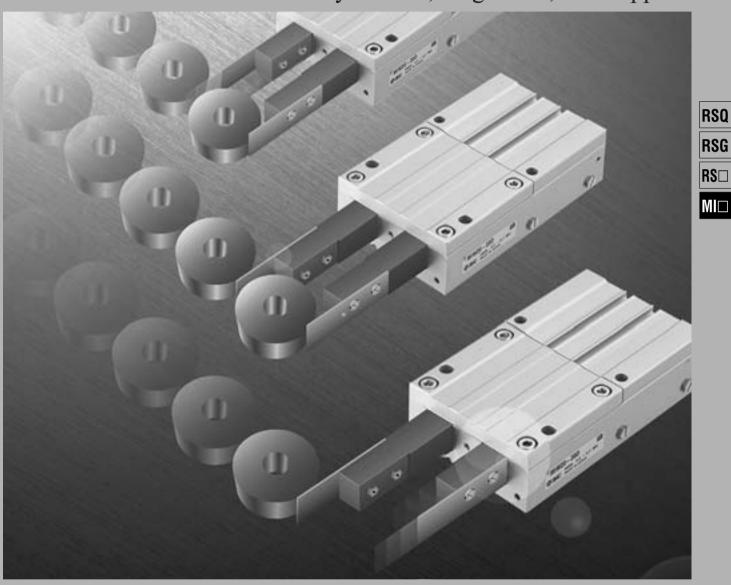
Escapements

Series MIW/MIS

ø8, ø12, ø20, ø25, ø32

Ideal for separating and feeding individual parts from vibratory feeders, magazines, and hoppers.

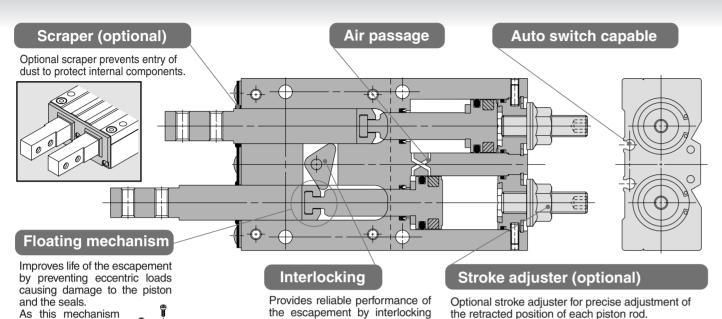


Series variations

Series	Bore size (mm)	8	10		troke		32	50	Finger option	Stroke adjuster	Scraper	
MIW	8 12 20 25 32	1		*	+	†	†					D- □
MIS	8 12 20 25 32	#	3		3			3				-X - Individual -X -

SMC

Ideal for separating and from vibratory feeders,



the two piston rods with a cam

mechanism

and control of

air passage

to the pistons.

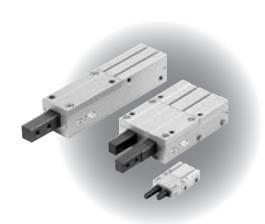
separates the fingers from the piston, it is possible to replace the fingers with ease when required.

For ø25 and ø32, lock mechanism for heavier load is available Three variations of fingers

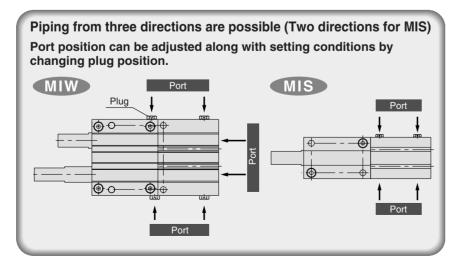
Flexibility in mounting the finger options. Finger options

Mounting is possible from 2 directions. through 0 0 body from

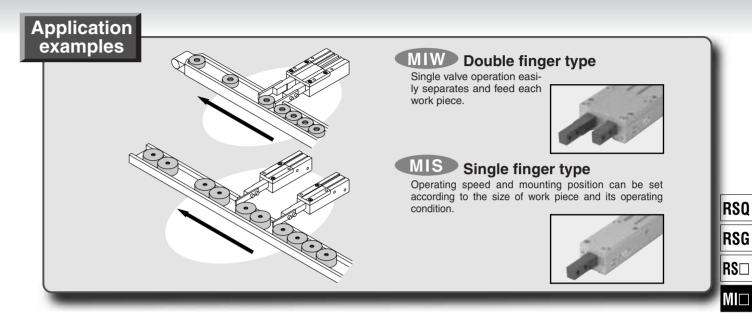
* Positioning pin holes allow for easy mounting



1416



feeding individual parts magazines, and hoppers.

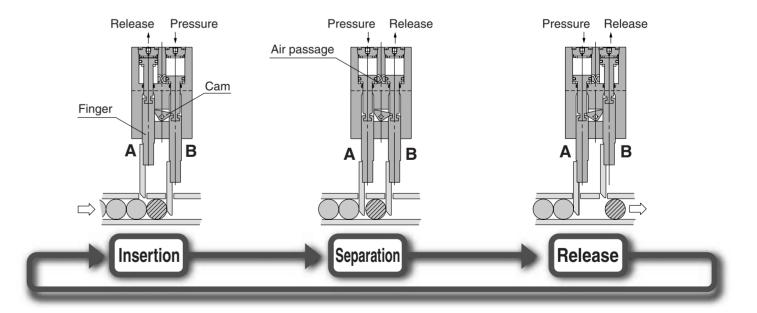




The cam locks Finger B.

reach the stroke end, air is supplied ! to retract Finger B.

When Finger A is extended to Extension of Finger A rotates the cam to unlock Finger B and lock finger A to allow retraction of Finger B.

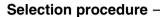


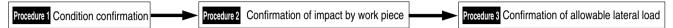
D-□ -**X**□

SMC

Series MIW/MIS Model Selection 1

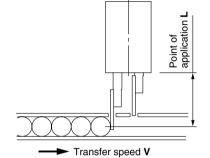
Model Selection





Procedure 1 Confirmation of conditions

• The work piece moves horizontally on the conveyor.



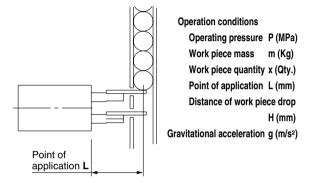
Operation conditions
Operating pressure P (MPa)
Work piece mass m (Kg)
Work piece quantity x (Qty.)
Point of application L (mm)

Coefficient of friction between the work piece and conveyor

Work piece transfer speed

V (m/min)

 \bullet When the work piece drops vertically from a shooter, etc.



Procedure 2 Confirmation of impact

From the graph of operating range, obtain the point of intersection of the total mass of the work piece $x \cdot m$ (kg) indicated by the axis of ordinates and the transfer speed V (m/min) indicated by the axis of abscissas. Select a model so that the intersection will fall below the point of application L indicated by a line.

