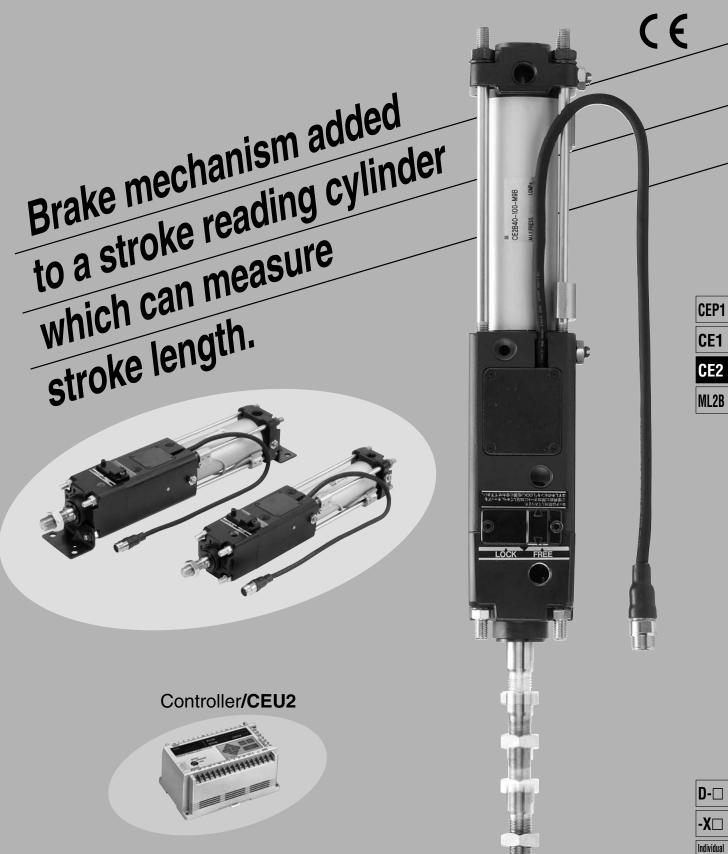
Stroke Reading Cylinder with Brake

Series CE2

Ø40, Ø50, Ø63, Ø80, Ø100



Stroke Reading Cylinder with Brake/CE2 Controller/CEU2

Ø40, Ø50, Ø63, Ø80, Ø100

Multi-counter

3 point preset counter: Series CEU1 : Seriss CEU5

A cylinder capable of highly reproducible positioning (stopping accuracy of ±0.5 mm) has been created by adding a brake mechanism to a stroke reading cylinder which can measure stroke length.

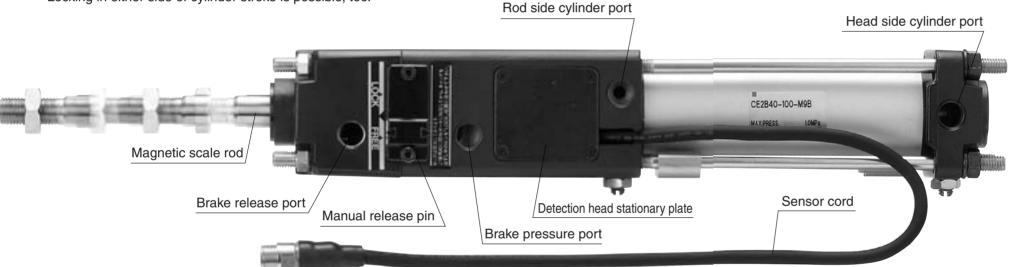
Brake mechanism

Employs a combination spring and pneumatic lock type.

When there is a drop in air pressure, the workpiece is held by a spring lock.

Locking in both directions is possible.

Locking in either side of cylinder stroke is possible, too.

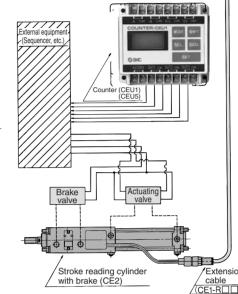


System configuration

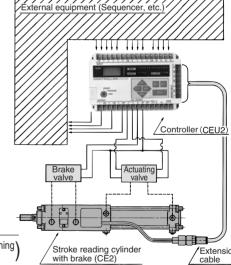
For safety measures

Stroke reading cylinder with brake + Counter

 Prevents dropping from raised positions during intermediate stops.

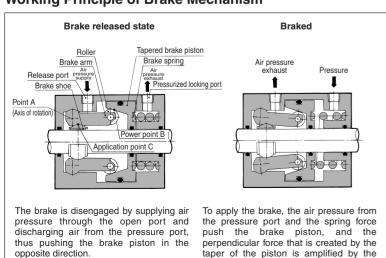


Controller: Series CEU2



Working Principle of Brake Mechanism

1484

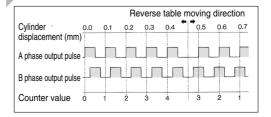


Measuring

Smallest measuring unit 0.1 mm

Magnetic scale rod and built-in detection head

Relation between displacement and output pulse on stroke reading cylinder

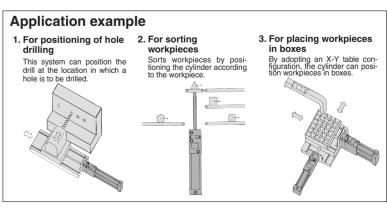


For precision positioning (Stopping accuracy ±0.5 mm)

Stroke reading cylinder with brake + Controller (Brake positioning system

- Positioning with high reproducibility has been achieved by prediction control and learning function.
- The stop position will be automatically redressed by re-try function.

Prediction control and learning function (Prediction control Stopping Operation from 2nd Corrects the brake point every time from the positioning error of the last operation



SMC

D-□ -**X**□ Individual

CEP1

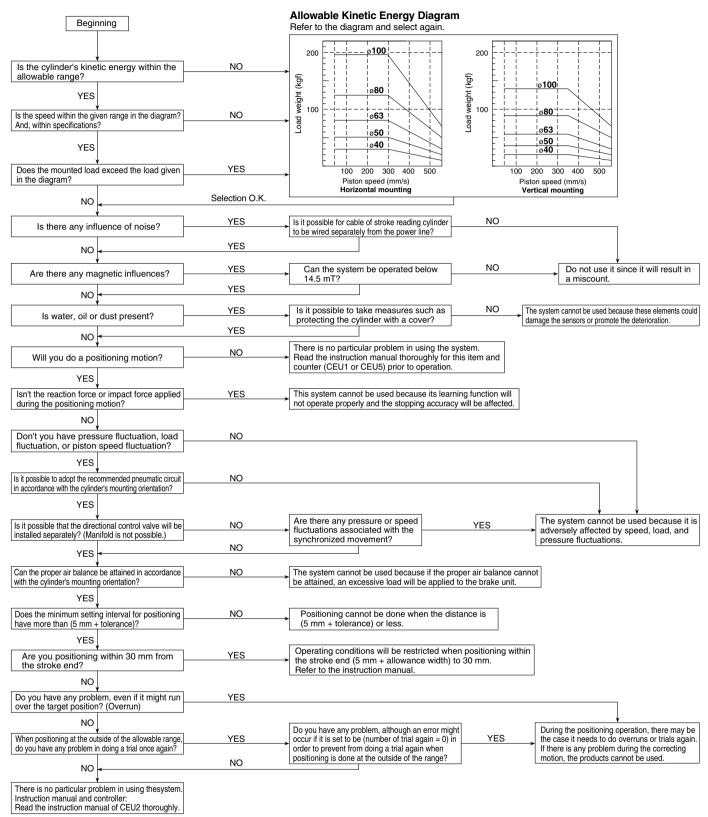
CE1

CE2

brake arm to push the brake shoe against

Flow Chart to Confirm Utility of Stroke Reading Cylinder with Brake

Depending on the operating conditions, stable stopping accuracy may not be obtained. Therefore, make sure to follow the flow chart shown below.



^{*} This series cannot be used in an environment where it is exposed to fluids (water, oil, coolant, etc.)

Handling Technical Material

Be sure to read before handling brake positioning system (CE2 + CEU2).

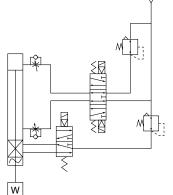


Example of Recommended Pneumatic

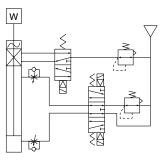
Horizontal mounting

W

Vertical flat mounting



Vertical overhead mounting



Note) In the case of light load, regulate head side supply pressure.

