of contact input signal 1	
1 n P 2	Pass through signal of contact input signal 2	
R.FIL	Signal output during automatic fluid filling	

Table 2.4-14	List of set values
--------------	--------------------

Contact output 2 operation Setting and checking

**27.**Press the [SEL] key once.

The set screen of contact output 2 operation is displayed on the digital display.

28. Select contact output 2 operation from the table below with [▲] key or [▼] key, and confirm by pressing "SEL".

Table 2.4-15	List of set values

Set values	Explanation	Initial value (Default setting)
<b></b>	N.O type	0
Ь	N.C type	

Contact output 2 selected alarm Setting and checking

**29.**Press the [SEL] key once.

The set screen of contact output 2 selected alarm is displayed on the digital display.

**30.** Select contact output 2 selected alarm from the table below with  $[\blacktriangle]$  key or  $[\lor]$  key, and confirm by pressing "SEL".

Set values	Explanation	Initial value (Default setting)
	Setting/checking are not available unless the function setting of contact output 2 is selected alarm status signal.	
A L.O 1 to A L. 3 6	Sets selection alarm. Set range is AL.01 to AL.36.	R L.O I

- . . . . . .

Contact output 3 function Setting and checking

**31.**Press the [SEL] key once.

The set screen of contact output 3 function is displayed on the digital display.



**32.**Select contact output 3 function from the table below with [▲] key or [▼] key, and confirm by pressing "SEL".

Set values	Explanation	Initial value (Default setting)
oFF	Without output signal	
r U n	Signal of operating status is output	
rñŁ	Signal of remote status is output	
r d Y	Signal for completion of preparation (TEMP READY)	
R.SEP	Signal for the status of the operation stop alarm is output	
R.r.U.n	Signal for the status of the operation continue alarm is output	
RLĀ	Signal for the alarm status is output	0
R.SEL	Signal for selected alarm status is output	
on. Eñ	Signal for Run timer set status is output	
oF.E ñ	Signal for Stop timer set status is output	
P.r 5 Ł	Signal for the recovery from power failure is output	
<b>F</b> . <b>P</b> .	Signal for anti-freezing setting is output	
InPl	Pass through signal of contact input signal 1	
1 n P 2	Pass through signal of contact input signal 2	
R.FIL	Signal output during automatic fluid filling	

Contact output 3 operation Setting and checking

## **33.**Press the [SEL] key once.

The set screen of contact output 3 operation is displayed on the digital display.



**34.**Select contact output 3 operation from the table below with [▲] key or [▼] key, and confirm by pressing "SEL".

Table 2.4-18 List of set values

Set values	Explanation	Initial value (Default setting)	
<b>R</b>	N.O type		
Ь	N.C type	0	

Contact output 3 selected alarm Setting and checking

**35.**Press the [SEL] key once.

The set screen of contact output 3 selected alarm is displayed on the digital display.

**36.**Select contact output 3 selected alarm from the table below with [▲] key or [▼] key, and confirm by pressing "SEL".

Set values	Table 2.4-19 List of set values Explanation	Initial value
	•	(Default setting)
	Setting/checking are not available unless the function setting of contact output 1 is selected alarm status signal.	
A L.O 1 to A L. 3 6	Sets selection alarm. Set range is AL.01 to AL.36.	A L.O I

----

Communication mode Setting and checking

**37.**Press the [SEL] key once.

The set screen of communication mode is displayed on the digital display.

confirm by pressing "SEL".

**38.**Select communication mode [DIO] from the table below with  $[\blacktriangle]$  key or  $[\lor]$  key, and

Table 2.4-20	List of set values

Set value	Explanation	Initial value (Default setting)
LoE	Sets LOCAL mode.	0
dlo	Sets DIO mode.	
5 E r	Sets SERIAL mode.	

## 2.5 Contact input signal

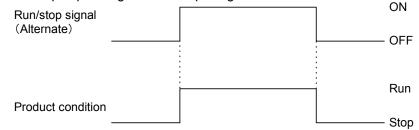
There are two contact input signals. As the default condition, contact input signal 1 is used for run/stop signal (signal type: alternate), and contact input signal 2 is not used. The input signals can be customized depending on the customer's application.

	Class of s	Class of signal		Signal configuration		ner	
	Description	Display	Description	Display	Delay timer of reading	OFF detection	Default setting
	Run/stop	RUN	Alternate	ALT	-	-	0
	signal	Ron	Momentary	MT	-	-	
Contact input	External switch signal input (N.O)	SW_A	Alternate	ALT	Used	Used	
signal 1	External switch signal input (N.C)	SW_B	Alternate	ALT	Used	Used	
	Without intput signal	OFF	_	—	-	-	
	Run/stop	RUN	Alternate	ALT	-	-	
	signal	KON	Momentary	MT	-	-	
Contact input signal 2	External switch signal input (N.O)	SW_A	Alternate	ALT	Used	Used	
	External switch signal input (N.C)	SW_B	Alternate	ALT	Used	Used	
	Remote signal	RMT	Alternate	ALT	-	-	
	i veniote signal		Momentary	MT	-	-	
	Without input signal	OFF	_	_	_	-	0

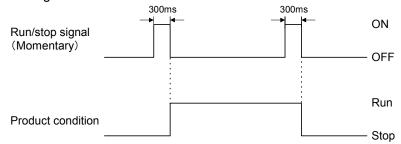
Table 2.5-1 Contact input signal

#### 2.5.1 Run/stop signal · Remote signal

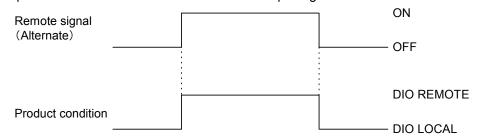
 Run/stop signal (Signal type: Alternate) The product keeps operating while the input signal from the customer is ON.



 Run/stop signal (Signal type: Momentary) The state changes when the input signal from the customer goes OFF. This signal operates while the product is stopped, and stops while the product is being operated. Maintain the ON condition for 300ms or longer.

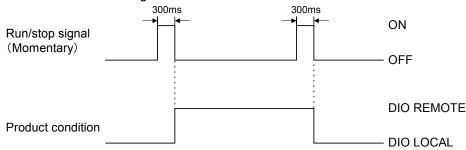


3) Remote signal (Signal type: Alternate) The product becomes DIO REMOTE while the input signal from the customer is ON.

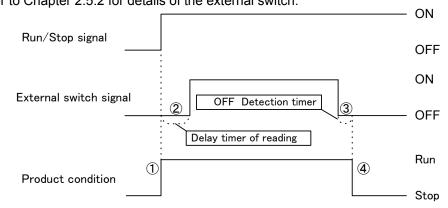


4) Remote signal (Signal type: Momentary)

The state changes when the input signal from the customer goes OFF. If DIO LOCAL is set, it is switched to DIO REMOTE. If DIO REMOTE, it is switched to DIO LOCAL. Maintain the ON condition for 300ms or longer.



 Digital input signal 1 is for Run/Stop signal (Signal type : Alternate), digital input signal 2 is for external switch signal (N.O. type) Refer to Chapter 2.5.2 for details of the external switch.



- 1 The product starts operation when the Run/Stop signal from the user is turned on.
- ② It reads the signal of the external switch signal (N.O type) after the time which has been set for the delay timer of reading.
  - The factory default setting of the delay timer of reading is 0sec. Refer to 2.4.2 for setting. .
- ③ When the external switch signal (N.O. type) has been turned off for the time set for OFF detection timer, it is recognized as OFF.
  The factors defended of the off of the off of the time of the off of the time of the off of the off

The factory default setting of the OFF detection timer is 0sec. Refer to 1.4.2 for setting.

- ④ AL32 contact input 2 signal detection alarm is generated. The operation of the product stops.
   "Operation stop" is the default setting for AL32. The product can be set to continue operation or not to detect the alarm. Refer to the "Installation / Operation" manual for details.
- \* The product stops operation when the Run/Stop signal is turned off during operation. Afterwards, the alarm is not generated even if the external switch signal (N.O type) is turned off.
- Input signal is not connected to either contact input signal 1 or contact input signal 2. This product cannot be controlled by the contact input.
- 7) Remote signal is connected to either contact input signal 1 or contact input signal 2. This product cannot be controlled by the contact input.

#### 2.5.2 Signal of the external switch

This product can be monitored during operation by reading the signal of the external switch prepared by the customer.

The product stops monitoring when it stops operation.

This product generates an alarm and stops operating when a problem is detected from the external switch.

Select the external switch 1 or 2 or both depending on the customer's system. Refer to 2.4.2 for setting.

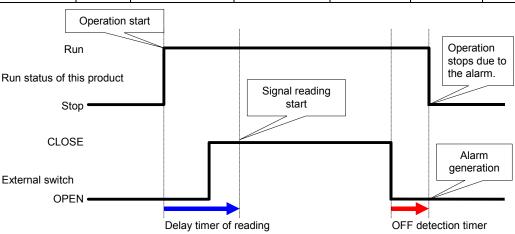
The number of monitored external switches depends on the communication mode. Refer to Table 2.5-2

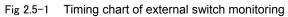
In the communication mode in which the external switches 1 and 2 are available, two products can be monitored simultaneously. If a problem is detected by one or both external switches, an alarm is generated and the operation stops.

You can set the product to continue operation or not to detect the alarm. Refer to the "Installation / Operation" manual for details

		DI	0	SERIAL			
	LOCAL	DIO LOCAL	DIO REMOTE	MODBUS	Sirr commu protoco	nication	
					1	2	
External switch 1	0	×	×	0	0	×	
External switch 2	0	0	0	0	0	0	

Table 2.5-2 Cross reference of communication modes and external switch monitoring





Delay timer of reading

If the signal of the external switch prepared by the customer is not closed instantly when the product is operated, set the delay timer for reading. By setting this timer, the external switch monitoring starts after the time set by the delay time of reading since the operation start.

