Stroke Reading Cylinder and Counter

Series CE







9

P. 1444

Series CE1

ø12, ø20, ø32, ø40

ø50, ø63

P. 1454

Stroke Reading

Cylinder







Individual

CEP1

CE1

CE₂

ML2B

P. 1470

Achieve rationalization

Stroke reading cylinder

Measurement is possible throughout the full stroke range.

The home position can be anywhere — When the counter is reset by pressing within the cylinder stroke.

the cylinder rod to the reference plane, that point becomes the home position.

Can be used in an environment where the product is exposed to fluids (water, oil, coolant, etc.)

(3 mounting surfaces)

Stroke Reading Cylinder (CE1)

High Precision Stroke Reading Cylinder (CEP1)

• Special scraper now standard (IP-67)

• Power supply voltage 12 to 24 VDC

• Resolution: 0.01 mm (Accuracy ±0.02 mm)

• 2 types of seal material available (Made to Order)

Auto switch mounting orientation can be freely selected

Series CE1 Special order (with scraper) *

Series CEP1 With special scraper as standard * The standard type of Series CE1 does not come with a scraper. Contact SMC since cylinders with a scraper are special orders.

of production lines with position feedback



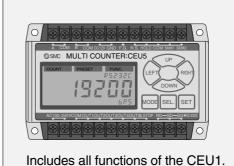
Tolerances of preset values can be set. (CEU1, CEU5)

Tolerances can be set for preset values.

CEU1: ± set tolerance

CEU5: + set tolerance, – set tolerance (separate settings)

Simple operation



Multi-counter (CEU5)

- Output terminal: 5 points
- · Number of output settings: 20 points (Bank switching) 31 points (Binary output)
- Communication function with RS-232C
- With BCD output (Option)
- Maximum counting speed 100 kHz
- Prescale function
- With multiplication switching
- (1, 2, 4 multiplication) • DIN rail mountable
- 6 digits count display

3-point Preset Counter (CEU1) · Output terminal: 3 points • DIN rail mountable

· Hold output, Comparison output, One shot output

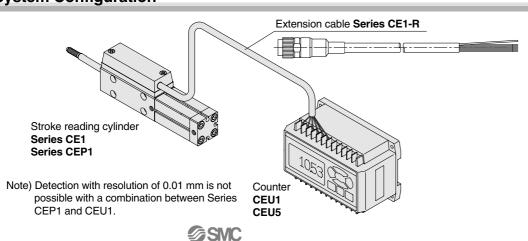
When used in an environment where the product is exposed to fluids (water, oil, coolant, etc.), the reading cylinder with a scraper is available as a special order. Contact SMC for details. (Except ø12, ø20)

Power supply voltage 12 to 24 VDC

• Resolution: 0.1 mm (Accuracy ±0.2 mm)

- · Abundant stroke variations
- · Improved noise resistance

System Configuration



Series Variations

Series CE1

CEU1

Bore size		Standard stroke (mm)											Manufacturable*
(mm)	25	50	75	100	125	150	175	200	250	300	400	500	stroke range
12	•	•	•	•	•	•							25 to 150
20	•	•	•	•	•	•	•	•					25 to 300
32		•	•	•	•	•	•	•	•	•			25 to 400
40				•	•	•	•	•	•	•	•	•	25 to 600
50								•		•		•	25 to 600
63								•		•		•	25 to 600

Output transistor Power mode supply voltage	NPN	PNP
100 VAC	•	
24 VDC	•	•

CEU₅

Output transi	RS-232	C+BCD	RS-2	232C
Output transistor mode supply voltage	NPN	PNP	NPN	PNP
100 to 240 VAC	•	•	•	•
24 VDC	•	•	•	•

Series CEP1

Bore size	Stan	dard s	troke	Manufacturable		
(mm)	25	50		100	stroke range	
12 equivalent	•	•	•	•	1 to 150	
20 equivalent	•	•	•	•	1 to 300	

^{*} Strokes other than standard strokes are available upon request. Consult with SMC separately

Extension Cable

Cable length (m)									
5	10	15	20						
•	•	•	•						





CEP1

CE2

ML2B

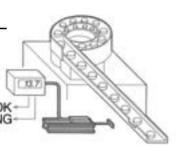


Series CE

Application Examples

Parts inspection

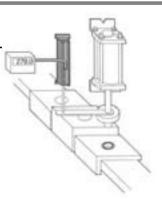
Measures the dimensions of parts, discriminates between good and defective articles, and prevents the mingling of different parts, etc.



Confirmation of press-in

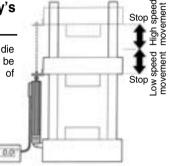
Can confirm the press-in of a hydraulic cylinder by detecting its stroke.

Even if the size of the workpiece changes, the point of press-in completion can be easily changed.



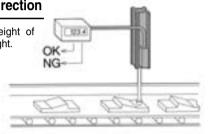
Detection of die assembly's deceleration point

Since the deceleration point of the die assembly can be set at will, it can be easily changed after replacement of the die assembly.



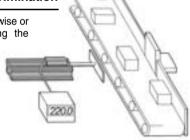
Discrimination of direction

Maintains a constant height of measuring workpiece height.



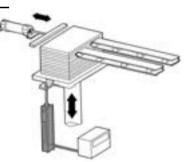
Length/breadth discrimination

Distinguishes either lengthwise or crosswise while correcting the position of a workpiece.



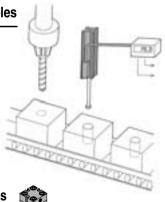
Detection of lifter position

Can continuously monitor a lifter's stroke.



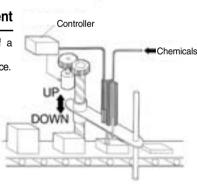
Inspection of machined holes

Can detect machined hole depth, burrs and foreign matter, etc.



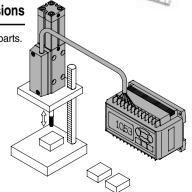
Nozzle height adjustment

Maintains a certain height of a workpiece and a nozzle by measuring the height of a workpiece.



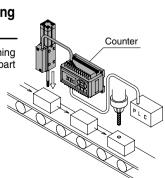
Measurement of dimensions

Can measure dimensions of parts.



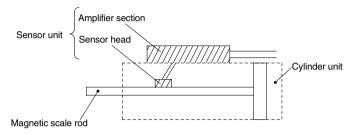
Measurement of machining dimensions

Performs adjustment of machining depth, etc. by measuring the part dimensions before machining.

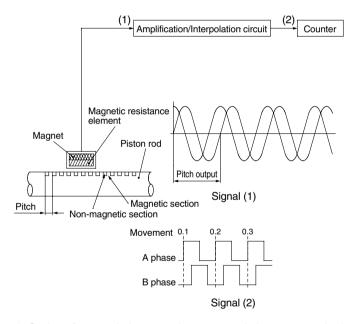


Measurement Principle

The amount of rod movement in the stroke reading cylinder is detected using an MR element (magnetic resistance element) whose resistance value changes due to magnetic force. The detection unit containing this MR element is called the sensor head. An amplifying circuit and a dividing circuit are required to produce output which can be read by the counter, and these are attached to the cylinder case. The sensor head and amplifier section together are referred to as the sensor unit.



The stroke reading cylinder is equipped with the capability of outputting the piston stroke movement as a pulse signal. The measurement principle is as shown in the drawing below.



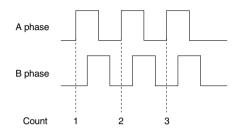
- **1.** Scales of magnetic layers and non-magnetic layers are etched at a certain pitch on the piston rod.
- With movement of the piston rod, a sin, cos 2-phase signal (Signal (1)) is received by the magnetic resistance element. For this wave form, 1 pitch (0.8 mm) becomes exactly 1 cycle.
- This is amplified and divided into 1/8 parts. As a result, a 90° phase difference pulse signal of 0.1 mm/pulse (Signal (2)) is output.
- **4.** By measuring this pulse signal with the counter, it is possible to detect the piston position with a resolution of 0.1 mm.
- **5.** In the case of the high precision stroke reading cylinder, the sin, cos 2-phase signal obtained in 2 is amplified and divided into 1/20 parts. As a result, a 90° phase difference pulse signal of 0.04 mm/pulse (Signal (2)) is output.
- 6. By multiplying this pulse signal by 4 with the counter, it is possible to detect the piston position with a resolution of 0.01 mm.

A/B Phase Difference Output (90° phase difference output)

When movement is expressed by a single line of pulses, it is impossible to accurately identify the current position, because pulse waves appear in both upward and downward directions.

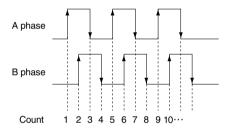
Accordingly, in A/B phase difference output, two lines of pulses are provided, wherein one line detects the movement and the other distinguishes the direction.

The CE1 also employs this system.



4 Times Multiplication Function

This function increases resolution 4 times by counting 4 for each cycle of pulses, instead of counting 1 for each cycle as is normally the case. In principle, this function counts each time there is a rise or fall in either of the A or B phase pulses.



CEP1

CE2

ML2B

Counting Speed (kHz, kcps)

Counting speed indicates the number of pulses that can be counted per second. If the stroke reading cylinder is operated at high speeds, pulse waves are output in shorter cycles. The counting speed of the counter must be higher than the pulse speed for the maximum piston speed when operating. Since the stroke reading cylinder outputs one pulse for each 0.1 mm of movement, 5,000 pulses will be output for each 500 mm of movement. Therefore, a speed of 500 mm/s is equivalent to 5 kcps (kHz), but a counting speed 2 to 3 times greater is recommended for actual operation.

Accuracy

The accuracy is the difference between the dimensions based upon the signals of the stroke reading cylinder and the absolute dimensions.

The maximum display error that will appear on the counter's digital display is equal to twice (± 1 count) the resolution when the home position is reset and when dimensions are measured.



-X□





Series CE Specific Product Precautions

Be sure to read before handling.

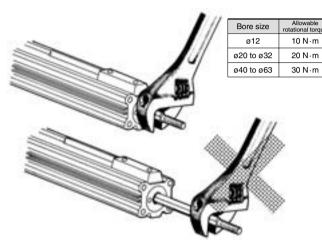
Refer to front matters 42 and 43 for Safety Instructions and pages 3 to 11 for Actuator and Auto Switch Precautions.

⚠ Caution

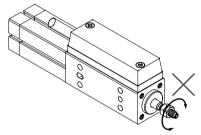
Mounting

1. When screwing a nut or fitting, etc. onto the threaded section at the end of the piston rod, return the piston rod to its fully retracted position, and grasp the exposed portion of the rod across two parallel sides with a wrench. In the case of the high precision stroke reading cylinder, there are no parallel sides. Secure the workpiece with a double nut.

Note) Do not apply rotational torque to the piston rod.



- Operate the cylinder in such a way that the load is always applied in the axial direction.
 - In case the load is applied in a direction other than the axial direction of the cylinder, provide a guide to constrain the load itself.
 - When mounting a cylinder, centering should be done carefully.
- Avoid using the air cylinder in such a way that rotational torque would be applied to the piston rod.



Be careful to avoid scratches or dents, etc. on the sliding sections of the piston rod.

Sensor Unit

- The sensor unit is adjusted to an appropriate position at the time of shipment. Therefore, never detach the sensor unit from the body.
- 2. The cylinder should be protected from contact with liquids such as coolants or coolant water. Do not use in an environment where the unit is exposed to fluids. (CE1, CE2, ML2)
- 3. The sensor cable should not be pulled with a strong force.
- 4. Since the sensor for stroke reading cylinder adopts the magnetic method, it may result in malfunction if there is a strong magnetic field around the sensor. Use it under the external magnetic field with 14.5 mT or less.

This is equivalent to a magnetic field of approximately 18 cm in radius from a welding area using a welding amperage of almost 15,000 amperes. To use the system in a magnetic field that exceeds this value, use a magnetic material to shield the sensor unit.

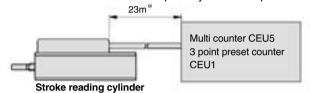
Switches or relays, etc. should not be installed in the power supply line (12 to 24 VDC).

