AC Servo Motor Driver Series LECS□

Pulse Input Type/ Positioning Type



Incremental Type
Series LECSA

Pulse Input Type



Absolute Type
Series LECSB

CC-Link Direct Input Type



Absolute Type
Series LECSC

SSCNET III Type



Absolute Type
Series LECSS

Ę

LEJ

핔

<u>""</u>

Œ

핖

EC-G LECA6

LECS□ LECPA LECP1 LEC-G

AC Servo Motor Driver



Series LECS□ list

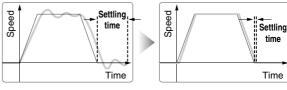
			npatible m 00/200 VA	otor C)	Co	Control method			Compatible option
	Series	100 W	200 W	400 W	Note 1) Positioning	Pulse	Network direct input	Note 2) Synchronous	Setup software LEC-MR-SETUP221
Incremental Type	LECSA (Pulse input type/ Positioning type)	•	•	•	Up to 7 points	•			•
	LECSB (Pulse input type)	•	•	•		0			•
Absolute Type	LECSC (CC-Link direct input type)	•	•	•	Up to 255 points		CC-Link Ver. 1.10		•
	LECSS (SSCNET III type) Compatible with Mitsubishi Electric's serve system controller network	•	•	•			SSCNET III	0	•

Note 1) For positioning type, setting needs to be changed to use with maximum set values. Setup software (MR Configurator) LEC-MR-SETUP221 is required. Note 2) Available when the Mitsubishi motion controller is used for the master equipment.



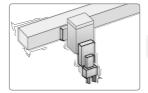
Auto resonant filter function

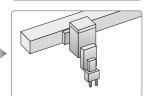
· Control the difference between command value and actual action



Auto damping control function

· Automatically suppress low frequency machine vibrations (up to 100 Hz)





With display setting function



One-touch adjustment button One-touch servo adjustment

Display

Display the monitor, parameter and alarm.

Settings

Set parameters and monitor display, etc. with push buttons.



LECSA

Display

Display the monitor, parameter and alarm.

Settings

Set parameters and monitor display, etc. with push buttons.



(With the front cover opened) **LECSB**

Display

Display the communication status with the driver, the alarm and the point table No.

Settings

Control Baud rate, station number and the occupied station count.



(With the front cover opened) **LECSC**

Display

Display the communication status with the driver and the alarm.

Settings

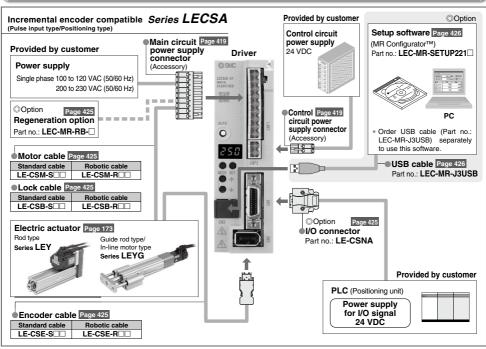
Switches for selecting axis and switching to the test operation