Recommended Pneumatic Equipment

Bore size (mm)		Directional control valve	Brake valve	Regulator	Piping	Silencer	Speed controller
	ø40	VFS24□OR	VFS21□O	AR425	Nylon ø8/6 or larger	AN200-02	AS4000-02
	ø50	VFS24□OR	VFS21□O	AR425	Nylon ø10/7.5 or larger	AN200-02	AS4000-02
	ø63	VFS34□OR	VFS21□O	AR425	Nylon ø12/9 or larger	AN300-03	AS4000-03
	ø80	VFS44□OR	VFS31□O	AR425	Nylon ø12/9 or larger	AN300-03	AS420-03
	ø100	VFS44□OR	VFS31□O	AR425	Nylon ø12/9 or larger	AN400-04	AS420-04

Caution on Pneumatic Circuit Design

Air balance

Unlike the conventional pneumatic cylinder that performs a simple reciprocal movement, the stroke reading cylinder with a brake also makes intermediate stops. Thus, it must maintain the proper air balance in a stopped state.

Therefore, the proper air balance must be established in accordance with the mounting orientation of the cylinder.

Use caution the piston rod may be lurched when the next motion gets started after the intermediate stops or commence the operation after the reverse motion gets done, unless the air balance is taken. It may result in degrading its accuracy.

Supply pressure

If line pressure is used directly as supply pressure, any fluctuation in pressure will appear in the form of changes in cylinder characteristics. Therefore, make sure to use a pressure regulator to convert line pressure into supply pressure (Drive: 0.1 to 1 MPa, Brake: 0.3 to 0.5 MPa) for the actuating valve and the brake valve. In order to actuate multiple cylinders at once, use a pressure regulator that can handle a large air flow volume and also consider installing a surge tank.

CEP1

CE1

CE2

ML2B



-X□





Series CE2 **Specific Product Precautions**

Be sure to read before handling.

Refer to front matters 42 and 43 for Safety Instructions and pages 3 to 11 for Actuator and Auto Switch Precautions.

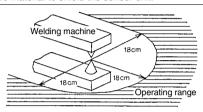
Sensor

♠ Caution

Because a magnetic system is adopted in the sensor unit of the stroke reading cylinder with brake, the presence of a strong magnetic fields in the vicinity of the sensor could lead to a malfunction

Operate the system with an external magnetic field of 14.5 mT.

This is equivalent to a magnetic field of approximately 18 cm in radius from a welding area using a welding amperage of almost 15,000 amperes. To use the system in a magnetic field that exceeds this value, use a magnetic material to shield the sensor unit.

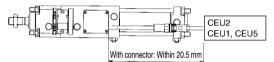


The sensor unit is adjusted to an appropriate position at the time of shipment. Therefore, never detach the sensor unit from the body. Make sure that water does not splash on the sensor unit (enclosure IP65). Do not pull on the sensor cable.

Noise

Operating the stroke reading cylinder with brake in the vicinity of equipment that generates noise, such as a motor or a welder, could result in miscounting. Therefore, minimize the generation of noise as much as possible, and keep the wiring separate.

Also, the maximum transmission distance of the stroke reading cylinder with brake is 20.5 m. Make sure that the wiring does not exceed this distance. Besides, when the transmission distance is over 20.5 m, use the dedicated transmission box (Part no. CE1-H0374).



How to Manually Disengage the Lock and Change from the Unlocked to the Locked

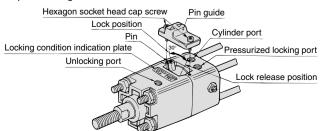
Manual unlocking

- 1. Loosen the two hexagon socket head cap bolts and remove the pin
- guide. 2. As viewed from the end of the rod, the pin is tilted 15 $^{\circ}$ to the left of the center.

 3. Supply an air pressure of 0.3 MPa or more to the unlocking port.
- 4. Rotate the pin 30° to the right with a wooden implement such as the grip of a wooden hammer or a resin stick without scratching.

How to manually change from an unlocked state to a locked state

- 1. Loosen the two hexagon socket head cap bolts and remove the pin guide.
- 2. As viewed from the end of the rod, the pin is tilted 15° to the right of the
- 3. Supply air pressure of 0.3 MPa to the unlocking port.
- 4. Rotate the pin 30° by pushing it with a wooden implement such as the grip of a wooden hammer or a resin stick.
- Note) Never rotate the pin by striking it since this may bend or damage the pin. Be careful when pushing the pin since the surface is slippery.
- 5. Inside the pin guide, there is a slotted hole that is slightly larger than the pin. Align the pin with the slotted hole and secure them to cover, using the hexagon socket head cap screws that were removed in step 1. The convex of the pin guide and "LOCK" on the locking condition indication plate will align



Caution on Handling

∕∖\ Caution

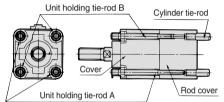
1. Operate the cylinder in such a way that the load is always applied in the

In case the load is applied in a direction other than the axial direction of the cylinder, provide a guide to constrain the load itself. In such a case, take precautions to prevent off-centering. If the piston rod and the load are off-centered, the speed of the movement of the piston could fluctuate, which could affect the piston's stopping accuracy and shorten the life of the brake unit.

- 2. If there is a large amount of dust in the operating environment, use a cylinder with a bellows to prevent the intrusion of dust.
 - Also, be aware that the operating temperature range is between 0 and
- 3. The brake unit and the cylinder rod cover area are assembled as shown in the diagram below. For this reason, unlike ordinary cylinders, it is not possible to use the standard style mounted directly onto a machine by screwing in the cylinder tie-rods.

Furthermore, when replacing mounting brackets, the unit holding tie-rods may get loosen. Tighten them once again in such a case.

Use a socket wrench when replacing mounting brackets or retightening the unit holding tie-rods.



(ø2 depth 1 mm hole is on the side of tie-rod for attaching unit A.)

Bore size	Mou	nting brac	ket nut	Unit holding tie-rod			
(mm)	Nut	Width across flats	Socket	Width across flats	Socket		
40	JIS B 1181 Class 3	13	JIS B 4636	10	JIS B 4636 2 point angle socket 10		
50	M8 x 1.25	13	2 point angle socket 13	10	JIS B 4636 2 point angle socket 13		
63	JIS B 1181 Class 3 M10 x 1.25		JIS B 4636 2 point angle socket 17	13	JIS B 4636 2 point angle socket 13		
80 100	JIS B 1181 Class 3 M12 x 1.75	19	JIS B 4636 2 point angle socket 19	17	JIS B 4636 2 point angle socket 17		

Operating Cautions

Counting speed of the counter

Be aware that if the speed of the stroke reading cylinder with brake is faster than the counting speed of the counter, the counter will miscount.

Use CEU1, CEU2, CEU5.

Cylinder speed < Counting speed of the counter (Cylinder speed 500 mm/sec = Counting speed of the counter 5 kcps)

Miscounting by lurching or bounding

If the stroke reading cylinder with brake lurches or bounds during an IN or OUT movement, or due to other factors, be aware that the cylinder speed could increase momentarily, possibly exceeding the counter's counting speed or the sensor's response speed, which could lead to miscounting.



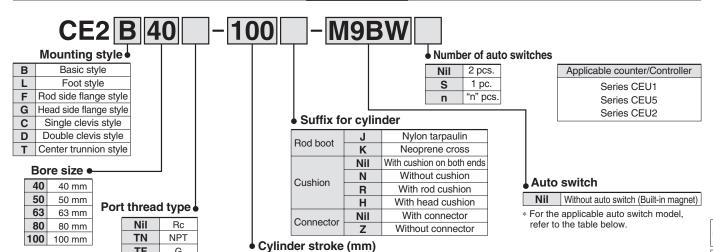
Stroke Reading Cylinder with Brake

Series CE2 ø40, ø50, ø63, ø80, ø100



Note) CE compliant: When connecting to a 3-point preset counter (CEU1□-D, power supply voltage 24 VDC) and a multi-counter (CEU5□-D, power supply voltage 24 VDC). Refer to the counter operation manual for details.