"0" is the default setting. Set a time which is suitable for your environment.

Example} When using a flow switch

When operation is started, it takes time for the fluid to reach the piping and the flow switch to detect the flow. Set the time for the flow switch to start.

#### ■OFF detection timer

If you do not want the alarm to be generated instantly when the external switch prepared by the customer is in open status, but instead want the alarm to be generated after the switch has been open for a specific time (continuous open status), set the OFF detection timer.

This timer enables the alarm to be generated when the time set for OFF detection time passes after the switch is in OPEN status.

The default setting is 0 sec. Set a time which is suitable for your application.

#### ■Contact input

N.O type or N.C. type can be selected for the external switch. Set the signal which is suitable for the external switch prepared by the customer.

## 2.6 Contact output signal

There are three contact output signals. As the default setting, contact output signal 1 is for operating condition (N.O type), contact output signal 2 is for remote signal (N.O type), and contact output signal 3 is for alarm signal (N.C type). Refer to Table 2-6-1. Depending on the product condition, contact output signal is turned on (closed) or turned off (open).

The signals can be customized depending on the customer's application. The Table 2.6-2 shows operation of contact output signal.

#### [Tips]

All contact output signals are turned off (open) when the power is not supplied.

Table2.6-1 Contact output signal (Default setting)							
	Class of signal		Signal config	Demerke			
	Description	Display	Description	Display	Remarks		
Contact output signal 1	Run status signal	RUN	N.O type	А			
Contact output signal 2	Remote signal	RMT	N.O type	A			
Contact output signal 3	Alarm signal	ALM	N.C type	В			

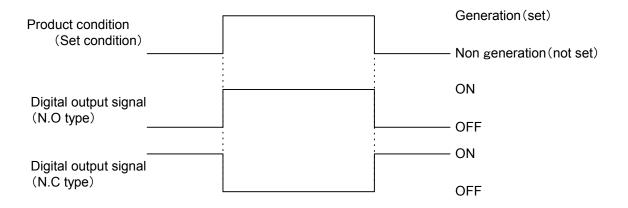


Table 2.6-2 Class of signal			Operation of contact output signal	
Display	Function	Oper ation	Operation of contact output signal	
0.55		N.O type	Normally, output signal is OFF (open)	
OFF	Without output	N.C type	Normally, output signal is ON (close)	
		N.O	When the product operates, signal turns on.	
RUN	Run status signal	type N.C	When the product operates, signal turns off.	
		type N.O	When the product becomes DIO REMOTE, signal turns on.	
RMT	Remote status signal	type N.C	When the product becomes DIO LOCAL, signal turns off.	
RDY	Signal for completion of preparation (TEMP READY)	type N.O type N.C type	When the product becomes completion of preparation (TEMP READY), signal turns on. When the product becomes completion of preparation (TEMP READY), signal turns off.	
A.STP	Signal for operation	N.O	When operation stop alarm occurs, signal turns on.	
A.STP	stop alarm	type N.C type	When operation stop alarm occurs, signal turns off.	
A.RUN	Signal for continuing	Ń.O type	When continuing operation alarm occurs, signal turns on.	
A.RUN	operation alarm	Ń.C type	When continuing operation alarm occurs, signal turns off.	
ALM	Alarm status signal	N.O type	When alarm occurs, signal turns on.	
	Alami status signal	Ń.C type	When alarm occurs, signal turns off.	
A.SEL	Signal for selection	N.O type	The signal is turned ON when the selected alarm goes off.	
A.OLL	alarm	N.C type	The signal is turned OFF when the selected alarm goes off.	
ON.TM	Signal for operation	N.O type	The signal is turned ON when the run timer is set.	
	start timer setting	Ń.C type	The signal is turned OFF when the run timer is set.	
OF.TM	Signal for operation	N.O type	The signal is turned ON when the stop timer is set.	
01.11	stop timer setting	N.C type	The signal is turned OFF when the stop timer is set.	
P.RST	Signal for power	N.O type	The signal is turned ON when the power recovery is set.	
F.N.51	recovery setting	N.C type	The signal is turned OFF when the power recovery is set.	
F.P.	Signal for anti-freezing	N.O type	The signal is turned ON when the anti-freezing is set.	
1.1.	setting	N.C type	The signal is turned OFF when the anti-freezing is set.	
		N.O type	Outputs the signal which is input to the contact input signal. Input signal is $ON \rightarrow Output$ signal is $ON$	
INP1. *1	INP1. *1 Pass through signal of contact input signal 1		Outputs the reverse of the signal which is input to the contact input signal 2. Input signal is OFF $\rightarrow$ Output signal is ON	
			Outputs the signal which is input to the contact input signal. Input signal is $ON \rightarrow Output$ signal is $ON$	
INP2 <sup>*1</sup>	Pass through signal of contact input signal 2	type N.C type	Outputs the reverse of the signal which is input to the contact input signal 2. Input signal is OFF $\rightarrow$ Output signal is ON	
	Signal output during	N.O type	Signal is turned ON during automatic fluid filling.*2	
A.F.	automatic fluid filling	N.C type	Signal is turned OFF during automatic fluid filling. *2	

 Table 2.6-2
 Operation of contact output signal

\*1: The signal of the product without an option [Automatic filling] also changes.

\*2: Signal changes even when option J [Automatic fluid filling] is not selected.

# **Chapter 3 Serial communication**

Serial communication (RS-485/RS232C) enables the remote control of run/start of the product, temperature setting and details of product condition, and alarm condition can be obtained.

The operating state of the product (run/stop) and the temperature setting can be monitored by sending a request message made by the program of the host computer (e.g. PC).

MODBUS communication and simple communication protocol can be selected as the serial communication protocol. This chapter illustrates the common specifications of serial communication. Chapter 4 and 5 illustrate each protocol.

#### **Precautions wiring communication** 3.1

OCommunication wiring

A communication cable that connects the product and customer system is not included with the product. Please prepare a cable, referring to 3.3 "Connected explanation" In order to avoid malfunction, do not connect to any place other than those shown in 3.3 "Connected explanation".

## 3.2 Communication specification

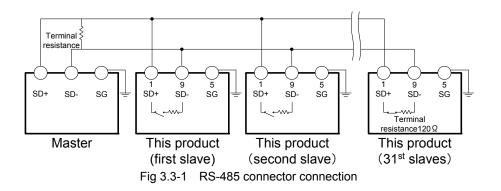
Table 3.2-1 Serial communication specification				
Item	Specification			
Connector type (for the product)	D-sub9P type Female connector			
Standard	Select from EIA RS-485 / RS-232C			
Circuit type Half duplex	Half duplex			
Transmission type	Start-stop			
Protocol	MODBUS terminal <sup>*1</sup> / Simple communication protocol			
Terminal resistance	Select from with terminal resistance (120 $\Omega$ ) /Without terminal			
	resistance			

: Default setting

\*1 : Refer to Modicon Co. protocol specifications "PI-MBUS-300 Rev.J".

## 3.3 Connected explanation

Fig 3.3-1 shows the wiring when RS-485 is selected as the communication standard. Fig 3.3-2 shows the wiring when RS-232C is selected. A communication cable that connects the product and customer system is not included with the product. Prepare a cable, referring to Fig 3.3-1 or Fig 3.3-2.

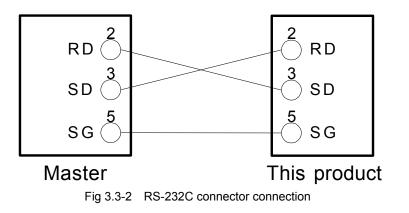


#### 【Tips】

• 1 master : 1 product, or 1 master: N products.

In the latter case, up to 31 products can be connected.

- Both ends of the communication connection (the end nodes) need to be connected to the higher level computer.
- The terminal resistance of this product can be set by the operation display panel. Refer to '4.3.2 Setting and checking'', '5.3.2 Setting and checking''.



# Chapter 4 MODBUS communication function

MODBUS protocol is a communication protocol developed by Modicon. It is used to communicate with a PC or PLC.

Register content is read and written by this communication protocol.

This communication has the following features.

- · Controls run/stop.
- · Sets and reads the circulating fluid set temperature.
- · Reads the circulating fluid discharge temperature.
- Reads the condition of the product.
- Reads the alarm generating condition of the product.

Refer to "4.10 Register Map" for the register of the product.

#### 4.1 **Precautions for communication**

#### 4.1.1 **Precautions after wiring and before communication**

OCheck or set the each communication setting by the operation display panel.

• The communication specification shall be the customer's communication standard.

- The serial protocol shall be the MODBUS.
- The communication mode shall be the SERIAL mode.

Other modes can perform reading, but only SERIAL mode can perform writing.

OCheck or set the communication parameters using the operation display panel.

Check or set the communication speed so that the product synchronizes with the host computer (master) prepared by the customer.

OCheck the slave address by the operation display panel.

No response is returned when a request message is sent from a slave address other than those set in the product.

#### 4.1.2 Precautions for communicating

OAllow a suitable interval between requests.

To send request messages in series, wait for 100 msec. or longer after receiving a response message from the product before sending the next message.

ORetry (resend request message).

The response may not be returned due to noise. If no message is returned 1sec. after sending a request message, resend the request message.

Olf necessary send a read request message to check if it was written correctly.

Message to notify the completion of the process is returned when the action for the written request message is completed.

Send a read request message to confirm if the setting was written as requested.