1. Calculation of work piece collision speed
The collision speed V is calculated from the distance of work piece fall H.

Work piece collision speed V = $\sqrt{\frac{2gH}{1000}}$ x 60 (m/min)

2. From the graph of operating range, obtain the intersection of the total mass of the work piece x m (kg) indicated by the axis of ordinates and the collision speed V (m/min) obtained by calculation. Select a model so that the intersection will fall below the point of application L indicated by a line.

Procedure 3 Confirmation of allowable lateral load

Calculation of applied lateral load F
 The lateral load F equals the coefficient between
 the work piece and the conveyor. Thus, from the
 total amount of the work piece and coefficient of
 friction.

 $\mathbf{F} = \mathbf{\mu} \cdot \mathbf{x} \cdot \mathbf{m} \cdot \mathbf{g} (\mathbf{N})$

Calculation of applied lateral load
 The lateral load F equals the total load of the work piece.

Thus, $F = x \cdot m \cdot g(N)$

2. From the graph of allowable lateral load, obtain the allowable lateral load F max from the intersection of the operating pressure and the point of application L indicated by the axis of abscissas. Select a model so that the value will be larger than the lateral load F applied in real operation.

Lateral load: F ≤ Allowable lateral load: Fmax

Model Selection

Operating range -

Procedure 1 Confirmation of conditions

• The work piece moves horizontally on the conveyor.

Operating conditions

 $\begin{array}{lll} \text{Operating pressure} & P = 0.4 \text{ MPa} \\ \text{Work piece mass} & m = 0.1 \text{ kg} \\ \text{Work piece quantity} & x = 10 \\ \text{Point of application} & L = 50 \text{ mm} \\ \text{Work piece transfer speed} & V = 12 \text{ m/min} \\ \text{Coefficient of friction between the work piece and conveyor } \mu = 0.2 \end{array}$

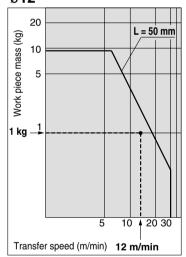
• When the work piece drops vertically from a shooter, etc.

Operating conditions

 $\begin{array}{lll} \text{Operating pressure} & P = 0.4 \text{ MPa} \\ \text{Work piece mass} & m = 0.05 \text{ kg} \\ \text{Work piece quantity} & x = 5 \\ \text{Point of application} & L = 60 \text{ mm} \\ \text{Distance of work piece drop} & H = 15 \text{ mm} \\ \text{Gravitation acceleration} & g = 9.8 \text{ m/s}^2 \end{array}$

Procedure 2 Confirmation of impact

- Obtain the total amount of the work piece.
 Total mass m = 10 x 0.1 (kg) = 1 (kg)
- Obtain the intersection of the transfer speed V and the total weight of work piece m. Confirm that the value is within the operating range of the point of application L = 50 mm $_{\varnothing12}$



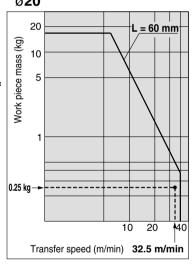
- Obtain the total amount of the work piece.
 Total mass m = 5 x 0.05 (kg) = 0.25 (kg)
- Obtain the collision speed of the work piece V.

$$V = \sqrt{2gH/1000} \times 60$$

$$=\sqrt{2 \times 9.8 \times 15/1000} \times 60$$

= 32.5 (m/min)

 Obtain the intersection of the collision speed V and the total mass of the work piece m.
 Confirm that the value is within the operating range of the point of application L = 60 mm.



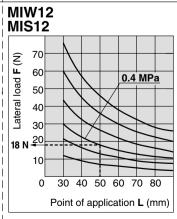
Procedure 3 Confirmation of allowable lateral load

Calculation of applied lateral load F

 $F = \mu \cdot N \cdot m \cdot g (N)$ = 0.2 x 10 x 0.1 x 9.8 = 2.1 (N)

2. Confirmation of allowable lateral load
From the graph, the allowable lateral load at
L = 50 mm and
P = 0.4 MPa is 18 N.
Because 2.1 N < 18 N, it is applicable.

Therefore select MIW (MIS) 12.



Calculation of applied lateral load
 The lateral load F equals the total load of the work piece. Thus,

F= 5 x 0.05 x 9.8

= 2.5 (N)

Confirmation of allowable lateral load
 In the same way, the lateral load at L = 50 mm and
 P = 0.4 MPa is 48 N from the graph. Because
 2.5 N < 48 N, it is applicable.

Therefore select MIW (MIS) 20.

..5 N < 48 N, it is applicable.

SMC

RS₀

RSG

RS□

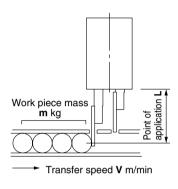
 $\mathsf{MI}\square$

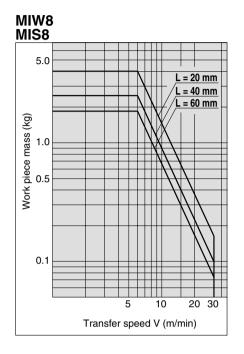
Series MIW/MIS Model Selection 2

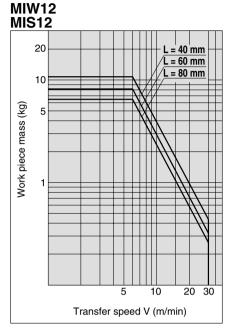
Model Selection

Operating range

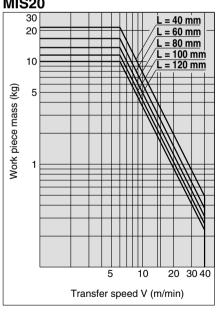
The graph at right shows conditions of the work piece to be stopped; that is, the mass, transfer speed and the operating range of the point of application L.