How to Order



Refer to "Standard Stroke" on page 1490. **Applicable Auto Switch**/Refer to pages 1719 to 1827 for further information on auto switches.

			ight		Lo	ad voltag	je	Auto swit	tch model	Lead v	vire le	ngth	(m)			
уре	Special function	Electrical entry	Indicator light	Wiring (Output)	С	C	AC	Tie-rod mounting	Band mounting	0.5 (Nil)	1 (M)	3 (L)	5 (Z)	Pre-wired connector	Applical	ble loa
								M9N	_	•	•	•	0	0		
				3-wire (NPN) 3-wire (PNP) 24V		5 V, 12 V			G59	•	1—	•	0	0	IC airavit	
					J V, 12 V	_	M9P	_		•	•	0	0	IC circuit		
		Grommet			24V			_	G5P	•	_	•	0	0		
	_					12 V		M9B	_		•	•	0	0		
				2-wire		12 V		_	K59	•	_	•	0	0	_	
ᇨ						_	100 V, 200 V	J51	_	•	_	•	0	_		
Solid state switch		Terminal		3-wire (NPN)		12 V		G39C	G39	_	_	_	_	_		
S		conduit		2-wire				K39C	K39		<u> </u>	_	_			
ate			Yes	3-wire (NPN)		5 V, 12 V		M9NW	_	•	•	•	0	0	IC circuit	Rela
st			>	o wile (141 14)					G59W	•	_	•	0			PLC
ji l	Diagnostic indication			3-wire (PNP)				M9PW	<u> </u>	•	•	•	0	0		
ŏ	(2-color indication)			` ′			_		G5PW	•	_	•	0	0		
				2-wire	24V	12 V		M9BW		•	•	•	0	0		
		Grommet		0 1 (1)				<u> </u>	K59W	•	<u> </u>	•	0	0		
				3-wire (NPN)		5 V, 12 V		M9NA***	_	0	0	•	0	0	-	
	Water resistant (2-color indication)			3-wire (PNP)				M9PA***	_	0	0	•	0	0		
	,			2-wire	12 V		M9BA***	— OFD4	0	0	•	0	0			
	With diagnostic output (2-color indication)			4-wire (NPN)	-	5 V, 12 V	-	— F59F	G5BA G59F	_	-	•	0	0	IC circuit	
	with diagnostic output (2-color indication)			3-wire		5 V, 12 V			GOSF		-	_	\vdash		IC Circuit	
			Yes	(NPN equivalent)	_	5 V	_	A96**	_		_	•	-	_	IC circuit	_
_			>	(THE TO GRANT COLOR)			100 V	A93**	_		_	•	_	_	_	
tch		Grommet	No				100 V or less	A90**	_	•	_	•		_	IC circuit	Rela
š			Yes				100 V, 200 V	A54	B54		_	•		_		PLC
ğ			No	2-wire		12 V	200 V or less	A64	B64	•	_	•	È	_		0
Reed switch		Terminal	1	1	24V		_	A33C	A33	_	_	_	_	_	ı	PLC
_		conduit	S				A34C	A34	_	_	_	_	_	_		
		DIN terminal	Kes				100 V, 200 V	A44C	A44	_	_	_	_	_	1	Rela
	Diagnostic indication (2-color indication)	Grommet	1			_	_	A59W	B59W	•	1_	•	_	_		PLC

*** Water resistant type auto switches can be mounted on the above models, but in such case SMC cannot guarantee water resistance.

Consult with SMC regarding water resistant types with the above model numbers.

* Lead wire length symbols: 0.5 m ······· Nil (Example) M9NW 1 m ····· M (Example) M9NWM

3 m L (Example) M9NWL 5 m Z (Example) M9NWZ

- * Solid state auto switches marked with "○" are produced upon receipt of order. ** Since D-A9□ and D-A9□V cannot be mounted on ø50, use of D-Z7□ or
- D-Z80 is recommended.

- * For details about auto switches with pre-wired connector, refer to pages 1784 and 1785.
- * D-A9 M9 M9 M9 M/9 A(V)L auto switches are shipped together (not assembled). (Only auto switch mounting brackets are assembled before shipped.)

1489 ®

D-

-X□

Individual

-X□

CEP1

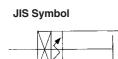
CE₁

CE2

ML2B

^{*} Since there are other applicable auto switches than listed, refer to page 1501 for details.







Model

Series	Туре	Action	Bore size (mm)	Lock action	
CE2	Non-lube	Double acting	40, 50, 63 80, 100	Spring and pneumatic lock	

Rod Boot Material

Symbol	Rod boot material	Maximum ambient temperature				
J	Nylon tarpaulin	60°C				
K	Neoprene cross	110°C*				

^{*} Maximum ambient temperature for the rod boot itself.

Cylinder Specifications

Bore size (m	ım)	ø 40	ø 50	ø 63	ø 80	ø 100			
Fluid		Air (Non-lube)							
D f	Drive			1.5 MPa					
Proof pressure	Brake		Air (Non-lube)						
Maximum	oof pressure Brake aximum Drive Brake Brake Brake Drive Brake Drive Brake Drive Brake Drive Brake Brake			1 MPa					
operating pressure	Brake			0.5 MPa					
Minimum	0.1 MPa								
operating pressure	Brake	0.3 MPa							
Piston speed			5	0 to 500 mm/s	s*				
Ambient temperatu	re		00 to	60°C (No free	ezing)				
Brake system			Spring a	nd pneumatic	lock type				
Sensor cord length	l		ø7-5	00 mm Oil-res	istant				
Stroke length tolera	ance	U	p to 250 mm	: ^{+1.0} , 251 mm	to 1000 mm	+1.4 0			

 $[\]ast$ Be aware of the constraints in the allowable kinetic energy.

Sensor Specifications

Sensor Specifications					
Cable	ø7, 6 core twisted pair shielded wire (Oil, Heat and Flame resistant cable)				
Maximum transmission distance	20.5 m (when using SMC cable while using controller or counter)				
Position detection method	Magnetic scale rod/Sensor head <incremental type=""></incremental>				
Magnetic field resistance	14.5 mT				
Power supply	10.8 to 26.4 VDC (Power supply ripple: 1% or less)				
Current consumption	40 mA				
Resolution	0.1 mm/pulse				
Accuracy	±0.2 mm ^{Note)}				
Output type	Open collector (Max. 35 VDC, 80 mA)				
Output signal	A/B phase difference output				
Insulation resistance	500 VDC, 50 M Ω or more (between case and 12E)				
Vibration resistance	33.3 Hz, 6.8 G 2 hrs. each in X, Y directions 4 hrs. in Z direction based upon JIS D 1601				
Impact resistance	30 G, 3 times at X, Y, Z				
Enclosure	IP65 (IEC standard) Except connector part				
Extension cable (Option)	5 m, 10 m, 15 m, 20 m				

Note) Digital error under Controller (CEU2), Counter (CEU1 or CEU5) is included. Besides, the whole accuracy after mounting on an equipment may be varied depending on the mounting condition and surroundings. As an equipment, calibration should be done by customer.

Standard Stroke

Bore size (mm)	Standard st	troke (mm)	Range of manufacturable stroke*			
Dore Size (ITIITI)	Without rod boot	With rod boot	Without rod boot	With rod boot		
40	25 to 850	25 to 700	Up to 1200	Up to 950		
50	25 to 800	25 to 650	Up to 1150	Up to 900		
63	25 to 800	25 to 650	Up to 1150	Up to 900		
80	25 to 750	25 to 600	Up to 1100	Up to 900		
100	25 to 750	25 to 600	Up to 1100	Up to 850		

^{*} Strokes longer than the standard stroke are made-to-order products.