OSetting limit of circulating fluid temperature

When the circulating fluid set temperature is written by communication, the data is stored in FRAM. When the product restarts, it restarts with the value which was set before the restart. The number of times it is possible to overwrite FRAM is limited. Data is only stored in FRAM when it receives a circulating fluid set temperature which is different from the previous temperatures. Please check how many times it is possible to overwrite FRAM, and avoid unnecessary changes of the circulating fluid set temperature during communication

## 4.2 Communication specification

Table 4.2-1 Comm	nunication specification of MODBOS communication function
Item	Specification
Standard	Select from EIA RS-485 / RS-232C
Communication speed	Select from 9600bps / 19200bps
Data • bit length	7bit
Stop • bit length	1bit
Data transfer direction	LSB
Parity	Even parity
Letter code	ASCII mode
Slave address set range	Select from 1 to 99 address
Error check	LRC method

 Table 4.2-1
 Communication specification of MODBUS communication function

: Default setting

## 4.3 Setting and checking

## 4.3.1 Setting and checking items

The table below explains the setting items of the MODBUS communication function and the initial values.

Display	ltem	Contents	Initial value (Default setting)
[ 0.0 ]	Communication mode	Sets communication mode of this product.	LOC
<u> </u>	Serial protocol	Sets serial communication protocol.	MDBS
<u> </u>	Communication specification	Sets standard of the serial communication.	485
<u> </u>	RS-485 terminal	Sets of the terminal of RS-485.	OFF
<u> </u>	Slave address (MODBUS)	Sets slave address of MODBUS protocol. [] is displayed when the setting of serial protocol is not MODBUS.	1
<u>Co.05</u>	Communication speed (MODBUS)	Sets communication speed of MODBUS protocol. [] is displayed when the setting of serial protocol is not MODBUS.	19.2

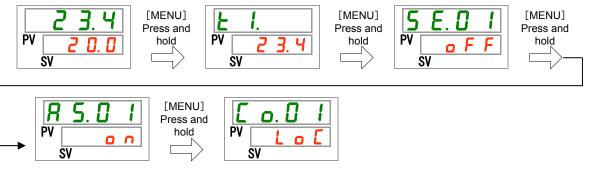
Table 4.3-1	Communication setting items
	Communication Setting items

#### 4.3.2 Setting and checking

Communication Setting and checking

**1.** Press and hold the [MENU] key for 2 sec.

Repeat pressing the key until the setting screen for communication mode [[...]] appears on the digital display.



**2.** Select "SER" from the table below with the  $\blacktriangle$ key, and confirm with "SEL".



Table 4.3-2 List of set values

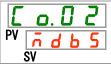
Set values	Explanation	Initial value (Default setting)
Lo[	Sets LOCAL mode.	0
dlo	Sets DIO mode.	
SEr	Sets SERIAL mode. *1	

\*1: If the serial protocol is "Simple communication protocol 2" and the contact input 1 is "external switch signal" or contact input 2 is "remote signal", "SERIAL mode" cannot be set.

Serial protocol Setting and checking

**3.** Press the [SEL] key once.

The set screen of serial protocol is displayed on the digital display.



**4.** Select serial protocol from the table below with [▲] key or [▼] key, and confirm by pressing "SEL".

	Table 4.3-3 List of set values									
Set values	Explanation	Initial value (Default setting)								
ndb 5	MODBUS protocol	0								
Prol	Simple communication protocol 1									
Pro2	Pro2 Simple communication protocol 2 <sup>*2</sup>									
*2 : When t	2: When the setting of the contact input 2 is "Remote signal". "Simplified									

communication protocol 2" cannot be set.

Communication specification Setting and checking

**5.** Press the [SEL] key once.

The set screen of communication specification is displayed on the digital display.



6.

Select communication specification from the table below with  $[\blacktriangle]$  key or  $[\nabla]$  key, and confirm by pressing "SEL".

Table 4.3-4 List of set values									
Set values	values Explanation Initial (Default								
3262	RS-232C standard								
485	RS-485 standard	0							

RS-485 terminal Setting and checking

7. Press the [SEL] key once.

The set screen of RS-485 terminal is displayed on the digital display.



**8.** Select RS-485 terminal from the table below with [▲] key or [▼] key, and confirm by pressing "SEL".

Table 4.3-5 List of set values

Set values	Explanation	Initial value (Default setting)
oFF	Without terminal	0
0 0	With terminal	

Slave addresses (MODBUS) Setting and checking

**9.** Press the [SEL] key once.

The set screen of slave addresses (MODBUS) is displayed on the digital display.



**10.**Select slave addresses (MODBUS) from the table below with [▲] key or [▼] key, and confirm by pressing "SEL".

Table 4.3-6 List of set values								
Set values	Explanation	Initial value (Default setting)						
	Setting/checking are not available unless the serial protocol setting is MODBUS.							
- 1 ~ 99	Sets of slave addresses for MODBUS. Set range is 1 to 99.	1						

Communication speed (MODBUS) Setting and checking

### **11.**Press the [SEL] key once.

The set screen of communication speed (MODBUS) is displayed on the digital display.

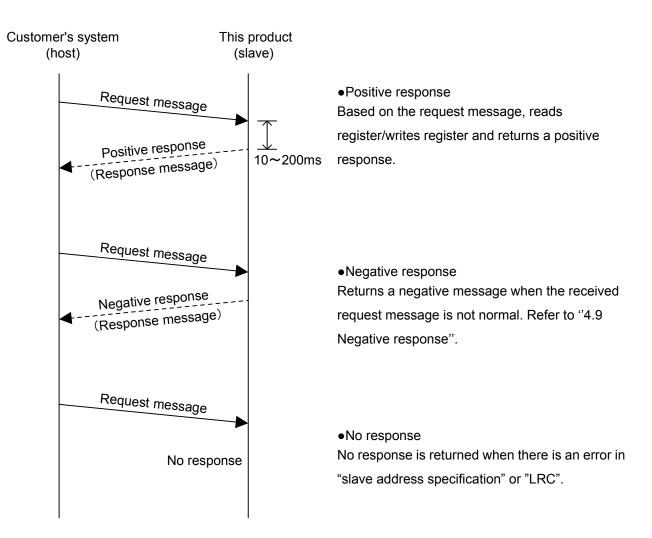


12.Select communication speed (MODBUS) from the table below with [▲] key or [▼] key, and confirm by pressing "SEL".

Table 4.3-7 List of set values								
Set values	Explanation	Initial value (Default setting)						
	Setting/checking are not available unless the serial protocol setting is MODBUS.							
9. 6	9600bps							
19.2	19200bps	0						

### 4.4 Communication sequence

Starts with a request message from the customer's system (host), and finishes with a response message from the product (slave). This product operates as a slave. It does not send any requests.



### 4.5 Message configuration

### 4.5.1 Message format

The message configuration is shown below. This product communicates in ASCII mode. ASCII mode is used from Start to End.

1)	2)		3)		4)			5)		6)	
Start	Slave A	ddress	Fund	ction		Data		LF	RC 05	Er	nd
[:]	XX	XX	XX	XX	XX	~	XX	XX	XX	[CR]	[LF]

1) Start

The start of the message. [:](3Ah)

2) Slave Address (1 to 99 3031h to 3939h)

This is a number to identify this product. "1" is the default setting. This can be changed by the operation display panel.

3) Function (Refer to "4.6 Function codes".)

Command is assigned.

4) Data

Depending on the function, the address and the number of the register, the value of reading/writing are assigned.

5) LRC

LRC method

Refer to "4.7 LRC".

6) END

The end of the message. [CR](0Dh)+[LF](0Ah)

A response message will not be returned unless the request includes [:] and [CR][LF]. This product clears all previously received code when [:] is received.

### 4.5.2 Message example

The example shows communication with the conditions below.

OSlave Address: No.1

ORead seven consecutive data from register 0000h.

(Read circulating fluid discharge temperature.)

### Communication example

### CAUTION



The communication example is expressed in hexadecimal value with []. The actual communication is performed in ASCII code. Refer to the request / response message in this section.

#### Your system

(Request): 01030000001FB [CR][LF]

(Response): 01030200EE0C [CR][LF]

#### This product

Data is sent and received in ASCII code.

	Request message	Response message			
Code	Contents	Code	Contents		
01	Slave Address	01	Slave Address		
03	Function	03	Function		
0000	Head address of specified register	02	Quantity of bytes to read		
0001	Quantity of register to read	00EE	Information of 0000h (circulating fluid discharge temperature: 23.8 °C)		
FB	LRC	0C	LRC		

### Request message (Master to Slave)

Start	Slave A	ddress	Fun	ction	Data	LF	RC	Ei	nd
3A	30	31	30	33		46	42	0D	0A
				/		/			

	-						<u> </u>
	Read A	ddress		(	Quantity	to Rea	d
	Hi	: L	0	F	li	: L	.0
30	30	30	30	30	30	30	31

### Response message (Slave to Master)

Start	Slave Address		Fun	ction	Data	LI	RC	Er	nd
3A	30	31	30	33		30	43	0D	0A

Byte (	Count		Read Data1				
Dyte	oount	F	łi	Lo			
30	32	30	30	45	45		

### 4.6 Function codes

Table 4.6-1 shows function codes to read or write register.

NO	Code	Name	Function							
1	03(03h)	Read holding registers	Reading multiple registers							
2	06(06h)	Preset single register	Writing registers <sup>*1</sup>							
3	16(10h)	Preset multiple registers	Writing multiple registers							
4	23(17h)	Read/write 4x registers	Reading/writing multiple registers							

Table 4.6-1 Function codes

\*1 : Broadcast is not supported.

### 4.7 LRC

LRC checks the content of the message other than [:] of START and [CR][LF] of END. The sending side calculates and sets. The receiving side calculates based on the received message, and compares the calculation result with the received LRC. The received message is deleted if the calculation result and received LRC do not match.

Add up the byte number of the message consisting of 8 consecutive bits. The result except the carry (overflow) is converted to 2's complement.