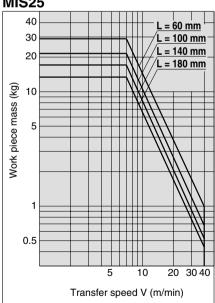




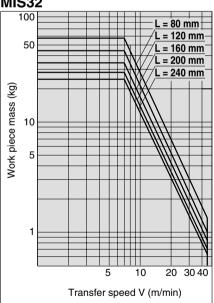
MIW20 MIS20



MIW25 MIS25

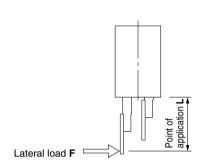


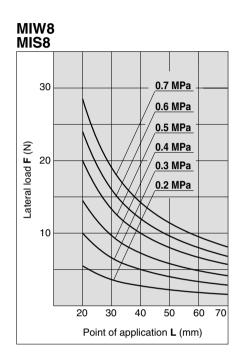
MIW32 MIS32

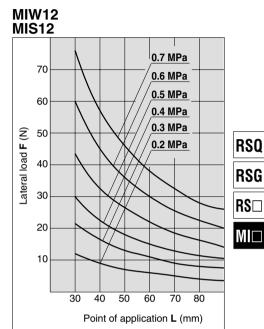


Model Selection

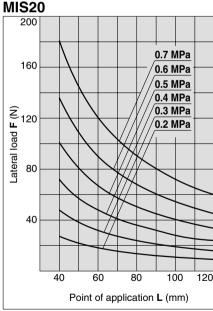
Allowable lateral load



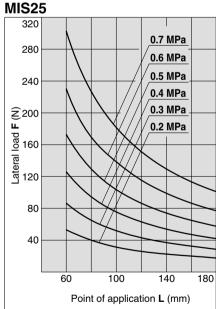




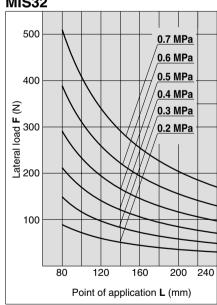
MIW20







MIW32 MIS32



D-□

-X□ Individual

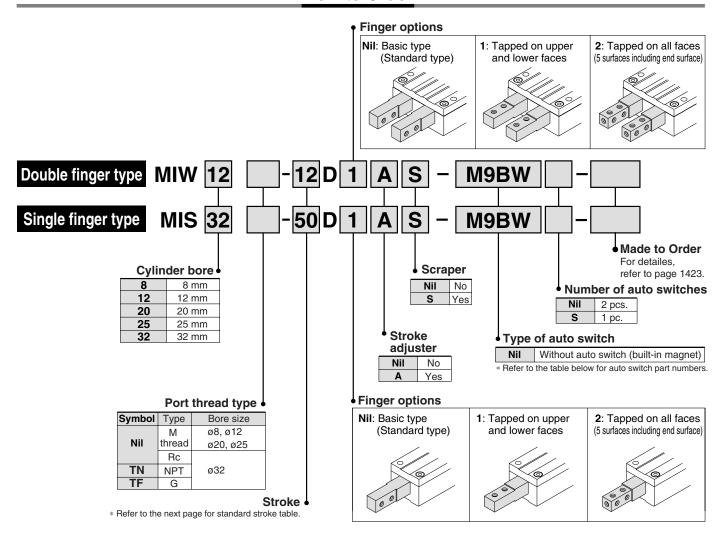


Escapements

Series MIW/MIS

ø8, ø12, ø20, ø25, ø32

How to Order



Applicable auto switches/Refer to pages 1719 to 1827 for detailed specifications of auto switches

ZPP	Applicable date switches to pages 1713 to 1027 for detailed specifications of auto switches.																
	Special function	Electrical	ight		L	oad volta	ige	Auto switch	h models	Lead	wire I	ength	n (m)	Pre-wired			
Туре		entry	Indicator	Wiring (output)		DC AC	Perpendicular	In-line	0.5 (Nil)	1 (M)	3 (L)	5 (Z)	connector	Applicable load			
ن				3-wire (NPN)		5 1/ 40 1/		M9NV	M9N	•	•	•	0	0	IC		
witch					3-wire (PNP)		5 V, 12 V		M9PV	M9P	•	•	•	0	0	circuit	
ie s		0	,,	2-wire		12 V		M9BV	M9B	•	•	•	0	0	_	Relay,	
	state				24 V	5 V 40 V	_	M9NWV	M9NW	•	•	•	0	0	IC	PLC	
Diagnostic indication (2-color display)			3-wire (PNP)		5 V, 12 V		M9PWV	M9PW	•	•	•	0	0	circuit			
တိ	(2-color display)			2-wire		12 V		M9BWV	M9BW	•	•	•	0	C	_		

* Solid state auto switches marked with "O" are produced upon receipt of order.

1 m ······ M (Example) M9NWM

3 m ······ L (Example) M9NWL

5 m ······· Z (Example) M9NWZ

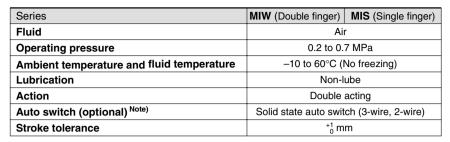


^{*} Lead wire length symbols: 0.5 m ······· Nil (Example) M9NW

^{*} Refer to pages 1784 and 1785 for the details of auto switches with a pre-wired connector.

^{*} Auto switches are shipped together (not assembled).







Finger options	Standard, Tapped on upper and lower faces, Tapped on all faces (5 surfaces including end surface)
	MI□8: Arrangement range 4 mm
Stroke adjuster	MI□12: Arrangement range 6 mm
(Rear end	MI□20: Arrangement range 12 mm
stroke only)	MI□25: Arrangement range 15 mm
	MI□32: Arrangement range 20 mm
Scraper	Can be mounted on standard products

RSQ

RSG



MI



									Unit: N	
Bore size	Rod size	Operating	Piston area	Operating pressure MPa						
(mm)	(mm)	direction	(mm²)	0.2	0.3	0.4	0.5	0.6	0.7	
8	4	OUT	50	10	15	20	26	31	36	
· ·	4	IN	38	7	11	15	19	23	26	
12	6	OUT	113	23	34	45	57	68	79	
12	0	IN	85	17	26	34	43	51	60	
20	10	OUT	314	63	94	126	157	188	220	
20	10	IN	236	47	71	94	118	142	165	
25	10	OUT	491	98	147	196	245	295	344	
25	10	IN	412	82	124	165	206	247	288	
32	12	OUT	804	161	241	322	402	482	563	
32	12	IN	691	138	207	276	346	415	484	

Standard Stroke

Double finger type/MIW (mr						
Bore size	Bore size Stroke					
8	8 mm					
12	12 mm					
20	20 mm					
25	25 mm					
32	32 mm					

^{*} For MIW, same stroke as bore size

Single finger type/MIS						
Bore size	Stroke					
8	10, 20 mm					
12	10, 20, 30 mm					
20	10, 20, 30 mm					
25	30, 50 mm					
32	30, 50 mm					



Made to Order

(For detailes, refer to page 2020.)

		, , ,			
	Symbol	Specifications			
	-X4	Heat resistant (-10 to 100°C)			
	-X5 Fluororubber seal				
	-X63 Fluorine grease				
-X79 Grease for food					