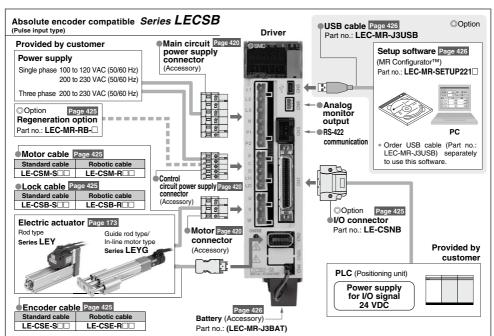


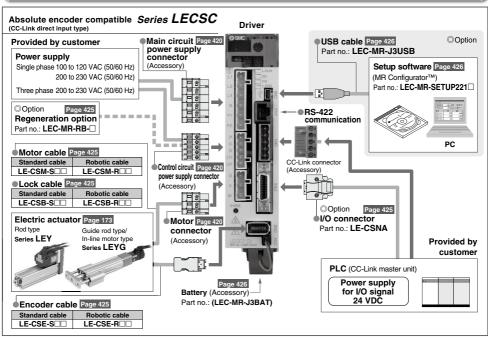
(With the front cover opened) **LECSS**

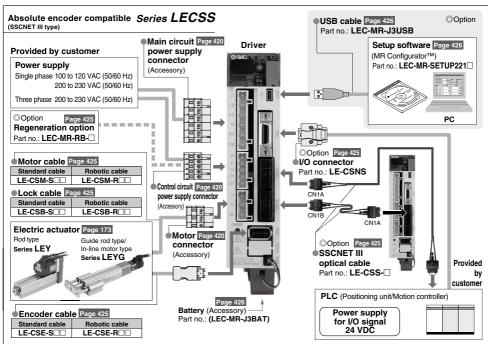


System Construction









@SMC

Щ

LE

LEYG FEYG

핔

LESH

Ē

LECP1 LEC-G LECP6

T3 LECS

LECPA

AC Servo Motor Driver

Series LECS

Power supply voltage 100 to 120 VAC 200 to 230 VAC

Motor capacity 100/200/400 W

CC-Link

ncremental Type

Series LECSA (Pulse input type/Positioning type)



- •Up to 7 positioning points by point table
- •Input type: Pulse input
- Control encoder: Incremental 17-bit encoder (Resolution: 131072 pulse/rev)
- Parallel input: 6 inputs
 output: 4 outputs

Series LECSB (Pulse input type)



- •Input type: Pulse input
- Control encoder: Absolute 18-bit encoder (Resolution: 262144 pulse/rev)
- Parallel input: 10 inputs output: 6 outputs

Series LECSC (CC-Link direct input type)



- Position data/speed data setting and operation start/stop
- Positioning by up to 255 point tables (when 2 stations occupied)
- Up to 32 drivers connectable (when 2 stations occupied) with CC-Link communication
- Applicable Fieldbus protocol: CC-Link (Ver. 1.10, max. communication speed: 10 Mbps)
- Control encoder: Absolute 18-bit encoder (Resolution: 262144 pulse/rev)

Series LECSS (SSCNET III type)



- Compatible with Mitsubishi Electric's servo system controller network
- Reduced wiring and SSCNET III optical cable for one-touch connection
- •SSCNET III optical cable provides enhanced noise resistance
- Up to 16 drivers connectable with SSCNET III communication
- Applicable Fieldbus protocol: SSCNET III
 (High-speed optical communication, max. bidirectional communication speed: 100 Mbps)
- Control encoder: Absolute 18-bit encoder (Resolution: 262144 pulse/rev)



Absolute Type

Incremental Type

Series LECSA (Pulse Input Type/Positioning Type)







Absolute Type Series LECS

(Pulse Input Type) (CC-Link Direct Input Type)

(SSCNET III Type)

How to Order

LECS A 1 Driver

	Dilver type •
A	Pulse input type/Positioning type (For incremental encoder)
В	Pulse input type (For absolute encoder)
С	CC-Link direct input type (For absolute encoder)
s	SSCNET III type (For absolute encoder)

Power supply voltage

	1 Office Supply Tollage
1	100 to 120 VAC, 50/60 Hz
2	200 to 230 VAC, 50/60 Hz

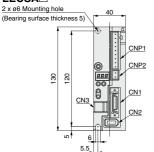


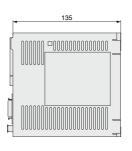
• Con	Compatible motor type								
Symbol	Туре	Capacity	Encoder						
S1	AC servo motor (S2)	100 W							
S3	AC servo motor (S3)	200 W	Incremental						
S4	AC servo motor (S4)*	400 W							
S5	AC servo motor (S6)	100 W							
S7	AC servo motor (S7)	200 W	Absolute						
S8	AC servo motor (S8)*	400 W							

^{*} Only available for power supply voltage "200 to 230 VAC".

Dimensions

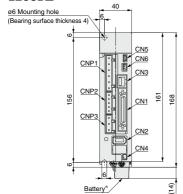
LECSA

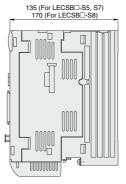




Connector name	Description			
CN1	I/O signal connector			
CN2	Encoder connector			
CN3	USB communication connector			
CNP1	Main circuit power supply connector			
CNP2	Control circuit power supply connector			

LECSB





CN1	I/O signal connector					
CN2	Encoder connector					
CN3	RS-422 communication connector					
CN4	Battery connector					
CN5	USB communication connector					
CN6	Analog monitor connector					
CNP1	Main circuit power supply connector					
CNP2	Control circuit power supply connector					
CNP3	Servo motor power connector					

Description

Connector name

* Battery included.