⚠ Caution

Effects of Noise

When the stroke reading cylinder is used near a motor, welding machine or other source of noise generation, there is a possibility of miscounting. In this case, noise should be suppressed as much as possible and the following countermeasure should be taken.

- 1. Connect the shield wire to FG (flame ground).
- The maximum transmission distance for the stroke reading cylinder is 23 m, but since the output signal is a pulse output, the sensor cable should be wired separately from other power lines.

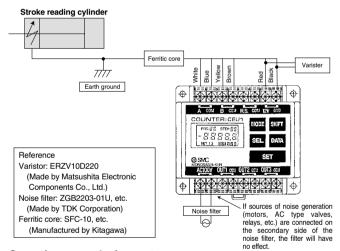


* When using SMC extension cable and counter.

Noise Counter Measures

Methods of dealing with noise are given below.

- 1. Connect only the shield wire to FG (frame ground).
- Use a power source separate from large motors and AC valves, etc.
- Run the stroke reading cylinder's cable away from other power lines.
- 4. Install a noise filter in the 100 VAC power line, a varistor in the DC power supply of the sensor cable and a ferritic core in the signal line (sensor cable).



<Counting speed of counter>

When the speed of the stroke reading cylinder is greater than the counting speed of the counter, the counter will miscount.

For CE1 (when measuring to 0.1 mm), a counter should be used with a counting speed of 10 kHz (kcps) or more.

And for CEP1 (when measuring to 0.01 mm), use a counter with a counting speed of 50 kHz (kcps) or more when 4 times multiplication is input.

<Malfunction due to lurching and bounding>

When lurching or bounding occurs at the beginning or end of stroke reading cylinder, or due to other causes, the cylinder speed momentarily increases, and there is a possibility of exceeding the counting speed of the counter or the response speed of the sensor, thereby causing a miscount.

Handling of Technical Material

The instruction manuals should be read before using the Series CEP1 high precision stroke reading cylinder, CEU5 multi counter, CE1 scale cylinder and CEU1 3 point preset counter.



CEP1

CE1

CE2

ML2B

High Precision Stroke Reading Cylinder Non-rotating Piston Type

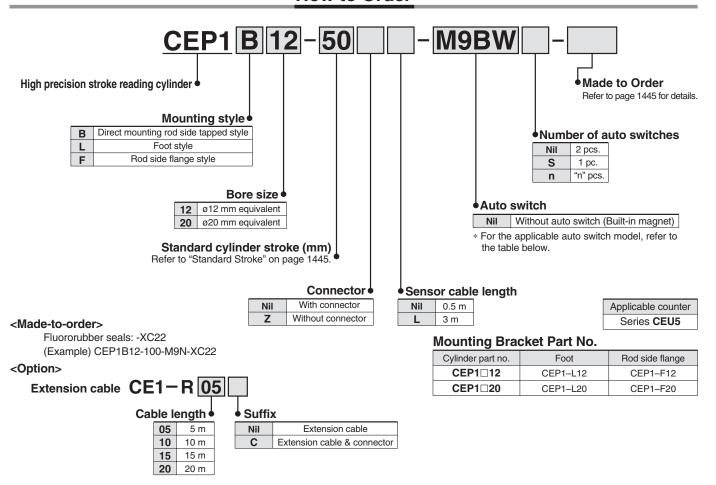
Series CEP1

ø12, ø20



Note) CE compliant: When connecting to a multi-counter (CEU5□□-D, power supply voltage 24 VDC). Refer to the multi-counter operation manual for details.

How to Order



Applicable Auto Switch/Refer to pages 1719 to 1827 for further information on auto switches.

	Fig			VA/:::::	Lo	oad volta	ıge	Auto swit	ch model	Lead wi	re le	ngth	(m)	Pre-wired						
Туре	Type Special function	Electrical entry	Indicator light	Wiring (Output)	D	С	AC	Perpendicular	In-line	0.5 (Nil)	1 (M)	3 (L)		connector	Applical	ble load				
				3-wire (NPN)	5 V. 12 V	, M9NV	M9N	•			0	0	10 -:							
뜻				3-wire (PNP)		5 V, 12 V		M9PV	M9P	•			0	0	IC circuit					
switch				2-wire		12 V		M9BV	M9B	•			0	0	_					
S	Dia ana atia in dia atian			3-wire (NPN)		E V 10 V		M9NWV	M9NW	•	•	•	0	0	10 -:	Delevi				
state	Diagnostic indication	(2-color indication) Grommet	Grommet (es	3-wire (PNP) 24 V	5 V, 12 V	_	M9PWV	M9PW	•			0	0	IC circuit	Relay, PLC				
st	(2-color indication)		_	2-wire				M9BWV	M9BW	•	•		0	0	_	0				
Solid	Matau aa alatau t					3-wire (NPN)		5 V, 12 V	V 10 V	**M9NAV	**M9NA	0	0		0	0	IC circuit			
So	Water resistant (2-color indication)			3-wire (PNP)		5 V, 12 V		**M9PAV	**M9PA	0	0		0	0	IC CITCUIT					
	(2-color malcation)			2-wire		12 V		**M9BAV	**M9BA	0	0		0	0	_					
witch	Reed switch		Grommet >	Grommet >	,es	3-wire (NPN equivalent)	_	5 V	_	A96V	A96	•	_	•	_	_	IC circuit	_		
ed s		—— Grommet					2 wire 04		24.1/	04.1/ 10.1/	100 V	A93V	A93	•	_		_	_	_	Relay,
æ					2	2-wire	24 V	12 V	100 V or less	A90V	A90	•	_		_	_	IC circuit	PLĆ		

^{**} Water resistant type auto switches can be mounted on the above models, but in such case SMC cannot guarantee water resistance. Consult with SMC regarding water resistant types with the above model numbers.

* Lead wire length symbols: 0.5 m Nil (Example) M9NW

1 m ······· M (Example) M9NWM

3 m ······· L (Example) M9NWL

5 m ······· Z (Example) M9NWZ

- * Solid state auto switches marked with "O" are produced upon receipt of order.
- * Refer to page 1452 for details on other applicable auto switches than listed above.
- * For details about auto switches with pre-wired connector, refer to pages 1784 and 1785.
- * Auto switches are shipped together (not assembled).



High Precision Stroke Reading Cylinder Non-rotating Piston Type Series CEP1

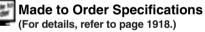
Cylinder Specifications



Action	Double acting, Single rod (Non-rotating piston)						
Fluid	Air						
Proof pressure		mPa					
Maximum operating pressure	1.0 MPa						
	ø12	ø20					
Minimum operating pressure	0.15 MPa	0.1 MPa					
Piston speed	50 to 30	00 mm/s					
Ambient and fluid temperature	0 to 60°C (No freezing)						
Lubrication	Non-lube						
Stroke length tolerance range	0 to +1	1.0 mm					
Cushion	With	hout					
Rod non-rotating accuracy	ø12	ø20					
nou non-rotating accuracy	±2°	±3°					
Mounting	Direct mounting rod side tapped style (Standard), Foot style, Rod side flange style						

JIS Symbol





	(
Symbol	Specifications
—XC22	Fluororubber seals

Sensor Specifications

2.11	
Cable	ø7, 6 core twisted pair shielded wire (Oil, Heat & Flame resistant)
Maximum transmission distance	23 m (when using SMC cable and counter)
Position detection method	Magnetic scale rod, sensor head < Incremental type>
Magnetic field resistance	14.5 mT
Power supply	10.8 to 26.4 VDC (Power supply ripple: 1% or less)
Current consumption	50 mA
Resolution	0.01 mm (With 4 times multiplication)
Accuracy	±0.02 mm ⁽¹⁾ (at 20°C)
Output type	Open collector (24 VDC, 40 mA)
Output signal	A/B phase difference output
Insulation resistance	500 VDC, 50 M Ω or more (between case and 12E)
Vibration resistance	33.3 Hz 6.8 G 2 hrs. each in X, Y directions 4 hrs. in Z direction based upon JIS D 1601
Impact resistance	30 G 3 times each in X, Y, Z directions
Enclosure	IP-67 (IEC Standard)(2)
Extension Cable (Option)	CE1-R* 5 m, 10 m, 15 m, 20 m

Note 1) This includes the digital display error of the counter (CEU5).

When strokes are over 100 mm, accuracy is ± 0.05 mm.

Moreover, the overall accuracy after mounting on equipment will vary depending on mounting conditions and the environment. Therefore, the customer should calibrate the equipment as a whole.

Note 2) Except for the connector, the cylinder section is the equivalent of an SMC water resistant cylinder.

Cylinder Stroke

		Standard s	troke (mm)		Manufacturable	
Model	25	50	75	100	stroke range	
CEP1B12	•	•	•	•	1 to 150	
CEP1B20	•	•	•	•	1 to 300	

 $[\]ast$ Strokes other than standard strokes are available upon request for special. Consult with SMC separately.



-X□

CEP1

CE₁

CE2

ML2B



Mass (Without mounting bracket/connector)

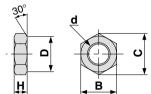
				(kg)
Bore size		Cylinder st	roke (mm)	
(mm)	25	50	75	100
12	0.29	0.33	0.37	0.41
20	0.62	0.68	0.74	0.80

Auto Switch Proper Mounting Position

Regarding dimensions for the auto switch proper mounting position (at stroke end), refer to page 1452.

Rod End Nut Dimensions

(2 pcs. are attached as standard.)



Material ø12, 20: Steel

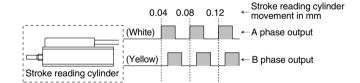
					(mm)
Applicable bore size (mm)	d	Н	В	С	D
12	M5 x 0.8	3	8	9.2	7.8
20	M8 x 1.25	5	13	15.0	12.5

Electrical Wiring

Output type

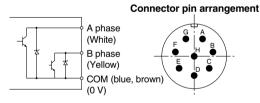
The output signal of the high precision stroke reading cylinder is A/B phase difference output (open collector output) as shown in the figure below.

The relation between the movement distance and the signal output of the high precision stroke reading cylinder is that for each 0.04 mm of movement a one pulse signal is output to both output terminals A and B. In order to measure with a discrimination of 0.01 mm, a counter with a 4 times multiplication function (CEU5) is required.



Input/Output

The input/output of the stroke reading cylinder is performed by a Ø7 shielded twisted pair wire from the sensor section plus a connector.



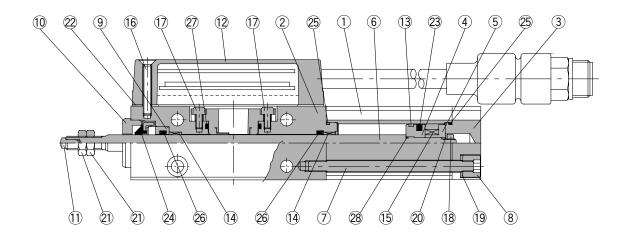
Output circuit of stroke reading cylinder

Signal

Contact signal	Wire color	Signal name			
Α	White	A phase			
В	Yellow	B phase			
С	Brown COM (0				
D	Blue	COM (0 V)			
E	Red	+12 to 24 V			
F	Black	0 V			
G	_	Shield			

Construction

ø12, ø20



Component Parts

No.	Description	Material	Note
1	Cylinder tube	Aluminum alloy	Hard anodized
2	Rod cover	Aluminum alloy	Hard chrome plated
3	Head cover	Aluminum alloy	Hard anodized
4	Piston A	Aluminum alloy	Hard anodized
5	Piston B	Aluminum alloy	Hard anodized
6	Piston rod	Carbon steel	Hard chrome plated
7	Tie-rod	Carbon steel	Chromated
8	Tie-rod nut	Carbon steel	Chromated
9	Seal ring	Aluminum alloy	White anodized
10	Centering location ring	Aluminum alloy	White anodized
11	Rod end pin	Stainless steel	Quenched
12	Sensor unit	_	With or without connector
13	Wear ring	Special resin	
14	Bushing	Cast iron	

Component Parts

CUI	Component Faits											
No.	Description	Material	Note									
15	Magnet	_										
16	Cross recessed countersunk head screw	Chromium molybdenum steel	Chromated									
17	Hexagon socket head cap screw	Stainless steel										
18	Hexagon nut	Carbon steel	Chromated									
19	Spring washer	Steel wire	Chromated									
20	Spring washer	Steel wire	Chromated									
21	Hexagon nut	Carbon steel	Rod end nut									
22	Sensor case gasket	NBR										
23	Piston seal	NBR										
24	Scraper	NBR										
25	Tube gasket	NBR										
26	Rod seal	NBR										
27	O-ring	NBR										
28	O-ring	NBR										

^{*} Since there is a possibility of improper operation, please contact SMC regarding the replacement of seals.