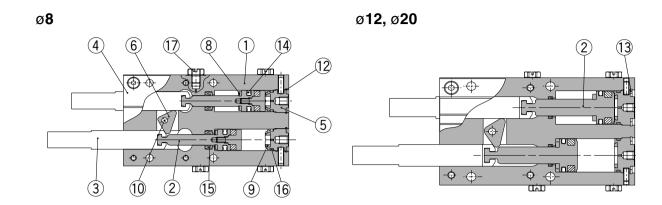
Mass

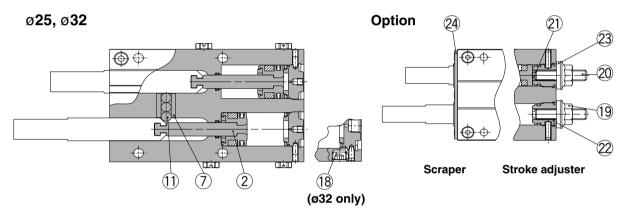
Model	Model	Stroke (mm)	Mass (g)	Increase by stroke adjuster (g)	Increase by scraper (g)	
	MIW8-8D	8	110	6	3	
	MIW12-12D	12	240	10	5	
MIW	MIW20-20D	20	650	30	10	
	MIW25-25D	25	1550	30	20	
	MIW32-32D	32	2650	100	35	
	MIS8-10D	10	62	3	2	
	MIS8-20D	20	80	<u>ی</u>	۷	
	MIS12-10D	10	130			
	MIS12-20D	20	160	5	3	
	MIS12-30D	30	190			
MIS	MIS20-10D	10	300			
WIIO	MIS20-20D	20	355	15	5	
	MIS20-30D	30	410			
	MIS25-30D	30	800	15	10	
	MIS25-50D	50	1000	15	10	
	MIS32-30D	30	1350	50	18	
	MIS32-50D	50	1650	50	10	





Construction/Double Finger Type (MIW)





Component parts

No.	Description	Material	Note
1	Body	Aluminium alloy	Hard anodized
2	Piston assembly		
3	Finger	Carbon steel	Heat treatment/Special treatment
4	Cover	Aluminium alloy	Hard anodized
5	Cap (W)	Aluminium alloy	White anodized
6	Cam	Stainless steel	Heat treatment (MIW8 to 20)
7	Roller holder	Stainless steel	Heat treatment (MIW25, 32)
8	Bumper	Urethane rubber	
9	Head bumper	Urethane rubber	
10	Needle roller	High carbon chromium bearing steel	(MIW8 to 20)

No.	Description	Material	Note
11	Cylinder roller	Carbon steel	(MIW25, 32)
12	Clip	Carbon steel	(MIW8)
13	R shape retaining ring	Carbon steel	(MIW12 to 32)
14	Piston seal	NBR	
15	Rod seal	NBR	
16	Gasket	NBR	
17	Dive		(MIW8 ··· M-3P)
17	Plug		(MIW12 to 25 ··· M-5P)
18	Hexagon socket taper plug		(MIW32 ··· Rc1/8)

Option: adjuster

No.	Description	Material	Note
19	Hexagon nut with flange	Carbon steel	Nickel plated
20	Adjustment bolt	Carbon steel	Nickel plated
21	Adjustment bumper	Urethane rubber	
22	Adjustment cap	Aluminium alloy	White anodized
23	Die thread		

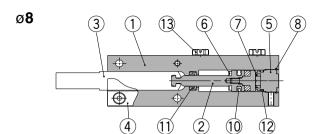
Option: scraper

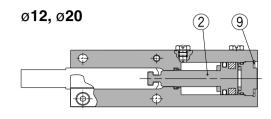
Ī	No.	Description	Material	Note
	24	Scraper	Stainless steel + NBR	

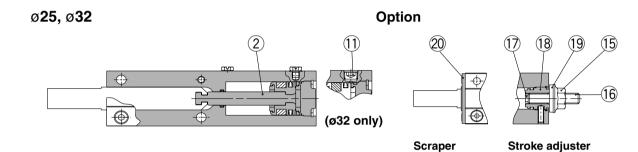
Replacement parts

p.ia.comont pan						
Description		Finger		Cool leit	Canananasaanahi	Cyanaa maak
Model	Standard	Tapped on upper and lower faces	Tapped on all faces	Seal kit	Scraper assembly	Grease pack
MIW8-8D	MI-A0801-8	MI-A0802-8	MI-A0803-8	MIW8-PS	MIW-A0804	
MIW12-12D	MI-A1201-12	MI-A1202-12	MI-A1203-12	MIW12-PS	MIW-A1204	MH-G01
MIW20-20D	MI-A2001-20	MI-A2002-20	MI-A2003-20	MIW20-PS	MIW-A2004	(contents quantity
MIW25-25D	MI-A2501-25	MI-A2502-25	MI-A2503-25	MIW25-PS	MIW-A2504	30 g)
MIW32-32D	MI-A3201-32	MI-A3202-32	MI-A3203-32	MIW32-PS	MIW-A3204	
Main parts No.		③ (1 pc.)		(14), (15), (16)	24)	

Construction/Single Finger Type (MIS)







MI

RSQ

RSG

RS□

Component parts

No.	Description	Material	Note
1	Body	Aluminium alloy	Hard anodized
2	Piston assembly		
3	Finger	Carbon steel	Heat treatment/Special treatment
4	Cover	Aluminium alloy	Hard anodized
5	Cap (S)	Aluminium alloy	White anodized
6	Bumper	Urethane rubber	
7	Head bumper	Urethane rubber	
8	Clip	Carbon steel	(MIS8)
9	R shape retaining ring	Carbon steel	(MIS12 to 32)

No.	Description	Material	Note
10	Piston seal	NBR	
11	Rod seal	NBR	
12	Gasket	NBR	
-10	Dive		(MIS8 ··· M-3P)
13	Plug		(MIS12 to 25 ··· M-5P)
14	Hexagon socket taper plug		(MIS32 ··· Rc1/8)

Option: adjuster

- 1	,		
No.	Description	Material	Note
15	Hexagon nut with flange	Carbon steel	Nickel plated
16	Adjustment bolt	Carbon steel	Nickel plated
17	Adjustment bumper	Urethane rubber	
18	Adjustment cap	Aluminium alloy	White anodized
19	Die thread		