同

岜

핔

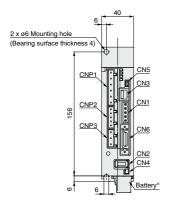
LER

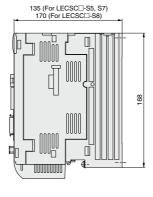
핕

LECS LECPA LECP1 LEC-G

Dimensions

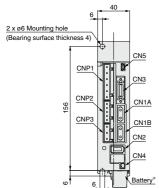
LECSC



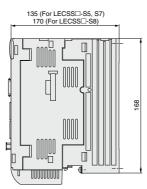


Connector name	Description
CN1	CC-Link connector
CN2	Encoder connector
CN3	RS-422 communication connector
CN4	Battery connector
CN5	USB communication connector
CN6	I/O signal connector
CNP1	Main circuit power supply connector
CNP2	Control circuit power supply connector
CNP3	Servo motor power connector

LECSS







Connector name	Description
CN1A	Front axis connector for SSCNET III optical cable
CN1B	Rear axis connector for SSCNET III optical cable
CN2	Encoder connector
CN3	I/O signal connector
CN4	Battery connector
CN5	USB communication connector
CNP1	Main circuit power supply connector
CNP2	Control circuit power supply connector
CNP3	Servo motor power connector

^{*} Battery included.

Specifications

Series LECSA

Model	LECSA1-S1	LECSA1-S3	LECSA2-S1	LECSA2-S3	LECSA2-S4		
le motor capacity [W]	100	200	100	200	400		
le encoder	Incremental 17-bit encoder (Resolution: 131072 p/rev)						
Power voltage [V]	Single phase 100 to	120 VAC (50/60 Hz)	Single pha	ase 200 to 230 VAC	50/60 Hz)		
Allowable voltage fluctuation [V]	Single phase 8	35 to 132 VAC	Sing	le phase 170 to 253	VAC		
Rated current [A]	3.0	5.0	1.5	2.4	4.5		
Control power supply voltage [V]			24 VDC				
Allowable voltage fluctuation [V]			21.6 to 26.4 VDC				
Rated current [A]			0.5				
put	6 inputs						
utput	4 outputs						
t pulse frequency [pps]	1 M (for differential receiver), 200 k (for open collector)						
In-position range setting [pulse]	0 to ± 65535 (Command pulse unit)						
Error excessive	±3 rotations						
Torque limit	Parameter setting						
Communication	USB communication						
temperature range [°C]	0 to 55 (No freezing)						
humidity range [%RH]	90 or less (No condensation)						
emperature range [°C]	-20 to 65 (No freezing)						
umidity range [%RH]	90 or less (No condensation)						
resistance [MΩ]	Between the housing and SG: 10 (500 VDC)						
]	600 700				700		
	le motor capacity [W] le encoder Power voltage [V] Allowable voltage fluctuation [V] Rated current [A] Control power supply voltage [V] Allowable voltage fluctuation [V] Rated current [A] put utput tt pulse frequency [pps] In-position range setting [pulse] Error excessive Torque limit Communication temperature range [°C] humidity range [°C] umidity range [°C] umidity range [°C] umidity range [°C]	le motor capacity [W] 100 le encoder Power voltage [V] Single phase 100 to Single pha	le motor capacity [W] 100 200 le encoder Inc (Re Power voltage [V] Single phase 100 to 120 VAC (50/60 Hz) Allowable voltage fluctuation [V] Single phase 85 to 132 VAC (50/60 Hz) Allowable voltage fluctuation [V] Single phase 85 to 132 VAC (50/60 Hz) Allowable voltage fluctuation [V] Rated current [A] Single phase 85 to 132 VAC (50/60 Hz) Allowable voltage fluctuation [V] Rated current [A] Single phase 85 to 132 VAC (50/60 Hz) Allowable voltage fluctuation [V] Rated current [A] Single phase 85 to 132 VAC (50/60 Hz) Intervet [A] Single phase 85 to 132 VAC (50/60 Hz) Intervet [A] Single phase 85 to 132 VAC (50/60 Hz) Intervet [A] Single phase 85 to 132 VAC (50/60 Hz) Intervet [A] Single phase 85 to 132 VAC (50/60 Hz) Intervet [A] Single phase 15 to 132 VAC	le motor capacity [W] 100 200 100 le encoder Incremental 17-bit enco (Resolution: 131072 p/r Power voltage [V] Single phase 100 to 120 VAC (50/60 Hz) Single phase 100 to 120 VAC (50/60 Hz) Allowable voltage fluctuation [V] Single phase 85 to 132 VAC Single phase 100 to 120 VAC (50/60 Hz) Single phase 85 to 132 VAC Single phase 85 to 132 VAC Single phase 85 to 132 VAC Single phase 100 to 120 VAC (50/60 Hz) Allowable voltage fluctuation [V] 21.6 to 26.4 VDC 21.6	Incremental 17-bit encoder		