CEP1

CE1

CE2

ML2B

D-□

-X□

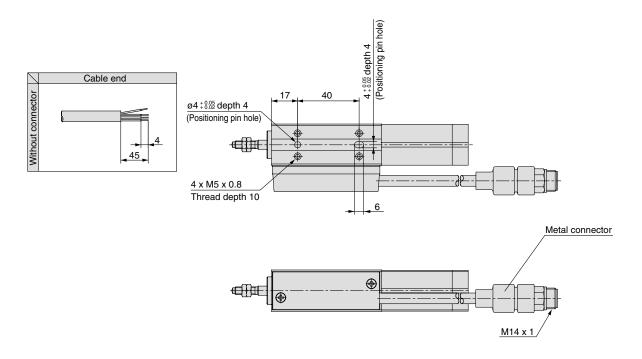


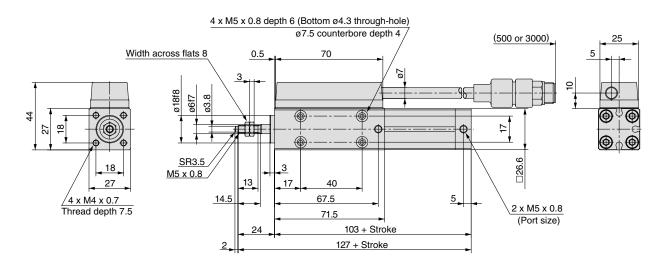
Series CEP1

Dimensions: Ø12

Direct mounting, rod side tapped style:

CEP1B12 - Stroke

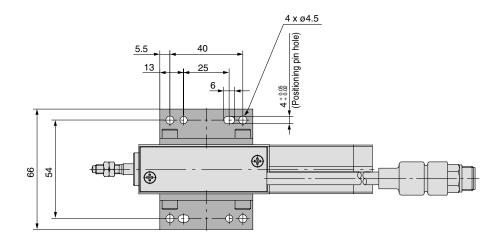


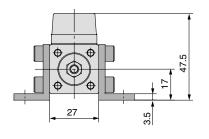


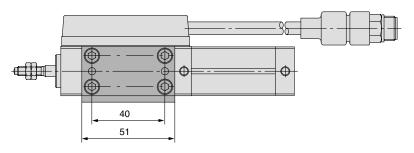
High Precision Stroke Reading Cylinder Non-rotating Piston Type Series CEP1

Foot style:

CEP1L12 - Stroke

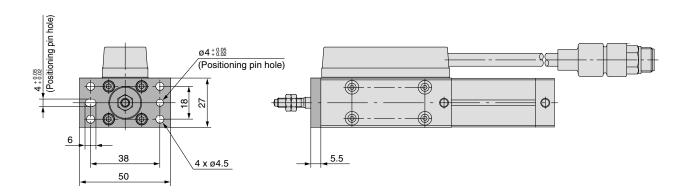






Rod side flange style:

CEP1F12 - Stroke



D-□

CEP1

CE1

CE2

ML2B

-X□

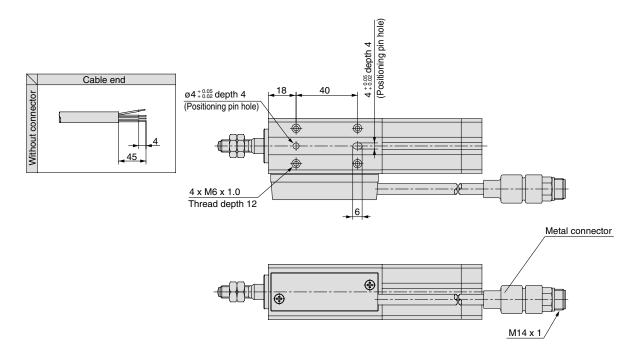


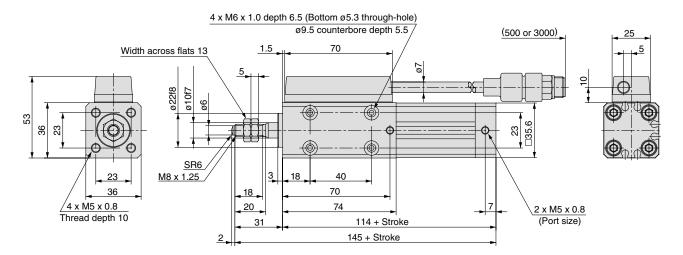
Series CEP1

Dimensions: Ø20

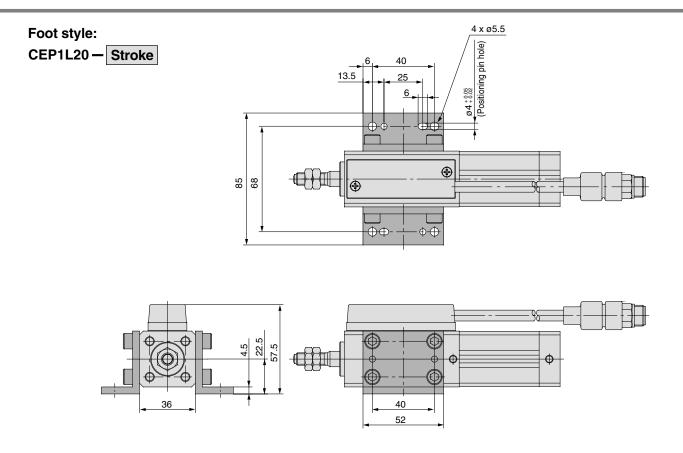
Direct mounting, rod side tapped style:

CEP1B20 — Stroke



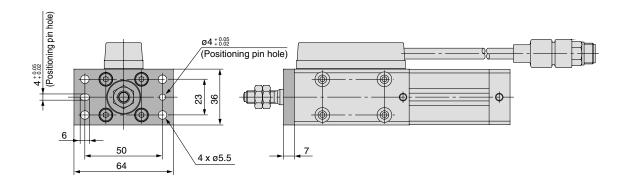


High Precision Stroke Reading Cylinder Non-rotating Piston Type Series CEP1



Rod side flange style:

CEP1F20 - Stroke



D-□

-X□

CEP1

CE1

CE2

ML2B



Series CEP1

Auto Switch Proper Mounting Position (Detection at Stroke End)

Auto switch A B

Auto Switch Proper Mounting Position (mm)

nate evitor i reper mounting i estitor (min)											
Auto switch model	D-A		D-M9 D-M9 D-M9 D-M9 D-M9	□V □W □WV							
Bore size \	Α	В	Α	В							
12	75	8	79	12							
20	82	12	86	16							

Note) Adjust the auto switch after confirming the operating conditions in the actual setting.

Operating Range

(mm)

		()				
A	Bore size					
Auto switch model	12	20				
D-A9□/A9□V	6	10				
D-M9□/M9□V D-M9□W/M9□WV D-M9□AL/M9□AVL	3	4				

^{*} Since the operating range is provided as a guideline including hysteresis, it cannot be guaranteed (assuming approximately ±30% dispersion). It may vary substantially depending on an ambient environment.

Other than the models listed in "How to Order", the following auto switches are applicable.

^{*} For solid state auto switches, auto switches with a pre-wired connector are also available. Refer to pages 1784 and 1785 for details.

^{*} Normally closed (NC = b contact), solid state auto switch (D-F9G/F9H type) are also available. For details, refer to page 1746.

CEP1

CE1

CE2

ML2B

-X□

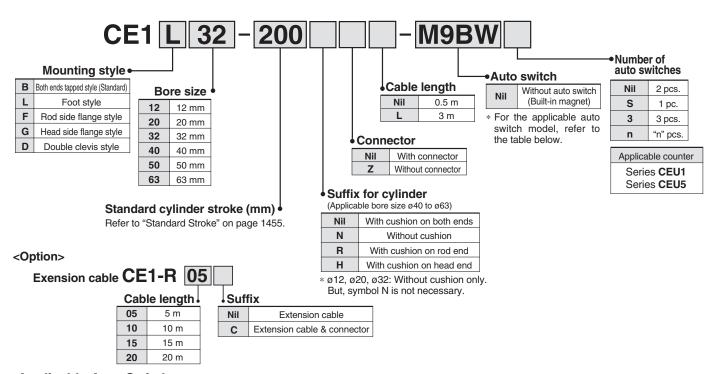


Stroke Reading Cylinder Series CE1 ø12, ø20, ø32, ø40, ø50, ø63



Note) CE compliant: When connecting to a 3-point preset counter (CEU1□-D, power supply voltage 24 VDC) and a multicounter (CEU5□□-D, power supply voltage 24 VDC). Refer to the counter operation manual for details.

How to Order



Applicable Auto Switch/Refer to pages 1719 to 1827 for further information on auto switches

API	Applicable Auto Switch/Hefer to pages 1/19 to 1827 for further information on auto switches.																															
		Electrical	light	VA/inim m	L	oad vol	tage	Auto swit	ch model	Lea	iw b	e ler	ngth	(m)	Pre-wired																	
Туре	Special function	entry	Indicator light	Wiring (Output)	С	C	AC	Perpendicular	In-line	0.5 (Nil)	1 (M)	3 (L)		None (N)	connector	Applical	ble load															
				3-wire (NPN)		5 V,		M9NV	M9N	•	•	•	0	_	0	10 -:																
		Grommet	Grommet		3-wire (PNP)		12 V		M9PV	M9P				0	_	0	IC circuit															
switch				2-wire		10.1/		M9BV	M9B			•	0	_	0																	
× it		Connector		2-WIIE		12 V		J79C	_		_				_																	
	Diagnostic indication			3-wire (NPN)		5 V,		M9NWV	M9NW	•			0	_	0	IC circuit	Relay,															
state	Diagnostic indication	olor indication) Grommet	×				Φ	3-wire (PNP)	24 V	12 V	_	M9PWV	M9PW				0	_	0	IO CIICUIL	PLC											
<u> </u>	(2-color iridication)											2-wire		12 V		M9BWV	M9BW	•	•		0	_	0		- = 0							
Solid	Water registent				3-wire (NPN)		5 V,		M9NAV**	M9NA**	0	0		0	_	0	IC circuit															
Š	(2-color indication)				3-wire (PNP)		12 V		M9PAV**	M9PA**	0	0		0	_	0	IC Circuit															
	,			2-wire		12 V		M9BAV**	M9BA**	0	0		0	_	0	_																
	With diagnostic output (2-color indication)			4-wire		5 V, 12 V			F79F	•	_		0	_	0	IC circuit																
ے			s	3-wire (NPN equivalent)	_	5 V	_	A96V	A96	•	_	•	_	_	_	IC circuit	_															
switch		Grommet	Yes			_	200 V	A72	A72H		_		_	_	_																	
S						12 V	100 V	A93V	A93		_		_	_	_																	
Ø	Connector	8	2-wire		5 V, 12 V	100 V or less	A90V	A90		_		_	_	_	IC circuit	Relay,																
Reed		Connector		Cannagtar		Connector		2-wile	24 V	12 V	_	A73C	_	•				•	_		PLĆ											
_		COLLIGECTOL	2]]]	l l				1	1		<u> </u>	5 V, 12 V	24 V or less	A80C	_	•		•	•	•	_	IC circuit	
	Diagnostic indication (2-color indication)	Grommet	Yes				_	_	A79W	_							_															

- ** Water resistant type auto switches can be mounted on the above models, but in such case SMC cannot guarantee water resistance. Consult with SMC regarding water resistant types with the above model numbers.
- * Lead wire length symbols: 0.5 m Nil (Example) M9NW 1 m M
 - (Example) M9NWM (Example) M9NWL (Example) M9NWZ
 - None ······· N (Example) J79CN
- * Refer to page 1466 for details on other applicable auto switches than listed above.
- *For details about auto switches with pre-wired connector, refer to pages 1784 and 1785.