Weight

Weight							(kg)
Bore siz	ze (mm)		40	50	63	80	100
	Basic sty	le	2.18	3.39	5.29	8.66	12.09
	Foot style	Foot style		3.61	5.63	9.33	13.08
Basic weight	Flange style		2.55	3.84	6.08	10.11	14.01
Dasic weight	Single clevis style		2.41	3.73	5.92	9.77	13.87
	Double clevis style		2.45	3.82	6.08	10.06	14.39
	Trunnion style		3.63	3.92	6.18	10.36	14.49
Additional weight per each 50 mm of stroke	Aluminum tube	Aluminum Mounting tube bracket		0.28	0.37	0.52	0.65
	Single kn	uckle	0.23	0.26	0.26	0.60	0.83
Accessory bracket	Double k	Double knuckle		0.38	0.38	0.73	1.08
	Knuckle	oin	0.05	0.05	0.05	0.14	0.19

Calculation: (Example) CE2L40-100

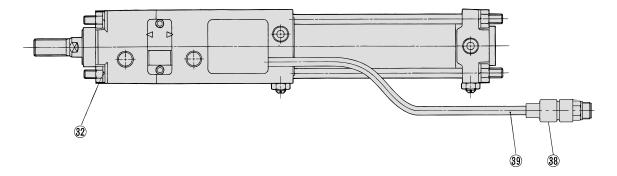
Basic weight ------2.37 (Foot style, ø40)

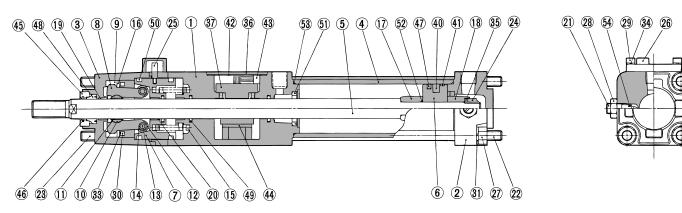
• Additional weight ······ 0.22/50 stroke

2.37 + 0.22 x 100/50= 2.81 kg

Stroke Reading Cylinder with Brake $\,$ Series $\,$ CE2 $\,$

Construction





CEP1

CE1

CE2

ML2B

Component parts

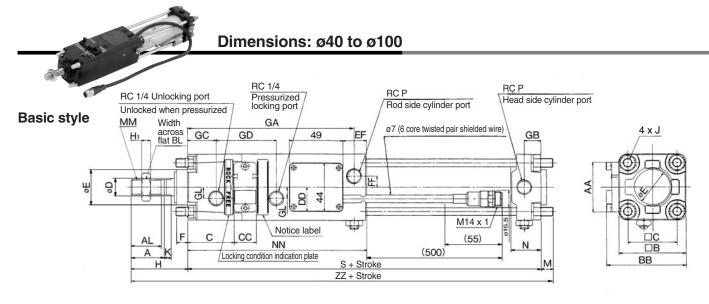
on ponon parto										
No.	Description	Material	Note							
1	Rod cover	Aluminum alloy	Black painted after hard anodized							
2	Head cover	Aluminum alloy	Black painted							
3	Cover	Aluminum alloy	Black painted after hard anodized							
4	Cylinder tube	Aluminum alloy	Hard anodized							
5	Piston rod	Free-cutting steel	Hard chrome plated							
6	Piston	Aluminum alloy	Chromated							
7	Brake piston	Carbon steel	Nitriding							
8	Brake arm	Carbon steel	Nitriding							
9	Brake arm holder	Carbon steel	Nitriding							
10	Brake shoe holder	Carbon steel	Nitriding							
11	Brake shoe	Special friction material								
12	Roller	Chromium molybdenum steel	Nitriding							
13	Pin	Chrome bearing steel	Heat treated							
14	Type E retaining ring	Stainless steel	JIS B 2805E							
15	Brake spring	Steel wire	Dacrodized							
16	Retaining plate	Rolled steel plate	Zinc chromated							
17	Cushion ring A	Rolled steel	Electroless nickel plated							
18	Cushion ring B	Rolled steel	Electroless nickel plated							
19	Bushing	Lead-bronze casted								
20	Bushing	Lead-bronze casted								
21	Cushion valve	Rolled steel plate	Electroless nickel plated							
22	Tie-rod	Carbon steel	Chromated							
23	Unit holding tie-rod	Carbon steel	Chromated							
24	Piston nut	Rolled steel plate	Zinc chromated							
25	Non-rotating pin	Carbon steel	High frequency quenched							
26	Pin guide	Carbon steel	Black painted after nitriding							
27	Tie-rod nut	Carbon steel	Black zinc chromated							

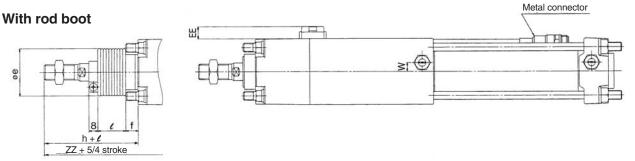
No.		Material	Note
28	Lock nut	Carbon steel	Nickel plated
29	Hexagon socket head cap screw	Chromium molybdenum steel	Black zinc chromated
30	Hexagon socket head cap screw	Stainless steel	
31	Spring washer	Steel wire	Black zinc chromated
32	Spring washer	Steel wire	Black zinc chromated
33	Spring washer	Steel wire	Black zinc chromated
34	Spring washer	Steel wire	Black zinc chromated
35	Spring washer	Steel wire	Zinc chromated
36	Sensor cover	Carbon steel	
37	Detection head assembly	_	
38	Connector	_	
39	Cable	_	
40	Rubber magnet	NBR	
41	Wear ring	Resin	
42	Gasket	NBR	
43	Bushing	NBR	
44	Amp cushion	NBR	
45	Seal retainer	Aluminum alloy	
46	Coil scraper	Phosphor bronze	
47	Piston seal	NBR	
48	Rod seal A	NBR	
49	Rod seal B	NBR	
50	Brake piston seal	NBR	
51	Cushion seal	NBR	
52	Piston gasket	NBR	
53	Cylinder tube gasket	NBR	
54	Cushion valve seal	NBR	

D-□

-X□

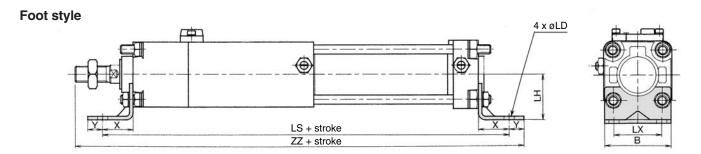






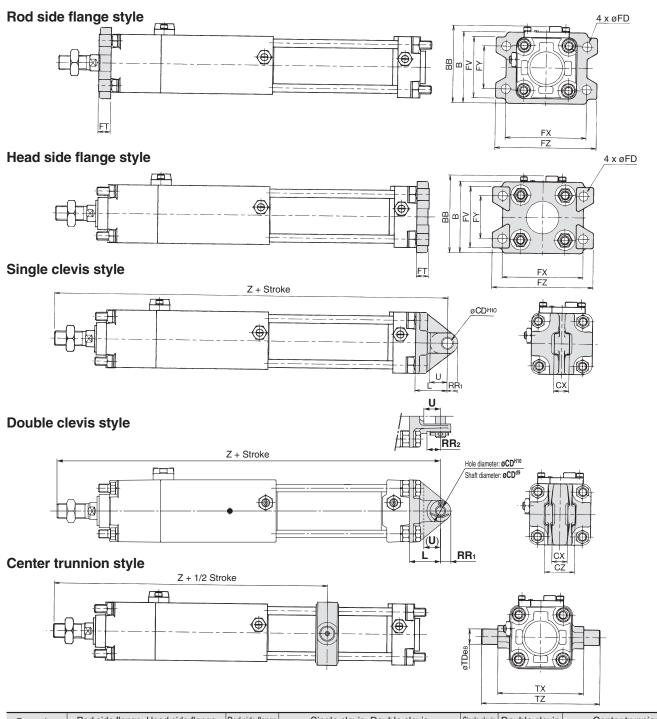
(mm) Stroke range Bore size (mm) BB BL □B С CC C DD D EF EE Ε F FF GA GB GC GD GL М Without rod boot With rod boot 25 to 850 | 25 to 700 71.5 11.5 150.5 M8 x 1.25 25 to 800 25 to 650 80.5 28.5 10.5 10 12 162.5 M8 x 1.25 25 to 800 | 25 to 650 98.5 48.5 28.5 13.5 17 26 67 11 M10 x 1.25 9 14 15.5 25 to 750 | 25 to 600 117.5 21 30 13 M12 x 1.75 11 17 78 26.5 37 | 131.5 | 41 | 116 | 56.5 | 92 35.5 15.5 52 14 198 21 31 76 25 16 M12 x 1.75 11 17 25 to 750 | 25 to 600