Option: scraper

No.	Description	Material	Note
20	Scraper	Stainless steel + NBR	

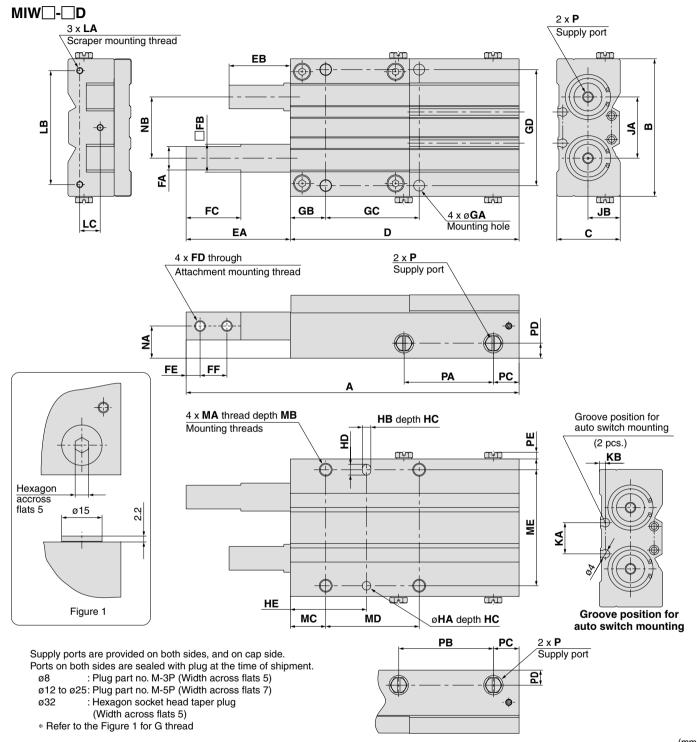
Replacement parts

ricpiacement par								
Description		Finger		Seal kit	Caranar agambly	Crosse neek		
Model	Standard	Tapped on upper and lower faces	Tapped on all faces	Seai Kil	Scraper assembly	Grease pack		
MIS8-10D	MI-A0801-10	MI-A0802-10	MI-A0803-10	MIS8-PS	MIS-A0804			
MIS8-20D	MI-A0801-20	MI-A0802-20	MI-A0803-20	W1130-F3	WII3-A0004			
MIS12-10D	MI-A1201-10	MI-A1202-10	MI-A1203-10					
MIS12-20D	MI-A1201-20	MI-A1202-20	MI-A1203-20	MIS12-PS	MIS-A1204			
MIS12-30D	MI-A1201-30	MI-A1202-30	MI-A1203-30					
MIS20-10D	MI-A2001-10	MI-A2002-10	MI-A2003-10			MH-G01		
MIS20-20D	MI-A2001-20	MI-A2002-20	MI-A2003-20	MIS20-PS	MIS-A2004	(contents quantity		
MIS20-30D	MI-A2001-30	MI-A2002-30	MI-A2003-30			30 g)		
MIS25-30D	MI-A2501-30	MI-A2502-30	MI-A2503-30	MIS25-PS	MIS-A2504			
MIS25-50D	MI-A2501-50	MI-A2502-50	MI-A2503-50	W11323-F3	WII3-A2504			
MIS32-30D	MI-A3201-30	MI-A3202-30	MI-A3203-30	MIS32-PS	MIC ACCOM			
MIS32-50D	MI-A3201-50	MI-A3202-50	MI-A3203-50	1011332-73	MIS-A3204			
Main parts No.		③ (1 pc.)		10, 11, 12	20			

D-□

-X□ Individual -X□

Dimensions/Double Finger Type



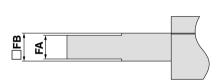
																	(111111)
Model	Α	В	С	D	EA	EB	FA	FB	FC	FD	FE	FF	FG	GA	GB	GC	GD
MIW8-8	83	34	16	57	26	18	6-0.1	7h9-0.036	15	M3 x 0.5	4	7	6 (Effective depth 2.5)	2.6	9	22	28
MIW12-12	111	44	21	76	35	23	8-0.1	10h9-0.036	19	M3 x 0.5	4.5	9.5	6 (Effective depth 3)	3.3	12.5	34	37
MIW20-20	155	64	29.5	106.5	48.5	28.5	11.0.1	13h9-0.043	25.5	M5 x 0.8	6.5	12.5	10 (Effective depth 4)	5.1	16.5	43.5	54
MIW25-25	200	84	40	134	66	41	15.0.1	17h9.0.043	37	M6 x 1	10	17	15 (Effective depth 7)	6.8	20	58	71
MIW32-32	256	95	47	169	87	55	19.5 %	21h9 %052	51	M8 x 1.25	12.5	22	17 (Effective depth 8.5)	8.6	24.5	73	80

Model	HA, HB	НС	HD	HE	JA	JB	KA	KB	LA	LB
MIW8-8	2H9 ^{+0.025}	2	3	15	14.5	7.5	20.3	1.6	M2 x 0.4	28.4
MIW12-12	2.5H9 ^{+0.025}	4	3.5	25	19	11	7.6	2.2	M2.6 x 0.45	37
MIW20-20	4H9 ^{+0.030}	5	5	35.5	28.5	15	14.5	2.8	M3 x 0.5	53
MIW25-25	5H9 ^{+0.030}	5	7	40	35.5	20	24.5	3	M3 x 0.5	70
MIW32-32	6H9 +0.030	6	8	50	44.5	25	24.1	2.5	M4 x 0.7	81

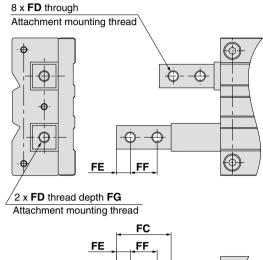


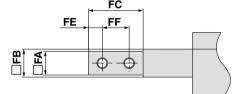
Finger options Tapped on upper and lower faces

4 x FD through Attachment mounting thread FE FF FC

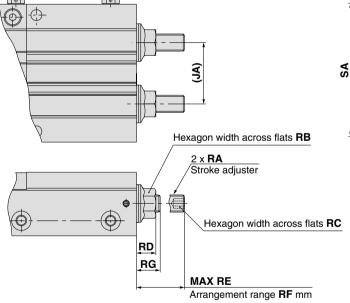


Tapped on all faces





Stroke adjuster



Note) Observe the specified adjustment range when adjusting with a stroke adjuster.

																		(mm)
Model	LC	MA	MB	MC	MD	ME	NA	NB	Р	PA	PB	PC	PD	PE	RA	RB	RC	RD
MIW8-8	4.5	M3 x 0.5	6	9	22	28	7.5	14.5	M3 x 0.5	22.5	24	8	4.5	2.2	M4 x 0.7	7	2	5.7
MIW12-12	7.5	M4 x 0.7	7	12.5	34	37	11	19	M5 x 0.8	25	27	10	6	2.8	M5 x 0.8	8	2.5	6
MIW20-20	9.5	M6 x 1	10	16.5	43.5	54	15	28.5	M5 x 0.8	41.5	44	12	7	2.7	M8 x 1	12	4	9
MIW25-25	12	M8 x 1.25	12	20	58	71	20	35.5	M5 x 0.8	50	55	14	8.5	2.7	M8 x 1	12	4	9
MIW32-32	16.5	M10 x 1.5	15	24.5	73	80	25	44.5	Rc1/8	69.5	75.5	14.5	11	_	M12 x 1.25	17	6	12.4

Model	RE	RF	RG	SA	SB	SC
MIW8-8	12.5	4	8.5	33	14.5	1.4
MIW12-12	14	6	8	43	18.5	1.8
MIW20-20	22.5	12	10.5	62	27	2.2
MIW25-25	26	15	11	81	35	2.8
MIW32-32	33	20	13	93	42	3.4

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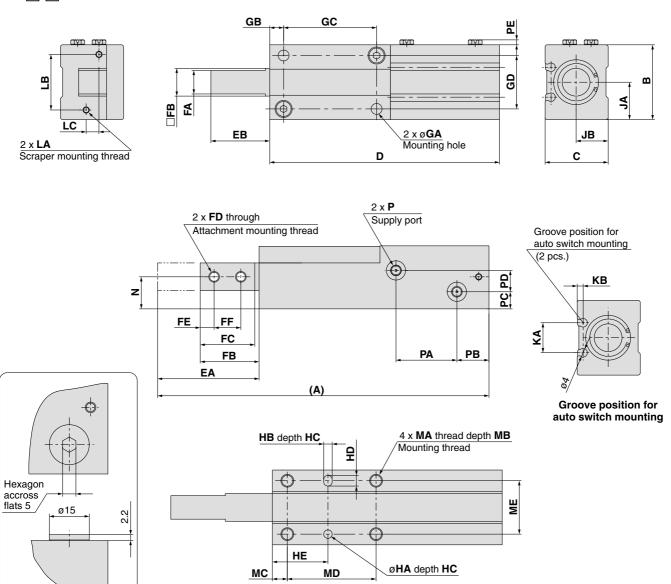
 $\mathsf{MI}\square$

-X□



Dimensions/Single Finger Type

MIS□-□D



Supply ports are provided on both sides.