 * When D-A9□(V)/M9□(V)/M9□W(V)/M9□A(V)L types with ø32 to ø63 are mounted on a side other than the port side, order auto switch mounting brackets. separately. Refer to page 1465 for details.

* Solid state auto switches marked with "O" are produced upon receipt of order.

- * Auto switches are shipped together (not assembled).
- * A9 and A9 V cannot be used with products with a bore size of ø12.



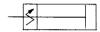
Stroke Reading Cylinder Series CE1

Cylinder Specifications



Fluid	Air						
Proof pressure	1.5 MPa						
Maximum operating pressure		1.0 N	л Ра				
Minimum operating pressure	ø12			ø20 to ø63			
willing pressure	0.07 MPa	0.05 MPa					
Piston speed		70 to 50	0 mm/s				
Ambient and fluid temperature	() to 60°C (N	No freezing)				
Humidity	25 to 85% RH (No condensation)						
Lubrication		Non-	lube				
Stroke length tolerance range	ø12, ø20: ⁺	1.0 0	ø32,	ø40, ø50, ø63: +1.6			
With Air cushion	ø12, ø20, ø32····	None	ø40,	ø50, ø63With			
Rod non-rotating accuracy	ø12	ø2	20	ø32, ø40, ø50, ø63			
riod non-rotating accuracy	±2°	±1	0	±0.8°			
Mounting	Both ends tapped style (S	andard), Foo	t style, Flang	e style, Double clevis style			
Auto switch	Reed type, Solid state type						

JIS Symbol



Mounting Bracket Part No.

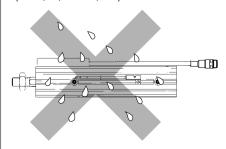
Bore size (mm)	Foot *	Flange	Double clevis
12	CQ-L012	CQ-F012	CQ-D012
20	CQ-L020	CQ-F020	CQ-D020
32	CQ-L032	CQ-F032	CQ-D032
40	CQ-L040	CQ-F040	CQ-D040
50	CQ-L050	CQ-F050	CQ-D050
63	CQ-L063	CQ-F063	CQ-D063

Note 1) When ordering the foot bracket., order 2

pcs. per cylinder.
Note 2) Parts belonging to each bracket are as follows.

Foot, Flange/Body mounting bolts Double clevis/Clevis pin, type C retaining ring for shaft, Body mounting bolts

This cannot be used in an environment where the product is exposed to fluids (water, oil, coolant, etc.).



The reading cylinder with a scraper is available as a special order. Contact SMC for details.

Sensor Specifications

Cable	ø7, 6 core twisted pair shielded wire (Oil, Heat & Flame resistant cable)						
Maximum transmission distance	23 m (when using SM	IC cable and counter)					
Position detection method	Magnetic scale rod <non-rotating></non-rotating>	Sensor head <incremental type=""></incremental>					
Magnetic field resistance	14.5	5 mT					
Power supply	10.8 to 26.4 DC (Power	supply ripple: 1% or less)					
Current consumption	40 mA						
Resolution	0.1 mm/pulse						
Accuracy	±0.2 mm (at 20°C) (1)						
Output type	Open collector (24 VDC, 40 mA)					
Output signal	A/B phase diff	ference output					
Insulation resistance	500 VDC, 50 MΩ or more	e (between case and 12E)					
Vibration resistance	· · · · · · · · · · · · · · · · · · ·	Y directions 4 hrs. in Z direction JIS D 1601					
Impact resistance	30 G 3 times each	in X, Y, Z directions					
Enclosure	IP65 (IEC Standard) (2) Except connector part						
Extension cable (Option)	5 m, 10 m,	15 m, 20 m					

Note 1) This includes the digital display error of the counter (CEU1, CEU5).

Moreover, the overall accuracy after mounting on equipment will vary depending on the mounting conditions and the environment. Therefore, the customer should calibrate the equipment as a whole.

Note 2) The cylinder section does not have a water resistant enclosure.

Cylinder Stroke

Bore size		* Manufacturable											
(mm)	25	50	75	100	125	150	175	200	250	300	400	500	stroke range
12	•	•	•	•	•	•	_	_		_	_		25 to 150
20	•	•	•	•	•	•	•	•	_	_	_	_	25 to 300
32	_	•	•	•	•	•	•	•	•	•	_	_	25 to 400
40	_	_	_	•	•	•	•	•	•	•	•	•	25 to 600
50	_	_	_	_	_	_	_	•	_	•	_	•	25 to 600
63	_	_	_	_	_	_	_	•	_	•	_	•	25 to 600

* Strokes other than standard strokes are available upon request for special. Consult with SMC separately.

Especially, be careful of an eccentric load applied to the rod when the stroke is over 100 mm with a bore size of 12 mm.



-X□

CEP1

CE₁

CE₂

ML2B

Individual



Mass (Without mounting bracket/connector)

												(kg)
Bore size					Cyli	inder st	troke (r	nm)				
(mm)	25	50	75	100	125	150	175	200	250	300	400	500
12	0.29	0.33	0.36	0.4	0.43	0.47	_	_	_		_	_
20	0.51	0.58	0.65	0.72	0.79	0.86	0.93	1.0	_	_	_	_
32	_	0.94	1.05	1.15	1.26	1.36	1.47	1.58	1.79	2.0	_	_
40	_	_	_	1.7	1.83	1.95	2.08	2.2	2.45	2.7	3.2	3.7
50	_	_	_	_	_	_		3.4	_	4.1	_	5.5
63	_	_	_	_	_	_	_	4.2	_	5.0	_	6.6

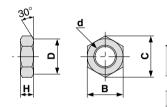
Auto Switch Proper Mounting Position

Regarding dimensions for the auto switch proper mounting position (at stroke end), refer to page 1463.

Rod End Nut Dimensions

(1 pc. is attached as standard.)

Material **ø12**, **20**: Steel **ø32** to **ø63**: Rolled steel



						(mm)
Part no.	Applicable bore size (mm)	d	н	В	С	D
NTJ-015A	12	M5 x 0.8	4	8	9.2	7.8
NT-02	20	M8 x 1.25	5	13	15.0	12.5
NT-04	32 · 40	M14 x 1.5	8	22	25.4	21.0
NT-05	50 · 63	M18 x 1.5	11	27	31.2	26

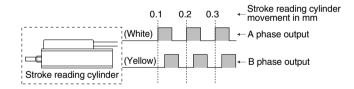
Electrical Wiring

Output type

The output signal of the stroke reading cylinder is A/B phase difference output (open collector output) as shown in the figure below.

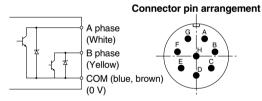
The relation between the movement distance and the signal output of the stroke reading cylinder is that for each 0.1 mm of movement a one pulse signal is output to both output terminals A and B.

Furthermore, the maximum response speed of the sensor for the stroke reading cylinder is at a maximum cylinder speed of 1500 mm/s (15 kcps).



Input/Output

The input/output of the stroke reading cylinder is performed by a Ø7 shielded twisted pair wire from the sensor section plus a connector.



Output circuit of stroke reading cylinder

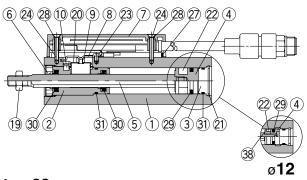
Signal

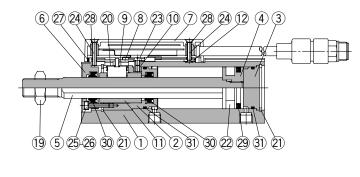
O.g.iai		
Contact signal	Wire color	Signal name
Α	White	A phase
В	Yellow	B phase
С	Brown	COM (0 V)
D	Blue	COM (0 V)
E	Red	+12 to 24 V
F	Black	0 V
G	_	Shield

Construction

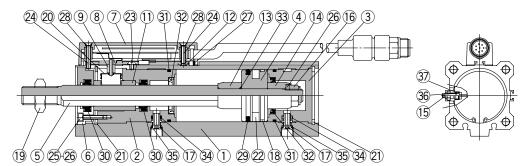
ø**12,** ø**20**

ø**32**





ø40 to ø63



CEP1

CE1

CE2

ML2B

Component Parts

	inponent i di to		
No.	Description	Material	Note
1	Cylinder body	Aluminum alloy	
2	Rod cover	Brass	ø12 to ø20
	Hod cover	Aluminum alloy	ø32 to ø63
3	Head cover	Aluminum alloy	
4	Piston	Aluminum alloy	
5	Piston rod	Stainless steel	
6	Rod cover disk	Aluminum alloy	
7	Sensor unit	_	
8	Sensor setting bracket	Stainless steel	
9	Sensor setting piece assembly	_	ø20 to ø63
10	Pin	Stainless steel	ø12 to ø32
11	Sensor guide	Lead-bronze casted	ø32 to ø63
12	Case setting nut	Carbon steel	ø32 to ø63
13	Cushion ring A	Rolled steel	ø40 to ø63
14	Cushion ring B	Rolled steel	ø40 to ø63
15	Cushion valve		ø40 to ø63
16	Piston nut	Rolled steel	ø40 to ø63
17	Port joint	Stainless steel	ø40 to ø63
18	Wear ring	Resin	ø40 to ø63

Component Parts

COI	iiponeni Faits		
No.	Description	Material	Note
19	Rod end nut	Carbon steel	
20	Sensor setting plate	Cold rolled special steel strip	
21	Type C retaining ring	Carbon steel	
22	Magnet	_	
23	Round head Phillips screw	Carbon steel wire	
24	Cross recessed countersunk head screw	Carbon steel wire	
25	Hexagon socket head cap screw	Chromium molybdenum steel	
26	Spring washer	Steel wire	
27	Case gasket	NBR	
28	Case screw gasket	NBR	
29	Piston seal	NBR	
30	Rod seal	NBR	
31	Gasket	NBR	
32	Cushion seal	NBR	
33	Piston gasket	NBR	
34	Port seal	NBR	
35	Joint seal	NBR	
36	Valve seal	NBR	
37	Valve retainer seal	NBR	
38	Spacer for switch type	Aluminum alloy	ø12
. Cinc	a there is a possibility of improp	or operation places of	ntoot CMC regarding

^{*} Since there is a possibility of improper operation, please contact SMC regarding the replacement of seals.

D-□

-X□ Individual

Individuai •X□

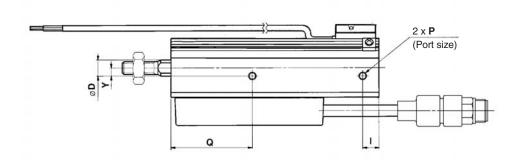


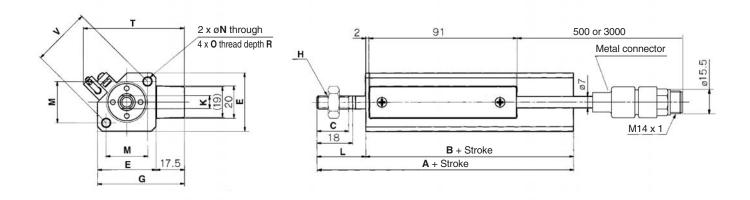
Series CE1

Dimensions: Ø12, Ø20

Both ends tapped style:

CE1B Bore size - Stroke





												(mm)
Bore size (mm)	Standard stroke	Α	В	С	D	E	G	Н	ı	K	L	M
12	25, 50, 75, 100, 125, 150	93.5	69	15	6	25	42.5	M5 x 0.8	16	5.2	24.5	15.5
20	25, 50, 75, 100, 125, 150, 175, 200	106	78	15.5	10	36	53.5	M8 x 1.25	10	8	28	25.5

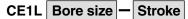
Bore size (mm)	N	0	Р	Q	R	T*	٧	Υ
12	_	M4 x 0.7	M5 x 0.8	47	7	53.5	22	7
20	5.5	M6 x 1	M5 x 0.8	50	15	62.5	36	5

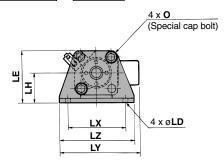
^{*} For rod end nut accessory bracket, refer to page 1456. * Dimensions for auto switch model D-F79W.