### ■ Calculation example

0106000B00FE
OAddition
01h+06h+00h+0Bh+00h+FEh=110h
OObject
110h→10h
Ocomplement of 2
10h→EFh→F0h
LRC is F0h
[:]0106000B00FEF0[CR][LF]

### 4.8 Explanation of function codes

### 4.8.1 Function code : 03 Reading multiple registers

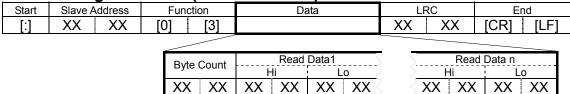
Register data of assigned points from assigned address is read.

### Request message <Normal> (Master to Slave)

Start	Slave A	Slave Address Function		ction	Data	LF	RC	Ei	nd
[:]	XX	XX	[0]	[3]		XX	XX	[CR]	[LF]
			_				/		

$\leq$							$\sim$	
	Read A	ddress		(	Quantity	to Rea	d	
Hi Lo				F	li	Lo		
XX	XX	XX	XX	XX	XX	XX	XX	

### Response message<Normal> (Slave to Master)



### Communication example

OSlave Address: No.1

ORead seven consecutive data from register 0000h.

(Read circulating fluid discharge temperature, circulating fluid discharge pressure, status information, alarm information.)

Your s	ystem This p	roduc	t
	(Request):01030000007F5 [CR][LF]		Data is sent and received in ASCII code.

	Request message		Response message
Code	Contents	Code	Contents
01	Slave Address	01	Slave Address
03	Function	03	Function
0000	Head address of specified register	0E	Quantity of bytes to read
0007	Quantity of register to read	00D4	Information of 0000h (circulating fluid discharge temperature)
F5	LRC	0000	Information of 0001h (Reserved)
		000D	Information of 0002h (circulating fluid discharge pressure)
		0000	Information of 0003h (Reserved)
		0201	Information of 0004h (Status flag)
		0000	Information of 0005h (Alarm flag 1)
		0000	Information of 0006h (Alarm flag 2)
		0A	LRC

### 4.8.2 Function code : 06 Writing registers

Write data to assigned address.

### Request message <Normal> (Master to Slave)

	U									
Start	art Slave Address Fun		Function Data		ata	LRC		End		
[:]	XX	XX	[0]	[6]			XX	XX	[CR]	[LF]
								_		
Write			Write A	ddress	Write	Data				
				ц; і		Ц; ч	10			

#### Response message <Normal> (Slave to Master)

۰.						/					
	Start	Slave A	ddress	Function		Data		LRC		End	
	[:]	XX	XX	[0]	[6]		XX XX		[CR]	[LF]	
				_				/	_		

	Write A	ddress		Write Data					
F	li	L	0	ŀ	li	Lo			
XX	XX	XX	XX	XX	XX	XX	XX		

XX XX XX XX XX XX XX XX

### Communication example

OSlave Address: No 1

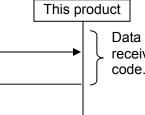
OWrite data to register 000Ch

(Commands to run)

Your system

(Request):0106000C0001EC [CR][LF]

(Response):0106000C0001EC [CR][LF]



Data is sent and received in ASCII code.

	Request message	Response message				
Code	Contents	Code	Contents			
01	Slave Address	01	Slave Address			
06	Function	06	Function			
000C	Address of specified register	000C	Address of register to write			
0001	Information written to 000Ch (Stop flag)	0001	Information of register to write			
EC	LRC	EC	LRC			

### 4.8.3 Function code : 16 Writing multiple registers

Register content of assigned points of assigned address is written.

#### Request message <Normal> (Master to Slave)

	<u> </u>								
Start	Slave Address		Slave Address Function		Data	LF	RC	Er	nd
[:]	XX	XX	[1]	[0]		XX	XX	[CR]	[LF]

	Write A	ddress		Quantity to Write					
H	li	L	0	ŀ	li	Lo			
XX	XX	ΧХ	ΧХ	ΧХ	XX	ΧХ	XX		

Byte	Count		Write	Data1		5 5		Write	Data n	
Dyte	Byte Count		Hi		Lo		۲ F	li	L	0
XX	XX	XX	XX	XX	XX	3 3	XX	XX	XX	XX

### ■ Response message <Normal> (Slave to Master)

Start	Slave A	ddress	Fun	ction	Data	LF	RC	Er	nd
[:]	XX	XX	[1]	[0]		XX	XX	[CR]	[LF]
						/			

ſ	Write A	ddress		(	Juantity	to Write	е	
H	li	L	0	F	li	Lo		
XX	XX	XX	XX	XX	XX	XX	XX	

### Communication example

OSlave Address: No 1

OWrite two consecutive data from register 000Bh.

(Commands to change of circulating fluid set temperature <39.9 °C > and run.)

Your s	system	This p	roduct
	(Request):0110000B000204018F00014D [CR][LF] (Response):0110000B0002E2 [CR][LF]		Data is sent and received in ASCII code.

	Request message	Response message				
Code	Contents	Code	Contents			
01	Slave Address	01	Slave Address			
10	Function	10	Function			
000B	Head address of specified register	000B	Head address of register to write			
0002	Quantity of register to write	0002	Quantity of register to write			
04	Quantity of byte to read	E2	LRC			
018F	Information written to 000Bh (Circulating fluid set temperature)					
0001	Information written to 000Ch (Stop flag)					
4D	LRC					

### 4.8.4 Function code : 23 Reading/writing multiple registers

Register content of assigned points of assigned address is read. Write the register data from the specified address with specified points simultaneously.

### Request message <Normal> (Master to Slave)

Start	Slave A	Address	Fund	ction	Data	LF	RC	Er	nd
[:]	XX	XX	[1]	[7]		XX	XX	[CR]	[LF]
							_		

Read Address         Quantity to Read         Write Address         Quantity to Write           Hi         Lo         Hi         Lo			
Hi Lo Hi Lo Hi Lo Hi Lo Hi L	Quantity to Write		
	5 C		
XX	XX		

	Byte (	Count	Write Data1					2	Write	Data n	
	Byte obuiit		Hi		Lo S			S Hi		Lo	
Ş	XX	XX	XX	XX	XX	XX		∑ XX	XX	XX	XX

### ■ Response message <Normal> (Slave to Master)

Start	Slave A	Address	Fur	iction	Data	LF	RC	Ei	nd
[:]	XX	XX	[1]	[7]		XX	XX	[CR]	[LF]

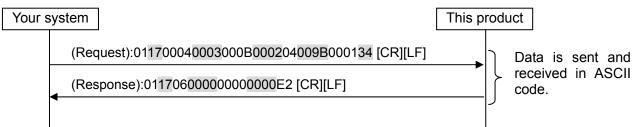
										_
Byte Count			Read	Data1		Read Data				
Byte	Count	H	li	Ĺ	o 🤇		F	li	L	0
XX	XX	XX	XX	XX	XX S	(	XX	XX	XX	
										_

### Communication example

OSlave Address: No 1

ORead three consecutive data from register 0004h, and write two consecutive data from register 000Bh.

(Command to change the circulating fluid set temperature to <15.5  $^{\circ}\text{C}$ >, and read status and alarm information.)



	Request message		Response message
Code	Contents	Code	Contents
01	Slave Address	01	Slave Address
17	Function	17	Function
0004	Head address of specified register	06	Quantity of byte to read
0003	Quantity of register to read	0000	Information of 0004h (Status flag)
000B	Head address of specified register	0000	Information of 0005h (Alarm flag 1)
0002	Quantity of register to write	0000	Information of 0006h (Alarm flag 2)
04	Quantity of byte to write	E2	LRC
009B	Information written to 000Bh (Circulating fluid set temperature)		
0001	Information written to 000Ch (Stop flag)		
34	LRC		

### 4.9 Negative response

A negative response is returned when the following request message is received.

- 1) When unspecified function code is used.
- 2) An address out of range is specified.
- 3) The data field is not normal.

#### Negative response message (Slave to Master)

				1)		2)					
Sta	art	Slave A	ddress	Fun	ction	Error	Code	LF	SC 35	E	nd
[:	]	XX	XX	[0]	[3]	XX	XX	XX	XX	[CR]	[LF]

#### 1) Function

Assign the value consisting of the request function code (hexadecimal value) plus 80h in ASCII code.

2) Error Code

Assign error code below.

- 01 : Function code of a command is outside the standard
- 02 : The specified address of register is outside the range.
- 03 : Data field of a command is not normal.

#### Communication example

OSlave Address: No 1

ORead seven consecutive data from register 0100h which is out of range.

Your	system	This produ	uct
	(Request):010301000007F4 [CR][LF] (Response):0183027A [CR][LF]	<b>}</b>	Data is sent and received in ASCII code.

	Request message	Response message		
Code	Code Contents		Contents	
01	Slave Address	01	Slave Address	
03	Function	83	Function (03h+80h)	
0100	Head address of register out of range	02	Error Code (Specified register address is out of range.)	
0007	Quantity of register to read	7A	LRC	
F4	LRC			

### 4.10 Register Map

A	Bit Format	
Address	15 14 13 12 11 10 9 8 7 6 5 4 3 2 1 0	- R/W
0000h	Circulating fluid discharge temperature-110.0 to $150.0^{\circ}C = FBB4h$ to $5DCh$ $(0.1 \circ C / dig)$ -166.0 to $302.0 \circ F = F984h$ to BCCh $(0.1 \circ F / dig)$	
0001h	Reserved	
0002h	Circulatingfluiddischarge0.00 to 3.00MPa = 0h to 12Ch(0.01MPa/dig)pressure0 to 435PSI = 0h to 1B3h(1PSI/dig)	]
0003h	Electric resistivity of the 0 to $4.5M\Omega \cdot cm = 0h$ to $2dh (0.1M\Omega \cdot cm / dig)$ circulating fluid	
0004h	Status flag	R
0005h	Alarm flag 1	
0006h	Alarm flag 2	
0007h	Alarm flag 3	
0008h	Reserved	
0009h	Reserved	
000Ah	Reserved	
000Bh	Circulating temperature         fluid         set $5.0$ to $40.0$ °C = 32h to 190h $(0.1$ °C /dig) $41.0$ to $104.0$ °F = 19Ah to $410h$ $(0.1$ °F /dig)	
000Ch	Reserved *1	
000Dh	Reserved	R/W
000Eh	Reserved	
000Fh	Reserved	

\*1 : Commands to run

### 4.10.1 Circulating fluid discharge temperature

Read the circulating fluid discharge temperature in the selected temperature unit (°C or °F). Read the circulating fluid discharge temperature which is displayed on the operation display panel PV. (Offset temperature is displayed if offset function is set).