Figure 1

A port on a side is sealed with plug at the time of shipment.

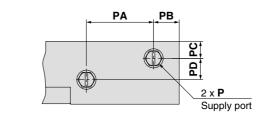
Ø8 : Plug part no. M-3P (Width across flats 5)

Ø12 to Ø25: Plug part no. M-5P (Width across flats 7)

: Hexagon socket head taper plug

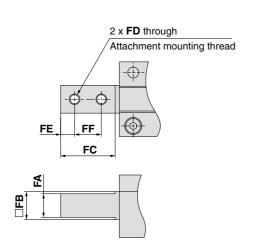
(Width across flats 5)

* Refer to the Figure 1 for G thread

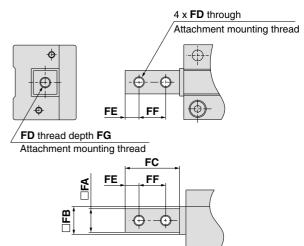


Model	Α	В	С	D	EA	EB	FA	FB	FC	FD	FE	FF	FG	GA	GB	GC	GD	HA, HB
MIS8-10	87	19	16	59	28	10	6.01	7h9 🐧 036	4-	M0 0 5			6	0.0	_	20	10	2H9 +0.025
MIS8-20	117	19	10	79	38	18	O -0.1	/119 -0.036	15	M3 x 0.5	4	′	(Effective depth 2.5)	2.6	4	30	13	2⊓9 ₀
MIS12-10	105			72	33								6			28		
MIS12-20	135	26	21	92	43	23	8 -0.1	10h9 -0.036	19	M3 x 0.5	4.5	9.5	(Effective depth 3)	3.3	5	38	18	2.5H9 ^{+0.025}
MIS12-30	165			112	53								uepiii 3)			48		
MIS20-10	125			86.5	38.5								10			32		
MIS20-20	155	35	29.5	106.5	48.5	28.5	11 .0.1	13h9 -0.043	25.5	M5 x 0.8	6.5	12.5	(Effective depth 4)	5.1	7	42	25	4H9 +0.030
MIS20-30	185			126.5	58.5								чорит ту			52		
MIS25-30	215	41	40	144	71	41	15.01	17h9 0.043	37	M6 x 1	10	17	15 (Effective	6.8	10	55	28	5H9 +0.030
MIS25-50	275	7'	70	184	91	71	10 -0.1	17110 -0.043	37	IVIO X I	10	' '	depth 7)	0.0	10	75	20	31 13 0
MIS32-30	250	50	47	165	85	55	19.5.01	21h9 🖔 052	51	M8 x 1.25	12.5	22	17 (Effective	8.6	12	64	34	6H9 +0.030
MIS32-50	310	30	47	205	105	33	19.5.0.1	∠ 1113 -0.052	31	IVIO X 1.25	12.5	~ ~	depth 8.5)	0.6	12	84	34	0119 0

Finger options Tapped on upper and lower faces



Tapped on all faces



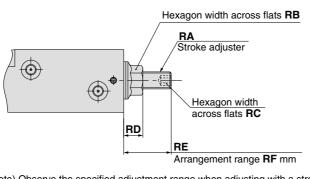
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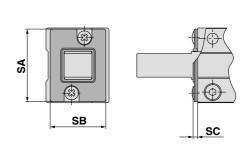
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With adjuster



With scraper



Note) Observe the specified adjustment range when adjusting with a stroke adjuster.

Model	НС	HD	HE	JA	JB	KA	KB	LA	LB	LC	MA	MB	MC	MD	ME	N	Р	PA	PB	PC
MIS8-10	2	3	14	9.5	7.5	6.2	1.6	M2 x 0.4	14	3	M3 x 0.5	5	4	20	13	7.5	M3 x 0.5	19	8	4.5
MIS8-20	_	٦	14	9.5	7.5	0.2	1.0	IVIZ X U.4	14	3	IVIS X U.S		4	30	13	7.5	IVIS X U.S	29	0	4.5
MIS12-10														28				19		
MIS12-20	4	3.5	17.5	13	11	11.6	2.2	M2.6 x 0.45	19	4	M4 x 0.7	7	5	38	18	11	M5 x 0.8	29	10	6
MIS12-30														48				39		
MIS20-10														32				20.5		
MIS20-20	5	5	26	17.5	15	14	2.8	M3 x 0.5	26	6	M6 x 1	10	7	42	25	15	M5 x 0.8	30.5	12	8
MIS20-30														52				40.5		
MIS25-30	5	7	32	20.5	20	11	3	M3 x 0.5	32	10	M8 x 1.25	14	10	55	28	20	M5 x 0.8	47	14	12
MIS25-50	ا	′	32	20.5	20	'	3	IVIS X 0.5	32	10	IVIO X 1.25	14	10	75	20	20	IVIO X U.O	67	14	12
MIS32-30	6	8	40	25	25	20.4	2.5	M4 × 0 7	20	10	M10 v 1 F	1.5	10	64	24	O.E.	Do1/9	47	115	44
MIS32-50	°	0	40	25	23	20.4	2.5	M4 x 0.7	39	12	M10 x 1.5	15	12	84	34	25	Rc1/8	67	14.5	11

Model	PD	PE	RA	RB	RC	RD	RE	RF	SA	SB	SC
MIS8-10	6	2.2	M4 x 0.7	7	2	5.7	12.5	4	18.6	14	1.4
MIS8-20	0	2.2	W4 X U.7	,	_	5.7	12.5	4	10.0	14	1.4
MIS12-10											
MIS12-20	7	3	M5 x 0.8	8	2.5	6	14	6	24	18	1.8
MIS12-30											
MIS20-10											
MIS20-20	10	3	M8 x 1	12	4	9	22.5	12	34	26	2.2
MIS20-30											
MIS25-30	14	2.7	M8 x 1	12	4	9	26	15	40	36	2.8
MIS25-50	14	۷.1	IVIOXI	12	4	Э	20	15	40	30	2.0
MIS32-30	27		M12 x 1.25	17	6	12.4	33	20	49	41	3.4
MIS32-50	21		WIIZ X I.25	17	0	12.4	33	20	49	41	J.4





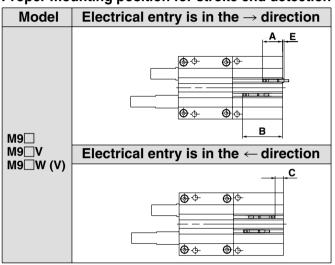
Auto Switch Mounting

When mounting an auto switch, insert the auto switch in the switch mounting groove on the escapement from the direction as below figure. Having set the mounting position, tighten the attached auto switch mounting screws with a flat head watchmaker's screwdriver.