Dava siza (mm)	ММ	N N	NN	D	s	W	Without rod boot		With rod boot					
Bore size (mm)	IVIIVI			F	0	VV	Н	ZZ	е	f	h	e	ZZ	
40	M14 x 1.5	27	161.5	1/4	218.5	8	51	280.5	43	11.2	59	1/4	288.5	
50	M18 x 1.5	30	175.5	3/8	235.5	0	58	304.5	52	11.2	66		312.5	
63	M18 x 1.5	31	187	3/8	254	0	58	326	52	11.2	66	1/4	334	
80	M22 x 1.5	37	205	1/2	284	0	71	372	65	12.5	80	stroke	381	
100	M26 x 1.5	40	214	1/2	300	0	72	389	65	14	81		398	



								(mm)
Bore size (mm)	В	LH	LS	LX	Х	Υ	ZZ	LD
40	58.5	40	272.5	42	27	13	309.5	9
50	68.5	45	289.5	50	27	13	333.5	9
63	83	50	322	59	34	16	362	11.5
80	100	65	372	76	44	16	415	13.5
100	114	75	386	92	43	17	432	13.5

Stroke Reading Cylinder with Brake Series CE2



															-		IZ	-			(mm)
Bore size	Bore size Rod side flange, Head side flang				ange	Rod side flange Single clevis, Double clevis					Single clevis	Double	clevis	С	enter tr	unnion					
(mm)	FT	FV	FX	FY	FZ	FD	В	BB	CDH10	L	RR ₁	RR ₂	U	Z	СХ	СХ	CZ	TDe8	TX	TZ	Z
40	12	60	80	42	100	9	71	77	10 +0.058	30	10	16	16	299.5	15-0.1	15+0.3	29.5	15 -0.032	85	117	227.5
50	12	70	90	50	110	9	81	86	12 +0.070	35	12	19	19	328.5	18-0.1	18+0.3	38	15 -0.032	95	127	248.5
63	15	86	105	59	130	11.5	101	107	16 +0.070	40	16	23	23	352	25 -0.1	25 ^{+0.3} _{+0.1}	49	18 -0.032	110	148	263
80	18	102	130	76	160	13.5	119	126	20 +0.084	48	20	28	28	403	31.5 -0.1	31.5 +0.3 +0.1	61	25 -0.040	140	192	297
100	18	116	150	92	180	13.5	133	140	25 +0.084	58	25	23.5	36	430	35.5 =0.1	35.5 +0.3	64	25 -0.040	162	214	309

Mounting Bracket Part No.

Bore size (mm)	40	50	63	80	100
Foot *	CA1-L04	CA1-L05	CA1-L06	CA1-L08	CA1-L10
Flange	CA1-F04	CA1-F05	CA1-F06	CA1-F08	CA1-F10
Single clevis	CA1-C04	CA1-C05	CA1-C06	CA1-C08	CA1-C10
Double clevis **	CA1-D04	CA1-D05	CA1-D06	CA1-D08	CA1-D10

* When ordering foot style brackets, 2 pcs. should be ordered for each cylinder. ** Clevis pin, flat washer and cotter pin are shipped together with double clevis style.



CEP1

CE₁

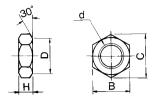
CE2

ML2B

D-□

-X□

Accessory Dimensions: Rod End Nut

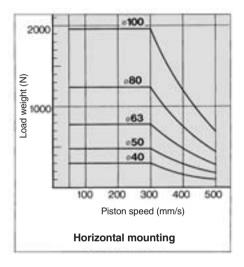


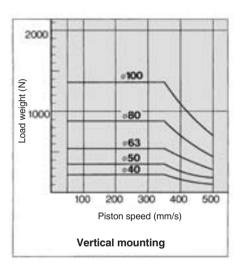
Material: Rolled steel

Part no.	Applicable bore size (mm)	d	н	В	С	D
NT-04	40	M14 x 1.5	8	22	25.4	21
NT-05	50, 63	M18 x 1.5	11	27	31.2	26
NT-08	80	M22 x 1.5	13	32	37.0	31
NT-10	100	M26 x 1.5	16	41	47.3	39

Allowable Kinetic Energy

Operate the stroke reading cylinder with brake within the proper allowable kinetic energy. It must not be operated out of the allowable range, which is shown in the graph on the right. All sizes must be operated within this range. (Supply pressure 0.5 MPa)





CEP1

CE1

....

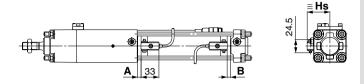
ML2B

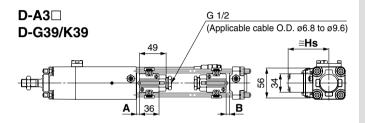
D-□

-**X**□

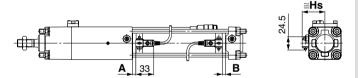
Auto Switch Proper Mounting Position (Detection at Stroke End) and Its Mounting Height

<Band mounting> D-B5□/B64/B59W

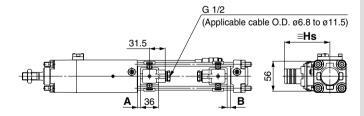




D-G5□/K59 D-G5 W/K59W D-G5BAL D-G59F/G5NTL



D-A44



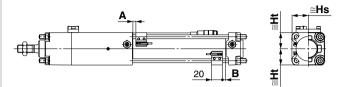
<Tie-rod mounting>

D-A9□/**A9**□**V** D-Z7□/Z80

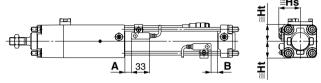
D-M9□/M9□V D-Y59 - /Y69 - /Y7P/Y7PV

D-M9□W/M9□WV D-Y7□W/Y7□WV

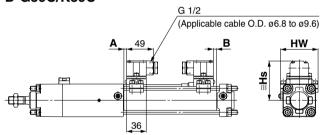
D-M9□AL/M9□AVL **D-Y7BAL**



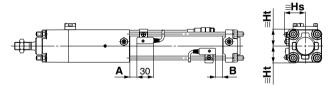
D-A5□/**A6**□ **D-A59W**

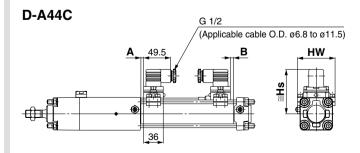


D-A3□C D-G39C/K39C



D-F5□/J5□ **D-F5NTL** D-F5 W/J59W D-F5BAL/F59F





Auto Switch Proper Mounting Position (Detection at Stroke End) and Its Mounting Height

Auto Switch Proper Mounting Position

(mm)

Auto switch model		D-A9□ D-A9□V		D-M9□ D-M9□V D-M9□W D-M9□WV D-M9□AL D-M9□AVL		D-B59W D-Z7□ D-Z80 D-Y59□ D-Y69□ D-Y7P D-Y7PV D-Y7□W D-Y7□WV D-Y7□WV		D-A5□ D-A6□ D-A3□ D-A3□C D-A44 D-A44C D-G39 D-G39C D-K39 D-K39		85□ 864	D-F5□ D-J5□ D-F59F D-F5□W D-J59W D-F5BAL		D-G5 D-K5 D-G5 D-G5 D-K5 D-G5	9 NTL S□W S9W SBAL	D-A59W		D-F5NTL	
(mm)	Α	В	Α	В	Α	В	Α	В	Α	В	Α	В	Α	В	Α	В	Α	В
40	6	4	10	8	3.5	1.5	0	0	0.5	0	6.5	4.5	2	0	4	2	11.5	9.5
50	-	_	10	8	3.5	1.5	0	0	0.5	0	6.5	4.5	2	0	4	2	11.5	9.5
63	8.5	7.5	12.5	11.5	6	5	2.5	1.5	3	2	9	8	4.5	3.5	6.5	5.5	14	13
80	12	10	16	14	9.5	7.5	6	4	6.5	4.5	4.5	12.5	8	6	10	8	17.5	15.5
100	13.5	12.5	17.5	16.5	11	10	7.5	6.5	8	7	14	13	9.5	8.5	11.5	10.5	19	18

^{*} D-A9□ and D-A9□V cannot be mounted on ø50.