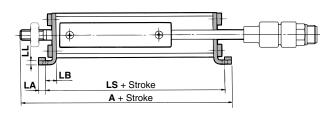


Stroke Reading Cylinder Series CE1

Foot style:

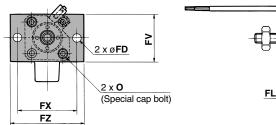


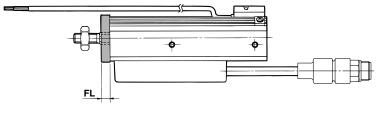




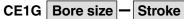
Rod side flange style:

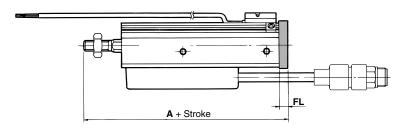
CE1F Bore size — Stroke

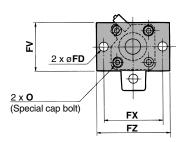




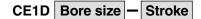
Head side flange style:

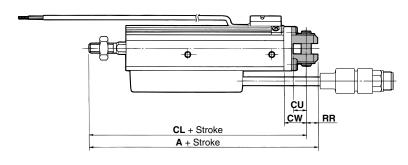


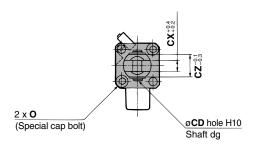




Double clevis style:







(mm)	
(mm)	

Bore size	Common					Fo	ot sty	/le					Rod si	de flan	ge, Hea	ad side	flange	Head side flange			Dou	ıble cl	evis s	tyle		
(mm)	0	Α	LA	LB	LD	LE	LH	LL	LS	LX	LY	LZ	FD	FL	F۷	FX	FZ	Α	Α	CD	CL	CU	CW	СХ	CZ	RR
12	M4 x 0.7	106	4.5	8	4.5	29.5	17	2	85	34	52	44	4.5	5.5	25	45	55	99	113.5	5	107.5	7	14	5	10	6
20	M6 x 1	121	5.8	9.2	6.6	42	24	3.2	96.4	48	66.5	62	6.6	8	39	48	60	114	133	8	124	12	18	8	16	9

CEP1

CE1

CE2

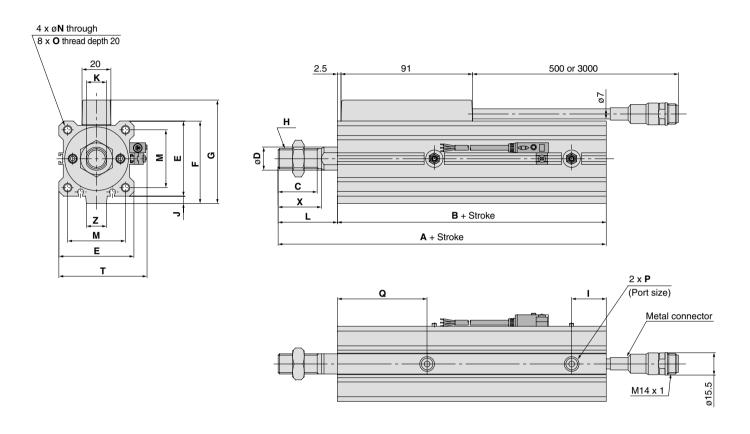
ML2B

Series CE1

Dimensions: Ø32, Ø40, Ø50, Ø63

Both ends tapped style:

CE1B Bore size - Stroke



												(mm)
Bore size (mm)	Standard stroke	Α	В	С	D	E	F	G	Н	I	J	K
32	50, 75, 100, 125, 150, 175, 200, 250, 300	131	90	27	16	45	49.5	64	M14 x 1.5	14	4.5	14
40	100, 125, 150, 175, 200, 250, 300, 400, 500	177	136	27	16	52	57	71.5	M14 x 1.5	24	5	14
50	200, 300, 500	193	144	32	20	64	71	85.5	M18 x 1.5	25.5	7	18
63	200, 300, 500	194	145	32	20	77	84	98.5	M18 x 1.5	21	7	18

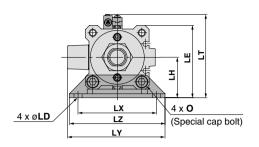
Bore size (mm)	L	М	N	0	Р	Q	T *	Х	Z
32	41	34	5.5	M6 x 1	Rc 1/8	56	57.5	30	14
40	41	40	5.5	M6 x 1	Rc 1/8	62	64.5	30	14
50	49	50	6.6	M8 x 1.25	Rc 1/4	61.5	76.5	35	19
63	49	60	9	M10 x 1.5	Rc 1/4	64	89.5	35	19

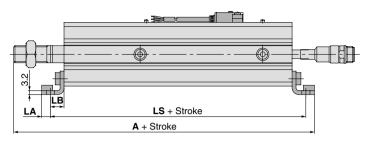
^{*} For rod end nut accessory bracket, refer to page 1456. * Dimensions for auto switch model D-F79W.

Stroke Reading Cylinder Series CE1

Foot style:

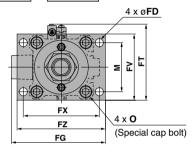
CE1L Bore size - Stroke

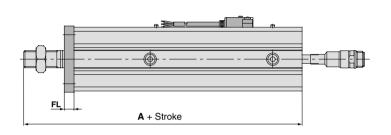




Rod side flange style:

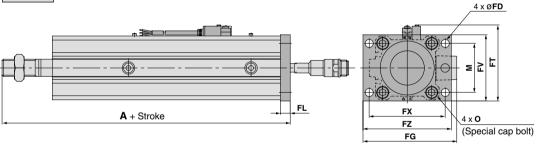
CE1F Bore size - Stroke





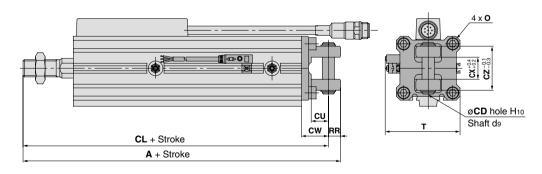
Head side flange style:

CE1G | Bore size | - | Stroke



Double clevis style:

CE1D Bore size — Stroke



																														((mm)
Bore size (mm)	Common					Fo	ot sty	yle					Ro	od sic	le fla	nge,	Head	d side	e flan	ge	Rod side flange	Head side flange			Do	ouble	clev	is sty	/le		
(111111)	0	Α	LA	LB	LD	LE	LH	LS	LT*	LX	LY	LZ	FD	FG	FL	FT*	F۷	FX	FZ	М	Α	Α	Α	CD	CL	CU	CW	СХ	CZ	RR	T
32	M6 x 1	148	5.8	11.2	6.6	52.5	30	112.4	65	57	72.5	71	5.5	69.5	8	59	48	56	65	34	131	139	161	10	151	14	20	18	36	10	57.5
40	M6 x 1	195.2	7	11.2	6.6	59	33	158.4	71.5	64	79.5	78	5.5	76.5	8	65.5	54	62	72	40	177	185	209	10	199	14	22	18	36	10	64.5
50	M8 x 1.25	215.7	8	14.7	9	71	39	173.4	83.5	79	94	95	6.6	91	9	78	67	76	89	50	193	202	235	14	221	20	28	22	44	14	76.5
63	M10 x 1.5	219.2	9	16.2	11	84.5	46	177.4	97	95	109.5	113	9	107	9	91	80	92	108	60	194	203	238	14	224	20	30	22	44	14	89.5
							7014																								

^{*} Dimensions for auto switch model D-F79W.



-X□

CEP1

CE1

CE2

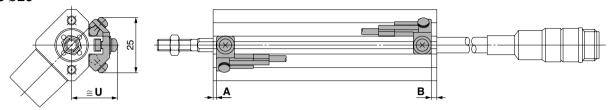
ML2B



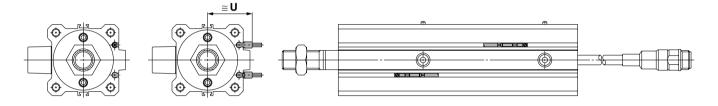
Series CE1

Auto Switch Proper Mounting Position (Detection at Stroke End) and Its Mounting Height

ø12 to ø20

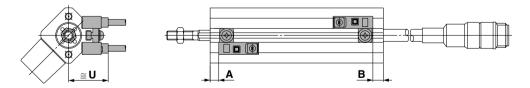


ø32 to ø63

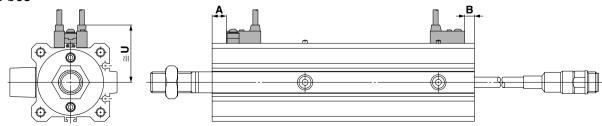


D-A7□ **D-F7NTL D-A80 D-F7BAL** D-A7□H **D-A73C D-A80H D-A80C D-F7**□ **D-J79C D-J79 D-A79W** D-F7□W D-F7□WV D-J7□V **D-J79W D-F7BAVL** D-F79F

ø12 to ø20



ø32 to ø63



Auto Switch Proper Mounting Position (Detection at Stroke End) and Its Mounting Height

Auto Switch Proper Mounting Position

1	

Auto switch model			D-M9 D-M9 D-M9 D-M9 D-M9	V □W □WV		473 480	D-A72/A7 D-A73C/A D-F79F/J D-J79C/F D-J79W/F D-F7BAV	A80C/F7□ 79/F7□V 7□W 7□WV	D-F	7NTL	D-A	79W
(mm)	Α	В	Α	В	Α	В	Α	В	Α	В	Α	В
12	37	5.5	41	9.5	38	6.5	38.5	7	43.5	12	35.5	4.5
20	46	12	50	16	47	13	47.5	13.5	52.5	18.5	44.5	10.5
32	54	16	58	20	55	17	55	17.5	60.5	22.5	52.5	14.5
40	78	38	82	42	79	39	79.5	39.5	84.5	44.5	76.5	36.5
50	81	43	85	47	82	44	82.5	44.5	87.5	49.5	79.5	41.5
63	84.5	40.5	88.5	44.5	85.5	41.5	86	42	91	47	83	39

Note) Adjust the auto switch after confirming the operating conditions in the actual setting.

Auto Switch Mounting Height

(mm

riate enrite	ni moanting							(11111)
Auto switch model Bore size		D-M9□V D-M9□WV D-M9□AVL	D-A7□ D-A80	D-A7□H D-A80H D-F7□ D-J79 D-F7□W D-J79W D-F7BAL D-F79F D-F7NTL	D-A73C D-A80C	D-F7□V D-F7□WV D-F7BAVL	D-J79C	D-A79W
(mm)	U	U	U	U	U	U	U	U
12	20.5	20.5	19.5	20.5	26.5	23	26	22
20	25.5	25.5	24.5	25.5	31.5	28	31	27
32	27	29	31.5	32.5	38.5	35	38	34
40	30.5	32.5	35	36	42	38.5	41.5	37.5
50	36.5	38.5	41	42	48	44.5	47.5	43.5
63	40	42	47.5	48.5	54.5	51	54	50

CEP1

CE1

CE2 ML2B



-X□



^{*} Auto switch mounting brackets BQ2-012 are not used for sizes over ø32 of D-A9□V/M9□V/M9□AVL types. In that case, the above values indicate the operating range when mounted with the conventional auto switch installation groove.