* When adjusting the auto switch mounting screws, use a watchmaker's screwdriver with a handle 5 to 6 mm in diamterer. (This is to prevent fracture due to an excessive torque.) The guideline of the tightening torque is 0.1 to 0.15 N·m.

Watchmaker's screwdriver ø5 to ø6 Auto switch mounting screw M2.5 x 4 Auto switch

Proper mounting position for stroke end detection



Auto Switch Operating Range

MIW (mm)						
Auto switch model	ø 8	ø 12	ø 20	ø 25	ø 32	
D-M9□(V) D-M9□W(V)	3	2.5	4	5.5	7	
MIS (r						
Auto switch model	ø 8	ø 12	ø 20	ø 25	ø 32	
D-M9□(V) D-M9□W(V)	3	3.5	4.5	5.5	7	

Note) The operating ranges are provided as guidelines including hysteresis and are not guaranteed values (with ±30% variations). Hysteresis may fluctuate due to the operating environments.

											(mm)
		Proper mou	inting position			Proper mou	nting	g position			Proper mounting position
Model		D-M9□	D-M9□V	Model		D-M9□	D-N	V □9	Model		D-M9□ D-M9□V
	D-M9_W D-M9_WV				D-M9⊡W	D-N	M9⊡WV			D-M9 W D-M9 WV	
	Α	10	6.5		Α	18	3.5			Α	7.5
	В	2	25		В	4	19			В	38
MIW8-8D	С	4	.5	MIS12-30D	C	6	.5		MIS25-30D	С	21
	D		_		D					D	_
	Е	6	4		Ε	3.5		1.5		Е	_ _
	Α		6.5		Α		0.5			Α	7.5
	В		27		В		1			В	38
MIS8-10D	С	4	.5	MIW20-20D	С	8	.5		MIS25-50D	С	21
	D		_		D		_			D	_
	Ε	6	4		E	4		2		Ε	
	Α		6.5		Α		0.5			Α	8.5
	В		37	MIS20-10D	В		31		MIW32-32D	В	41
MIS8-20D	C	4	.5		C	8	.5			C	29
	D		_		D		_			D	_
	E	6	4		E	4		2		E	
	A		8.5		A		0.5			A	8.5
	В		31		В		51			В	39
MIW12-12D	C	C	3.5	MIS20-20D	C	8	.5		MIS32-30D	C	29
	D E	3.5	1.5		D E	4		2		D E	
	A		1.5 8.5		A	· ·).5			A	8.5
	В		29		В		3.3 31			В	59
MIS12-10D	C		3.5	MIS20-30D	C		.5		MIS32-50D	C	29
WII312-10D	D		_		D		_		W1332-30D	D	_
	E	3.5	1.5		E	4		2		E	
	A		8.5		Ā	· ·	.5			_	
	В		39		В		33		, ,		e auto switch after con
MIS12-20D	C	ϵ	6.5	MIW25-25D	c	2	21		opera	ing	conditions in the actua
	Ě				Ĕ						

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Series MIW/MIS Specific Product Precautions 1

Be sure to read before handling. Refer to front matters 42 and 43 for Safety Instructions and pages 3 to 11 for Actuator and Auto Switch Precautions.

Selection

⚠ Warning

- 1. Design the attachment to be light and short.
 - 1) A long and heavy attachment can cause a large inertia force in operation, sometimes affecting the life time.
 - Design the attachment to be as short and light as possible even within the limitation.

Mounting

⚠ Warning

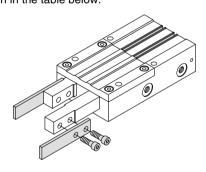
- 1. Do not scratch or gouge the escapement by dropping or bumping it when mounting.
 - Even a slight deformation can cause inaccuracy or malfunction.
- 2. Please observe the specified torque limits when tightening screws to mount the attachment.

A tightening torque beyond the specified limits can cause malfunction, while a tightening torque below the specified limits can cause dislocation or drop off.

Mounting attachment on finger

When mounting an attachment on the finger, support the finger with a tool like a spanner to prevent twisting.

Mount attachments by inserting bolts, etc. into the female mounting threads on the fingers and tightening with the torque shown in the table below.



Model	Bolt	Max tightening torque (N·m)
MIW8	M3 x 0.5	0.00
MIS8	IVI3 X U.5	0.88
MIW12	M3 x 0.5	0.88
MIS12	IVIS X U.S	0.00
MIW20	M5 x 0.8	4.0
MIS20	O.O X CIVI	4.3
MIW25	M6 x 1	7.3
MIS25	IVIOXI	7.3
MIW32	M8 x 1.25	17.5
MIS32	IVIO X I.25	17.5

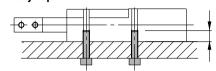
3. Please observe the specified torque limits when tightening screws to mount the attachment.

A tightening torque above the specified limits can cause malfunction, while a tightening torque below the specified limits can cause dislocation or drop off.

Mounting

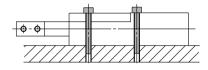
Mounting

Body tap



Model	Bolt	Max tightening torque (N⋅m)	Max screw-in depth (mm)	
MIW8	M3 x 0.5	0.88	6	
MIS8	IVIS X U.S	0.63	4.5	
MIW12	M4 x 0.7	1.5	6	
MIS12	IVI4 X 0.7	1.5	0	
MIW20	M6 x 1	5.2	0	
MIS20	IVIOXI	5.2	9	
MIW25	M8 x 1.25	12.5	12	
MIS25	1VIO X 1.23	12.5	12	
MIW32	M10 x 1.5	24.5	15	
MIS32	C.I X DIIVI	∠4.5	15	

Body through hole



Model	Bolt	Max tightening torque (N·m)		
MIW8	M2.5 x 0.45	0.5		
MIS8	IVIZ.3 X 0.43	0.5		
MIW12	M3 x 0.5	0.88		
MIS12	IVIO X U.S	0.00		
MIW20	M5 x 0.8	4.3		
MIS20	IVIO X U.O	4.5		
MIW25	M6 x 1	7.3		
MIS25	IVIO X I	7.3		
MIW32	M8 x 1.25	17.5		
MIS32	IVIO X 1.23	17.5		

⚠ Caution

1. When mounting an attachment on the finger, support the finger with a tool like a spanner to prevent twisting.

Otherwise malfunction may result.

2. Please do not scratch or gouge the sliding part of the finger.

It may increase the sliding resistance or cause abrasion.