Auto Switch Mounting Height

(mm)

Bore size		□ □ W	D-AS	P□V	D-M90 D-M90 D-M90	□WV	D-Z7 D-Z8 D-Y5 D-Y7 D-Y7	0 59□ ′P ′BAL	D-Y6 D-Y7 D-Y7	PV	D-B5 D-B64	D-A3□ D-G39 D-K39	D-A44	D-A D-A D-A	6□	D-F5 D-J5 D-J5 D-F5 D-F5	59 5□W 59W 5BAL 59F	D-A: D-G: D-K:	39C	D-A	44C
(mm) \	Hs	Ht	Hs	Ht	Hs	Ht	Hs	Ht	Hs	Ht	Hs	Hs	Hs	Hs	Ht	Hs	Ht	Hs	Hw	Hs	Hw
40	30	30	32	30	35	30	30	30	30.5	30	38	72.5	80.5	40	31	38.5	31	73	69	81	69
50	34	34	36.5	34	39	34	34	34	35	34	43.5	78	86	43.5	35	42.5	35	78.5	77	86.5	77
63	41	41	43.5	41	46	41	41	41	42.5	41	50.5	85	93	49	42	48	42	85.5	91	93.5	91
80	49.5	49	51.5	49	54	49	49.5	48.5	51	48.5	59	93.5	101.5	55.5	50	54	50	94	107	102	107
100	57	56	59.5	56	62.5	56	58.5	56	59	56	69.5	104	112	63	57.5	62	57.5	104	121	112	121

^{*} D-A9 \square and D-A9 $\square V$ cannot be mounted on ø50.

CE1

CE1

CE2

ML2B





Note) Adjust the auto switch after confirming the operating conditions in the actual setting.

Minimum Auto Switch Mounting Stroke

		1				n: No. of	auto switches (mm)
Auto switch model	No. of auto switch mounted	Mounting brackets other than center trunnion	ø 40	ø 50	Center trunnion Ø63	ø 80	ø100
	2 (Different surfaces, Same surface) 1	15	75	200	80	85	90
D-A9 □	n	$15 + 40 \frac{(n-2)}{2}$	_	_		$85 + 40 \frac{(n-4)}{2}$	
	2 (Different surfaces,	(n = 2, 4, 6, 8 ···)	(n = 4, 8, 12, 16 ···)		(n = 4, 8, 12, 16 ···)	(n = 4, 8, 12, 16 ···)	(n = 4, 8, 12, 16 ···)
D-A9□V	Same surface) 1	$10 + 30 \frac{(n-2)}{2}$	$50 + 30 \frac{(n-4)}{2}$	_	55 + 30 (n - 4)	$60 + 30 \frac{(n-4)}{2}$	$65 + 30 \frac{(n-4)}{2}$
	2 (Different surfaces,	(n = 2, 4, 6, 8 ···)	(n = 4, 8, 12, 16 ···)			(n = 4, 8, 12, 16 ···)	(n = 4, 8, 12, 16 ···)
D-M9□ D-M9□W	Same surface) 1	15		80 (n – 4)	85	90	95
D-INI9 W	n	$15 + 40 \frac{(n-2)}{2}$ $(n = 2, 4, 6, 8 \cdots)$	80 + 40 (n = 4, 8,		$85 + 40 \frac{\sqrt{2}}{2}$ (n = 4, 8, 12, 16 ···)	$90 + 40 \frac{(n-4)}{2}$ (n = 4, 8, 12, 16 ···)	$95 + 40 \frac{1}{2}$ (n = 4, 8, 12, 16 ···)
D-M9□V	2 (Different surfaces, Same surface) 1	10		55	60	65	70
D-M9□WV	n	$10 + 30 \frac{(n-2)}{2}$ $(n = 2, 4, 6, 8 \cdots)$	55 + 30 (n = 4, 8,	_	$60 + 30 \frac{(n-4)}{2}$ $(n = 4, 8, 12, 16 \cdots)$	$65 + 30 \frac{(n-4)}{2}$ (n = 4, 8, 12, 16 ···)	$70 + 30 \frac{(n-4)}{2}$ (n = 4, 8, 12, 16 ···)
D MODAL	2 (Different surfaces, Same surface) 1	15	80		85	95	100
D-M9□AL	n	$15 + 40 \frac{(n-2)}{2}$ $(n = 2, 4, 6, 8 \cdots)$	80 + 40 (n = 4, 8,)	$85 + 40 \frac{(n-4)}{2}$ (n = 4, 8, 12. 16 ···)	$95 + 40 \frac{(n-4)}{2}$ (n = 4, 8, 12, 16 ···)	$100 + 40 \frac{(n-4)}{2}$ (n = 4, 8, 12, 16 ···)
	2 (Different surfaces, Same surface) 1	10	, , ,	60	65	70	75
D-M9□AVL	n	$10 + 30 \frac{(n-2)}{2}$ $(n = 2, 4, 6, 8 \cdots)$	60 + 30 (n = 4, 8,) (n - 4) 2 12 16)		$70 + 30 \frac{(n-4)}{2}$ (n = 4, 8, 12, 16 ···)	
D-A5□/A6 D-F5□/J5	2 (Different surfaces, Same surface) 1	15	, , ,	90	100	110	120
D-F5□W/J59W D-F5BAL/F59F	n (Same surface)	$15 + 55 \frac{(n-2)}{2}$ $(n = 2, 4, 6, 8 \cdots)$	90 + 55 (n = 4, 8,	_	$100 + 55 \frac{(n-4)}{2}$ $(n = 4, 8, 12, 16 \cdots)$	$110 + 55 \frac{(n-4)}{2}$ (n = 4, 8, 12, 16 ···)	
	2 (Different surfaces, Same surface)	20	,	90	100	110	120
D-A59W	n (Same surface)	20 + 55 (n - 2)	90 + 55		$100 + 55 \frac{(n-4)}{2}$	$110 + 55 \frac{(n-4)}{2}$	$120 + 55 \frac{(n-4)}{2}$
	1	(n = 2, 4, 6, 8 ···) 15	(n = 4, 8,	12, 16 ···) 90	(n = 4, 8, 12, 16 ···) 100	(n = 4, 8, 12, 16 ···) 110	(n = 4, 8, 12, 16 ···) 120
D-F5NTL	2 (Different surfaces, Same surface) 1	25		10	120	130	140
BTONTE	n (Same surface)	$25 + 55 \frac{(n-2)}{2}$ $(n = 2, 4, 6, 8 \cdots)$	110 + 5 (n = 4, 8,	55 <u>(n – 4)</u> 12, 16 ···)	$120 + 55 \frac{(n-4)}{2}$ $(n = 4, 8, 12, 16 \cdots)$	$130 + 55 \frac{(n-4)}{2}$ (n = 4, 8, 12, 16 ···)	
D-B5□/B64	2 (Different surfaces) (Same surface)	15 75	!	90	100	11	10
D-G5□/K59 D-G5□W	(Different surfaces)	$15 + 50 \frac{(n-2)}{2}$		0 (n - 4)	$100 + 50 \frac{(n-4)}{2}$	110 + 50	
D-K59W D-G5BAL	n (Same surface)	$(n = 2, 4, 6, 8, \cdots)$ 75 + 50(n - 2)	(n = 4, 8, 90 + 5)	12, 16, ···) 0(n – 2)	$(n = 4, 8, 12, 16, \cdots)$ 100 + 50(n - 2)	(n = 4, 8, 110 + 5	
D-G59F D-G5NTL	1	(n = 2, 3, 4, ···)	·	, 6, 8, ···) 90	(n = 2, 4, 6, 8, ···)	(n = 2, 4,	
	2 (Different surfaces)			90	100	11	
	(Same surface)	$75 \\ 20 + 50 \frac{(n-2)}{2}$		0 (n - 4) 2	$100 + 50 \frac{(n-4)}{2}$	110 + 50	
D-B59W	(Different surfaces)	$(n = 2, 4, 6, 8, \cdots)$ 75 + 50(n - 2)	(n = 4, 8,	0 2 12, 16, ···) 0(n – 2)	$\begin{array}{c} 100 + 30 & 2 \\ (n = 4, 8, 12, 16, \cdots) \\ \hline 100 + 50(n - 2) \end{array}$	(n = 4, 8, 110 + 5	12, 16, …)
	(Same surface)	(n = 2, 3, 4, ···)	(n = 2, 4	, 6, 8, ···) 90	(n = 2, 4, 6, 8, ···)	(n = 2, 4,	6, 8,)
	(Different surfaces)	35		75	80		90
	(Same surface)	100 35 + 30(n – 2)		00 0(n – 2)	100 80 + 30(n – 2)	90 + 30	00 0(n 2)
D-A3□ D-G39	(Different surfaces)	(n = 2, 3, 4, ···)		, 6, 8, ···)	(n = 2, 4, 6, 8, ···)	90 + 30 (n = 2, 4)	, ,
D-K39	(Same surface)	100 + 100(n - 2) (n = 2, 3, 4, ···)			100 + 100(n - 2) (n = 2, 4, 6, 8, ···)		
	1	10		75	80	9	90
	2 (Different surfaces) (Same surface)	35 55		75	80	,	90
D-A44	(Different surfaces)	35 + 30(n - 2) (n = 2, 3, 4, ···)	(n = 2, 4	0(n – 2) , 6, 8, ···)	80 + 30(n - 2) (n = 2, 4, 6, 8, ···)	90 + 30 (n = 2, 4	6, 8,)
	(Same surface)	55 + 50(n - 2) (n = 2, 3, 4, ···)		0(n – 2) , 6, 8, ···)	80 + 50(n - 2) (n = 2, 4, 6, 8, ···)	90 + 50 (n = 2, 4,	, ,
	1	10		75	80	(90