Series CE1

Minimum Auto Switch Mounting Stroke

(mm)

No. of auto switches mounted	D-M9□V D-F7□V D-J79C	D-A9□V D-A7□ D-A80 D-A73C D-A80C	D-A9□	D-M9□WV D-M9□AVL D-F7□WV D-F7BAVL	D-M9□ D-M9□W D-M9□AL D-A7□H D-A80H D-F7□ D-J79	D-A79W	D-F7□W D-J79W D-F7BAL D-F79F D-F7NTL
1 pc.	5	5	10	10	15	15	20
2 pcs.		10	10	15	15	20	20

Operating Range

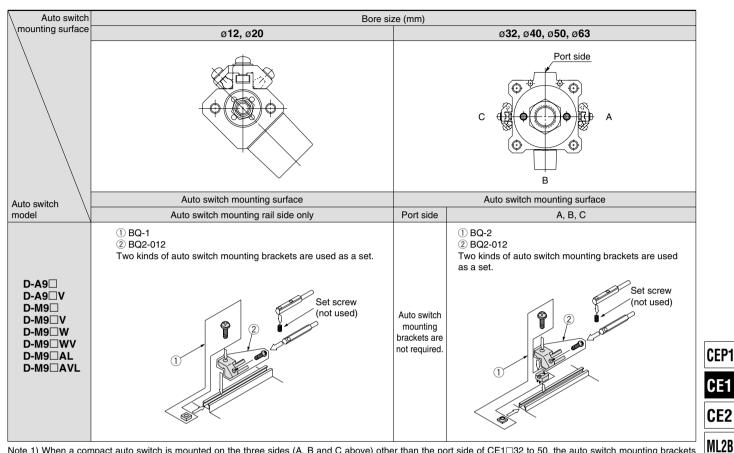
(mm)

Auto switch model		Bore size (mm)							
Auto Switch model	12	20	32	40	50	63			
D-A9□ (V)	7	9	9.5	9.5	9.5	11.5			
D-M9□ (V) D-M9□W (V) D-M9□A (V)L	2.5	4	6	6	6	6.5			
D-A7□ (H)(C) D-A80□ (H)(C)	9.5	12	12	11	10	12			
D-A79W	11.5	13	13	14	14	16			
D-F7□ (V) D-J79 (C) D-F7□W (V) D-F7BA (V) L D-F7NTL D-F79F	4	5.5	6	6	6	6.5			

^{*} Since the operating range is provided as a guideline including hysteresis, it cannot be guaranteed (assuming approximately ±30% dispersion). It may vary substantially depending on an ambient environment.

Stroke Reading Cylinder Series CE1

Auto Switch Mounting Bracket: Part No.



Note 1) When a compact auto switch is mounted on the three sides (A, B and C above) other than the port side of CE1□32 to 50, the auto switch mounting brackets above are required. Order them separately from cylinders.

(It is the same as when mounting compact cylinders with an auto switch mounting rail, but not with CE1□63 to 100 compact auto switch installation groove.) Example order:

CE1B32-100-M9BW 1 unit

BQ-2 ····· 2 pcs. BQ2-012 ···· 2 pcs.

Note 2) Auto switch mounting brackets and auto switches are shipped together with cylinders.

Note 3) D-A9□ and D-A9□V auto switches cannot be used with the product with a bore size of ø12 (CE1□12).

Auto switch model		Bore size (mm)						
Auto switch model	ø12 to ø20	ø 32	ø40 to ø63					
D-A7□/A80 D-A73C/A80C D-A7□H/A80H D-A79W D-F7□J/J79 D-F7□V D-J79C D-F7□W/J79W D-F7□WV D-F7BAL/F7BAVL D-F79F/F7NTL	BQ-1		BQ-2					

Note 3) Auto switch mounting brackets and auto switches are shipped together with cylinders.

[Mounting screw set made of stainless steel]

The following set of mounting screws made of stainless steel (including nuts) is available. Use it in accordance with the operating environment. (Please order BQ-2 separately, since the auto switch spacer (for BQ-2) is not included.)

BBA2: For D-A7/A8/F7/J7 types

D-F7BAL/F7BAVL auto switches are set on the cylinder with the stainless steel screws above when shipped.

When an auto switch is shipped independently, BBA2 is attached.

Note 4) Refer to page 1817 for the details of BBA2.

Note 5) When mounting D-M9□A(V)L on a port other than the ports for ø32, ø40 and ø50, order auto switch mounting brackets BQ2-012S, BQ-2 and stainless steel screw set BBA2 separately.

Auto Switch Mounting Bracket Mass

Auto switch mounting bracket part no.	Applicable bore size	Mass (g)		
BQ-1	ø12 to ø20	1.5		
BQ-2	ø32 to ø63	1.5		
BQ2-012	ø12 to ø63	5		







Series CE1

Other Applicable Auto Switches

Auto switch type	Model	Electrical entry (Fetching direction)	Features
	D-A73	Grommet (Perpendicular)	_
Reed	D-A80	Grommet (Perpendicular)	Without indicator light
	D-A73H, A76H	Grommet (In-line)	_
	D-A80H	Grommet (m-ine)	Without indicator light
	D-F7NV, F7PV, F7BV		_
	D-F7NWV, F7BWV	Grommet (Perpendicular)	Diagnostic indication (2-color indication)
	D-F7BAVL		Water resistant (2-color indication)
Solid state	D-F79, F7P, J79		_
	D-F79W, F7PW, J79W	Grommet (In-line)	Diagnostic indication (2-color indication)
	D-F7BAL	Grommet (m-ine)	Water resistant (2-color indication)
	D-F7NTL		With timer

^{*} For solid state auto switches, auto switches with a pre-wired connector are also available. Refer to pages 1784 and 1785 for details.
* Normally closed (NC = b contact), solid state auto switch (D-F9G/F9H type) are also available. For details, refer to page 1746.

Series CEU Series CE

Counter/Extension Cable

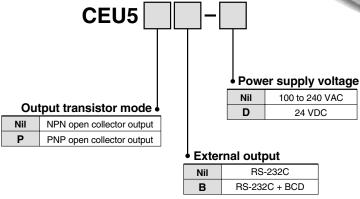


■ Multi-counter

How to Order

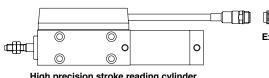


Note) CE compliant: When connecting to a stroke reading cylinder (CE1), a high precision stroke reading cylinder (ČEP1) and a stroke reading cylinder with brake (CE2). (CEU5□□-D type) Refer to the operation manual for details.





Connection Method



Extension cable

High precision stroke reading cylinder

If the distance between high precision stroke reading cylinder and multi-counter is over 23 meter, use transmission box. (CE1-H0374) When changing the wiring combination of White-A/Blue-COM and Yellow B/Brown-COM to the combination of White B/Blue-COM and Yellow-A/Brown-COM, the counting direction reverses.

BCD output function is available only for CEU5□B-□.

(1) BCD output connector: D-Sub half pitch connector

(Built in CEU5□B-D) D x 10M-36S (Made by Hirose Electric Co., Ltd.)

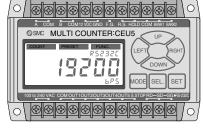
(2) Applicable connectors: D x 30AM-36P (Plug: Made by Hirose Electric Co., Ltd.)

D x 30M-36-CV (Cover: Made by Hirose Electric Co., Ltd.)*

Other interchangeable commercial cables with connectors can be also used.

* Pressure welding tools are required to connect the connector (plug, cover) models listed above and cables (order separately). The following products, including pre-assembled connectors and cables, are also available. Contact the manufacturer (Misumi Corporation) directly. SHPT-H-36-L (length): Cable with separate lines on one end

SHPT-HH-36-L (length): Cable with BCD connectors (male) on both ends

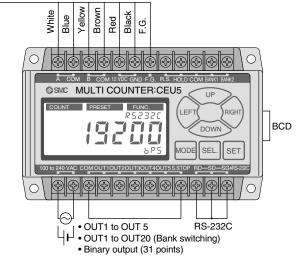


CEP1

CE₁

CE₂

ML2B



D-□

-X□

Individual

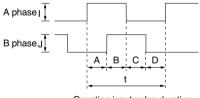


Series CEU

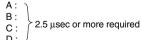
Multi-counter/Specifications

Model	CEU5	CEU5-D	CEU5P	CEU5P-D	CEU5B	CEU5B-D	CEU5PB	CEU5PB-D		
Туре		Multi-counter								
Mounting		Surface mounting (DIN rail or Screw stop)								
Operating system		Adding - subtracting type								
Operation mode		Operating mode, Data setting mode, Function setting mode								
Reset system		External reset terminal								
Display system		LCD (With back light)								
Number of digits		6 digits								
Memory holding (Storage medium)	Setting value (alv	etting value (always held), Count value (Hold/Non-hold switching), {E²ROM (Warning display after writing approx. 800,000 times: E2FUL)}								
Input signal type			Count input, C	ontrol signal inpu	ıt (Reset, Hold, E	Bank selection)				
Count input		No-voltage pulse input								
Pulse signal system		90° phase difference input *1/ UP/DOWN separate input *2								
Counting speed	100 kHz *1									
Control signal input	Voltage input (12 VDC or 24 VDC)									
Sensor power supply	10.8 to 13.2 VDC, 60 mA									
Output signal type	Preset output, Cylinder stop output Preset output, Cylinder stop output, BCD output							output		
Preset output configuration		Compare/Hold/One-shot (100 ms fixed pulse)								
Output type			Sepa	arate 5 point outp	ut/Binary code o	utput				
Output delay time			5 ms or less (for normal output)/60 ms or less (Binary output)				
Communication system				RS-2	232C					
Output transistor mode	NPN open Max 30 VD		PNP oper Max 30 VI	n collector DC, 50 mA	NPN oper Max 30 VD0			n collector C, 50 mA *3		
Power supply voltage	90 to 264 VAC	21.6 to 26.4 VDC	90 to 264 VAC	21.6 to 26.4 VDC	90 to 264 VAC	21.6 to 26.4 VDC	90 to 264 VAC	21.6 to 26.4 VDC		
Power consumption	20 VA or less	10 W or less	20 VA or less	10 W or less	20 VA or less	10 W or less	20 VA or less	10 W or less		
Withstand voltage				en case and AC I en case and sign						
Insulation resistance			Betwe	en case and AC I	ine: 500 VDC, 5	0 MΩ or more				
Ambient temperature				0 to +50°C (No freezing)					
Ambient humidity		35 to 85% RH (No condensation)								
Noise resistance	Square wa	ve noise from a r	noise simulator (oulse duration 1 µ	ıs) between pow	er supply termina	als ±2000 V, I/O	line ±600 V		
Shock resistance		E	ndurance 10 to	55 Hz; Amplitude	0.75 mm; X, Y,	Z for 2 hours eac	h			
Impact resistance			Endura	nce 10 G; X, Y, Z	directions, 3 tim	es each				
Mass				350 g	or less					

*1) 90° phase difference input



Counting input pulse duration



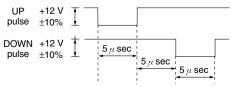
t: 10 μsec or more required

Counting speed
$$f = \frac{1}{t} = \frac{1}{10 \times 10^{-6}} = 100000 \text{ Hz}$$

 $\cong 100 \text{ kHz}$

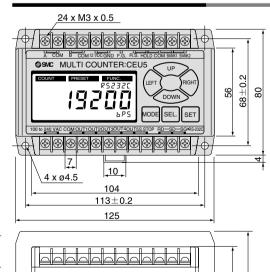
* 2) UP/DOWN input

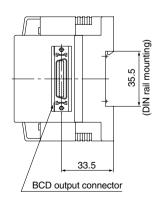
Input wave form conditions: At a maximum of 100 kHz, the UP/DOWN wave form should be as shown below.

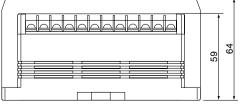


* 3) 15 mA when BCD is output.

Multi-counter/Dimensions







Wiring with External Equipment

<Wiring with multi-counter CEU5>

Wiring of power source for driving counter For power source for driving counter, use the counter. The power source for driving counter use the counter. The power source for driving counter use the counter. The power source for driving counter use the counter. The power source for driving counter use the counter. The power source for driving counter use the counter. The power source for driving counter use the counter.

For power source for driving counter, use the one with 90 to 264 VAC, 50/60 Hz or 21.6 to 26.4 VDC, 0.4 A or more.

2. Wiring for control signal input (Selection among Reset, Hold, Bank)

Make each control signal to be the transistor which can run more than 15 mA or the contact output. Input time for reset signal should be more than 10 ms. Bank selection and hold will function only when the input signal is applied.

COM is common to each signal input. Applicable to NPN and PNP input. Use 24 VDC or 12 VDC for the power source of COM. Connect DC—when PNP is applied, and DC+ when NPN is applied.