### 4.10.2 Circulating fluid discharge pressure

Read the circulating fluid discharge pressure in the selected pressure unit (MPa or PSI).

### 4.10.3 Electric resistivity of the circulating fluid

Electric resistivity (DI level) of the circulating fluid is informed. The value is 0 M $\Omega$  ·cm when the optional [Electric resistivity sensor] is invalid.

### 4.10.4 Status flag

Name	Status flag							
Bit	15 14 13 12 11 10	9 8 7 6 5 4 3 2 1 0						
	· · · · · · ·							
Bit	Name	Explanation						
0	Run flag	Run status (Include the independent operation of the pump) 0= Stop 1=Run						
1	Operation stop alarm flag	Operation stop alarm given off status 0= Not occurred 1= Operation stop alarm given off						
2	Operation continued alarm flag Operation continued alarm given off status 0= Not occurred 1= Operation continued alarm given off							
3	Unused	<u>v</u>						
4	Press Unit flag Pressure unit set status 0=MPa 1=PSI							
5	Remote status flag	Remote status 0= Other than SERIAL mode 1=SERIAL mode						
6	Unused							
7	Unused							
8	Unused							
9	Completion of preparation (TEMP READY) flag	Completion of preparation (TEMP READY) status 0= Condition isn't formed 1= Condition is formed						
10	Temperature unit flag	Temperature unit set status 0= Centigrade (°C) 1= Fahrenheit (°F)						
11	Run timer flag	Run timer set status 0=Not set 1= Set						
12	Stop timer flag	Stop timer set status 0= Not set 1=Set						
13	Reset after power failure flag	Peset after power failure set status						
14	Anti-freezing flag	Anti-freezing set status 0= Not set 1= Set						
15	Automatic fluid filling flag       0= Not set 1= Set         Automatic fluid filling flag       Automatic fluid filling condition         0= Stop 1= Fluid       * The signal of the product without an option [Automatic filling] also changes.							

The status of the product is read by the following assignment.

### 4.10.5 Alarm flag

				n type gnme		larm	which	n occur	s in th	ne p	roduc	ct is r	ead w	ith th	e foll	owing	g
Na	me	Alarm flag 1															
Bit		15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Na	ime							A	arm fl	lag	2						
Bit		15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Na	ime							A	arm fl	lag :	3						
Bit		15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	Bit				Nam	е						Ex	plana	ation			
	0	Low	level i	n tanl													
	1	High	circul	ating	fluid d	ischa	rge te	mp.	1								
	2		ulating						]								
	3		ulating						]								
	4		circul						]								
	5						ge pr	essure	]								
	6		ormal						]								
<u>⊿</u>	7							re rise									
Alarm flag	8	drop						essure									
ag	9		comp														
-	10		comp														
	11		super														
	12		comp	resso	r disc	narge	press	sure									
	13 14		geran		cuit	pres	sure	(high	1								
	15	Refri	sure s geran sure s	t ci	rcuit	pres	sure	(low									
	0	Refri	geran sure s	t ci	rcuit	pres	sure	(low									
	1		press						0= N	lot o	ccurre	ed 1	= Occ	urred			
	2		munic						1								
	3		ory ei		5				1								
	4		ne fus						1								
	5		ulating		discha	arge te	emp.	sensor									
Alarm flag	6	failur	e				-	sensor	r								
З	7							failure	_								
flag 2	8	sens	or fail	ure		-	-	essure	Dr								
2	9	failur	e		-	-		sensor									
	10	failur	e			press	ure	sensor	-								
	11		tenan			-1			-								
	12		tenan						-								
	13		tenan					lorne	4								
	14		act in						{								
	15	Cont	act in	Jul Z	signal	uetec	aion a	lidiiii	L								

#### HRX-OM-M091 Chapter 4 MODBUS communication function

	Bit	Name	Explanation
	0	Water leakage	
	1	DI level rise	
	2	DI level drop	
	3	DI sensor error	
	4	Unused	
⊳	5	Unused	
Alarm	6	Unused	
Ľ.	7	Unused	Alarm given off status
flag	8	Unused	0= Not occurred 1= Occurred
	9	Unused	
ω	10	Unused	
	11	Unused	
	12	Unused	
	13	Unused	
	14	Unused	
	15	Unused	

The current alarm flag bit assignment will be changed in the future due to the addition of

optional functions.

Unused bit is fixed to 0.

### 4.10.6 Circulating fluid set temperature

The circulating fluid set temperature can be set by specifying the circulating fluid set temperature with the selected temperature unit (°C or °F) during SERIAL mode.

If the temperature exceeds the upper limit of the circulating fluid set temperature range, the circulating fluid set temperature is changed to the upper limit value. If it is lower than the lower limit, the circulating fluid set temperature is changed to the lower limit value.

### 4.10.7 Operation Start Command

The operation can be controlled by sending the operation start command during SERIAL mode.

0=Run stop 1=Run start

# Chapter 5 Simple communication protocol function

Data can be read / written by this communication protocol. This protocol complies with SMC thermo-cooler HRG, HRGC series.

This communication has the following features.

- Sets and reads the circulating fluid set temperature.
- · Reads the circulating fluid discharge temperature.

### **5.1** Precautions for communication

### 5.1.1 Precautions after wiring and before communication

OCheck or set each communication setting by the operation display panel.

- The communication specification shall be the customer's communication standard.
  - The serial protocol shall be the simple communication protocol 1 or 2.

Simple communication protocol 1: Operation display panel controls the start and stop of the product.

Simple communication protocol 2: Controls the start and stop of the product remotely.

Refer to chapter 2.4 for remote setting when this protocol is selected.

• The communication mode shall be the SERIAL mode.

Other modes can perform reading, but only SERIAL mode can perform writing of values.

OCheck or set the communication parameters using the operation display panel.

Check or set the communication speed, the presence of BCC, data length, parity check, stop bit length, response delay time, and communication range (RO or RW) to synchronize the product with the host computer (master) prepared by the customer.

OCheck the slave address of this product.

No response is returned when a request message is sent from a slave address other than those set in the product.

### 5.1.2 Precautions for communicating

OCheck the data digit number and the decimal point location when requesting to write the set value.

OAllow a suitable interval between requests.

To send request messages in series, wait for 100msec. or longer after receiving a response message from the product before sending the next message.

 $\circ \text{No}$  response is returned for a request message of a command which is not supported by the product.

ORetry (resend request message).

The response may not be returned due to noise. If no message is returned after 1sec. of sending a request message, resend the request message.

Olf necessary send a read request message to check if it was written correctly.

Message to notify the completion of the process is returned when the action for the written request message is completed.

### 5.1.3 **Precautions after the completion of the communication**

OSend the data storage request (STR) if necessary.

Data which is set by communication is stored in RAM. Set values stored in RAM are deleted when the power supplied to the product is cut. When the power is supplied again, operation starts with the values set before communication (values stored in FRAM of the product).

Store the values set by communication in FRAM (rewrite FRAM) by sending a data storage request message (STR) before cutting the power supply to the product.

Please check how many times it is possible to write to FRAM, and avoid unnecessary rewriting of the data during communication

### 5.2 Communication specification

Item	Specification
Standard	Select from EIA RS-485/RS-232C
Communication speed	Select from 1200bps/2400bps/4800bps/9600bps/19200bps
Data · bit length	Select from 7bit/8bit
Stop · bit length	Select from 1bit、2bit
Parity	Select from without parity, odd number, even number
Letter code	ASCII mode
Slave address set range	Select from 1 to 99
Response delay time setting	Select from 0 to 250[msec]
Communication range	RO(Can read data only),
Communication range	Select from RW(can read and write data)
BCC	Select from with BCC, without BCC
Error check	EXOR algorithm of all data from STX to ETX is read only when BCC
EITOI CHECK	is selected.

 Table 5.2-1
 Communication specification of simple communication protocol

: Default setting

### 5.3 Setting and checking

### 5.3.1 Setting and checking items

The table below explains the setting items of the simple communication protocol function and the initial values.