Stroke Reading Cylinder with Brake Series CE2

Minimum Auto Switch Mounting Stroke

							n: No. of	auto switches (mm)
Auto switch model			Mounting brackets other			Center trunnion		
Auto switch model	S	witch mounted	than center trunnion	ø 40	ø 50	ø 63	ø 80	ø 100
	2	(Different surfaces)	20		75	80		90
	-	(Same surface)	100	1	00	100	1	00
D-A3□C		(5)"	20 + 35(n - 2)	75 + 35	5(n – 2)	80 + 35(n - 2)	90 + 35	5(n – 2)
D-G39C	_	(Different surfaces)	(n = 2, 3, 4, ···)	(n = 2, 4,	, 6, 8,)	(n = 2, 4, 6, 8, ···)	(n = 2, 4,	, 6, 8,)
D-K39C	n	(Cama aurifaga)	100 + 100(n - 2)			100 + 100(n - 2)		
		(Same surface)	(n = 2, 3, 4, 5 ···)			(n = 2, 4, 6, 8, ···)		
		1	10	-	75	80	(90
	2	(Different surfaces)	20		75	80		90
	Ľ	(Same surface)	55	'	75	80	,	30
		(Different surfaces)	20 + 35(n - 2)	75 + 35	5(n – 2)	80 + 35(n - 2)	90 + 35	5(n – 2)
D-A44C	<u>_</u>	(Dillerent Surfaces)	(n = 2, 3, 4, ···)	(n = 2, 4	, 6, 8,)	(n = 2, 4, 6, 8, ···)	(n = 2, 4	, 6, 8,)
	n n		55 + 50(n - 2)	75 + 50	O(n – 2)	80 + 50(n - 2)	90 + 50	0(n – 2)
	(Same surface)		(n = 2, 3, 4, ···)	(n = 2, 4	, 6, 8,)	(n = 2, 4, 6, 8, ···)	(n = 2, 4	, 6, 8,)
		1	10	-	75	80	(90
D-Z7□/Z80		Different surfaces, Same surface) 1	15	80	85	90	95	105
D-Y59□/Y7P D-Y7□W		n	_	_	$85 + 40 \frac{(n-4)}{2}$	_	_	$105 + 40\frac{(n-4)}{2}$
			(n = 2, 4, 6, 8 ···)	(n = 4, 8, 12, 16 ···)	(n = 4, 8, 12, 16 ···)	(n = 4, 8, 12, 16 ···)	(n = 4, 8, 12, 16 ···)	(n = 4, 8, 12, 16 ···)
D-Y69□/Y7PV	١,	Different surfaces, Same surface) 1	10	•	35	75	80	90
D-Y7□WV		n	$10 + 30 \frac{(n-2)}{2}$		0 <u>(n - 4)</u>	$75 + 30\frac{(n-4)}{2}$	_	$90 + 30 \frac{(n-4)}{2}$
			(n = 2, 4, 6, 8 ···)	(n = 4, 8,	12, 16 ···)	(n = 4, 8, 12, 16 ···)	(n = 4, 8, 12, 16 ···)	(n = 4, 8, 12, 16 ···)
		Different surfaces, Same surface) 1	20	9	95	100	105	110
D-Y7BAL		n	20 + 45 \frac{(n-2)}{2}		5 (n - 4) 2	_	105 + 45 (n - 4) 2	-
			(n = 2, 4, 6, 8 ···)	(n = 4, 8,	12, 16 ···)	(n = 4, 8, 12, 16 ···)	(n = 4, 8, 12, 16 ···)	(n = 4, 8, 12, 16 ···)

CEP1

CE1

CE2

ML2B



-X□ Individual





Operating Range

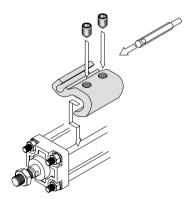
					(mm)					
Auto switch model	Bore size (mm)									
Auto switch model	40	50	63	80	100					
D-A9□/A9□V	7	_	9	9	9					
D-M9□/M9□V D-M9□W/M9□WV D-M9□AL/M9□AVL	5	5	5.5	6	6.5					
D-Z7□/Z80	8	7	9	9.5	10.5					
D-A3□/A44 D-A3□C/A44C D-A5□/A6□ D-B5□/B64	9	10	11	11	11					
D-A59W	13	13	14	14	15					
D-B59W	14	14	17	16	18					

					(mm)
Auto switch model		Bore	e size (r	nm)	
Auto switch model	40	50	63	80	100
D-Y59□/Y69□ D-Y7P/Y7□V D-Y7□W/Y7□WV D-Y7BAL	8	7	5.5	6.5	6.5
D-F5□/J5□/F5□W D-J59W/F5BAL D-F5NTL D-F59F	4	4	4.5	4.5	4.5
D-G5□/K59/G5□W D-K59W/G5BAL D-G5NTL/G59F	5	6	6.5	6.5	7
D-G39/K39 D-G39C/K39C	9	9	10	10	11

Auto Switch Mounting Bracket: Part No.

<Tie-rod mounting>

		В	ore size (mn	n)	
Auto switch model	40	50	63	80	100
D-A9□/A9□V D-M9□/M9□V D-M9□W/M9□WV D-M9□AL/M9□AVL	BA7-040	BA7-040	BA7-063	BA7-080	BA7-080
D-A5□/A6□ D-A59W D-F5□/J5□ D-F5□W/J59W D-F59F/F5NTL	BT-04	BT-04	BT-06	BT-08	BT-08
D-A3 C/A44C D-G39C/K39C	BA3-040	BA3-050	BA3-063	BA3-080	BA3-100
D-Z7□/Z80 D-Y59□/Y69□ D-Y7P/Y7PV D-Y7□W/Y7□WV D-Y7BAL	BA4-040	BA4-040	BA4-063	BA4-080	BA4-080



Mounting example of D-A9□(V)/M9□(V)/M9□W(V)/M9□A(V)L

<Band mounting>

A	Bore size (mm)										
Auto switch model	40	50	63	80	100						
D-A3□/A44 D-G39/K39	BD1-04M	BD1-05M	BD1-06M	BD1-08M	BD1-10M						
D-B5□/B64 D-B59W D-G5□/K59 D-G5□W/K59W D-G59F D-G5NTL	BA-04	BA-05	BA-06	BA-08	BA-10						

Note 1) D-A9 \square and D-A9 \square V cannot be mounted on ø50.

Note 2) Auto switch mounting brackets are included in D-A3 C/A44C/G39C/K39C.

Order them in accordance with the cylinder size as shown below.

(Example) ø40: D-A3□C-4, ø50: D-A3□C-5

ø63: D-A3□C-6, ø80: D-A3□C-8, ø100: D-A3□C-10

Order them with the part numbers above when the mounting brackets are required separately.

[Mounting screw set made of stainless steel]

The following set of mounting screws made of stainless steel (including nuts) is available. Use it in accordance with the operating environment.

(Please order the auto switch mounting bracket and band separately, since they are not included.)