3. Use a speed controller, etc. to keep the operating speed of the finger within the proper range.

Otherwise the life time may be adversely affected by inertia force of the attachment.

4. Conduct meter-out control to throttle down the speed.

Applicable speed controller

Direct connection type –AS120

Direct connection type –AS120□ Piping type – AS1001F
Direct connection type –AS220□ Piping type – AS2001F etc.



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Series MIW/MIS Specific Product Precautions 2

Be sure to read before handling. Refer to front matters 42 and 43 for Safety Instructions and pages 3 to 11 for Actuator and Auto Switch Precautions.

Changing of Piping Directions

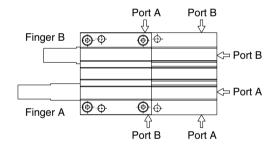
⚠ Caution

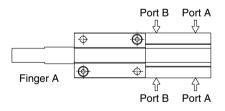
1. Please observe the specified torque limits when tightening a plug to change the piping directions.

A tightening torque above the specified limits can cause a damage to the plug, while tightening torque below the specified limits can cause a damage to seal or the screw come loose during the operation.

Model	Port size	How to tight
MIW8 MIS8	M3 x 0.5 (Plug part no: M-3P	Turn another 1/4 turn with a tool after manual tightening.
MIW12		
MIS12		
MIW20	M5 x 0.8	Turn another 1/6 turn with a tool
MIS20	(Plug part no: M-5P	after manual tightening.
MIW25		
MIS25		
MIW32	Rc1/8	Tightoning torque 7 to 0 Nem
MIS32	HC1/8	Tightening torque 7 to 9 N·m

Supply port operation





Pressured from A port \rightarrow Finger A extends, finger B retracts Pressure from B port \rightarrow Finger B extends, finger A retracts

Handling of Adjuster Options

Stroke adjuster

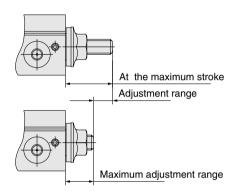
⚠ Warning

1. Observe the specified adjustment range as shown on right when adjusting with a stroke adjuster.

Bolts may shoot out when adjusting stroke adjuster over the maximum stroke as shown on right. Be sure to observe the specified adjustment range, otherwise malfunction may results.

Handling of Adjuster Options

Model	At the maximum stroke (mm)	At the maximum adjustment (mm)	Adjustment range (mm)	
MIW8	12.5	8.4	4	
MIS8	12.0	0.1	-	
MIW12	14	8	6	
MIS12	17	O		
MIW20	22.5	10.5	12	
MIS20	22.5	10.5	12	
MIW25	26	11	15	
MIS25	20	11	15	
MIW32	00	10	00	
MIS32	33	13	20	



- **2.** Be sure to use specified adjuster bolts for replacement. Otherwise, fracture may be caused by an impact etc.
- 3. Refer to the table below for the lock nut tightening torque.

Insufficient tightening can cause air leakage.

Model	Tightening torque (N⋅m)		
MIW8	1.2 to 1.5		
MIS8	1.2 to 1.5		
MIW12	2.5 to 3.0		
MIS12			
MIW20	10.5 to 12.5		
MIS20	10.5 to 12.5		
MIW25	10.5 to 12.5		
MIS25	10.5 to 12.5		
MIW32	24 to 42		
MIS32	34 to 42		

Operating Environment

⚠ Caution

- 1. Do not use in an environment where the product is directly exposed to liquid such as cutting lubricant.
 - Avoid use in an environment where the product is exposed to cutting lubricant, liquid coolant or oil mist. It can cause rattles, increase in sliding resistance and air leakage.
- 2. Do not use in an environment where the product is directly exposed to foreign matter such as dust, coarse particular, chips and polishing powder from a spatter grinder, etc.

It can cause rattles, increase in sliding resistance and air leakage.





Series MIW/MIS Specific Product Precautions 3

Be sure to read before handling.
Refer to front matters 42 and 43 for Safety Instructions and pages 3 to 11 for Actuator and Auto Switch Precautions.

Operating Environment

- 3. Provide shading in an environment where the product is exposed to the sunlight.
- 4. Block off heat radiation in an environment where a heat source is at a close distance.

Block off heat radiation with a cover if a heat source is at a close distance because the temperature of the product can rise to exceed the operating temperature range due to radiation.

Do not use in an environment where vibration or impact occurs.

Contact SMC about use under such conditions because it can cause fracture or malfunction.

Lubrication

⚠ Caution

 The non-lubricant type escapement is lubricated at the factory and does not need further lubrication for use.

In case the product is lubricated by the customer, apply class 1 turbin oil (non additive) ISO VG32.

In case the product is lubricated by the customer, be sure to continue lubrication.

If it is discontinued, malfunction may result due to loss of initial lubricant.

Maintenance

Marning

 Keep away hands and other body parts from the fingers of the escapement or movement range of the attachment.

It can lead to an injury or accident.

When removing the escapement, first block off or remove the work piece on the primary side of the escapement, release compressed air and remove it.

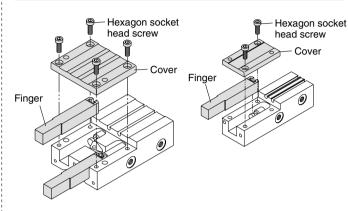
If the work piece remains, it can be transferred by mistake and cause failure to the equipment on the secondary side.

Finger replacement

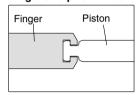
- 1. Remove the hexagon socket head screws.
- 2. Remove the cover.
- 3. Replace the finger.
 - · Apply the specified grease to the sliding part and T groove part of the finger.
 - · Insert the piston in the T groove so that it will be hooked there.
- 4. Mount the cover and tighten the hexagon socket head screws with the tightening torque in the table below.

Bore size	Hexagon socket head screw	Hexagon width across flats	Tightening torque (N·m)
8 M2 x 6		1.5	0.24
12	M2.5 x 6	2	0.36
20 M4 x 10		3	1.5
25 M5 x 14		4	3.0
32	M6 x 15	5	5.2

Maintenance



Finger and position connection



For information on the replacement parts and specified grease, refer to the replacement parts on page 1425.

Scraper Option

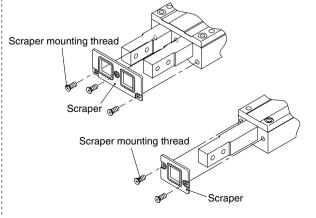
⚠ Caution

1. Please observe the specified torque limits when mounting a scraper.

A tightening torque above the specified limits can cause a damage, while tightening torque below the specified limits can cause a dislocation or drop off.

Tightening torque

9				
Model	Bolt (N⋅m)			
MIW8	0.176			
MIS8	0.176			
MIW12	0.26			
MIS12	0.36			
MIW20	0.00			
MIS20	0.63			
MIW25	0.63			
MIS25	0.63			
MIW32	1.5			
MIS32	1.5			





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