Series LECSB

	Model	LECSB1-S5	LECSB1-S7	LECSB2-S5	LECSB2-S7	LECSB2-S8		
Compatil	ole motor capacity [W]	100	200	100	200	400		
Compatil	ole encoder	Absolute 18-bit encoder (Resolution: 262144 p/rev)						
Main	Power voltage [V]	Single phase 100 to	120 VAC (50/60 Hz)		ase 200 to 230 VAC (ase 200 to 230 VAC			
power supply	Allowable voltage fluctuation [V]	Single phase 8	35 to 132 VAC		Three phase 170 to 253 VAC Single phase 170 to 253 VAC			
	Rated current [A]	3.0	5.0	0.9	1.5	2.6		
Control	Control power supply voltage [V]	Single phase 100 to	120 VAC (50/60 Hz)	Three pha	ase 200 to 230 VAC (50/60 Hz)		
power	Allowable voltage fluctuation [V]	Single phase 8	85 to 132 VAC	Single phase 170 to 253 VAC				
supply	Rated current [A]	0.	.4	0.2				
Parallel i	• • • • • • • • • • • • • • • • • • • •	10 inputs						
Parallel c	output	6 outputs						
Max. inpu	ut pulse frequency [pps]	1 M (for differential receiver), 200 k (for open collector)						
	In-position range setting [pulse]	0 to ±10000 (Command pulse unit)						
Function	Error excessive	±3 rotations						
i unction	Torque limit	F	Parameter setting or e	external analog input	ernal analog input setting (0 to 10 VDC)			
	Communication	USB communication, RS422 communication*1						
Operating	g temperature range [°C]	0 to 55 (No freezing)						
Operating	g humidity range [%RH]	90 or less (No condensation)						
Storage t	emperature range [°C]	-20 to 65 (No freezing)						
Storage I	numidity range [%RH]	90 or less (No condensation)						
Insulation	n resistance [MΩ]	Between the housing and SG: 10 (500 VDC)						
Weight [c	3]	800 1000				1000		

^{*1} USB communication and RS422 communication cannot be performed at the same time.