BBA1: For D-A5/A6/F5/J5 types

BBA3: For D-B5/B6/G5/K5 types

D-F5BAL/G5BAL auto switches are set on the cylinder with the stainless steel screws above when shipped. When an auto switch is shipped independently, BBA1 or BBA3 is attached.

Note 3) Refer to pages 1813 and 1821 for the details of BBA1 and BBA3.

Note 4) When using M9□A(V)L/Y7BAL, do not use the steel set screws which is included with the auto switch mounting brackets above (BA7-□□□, BA4-□□□). Order a stainless steel screw set (BBA1) separately, and select and use the M4 x 6L stainless steel set screws included in the BBA1.



^{*} D-A9□ and D-A9□V cannot be mounted on ø50.

^{*} Since the operating range is provided as a guideline including hysteresis, it cannot be guaranteed (assuming approximately

^{± 30%} dispersion). It may vary substantially depending on an ambient environment.

Besides the models listed in How to Order, the following auto switches are applicable. Refer to pages 1719 to 1827 for detailed specifications.

Auto switch type	Part no.	Electrical entry (Fetching direction)	Features
Reed	D-A93V, A96V	Crommet (Dernendieuler)	_
	D-A90V	Grommet (Perpendicular)	Without indicator light
	D-A53, A56, B53, Z73, Z76	Grommet (In-line)	_
	D-A67, Z80	aronimot (iii iiiio)	Without indicator light
Solid state	D-M9NV, M9PV, M9BV	- Grommet (Perpendicular)	_
	D-Y69A, Y69B, Y7PV		
	D-M9NWV, M9PWV, M9BWV		Diagnostic indication
	D-Y7NWV, Y7PWV, Y7BWV		(2-color indication)
	D-M9NAVL, M9PAVL, M9BAVL		Water resistant (2-color indication)
	D-Y59A, Y59B, Y7P		_
	D-F59, F5P, J59	Grommet (In-line)	
	D-Y7NW, Y7PW, Y7BW		Diagnostic indication
	D-F59W, F5PW, J59W		(2-color indication)
	D-F5BAL, Y7BAL		Water resistant (2-color indication)
	D-F5NTL, G5NTL		With timer

^{*} For solid state auto switches, auto switches with a pre-wired connector are also available. Refer to pages 1784 and 1785 for details.

* Wide range detection type, solid state auto switches (D-G5NBL type) are also available. Refer to page 1776 for details.

CEP1

CE1

CE2

ML2B



-X□



^{*} Normally closed (NC = b contact) solid state auto switches (D-F9G/F9H/Y7G/Y7H types) are also available. Refer to pages 1746 and 1748 for details.

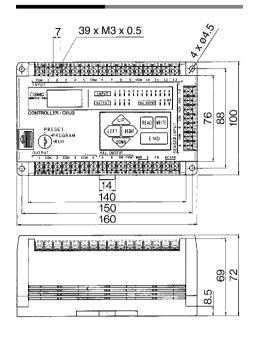
CEU2 Controller

Controller CEU2/Specifications

Model	CEU2	CEU2P	
Туре	Controller		
Mounting	Surface mounting (DIN rail or screw stop)		
Operation mode	PRESET mode, PROGRAM mode, RUN mode		
Display system	LCD (with back light)		
No. of digits	Program 1 to 16, Step 1 to 32		
Position control system	P.T.P control (point to point)		
No. of control shaft	1 axis		
Positioning system	Key input (on front face)		
Positioning range	9999.9 mm		
Min. setting range	0.1 mm		
Memory system	Static RAM 8 K bite (Battery back up: life 5 years)		
Min. interval	5 mm or more		
Input signal	● Start ● Return to origin ● Program selection (4 bit) ● Hold ● Emergency stop ● Input origin ● Automatic/Manual ● Manual: extended, retracted (2 bit) ● Reset		
Output signal		Completion to figure out origin signalAbnormal signal	
Control output	NPN open collector (30 VDC, 50 mA)	PNP open collector (30 VDC, 50 mA)	
Counting speed	20 kHz (kcps)		
Power supply	90 to 110 VAC, 50/60 Hz and 21.6 to 26.4 VDC, 0.4 A		
Operating temperature range	0 to 50°C (No freezing)		
Humidity range	25 to 85% (No condensation)		
Shock resistance	Endurance 10 to 55 Hz, Amplitude 0.75 mm, X, Y, Z for 2 hours each		
Noise resistance	Square wave noise from a noise simulator (Pulse duration 1 μs) Between 100 VAC line ±1500 V, I/O line ±600 V		
Impact resistance	Endurance 10 G; X, Y, Z directions, 3 times each		
	Between case and AC line: 1500 VAC for 1 min. (3 mA or less)		
Withstand voltage	Between case and 12 VDC line: 500 VAC for 1 min. (3 mA or less)		
Power consumption	100 VA or less		
rower consumption	100 VA	or less	
Insulation resistance		: 500 VDC, 50 MΩ or more	

\ast Refer to operation manual of CEU2 regarding detailed positioning system.

Dimensions



As for 3 point preset counter and multi counter, it will be common to CEP1 and CE1 series. For details, refer to 3 point preset counter/CEU1 on page 1470, and Multi counter/CEU5 on page 1467 respectively.



Wiring with External Equipment

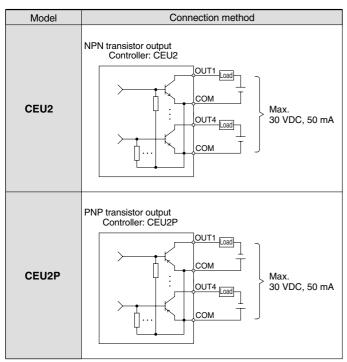
<Wiring with controller CEU2>

1. Wiring of driving power of controller

To operate the controller, use a power supply with the following specifications: 90 to 110 VAC, 50/60 Hz, and 21.6 to 26.4 VDC, 0.4 A or higher.

3. Output circuit

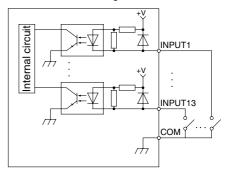
There are two outputs, the NPN open collector and the PNP open collector. The maximum rating is 30 VDC, 50 mA. Operating the controller by exceeding this voltage and amperage could damage the electric circuit. Therefore, the equipment to be connected must be below this rating.



* However, on the valve output side, the COM of the input circuit and the COM of the output circuit are electrically insulated from each other.

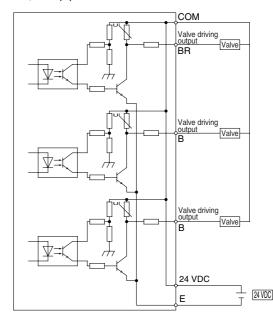
2. Input circuit

The voltage and the amperage capacity of the switch or the PLC to be connected are 24 VDC, 10 mA or higher.



4. Valve output circuit

The maximum rating is 24 VDC, 80 mA. Operating the controller by exceeding this voltage and amperage could damage the electric circuit. Therefore, the equipment to be connected must be below this rating.



CEP1

CE1

CE2

ML2B

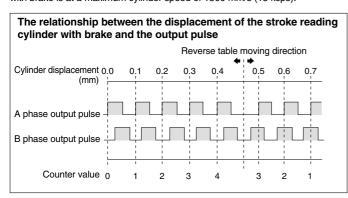
Electrical Wiring

<Output system of positioning detection sensor>

The position detection sensor of the stroke reading cylinder outputs an A/B phase difference (open collector output) as shown in the diagram below.

The relation between the moving distance and the output signal of the stroke reading cylinder with brake is as follows: Every 0.1 mm of movement of the stroke reading cylinder with brake outputs 1 pulse signal to both output terminals A and B.

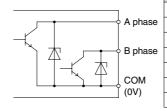
The maximum response speed of the sensor for the stroke reading cylinder with brake is at a maximum cylinder speed of 1500 mm/s (15 kcps).



<Input, Output>

The connection of the input/output signals of the position detection sensor of the stroke reading cylinder is effected through the connector that extends from the cylinder. The output circuit and the connection of the connectors are described in the diagram below.

Output circuit of stroke reading cylinder with brake



Signal

Contact signal	Wire color	Signal name
Α	White	A phase
В	Yellow	B phase
С	Brown	COM (0 V)
D	Blue	COM (0 V)
E	Red	+12 V to 24 V
F	Black	0 V
G	_	Shield

Connector pin arrangement