Initial value					
Display	ltem	Contents	(Default setting)		
<u>[ o.0  </u>	Communication mode	Sets communication mode.	LOC		
<u> </u>	Serial protocol	Sets serial communication protocol.	MDBS		
[ 0.0 ]	Communication specification	Sets standard of the serial communication.	485		
<u> </u>	RS-485 terminal	Sets of the terminal of RS-485.	OFF		
[ 0.07	Slave address (Simple communication protocol)	Sets slave address of simple communication protocol. [] is displayed when the setting of serial protocol is not simple communication protocol.	1		
<u>[ o.0 8</u> ]	Communication speed (Simple communication protocol)	Sets communication speed of simple communication protocol. [] is displayed when the setting of serial protocol is not simple communication protocol.	9.6		
[ 0.0 9	BCC (Simple communication protocol)	Sets error detection code of communication of simple communication protocol. [] is displayed when the setting of serial protocol is not simple communication protocol.	ON		
<u>[ o. 10</u>	Data length (Simple communication protocol)	Sets data length. [] is displayed when the setting of serial protocol is not simple communication protocol.	8BIT		
<u>[ o. 1 1</u>	Parity check (Simple communication protocol)	Sets parity check. [] is displayed when the setting of serial protocol is not simple communication protocol.	NON		
[ 0. 12	Stop bit length (Simple communication protocol)	Sets bit length. [] is displayed when the setting of serial protocol is not simple communication protocol.	2BIT		
<u>[ o. 13</u>	Response delay time (Simple communication protocol)	Sets time to delay the response message of simple communication protocol. [] is displayed when the setting of serial protocol is not simple communication protocol.	0		
<u>[ o. 14</u> ]	Communication range (Simple communication protocol)	Sets communication range of simple communication protocol. [] is displayed when the setting of serial protocol is not simple communication protocol.	RW		

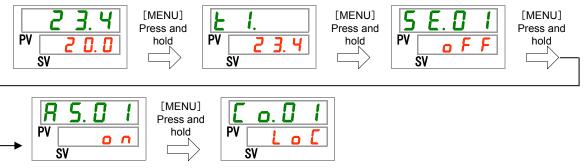
 Table 5.3-1
 Communication setting items

### 5.3.2 Setting and checking

Communication mode Setting and checking

**1.** Press and hold the [MENU] key for 2 sec.

Repeat pressing the key until the setting screen for communication mode [[ . . . . ] ] appears on the digital display.



**2.** Select "SER" from the table below with the  $[\blacktriangle]$  key, and confirm with "SEL".



Table 5.3-2 List of set values

Set values	Explanation	Initial value (Default setting)
Lo[	Sets LOCAL mode	0
dlo	Set s DIO mode	
5 E r	Sets SERIAL mode <sup>*1</sup>	

\*1: If the serial protocol is "Simple communication protocol 2" and the contact input 1 is "external switch signal" or contact input 2 is "remote signal", "SERIAL mode" cannot be set.

Serial protocol Setting and checking

**3.** Press the [SEL] key once.

The set screen of serial protocol is displayed on the digital display.

**4.** Select serial protocol from the table below with [▲] key or [▼] key, and confirm by pressing "SEL".

Table 5.3-3	List of set values

Set values	Explanation	Initial value (Default setting)			
ndb 5	MODBUS protocol	0			
Prol	Simple communication protocol				
Pro2	Simple communication protocol 2*2,*3				
Q Million the active of the context issue Q is "Dependent in all" "Qian life d					

\*2 : When the setting of the contact input 2 is "Remote signal", "Simplified communication protocol 2" cannot be set.

\*3:Refer to chapter 2.4 for remote setting when the communication mode is SERIAL and the simple communication protocol 2 is selected as the serial protocol.

Communication specification Setting and checking

### **5.** Press the [SEL] key once.

The set screen of communication specification is displayed on the digital display.



**6.** Select communication specification from the table below with [▲] key or [▼] key, and confirm by pressing "SEL".

Table 5.3-4 List of set values

Set values	Explanation	Initial value (Default setting)
3262	RS-232C Standard	
485	RS-485 Standard	0

RS-485 terminal Setting and checking

**7.** Press the [SEL] key once.

The set screen of RS-485 terminal is displayed on the digital display.



8. Select RS-485 terminal from the table below with [▲] key or [▼] key, and confirm by pressing "SEL".

	Table 5.3-5 List of set values	
Set values	Explanation	Initial value (Default setting)
oFF	Without terminal	0
0 0	With terminal	

Slave addresses (simple communication protocol) Setting and checking

**9.** Press the [SEL] key 3 times.

The set screen of slave addresses (simple communication protocol) is displayed on the digital display.



**10.**Select slave addresses (simple communication protocol) from the table below with [▲] key or [▼] key, and confirm by pressing "SEL".

Set values	Explanation	Initial value (Default setting)
	Setting/checking are not available unless the serial protocol setting is simple communication protocol.	
to 99	Sets of slave addresses for simple communication protocol. Set range is 1 to 99.	1

Table 5.3-6	List of set values
Table 5.5-0	

Communication speed (simple communication protocol) Setting and checking

### **11.**Press the [SEL] key once.

The set screen of communication speed (simple communication protocol) is displayed on the digital display.

12.Select communication speed (simple communication protocol) from the table below with [▲] key or [▼] key, and confirm by pressing "SEL".

Set values	Explanation	Initial value (Default setting)
	Setting/checking are not available unless the serial protocol setting is simple communication protocol.	
1. 2	1200bps	
2. 4	2400bps	
Ч. 8	4800bps	
9. 6	9600bps	0
1 9. 2	19200bps	

Table 5.3-7	List of set values
10010 0.0 1	

BCC (simple communication protocol) Setting and checking

### **13.**Press the [SEL] key once.

The set screen of BCC (simple communication protocol) is displayed on the digital display.



**14.** Select BCC (simple communication protocol) from the table below with  $[\blacktriangle]$  key or  $[\nabla]$  key, and confirm by pressing "SEL".

	Table 5.3-8 List of set values	
Set values	Explanation	Initial value (Default setting)
	Setting/checking are not available unless the serial protocol setting is simple communication protocol.	
oFF	Without BCC	
0 0	With BCC	0

Data length (simple communication protocol) Setting and checking

### **15.**Press the [SEL] key once.

The set screen of data length (simple communication protocol) is displayed on the digital display.

L	0	۱.	<u>i</u>	U
PV	8	Ь	1	Ł

**16.**Select data length (simple communication protocol) from the table below with  $[\blacktriangle]$  key or [▼] key, and confirm by pressing "SEL".

	Table 5.3-9 List of set values	
Set values	Explanation	Initial value (Default setting)
	Setting/checking are not available unless the serial protocol setting is simple communication protocol.	
761E	7 bit	
861E	8 bit	0

Parity check (simple communication protocol) Setting and checking

**17.**Press the [SEL] key once.

The set screen of parity check (simple communication protocol) is displayed on the digital display.

**18.** Select parity check (simple communication protocol) from the table below with  $[\blacktriangle]$  key or [▼] key, and confirm by pressing "SEL".

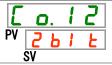
Set values	Explanation	Initial value (Default setting)
	Setting/checking are not available unless the serial protocol setting is simple communication protocol.	
000	None	0
odd	Odd number	
EuEn	Even number	

|--|

Stop bit(simple communication protocol) Setting and checking

### **19.**Press the [SEL] key once.

The set screen of stop bit (simple Communication protocol) is displayed on the digital display.



**20.** Select stop bit (simple communication protocol) from the table below with  $[\blacktriangle]$  key or  $[\lor]$ key, and confirm by pressing "SEL".

Table 5.3-11	List of set values
--------------	--------------------

Set values	Explanation	Initial value (Default setting)
	Setting/checking are not available unless the serial protocol setting is simple communication protocol.	
IPIF	1 bit	
<u>5915</u>	2 bit	0

Response delay time (simple communication protocol) Setting and checking

### **21.**Press the [SEL] key once.

The set screen of response delay time (simple communication protocol) is displayed on the digital display.



22.Select response delay time (simple communication protocol) from the table below with [▲] key or [▼] key, and confirm by pressing "SEL".

Set values	Explanation	Initial value (Default setting)
	Setting/checking are not available unless the serial protocol setting is simple communication protocol.	
to 250	Sets of response delay time Set range is 0 to 250m sec.	

Communication range (simple communication protocol) Setting and checking

### **23.**Press the [SEL] key once.

The set screen of communication range (simple communication protocol) is displayed on the digital display.

				_
E	0.	1	4	
PV		r	Н	
	SV			_

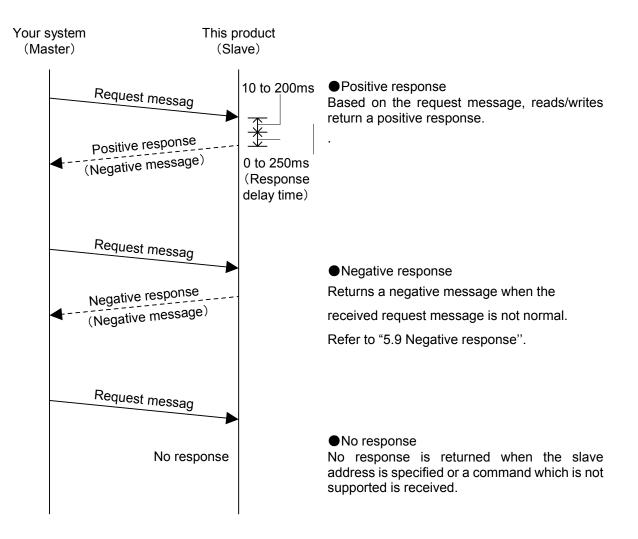
24. Select communication range (simple communication protocol) from the table below with [▲] key or [▼] key, and confirm by pressing "SEL".

Table 5.3-13	List of set values
--------------	--------------------

Set values	Explanation	Initial value (Default setting)
	Setting/checking are not available unless the serial protocol setting is simple communication protocol.	
r 0	Only reading is available	
r 8	Reading and writing are available	0

### 5.4 Communication sequence

Starts with a request message from the customer's system (host), and finishes with a response message from the product (slave). This product operates as a slave. It does not send any requests.



### 5.5 Message configuration

The message configuration is shown in the following. The explanation of data in message is shown in the Table 5.5-1.

This product communicates in ASCII mode. ASCII mode is used from STX to ETX. Hexadecimal value is used for BCC.