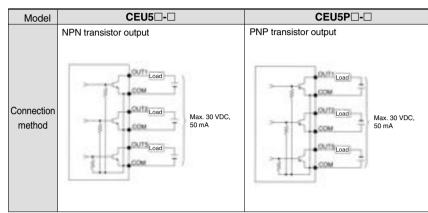
cable Cor

3. Output circuit

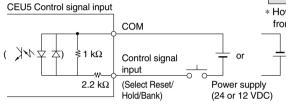
There are two outputs, the NPN open collector and the PNP open collector.

The maximum rating is 30 VDC, 50 mA. Operating the controller by exceeding this voltage and amperage could damage the electric circuit.

Therefore, the equipment to be connected must be below this rating.



* However, the COM of the input circuit and the COM of the output circuit are electrically insulated from each other.



CEP1

CE1

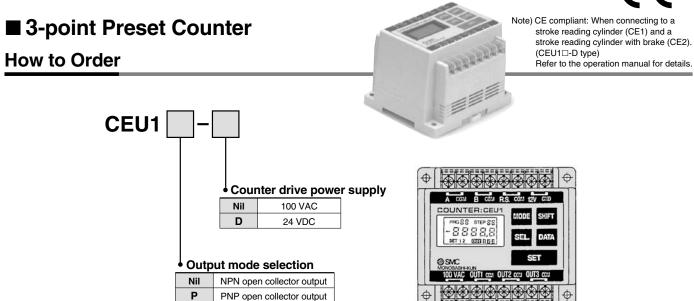
CE2

ML2B

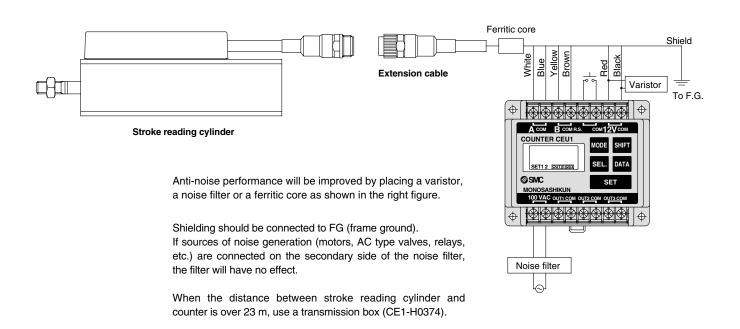


Series CEU





Connection Method



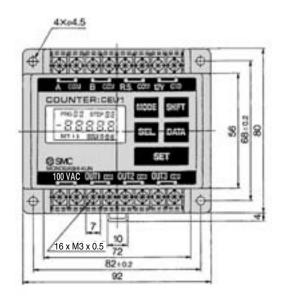
When changing the wiring combination of White-A/Blue-COM and Yellow-B/Brown-COM to the combination of White-B/Blue-COM and Yellow-A/Brown-COM, the counting

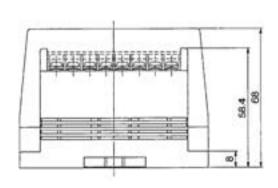
direction reverses.

3-point Preset Counter/Specifications

Model	CEU1 CEU1P CEU1-D CEU1P-						
Туре		3-point preset counter					
Mounting		Surface mounting (DIN rail or Screw stop)					
Operating system		Adding - subtracting type					
Operation modes		Operating mode, Data setting mode					
Reset system		External res	set terminal				
Display system		LCD (With	back light)				
Number of digits		5 digits display (-	9999.9 to 9999.9)				
Memory holding {Storage medium}	Preset data (always he	eld) {E2ROM (Warning d	isplay after writing appr	ox. 65,000 times: /=' <u>/</u>)}			
Input signal type		Count input,	Reset input				
Count input		No-voltage	pulse input				
Pulse signal system	90° phase difference input						
Counting speed	20 kHz						
Reset input	R.S. and COM terminals are shorted for 10 ms or more (Pulse input)						
Sensor power supply	10.8 to 13.2 VDC, 60 mA						
Output signal type	Preset output						
Preset output configuration	(Compare/Hold/One-sh	ot (100 ms fixed pulse)			
Output delay time		5 ms (or less				
Output transistor mode	NPN open collector Max. 30 VDC, 50 mA	PNP open collector Max. 30 VDC, 50 mA	NPN open collector Max. 30 VDC, 50 mA	PNP open collector Max. 30 VDC, 50 mA			
Power supply voltage	80 to 120 V/	AC 50/60 Hz	21.6 to 2	6.4 VDC			
Power consumption	10 VA	or less	5 W c	or less			
Withstand voltage		Setween case and AC Setween case and sign					
Insulation resistance	Betw	een case and AC line	: 500 VDC, 50 MΩ or ι	more			
Ambient temperature		0 to +50°C (No freezing)				
Ambient humidity	35 to 85% RH (No condensation)						
Noise resistance	Square wave noise from a noise simulator (pulse duration 1 µs) between power supply terminals ±1500 V, I/O line ±600 V						
Shock resistance	Endurance 1	0 to 55 Hz; Amplitude	0.75 mm; X, Y, Z for 2	2 hours each			
Impact resistance	Er	durance 10 G; X, Y, Z	directions, 3 times ea	ch			
Mass		250 g	or less				

3-point Preset Counter/Dimensions





D-□

CEP1

CE1

CE2

ML2B

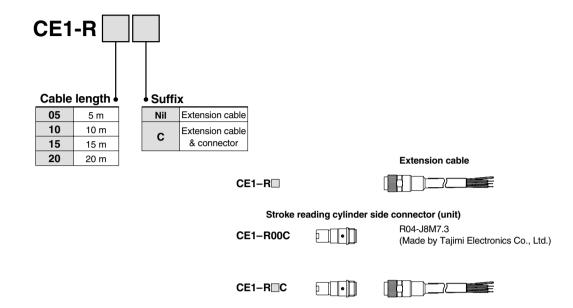
-X



Series CEU

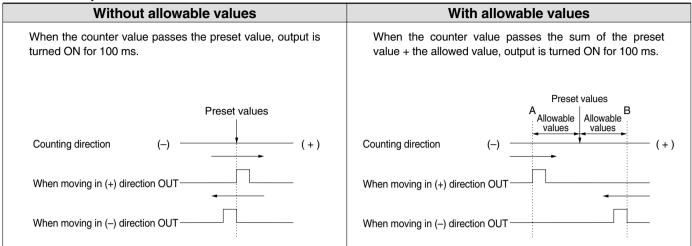
■ Extension Cable

How to Order

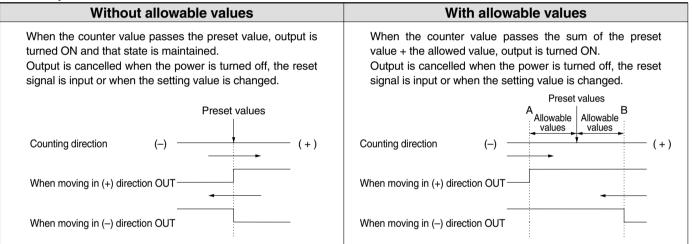


Operating Condition of each Output Mode

One-shot Output



Hold Output



Compare Output

Without allowable values	With allowable values				
Output is turned ON only when the counter value coincides with the preset value.	When the counter value passes the sum of the preset value + the allowed value, output is turned ON.				
Preset values Counting direction (-) When moving in (+) direction OUT When moving in (-) direction OUT	Preset values A Allowable values Counting direction (-) When moving in (+) direction OUT When moving in (-) direction OUT				

CEP1

CE1

CE2

ML2B

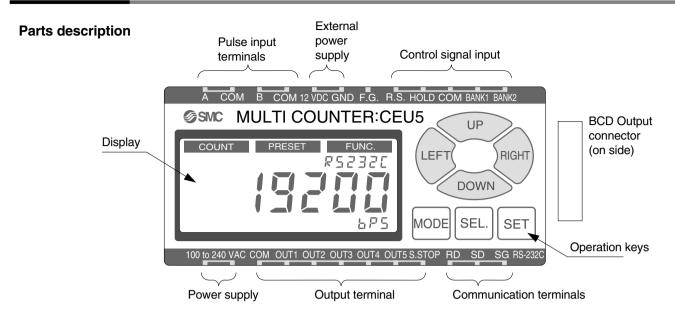
-X□

D-□

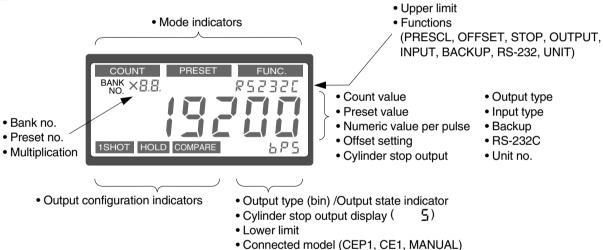


Series CEU

CEU5 Operation







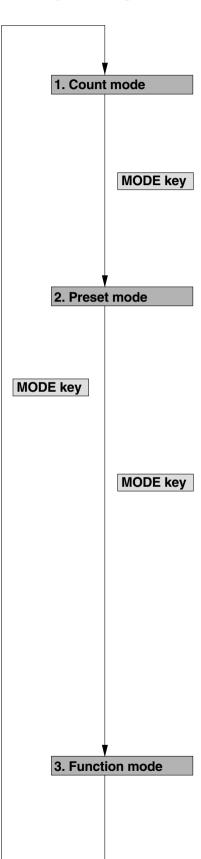
• RS-232C communication speed unit (bps)

Key and Functions

Key	Functions
MODE	Changes the mode. In any given condition, it shifts to the next mode. Does not write data.
SEL.	Shifts the cursor to the next item. Does not write data.
SET	Writes displayed data into the memory when setting.
RIGHT	Shifts the cursor to the right when setting numerical values.
LEFT	Shifts the cursor to the left when setting numerical values.
UP	Changes the contents of a setting. Increases the value when setting numerical values.
DOWN	Changes the contents of a setting. Decreases the value when setting numerical values.

In the explanations of the operating method, references to "Direction keys" indicate the 4 keys RIGHT, LEFT, UP and DOWN.

Mode cycle using mode key



Basic Operation

- SET key
 - : In any of the conditions (1) through (5), this writes the display
 - data into the memory and shifts to (1).
- SEL. key : Shifts to the next item, but does not write data. MODE key
 - : In any given condition, this shifts to the next mode, but does not write data.
- Direction keys: LEFT/RIGHT keys shift the digits, and UP/DOWN keys increase or decrease numerical values.

1. Explanation of display in count mode

Normal output display

Binary output display

Displays only when matched with preset





Displays output state of each OUT terminal

Display of binary output selection.

2. Setting of preset mode



Selection of preset No.

- Select a preset number from 1 to 31 with the UP/DOWN keys.
- Shift to the next item with the SEL. key.



+00000.00

SEL. key

Setting the preset values

- Shift the digits with the LEFT/RIGHT keys, and increase or decrease the numerical values with the UP/DOWN keys.
- Shift to the next item with the SEL. key.

SEL. key (3)**-**000000 0 1 +000000

Setting the upper limit tolerance

- Set numerical values in the same way with the direction keys.
- When \pm is selected, the lower limit display is cleared and \pm setting is possible.
- Shift to the next item with the SEL. key.



Setting the lower limit tolerance

- Set numerical values in the same way with the direction keys.
- \bullet When \pm is selected in the upper limit setting , this item is not displayed.
- · Shift to the next item with the SEL. key.



Setting the output configuration

- Switch to 1SHOT, HOLD or COMPARE with the UP/DOWN keys.
- Store the setting with the SET key.
- The SEL. key only shifts to another item without storing the setting.