### 5.5.1 Message format

1) Request message format

1-1) Request message (Request to read)

STX	Slave A	ddress	Request	Command			ETX	ETX BCC	
[STX]	XX	XX	[R]	XX	XX	XX	[ETX]	XX	

1-2) Request message (Request to write)

Ē	STX	Slave A	ddress	Request	/	Command	ł	Writing data					ETX	BCC
	[STX]	XX	XX	[W]	XX	XX	XX	XX	ΧХ	XX	XX	XX	[ETX]	XX

1-3) Request message (Request to store the data)

STX	Slave A	ddress	Request	Command			ETX	BCC
[STX]	XX	XX	[W]	XX	XX	XX	[ETX]	XX

2) Response message format

2-1) Response message (Normal response to request to write)

STX	Slave Address ACK		Command		Reading data				ETX	BCC			
[STX]	XX	XX	[ACK]	XX	XX	XX	XX	XX	XX	XX	XX	[ETX]	XX

2-2) Response message (Normal response to request to write or store the data)

STX	Slave A	ddress	ACK	ETX	BCC
[STX]	XX	XX	[ACK]	[ETX]	XX

2-3) Response message (Response when a receiving error occurred)

STX	Slave Address		NAK		ETX	BCC
[STX]	XX	XX	[NAK]	XX	[ETX]	XX
					\ Exc	ception code

Response is not returned unless STX and ETX (BCC) are included in the request. This product clears all previously received code when STX is received.

Item STX(02h) ETX(03h) Slave	Start text The code to sp be sent. End text	Explanation becify the head of the message. Added to the head of the characters to								
ETX(03h) Slave	The code to sp be sent.	becify the head of the message. Added to the head of the characters to								
Slave	⊨na text									
	sent. Other the									
Address										
Request										
Command	Command to r	eading or writing.								
Writing Reading	To request rea	quest identifier. R (reading) or W (writing)         mmand to reading or writing.         request writing, write the data in this area to the object data.         request reading, set the object data in this area.         OR algorithm of all characters from STX to ETX is read with the check code for or detection.         is code (BCC) is not included in "response" if BCC check is not selected when ting the communication.         knowledge code.         is is included in the response from the product when there is no error in the revived request.         gative acknowledge code.         is is included in the response from the product when there is an error in the revived request.         or content is included in the response when there is an error in the received request.         or content is included in the response when there is an error in the received request.         0       Exception         0       Equipment malfunction Memory error         1       Out of set range         1       Value data is out of "set range specified independently by set parameter"								
BCC	error detection This code (BC	Immand to reading or writing.equest writing, write the data in this area to the object data.equest reading, set the object data in this area.DR algorithm of all characters from STX to ETX is read with the check code forr detection.a code (BCC) is not included in "response" if BCC check is not selected whening the communication.nowledge code.a is included in the response from the product when there is no error in theeived request.ative acknowledge code.a is included in the response from the product when there is an error in theeived request.ative acknowledge code.a is included in the response from the product when there is an error in theeived request.ative acknowledge code.a is included in the response when there is an error in the receivedeet. Refer to the table below for exception codes.ExceptionCodeException0Equipment malfunction Memory error10Value data is out of "set range specified independently by set parameter"22222223444454544445445444454445								
ACK(06h)	Acknowledge This is include received reque	nowledge code. s is included in the response from the product when there is no error in the eived request. gative acknowledge code. s is included in the response from the product when there is an error in the								
NAK(15h)	This is include received reque	eived request. gative acknowledge code. s is included in the response from the product when there is an error in the eived request. or content is included in the response when there is an error in the received juest. Refer to the table below for exception codes.								
Exception code	request. Refer Exception code 0 1 2 2 3 4 5 6 7 8 *1 : Exception request of	to the table below for exception codes. Exception Equipment malfunction Memory error Out of set range Value data is out of "set range specified independently by set parameter" Setting not allowed. Changing of requested communication parameter is prohibited. Or communication parameter to read does not exist. Writing of the communication mode is requested while the								
	Writing Reading BCC ACK(06h) NAK(15h)	Writing Reading To request writing BCC EXOR algorith error detection This code (BC setting the con Acknowledge of Acknowledge of Acknowledge of Acknowledge of Acknowledge of Regative ackn This is include received reque Error content request. Refer Exception code 0 1 2 Exception code 3 4 5 6 7 8 *1 : Exception request of *1 : Exception *1 :								

Table 5.5-1 Format data

### 5.5.2 Message example

The example shows communication with the conditions below.

OSlave Address: No.1

ORead seven consecutive data from register 0000h.

(Read circulating fluid discharge temperature.)

### Communication example

### CAUTION



The communication example is expressed in hexadecimal value with []. The actual communication is performed with ASCII code. Refer to the request / response message in this section.

#### Your system

This product

(Request): [STX] 01RPV1 [ETX] [65h]

(Response): [STX] 01[ACK] PV100187 [ETX] [0Fh]

Data is sent and received in ASCII code.

	Request message		Response message
Code	Contents	Code	Contents
01	Slave Address	01	Slave Address
R	Request message to read	[ACK]	Normal response message
PV1	Circulating fluid discharge temperature	PV1	Circulating fluid discharge temperature
[65h]	BCC value	00187	Read information
		[0Fh]	BCC value

### Request message (Master to Slave)

		<u> </u>							
STX	Slave Address		Request	Command			ETX	BCC	
02	30	31	52	50	56	31	03	65	

### Response message (Slave to Master)

	<u> </u>										
STX	Slave Address	ACK	Command			Re	ading da	ata		ETX	BCC
02	30 31	06	50 56	31	30	30	31	38	37	03	0F

### 5.6 BCC

 $\mathsf{EXOR}$  algorithm of all characters from STX to  $\mathsf{ETX}$  is read with the check code for error detection.

This BCC is not included in "response" if BCC check is not selected when setting the communication.

Displayed in one digit of ASCII code in the message frame.

#### **Calculation example**

Message for BCC

[STX] 01RPV1 [ETX]

Calculation

ASCII	HEX
[STX]	02
<b>'</b> 0'	30
'1'	31
'R'	52
'P'	50
'V'	56
'1'	31
[ETX]	03
'e'	65

 $\leftarrow$  Code for EXOR from STX to ETX is BCC.

•Sending message [STX] 01RPV1 [ETX] e

### 5.7 Command

Table 5.7-1 shows the commands which are supported by the product. No response is returned for a request message of a command which is not in

Table 5.7-1.

	Table 5.7-1	Command list
--	-------------	--------------

NO	Command	Name	R/W	Explanation
1	PV1	Circulating fluid discharge temperature	R	Read the circulating fluid discharge temperature in the temperature unit of the product. The circulating fluid discharge temperature (offset temperature if offset setting is selected) which is displayed on the operation display panel PV part. e.g. In case of 19.8°C 00198
2	2 SV1 Circulating fluid R/V		R/W	Write/read the circulating fluid set temperature in the temperature unit of the product. Writing is available only in serial mode. e.g. In case of 35.8°C 00358
3	LOC	Key-lock setting	R/W	Write and read the key-lock setting. 00000 : Unlocked 00001 : All locked 00002 : Setting mode value is locked 00003 : Key lock other than for set temp. Key-lock setting of this product just receives the command. This command does not actually lock the keys. This function is to make this product interchangeable with the communication specifications of SMC's HRG/HRGC series thermo coolers. When not using this product as a replacement for HRG/HRGC, this function is not needed.
4	STR	Store the data	W	Store the data to the product (Write to FRAM)

### 5.8 Command explanation

### 5.8.1 Command: PV1 Circulating fluid discharge temperature

Read the circulating fluid discharge temperature in the selected temperature unit (°C or °F). The circulating fluid discharge temperature (offset temperature if offset setting is selected) which is displayed on the operation display panel PV part.

	Request	message	<normal></normal>	(Master	to Slave)	
--	---------	---------	-------------------	---------	-----------	--

 			1					
STX	Slave Address	Request	(	Command	ETX	BCC		
[STX]	XX XX	[R]	[P]	[V]	[1]	[ETX]	XX	

#### Response message <Normal> (Slave to Master)

(Request) [STX] 01RPV1 [ETX] [65h]

[	STX	Slave Address	ACK	(	Command		Re	eading da	ta	ETX	BCC
	[STX]	XX XX	[ACK]	[P]	[V]	[1]	XX XX	XX	XX XX	[ETX]	XX

### Communication example

OSlave Address : No 1

OBCC selection

Your system

(Response) [STX] 01[ACK] PV100187 [ETX] [0Fh]

Data is sent and received in ASCII code.

This product

	Request message	Response message				
Code	Contents	Code	Contents			
01	Slave Address	01	Slave Address			
R	Request message to read	[ACK]	Normal response message			
PV1	Circulating fluid discharge temperature	PV1	Circulating fluid discharge temperature			
[65h]	BCC value	00187	Read information (18.7°C)			
		[0Fh]	BCC value			

### 5.8.2 Command:SV1 Circulating fluid set temperature (R)

Read the circulating fluid set temperature in the selected temperature unit (°C or °F).

### Request message <Normal> (Master to Slave)

STX	Slave Address	Request	Command	ETX	BCC
[STX]	XX XX	[R]	[S] [V] [1]	[ETX]	XX

#### Response message <Normal> (Slave to Master)

STX	Slave A	ddress	ACK	(	Command			R	eading da	ta		ETX	BCC
[STX]	XX	ΧХ	[ACK]	[S]	[V]	[1]	XX	ΧХ	XX	ΧХ	XX	[ETX]	XX

### Communication example

 $\circ \text{Slave Address}$  : No 1

∘BCC selection

Your s	system	This p	roduct
	(Request) [STX] 01RSV1 [ETX] [66h] (Response) [STX] 01[ACK] SV100258 [ETX] [0Dh]		Data is sent and received in ASCII code.

	Request message	Response message			
Code Contents		Code	Contents		
01	Slave Address	01	Slave Address		
R	Request message to read	[ACK]	Normal response message		
SV1	Circulating fluid set temperature	SV1	Circulating fluid set temperature		
[66h]	BCC value	00258	Read information (25.8°C)		
<u>.</u>		[0Dh]	BCC value		

### 5.8.3 Command:SV1 Circulating fluid set temperature (W)

Read the circulating fluid set temperature in the selected temperature unit (°C or °F).

This product

Data is sent and

received in ASCII

code.

#### Request message <Normal> (Master to Slave)

					/		
ĺ	STX	Slave Address	Request	Command	Writing data	ETX	BCC
	[STX]	XX XX	[W]	[S] [V] [1]	XX XX XX XX XX	[ETX]	XX

#### Response message <Normal> (Slave to Master)

STX	Slave Address		ACK	ETX	BCC
[STX]	XX	XX	[ACK]	[ETX]	XX

### Communication example

OSlave Address : No 1

OBCC selection

Your system

(Request)[STX] 01WSV100258 [ETX] [5Ch]

(Response)[STX] 01[ACK] [ETX] [06h]

**Request message** Response message Code Contents Code Contents 01 Slave Address 01 Slave Address W Request message to write [ACK] Normal response message SV1 Circulating fluid set temperature BCC value [06h] Write information (25.8 °C) 00258 [5Ch] BCC value

### 5.8.4 Command:LOC Key-lock setting (R)

Read the key-lock condition set in 5.8.5 ''Command:LOC Key-lock setting (W)''.

It is different from the key-lock information which is set by the operation display panel.

#### Request message <Normal> (Master to Slave)

							/	
STX	Slave A	Address	Request	Command			ETX	BCC
[STX]	XX	XX	[R]	[L]	[O]	[C]	[ETX]	XX

#### Response message <Normal> (Slave to Master)

-							
	STX	Slave Address	ACK	Command	Reading data	ETX	BCC
	[STX]	XX XX	[ACK]	[L] [O] [C]	XX XX XX XX XX	[ETX]	XX

### Communication example

OSlave Address : No 1

OBCC selection

 Your system
 This product

 (Request) [STX] 01RLOC[ETX][12h]
 Data is sent and received in ASCII code.

 (Response) [STX] 01 [ACK]LOC00001[ETX][77h]
 Data is sent and received in ASCII code.

	Request message	Response message			
Code	Contents	Code	Contents		
01	Slave Address	01	Slave Address		
R	Request message to read	[ACK]	Normal response message		
LOC	Key-lock setting	LOC	Key-lock setting		
[12h]	BCC value	00001	Read information (00001 : All locked)		
<u> </u>		[77h]	BCC value		

### 5.8.5 Command:LOC Key-lock setting (W)

Sets key-lock of this product. This setting is different from the key-lock information which is set by the operation display panel.

Key-lock setting of this product just receives the command. This command does not actually lock the keys.

This function is to make this product interchangeable with the communication specifications of SMC's HRG/HRGC series thermo coolers. When not using this product as a replacement for HRG/HRGC, this function is not needed.

#### Request message <Normal> (Master to Slave)

STX	Slave A	ddress	Request	(	Command	ł		V	Vriting dat	a		ETX	BCC
[STX]	XX	XX	[W]	[L]	[0]	[C]	XX	XX	XX	XX	XX	[ETX]	XX

#### Response message <Normal> (Slave to Master)

 STX
 Slave Address
 ACK
 ETX
 BCC

 [STX]
 XX
 XX
 [ACK]
 [ETX]
 XX

### Communication example

OSlave Address : No 1

**OBCC** selection

Your system

(Request)[STX] 01WLOC00001 [ETX] [26h]

(Response)[STX] 01[ACK] [ETX] [06h]

This product

Data is sent and received in ASCII code.

	Request message	Response message			
Code	Contents	Code	Contents		
01	Slave Address	01	Slave Address		
W	Request message to write	[ACK]	Normal response message		
LOC	Key-lock setting	[06h]	BCC value		
00001	Read information (00001 : All locked)				
[26h]	BCC value				

### 5.8.6 Command:STR Saves data (W)

Store the circulating fluid set temperature set in 5.8.3 "Command:SV1 Circulating fluid set temperature". Key-lock set data which is set in 5.8.5 "Command:LOC Key-lock setting (W)" is not the object to store.

#### Request message <Normal> (Master to Slave)

	V						
STX	Slave Address	Request	(	Comman	d	ETX	BCC
[STX]	XX XX	[W]	[S]	[T]	[R]	[ETX]	XX

#### Response message <Normal> (Slave to Master)

STX	Slave A	Slave Address		ETX	BCC	
[STX]	XX	XX	[ACK]	[ETX]	XX	

### Communication example

OSlave Address : No 1

OBCC selection

Your sys	stem	This product	
	(Request) [STX] 01WSTR[ETX][02h]	Data is sent and	
•	(Response) [STX] 01 [ACK][ETX][06h]		received in ASCII code.
Cada	Request message	Cada	Response message

	Request message	Response message			
Code	Contents	Code	Contents		
01	Slave Address	01	Slave Address		
W	Request message to write	[ACK]	Normal response message		
STR	Saves data	[06h]	BCC value		
[02h]	BCC value				

### 5.9 Negative response

If the request is not normal when receiving the request, or the request cannot be received due to the state of the product, a negative response is returned. Refer to the exception codes in Table 5.5-1 for exceptions.

#### Response message <Normal> (Slave to Master)

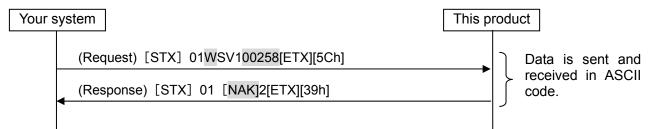


Exception code

### Communication example

OSlave Address : No 1

OWriting of the circulating fluid set temperature when the communication range setting is RO (read only).



Request message			Response message			
Code	Contents	Code	Contents			
01	Slave Address	01	Slave Address			
W	Request message to write	[NAK]	Negative response message			
SV1	Circulating fluid set temperature	2	Exception code for setting is prohibited			
00258	Write information (15.1 °C)	[39h]	BCC value			
[5Ch]	BCC value					

# Chapter 6 Communication alarm function

Monitors whether the serial communication is sent/received properly between the product and the customer's device. This feature is only valid when the communication mode is set to SERIAL mode.

Abnormal signals or disconnection of the communication cable can be notified immediately by setting the alarm function to match the interval at which messages are sent from the customer device. When the communication is restored, the alarm is automatically reset.

Do not use this function when the customer device does not send messages regularly.

The default setting of this function is "off".

### 6.1 Communication alarm occurs

Fig 6.1-1 shows when an alarm occurs. Refer to 6.3 "Setting and checking" for the setting method.

•Changing of communication error

Operation continues when an alarm occurs.

- •Time for monitoring the communication error
  - 180 sec

When the customer's device is sending messages every 60sec, if the communication cable is disconnected and no message is received for 180sec, the product generates AL19 communication error alarm to notify the error.

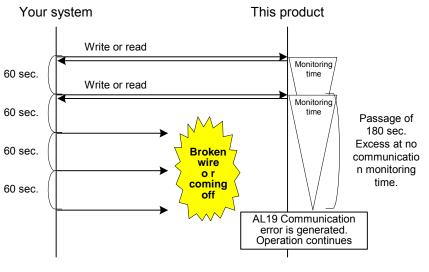


Fig 6.1-1 Communication alarm example

### 6.2 Communication alarm reset

When AL19 communication error has been generated, the alarm is automatically reset when the disconnection of the communication cable is fixed, and the message from the customer is received. If operation is set to stop when a communication alarm occurs, restart the operation if necessary.

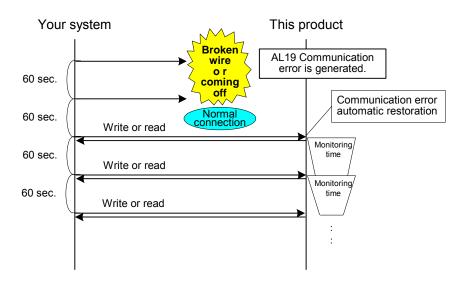


Fig 6.2-1 Communication alarm restoration example

### 6.3 Setting and checking

### 6.3.1 Setting and checking items

The table below explains the setting items of the communication alarm function and default values.

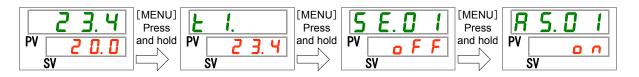
Display	ltem	Contents	Initial value (Default setting)
<u>A 5. I I</u>	Changing of communication error	Set the operation when the alarm No. AL19 "Communication error" is generated.	OFF
<u>R 5. I 2</u>	The monitoring time of communication error	Set the alarm monitoring time when the alarm No. AL19 "Communication error" is generated. Alarm signal is generated when the monitoring time is exceeded. Setting unit is 1 sec. [] is displayed when the communication error setting is OFF.	30

Table 6.3-1 Communication setting item

### 6.3.2 Setting and checking

**1.** Press and hold the [MENU] key for 2 sec.

Repeat pressing the key until the setting screen for alarm buzzer sound  $[\underline{R 5.0 l}]$  appears on the digital display.



Changing of communication error Setting and checking



The set screen of "changing of communication error" is displayed on the digital display.



3. Select changing of operation when communication error from the table below with [▲] key or [▼] key, and confirm by pressing "SEL".

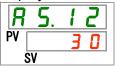
Table 6.3-2	List of set values

Set values	Explanation	Initial value (Default setting)
oFF	This alarm signal is not detected.	0
R.r.U.n	Operation continues when this communication error is generated.	
R.SEP	Operation is stopped when this communication error is generated.	

The monitoring time of communication error Setting and checking

**4.** Press the [SEL] key once.

The set screen of the "monitoring time of communication error" is displayed on the digital display.



**5.** Select the monitoring time of communication error from the table below with [▲] key or [▼] key, and confirm by pressing "SEL".

Set values	Explanation	Initial value (Default setting)
	Setting/checking are not available if the setting of the changing of communication error is OFF.	
30 to 600	Sets monitoring time of communication error Setting range is 30 to 600 sec.	30

Table 6.3-3 List of set values

## **SMC** Corporation

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