CEP1

CE₁

CE₂

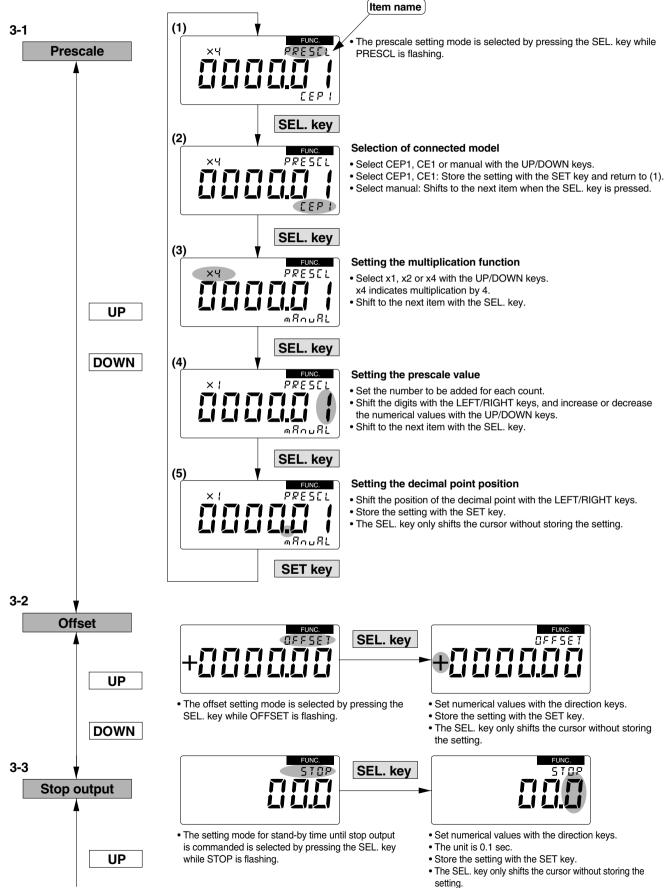
ML2B



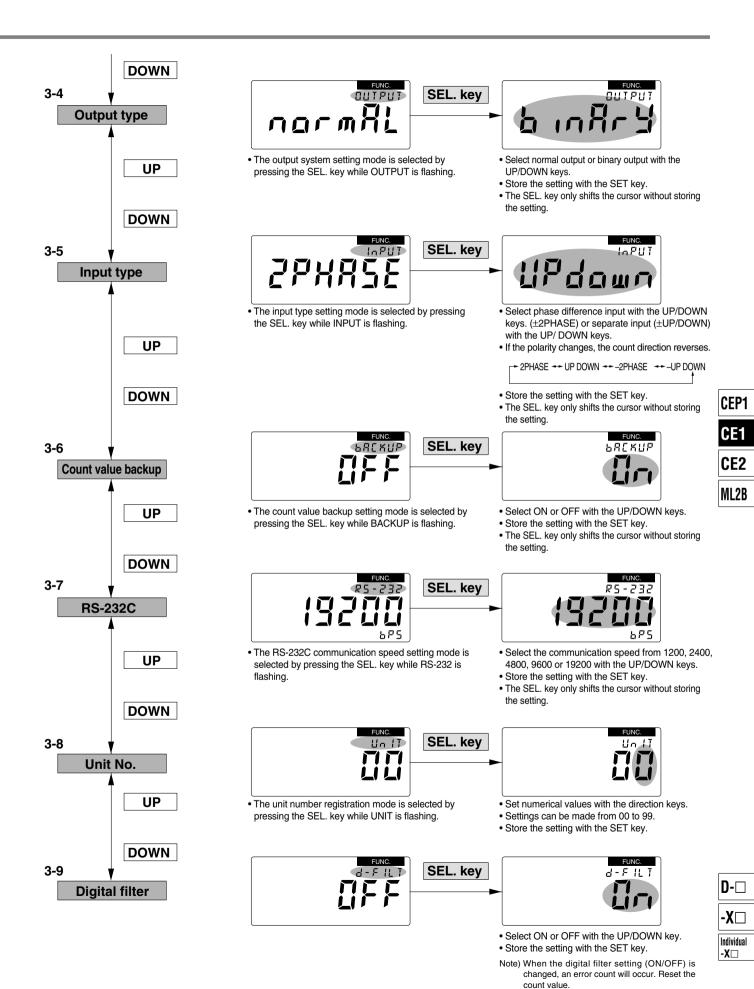
CEU5 Operation

3. Explanation of settings in the function mode

If the UP/DOWN keys are pressed when an item name is flashing, it shifts to another setting item. When the SEL key is pressed, the cursor shifts and it is possible to change the content of the setting for the item which is being displayed.

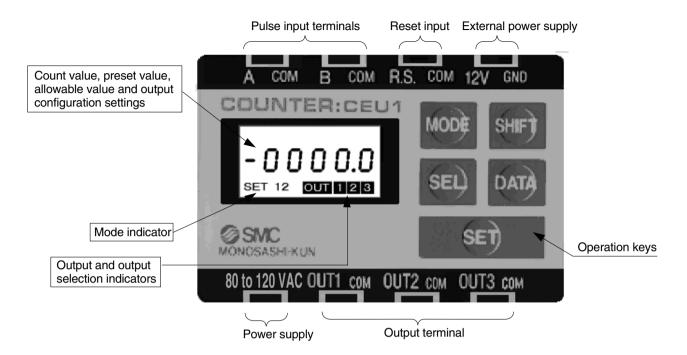


Counter Series CEU



Series CEU

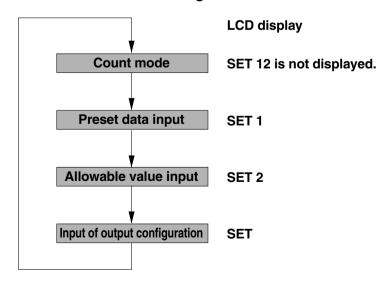
CEU1 Operation



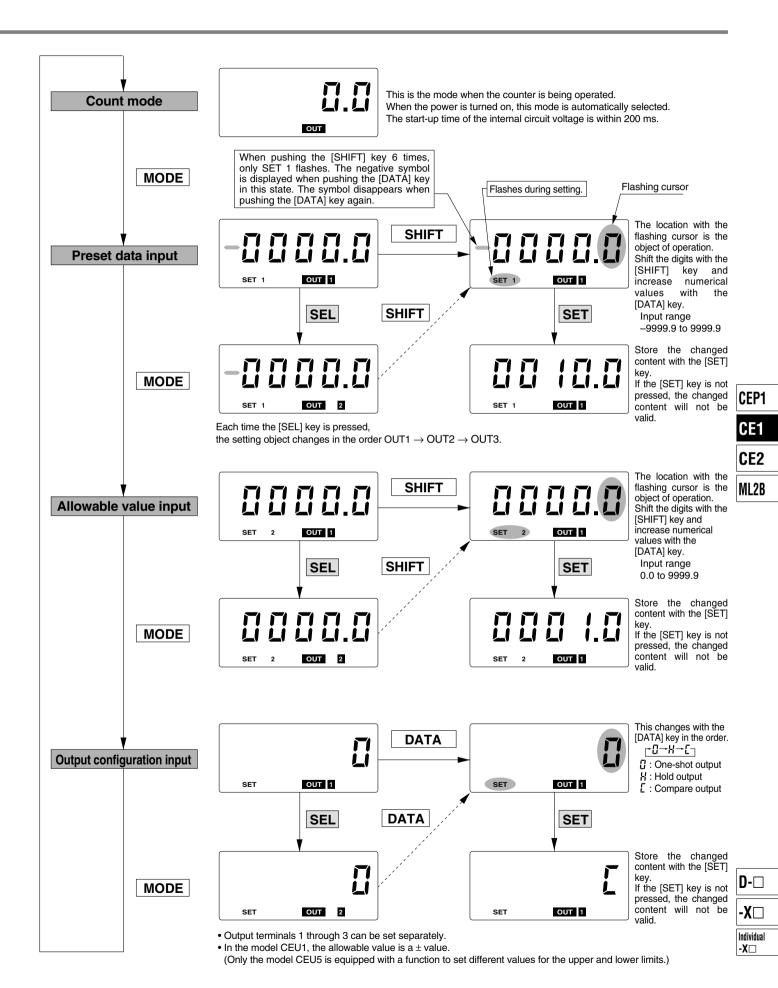
Key and Functions

Key	Functions
MODE	Switches between the count mode and the setting mode.
SHIFT	Switches digits for preset data input and allowable value input. Shifts the flashing cursor to the left each time it is pressed.
SEL	In the setting mode, this switches the output terminal number which is to be set. Switches in the order OUT1 \rightarrow OUT2 \rightarrow OUT3 each time it is pressed.
DATA	In the setting mode, this changes numerical values, or codes and symbols. Numerical values increase by 1 each time it is pressed. For positive and negative codes, a minus sign turns on or off.
SET	Registers the setting contents in the setting mode. Press this key to perform registration after making setting changes. The setting will not be registered if the screen is changed by pressing the [MODE] or [SEL] keys without pressing the [SET] key.

The counter mode changes in the order shown below each time the [MODE] key is pressed.



Counter Series CEU



Series CEU

Glossary (Functions of CEU5)

BCD Output

This is a system which expresses one digit of a decimal number with a 4 digit binary number.

The count value is expressed by the ON/OFF state of each BCD output terminal. In the case of 6 digits, 24 terminals are required.

The relation between decimal numbers and BCD codes is shown in the table below.

Decimal no.	0	1	2	3	4	5	6	7	8	9
BCD	0000	0001	0010	0011	0100	0101	0110	0111	1000	1001

Ex.) 1294.53 is expressed as follows. 0001 0010 1001 0100 0101 0011

RS-232C

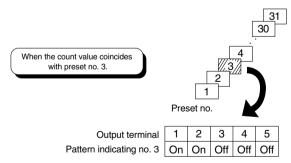
This is the interface standard for the serial transmission method, which is standard equipment on a personal computer.

Prescale Function

This function allows free setting of how many millimeters will indicate one pulse.

Binary Output

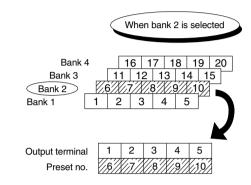
31 point preset output is possible without bank switching, by means of binary system output from a 5 point output terminal. Cylinder stop output is used as the readout release signal.



The coincident preset number is expressed as a 5 digit binary number.

Bank Function

5 points of preset output are possible simultaneously, however, a maximum of 20 types of work discrimination, etc. can be performed by using the 5 points of preset values as one of a maximum of four quadrats, and switching its use during operation.



For example, when bank 2 is selected, presets 6 through 10 are valid and when the count value coincides with the setting value of 6 through 10, the respective output terminals 1 through 5 are turned ON.

Bank Switching Correspondence

Input terminal Bank no.	BANK2	BANK1
1	OFF	OFF
2	OFF	ON
3	ON	OFF
4	ON	ON



Display Offset Function

Normally the count value returns to "0" after resetting, but with this function, the initial value can be set to any desired value.

Hold Function

When "hold" is input, the counter holds the current count value in memory. Next, when the count value is read into a PLC which uses serial or BCD output, etc., the count value that was held can be read in, even if there is a time lag.

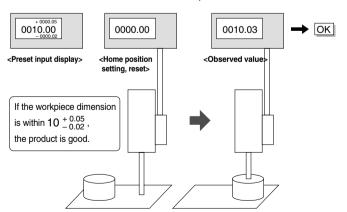
Setting the Tolerances of Preset Values

In the current model CEU1, the preset value tolerances could only be set as \pm , but now it has become possible to set an upper and lower limit of + \bigcirc mm and - \triangle mm.

By including preset tolerance setting, superior performance is exhibited in parts inspections, etc. In a workpiece to be measured, there are tolerances which assure a good product. For example, in the case of $10^{+0.05}_{-0.02}$, the CEU5 allows these tolerances to be input as they stand. If the workpiece is within tolerances the OK signal is sent.

On the other hand, in ordinary counters, no. 1 is set to 9.98 and no. 2 is set to 10.06, and if no. 1 is ON and no. 2 is OFF, an acceptance decision is made. 2 points of output are used in order to check whether or not the product is within dimension tolerances. In this example, one preset of the CEU5 performs the same function as two presets of an ordinary counter.

<Simple input as per drawing dimensions> Tolerances can be set with the preset value. OK/NG signal is output by the counter. Labor savings can be realized in parts inspections.



Count Value Protection

In the past, the count value returned to "0" when the power supply was cut off, but this function holds the previous value even after a power failure. This function can be switched between active and inactive settings.

Cylinder Stop Output

When workpiece discrimination is performed using a preset counter, it has been common to estimate the amount of time from the cylinder's start of operation until it touches the workpiece and stops, using a timer to read the output after a fixed amount of time. Since cylinder stop output is now output when there is no cylinder movement for a fixed amount of time, timing of preset output and external output, etc. is simplified.

CEP1

CE1

CE2

ML2B



-X□