삠

핔

LECS□ LECPA LECP1 LEC-G LECA6





Specifications

Series LECSC

	Мо	del	LECSC1-S5 LECSC1-S7 LECSC2-S5 LECSC2-S7 LECSC2					
Compatibl	le motor cap	acity [W]	100	200	100	200	400	
Compatibl	le encoder		Absolute 18-bit encoder (Resolution: 262144 p/rev)					
	ower			00 to 120 VAC 0 Hz)		se 200 to 230 VAC se 200 to 230 VAC		
power supply	Allowable vo	Itage fluctuation [V]	Single phase 8	35 to 132 VAC	Three phase 170 to	253 VAC, Single pha	ase 170 to 253 VAC	
oupp.y	Rated currer	nt [A]	3.0	5.0	0.9	1.5	2.6	
Control	Control pow	er supply voltage [V]	Single phase 1 (50/6	00 to 120 VAC 0 Hz)	Single	e phase 200 to 230 (50/60 Hz)	VAC	
supply	Allowable vo	Itage fluctuation [V]	Single phase 8	35 to 132 VAC	Single	e phase 170 to 253	VAC	
,	Rated currer	nt [A]	0.	4		0.2		
	Applicable Fi	eldbus protocol (Version)			communication (V	,		
	Connection	cable	CC-Link	Ver. 1.10 complia	nt cable (Shielded	3-core twisted pair	cable)*1	
	Remote stat				1 to 64			
		Communication speed [bps]	16 k	625 k	2.5 M	5 M	10 M	
	Cable length	Maximum overall cable length [m]	1200	900	400	160	100	
specifications	Cable length between stations [m]		0.2 or more					
	I/O occupation	on area (Inputs/Outputs)	1 station occupied (Remote I/O 32 points/32 points)/(Remote register 4 words/4 words) 2 stations occupied (Remote I/O 64 points/64 points)/(Remote register 8 words/8 words)					
	Number of c	onnectable drivers	Up to 42 (when 1 station is occupied by 1 driver), Up to 32 (when 2 stations are occupied by 1 driver), when there are only remote device stations.					
	Remote regi	ster input	Available with CC-Link communication (2 stations occupied)					
Command method				Available with CC-Link communication, RS-422 communication CC-Link communication (1 station occupied): 31 points CC-Link communication (2 stations occupied): 255 points RS-422 communication: 255 points				
	Indexer posi	tioning input	Available with CC-Link communication CC-Link communication (1 station occupied): 31 points CC-Link communication (2 stations occupied): 255 points					
Communic	cation function	on	USB communication, RS-422 communication*2					
	temperature	· · ·	0 to 55 (No freezing)					
Operating humidity range [%RH]			90 or less (No condensation)					
Storage temperature range [°C]			-20 to 65 (No freezing)					
	umidity range	· ·	90 or less (No condensation)					
Insulation	resistance [l	MΩ]	Between the housing and SG: 10 (500 VDC)					
Weight [g]				80	00		1000	
		th CC Link Var. 1 00 and Var. 1	10 compliant cables. Ver 1 00 specifications are applied to the cable extensions and the cable length between stations					

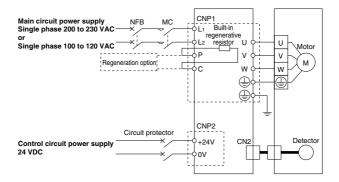
^{*1} If the system comprises of both CC-Link Ver. 1.00 and Ver. 1.10 compliant cables, Ver. 1.00 specifications are applied to the cable extensions and the cable length between stations. *2 USB communication and RS422 communication cannot be performed at the same time.

Series LECSS

	Model	LECSS1-S5	LECSS1-S7	LECSS2-S5	LECSS2-S7	LECSS2-S8	
Compati	ble motor capacity [W]	100	200	100	200	400	
Compati	ble encoder	Absolute 18-bit encoder (Resolution: 262144 p/rev)					
Main Power voltage [V]			00 to 120 VAC 0 Hz)		Three phase 200 to 230 VAC (50/60 Hz) Single phase 200 to 230 VAC (50/60 Hz)		
power supply	Allowable voltage fluctuation [V]	Single phase a	85 to 132 VAC	Three phase 170 to	253 VAC, Single ph	ase 170 to 253 VAC	
oupp.y	Rated current [A]	3.0	5.0	0.9	1.5	2.6	
Control	Control power supply voltage [V]	Single phase 100 to 120 VAC (50/60 Hz)		Single phase 200 to 230 VAC (50/60 Hz)			
supply	Allowable voltage fluctuation [V]	Single phase	85 to 132 VAC	Singl	Single phase 170 to 253 VAC		
oupp.y	Rated current [A]	0	.4	0.2			
Applicab	le Fieldbus protocol	SSCNET III (High-speed optical communication)					
Commun	nication function	USB communication					
Operatin	g temperature range [°C]	0 to 55 (No freezing)					
Operatin	g humidity range [%RH]	90 or less (No condensation)					
Storage	temperature range [°C]	-20 to 65 (No freezing)					
Storage	humidity range [%RH]	90 or less (No condensation)					
Insulatio	n resistance [MΩ]	Between the housing and SG: 10 (500 VDC)					
Weight [g]	800 1000				1000	

Power Supply Wiring Example: LECSA

LECSA□-□

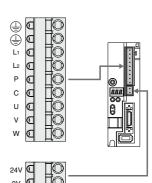


Main Circuit Power Supply Connector: CNP1 * Accessory

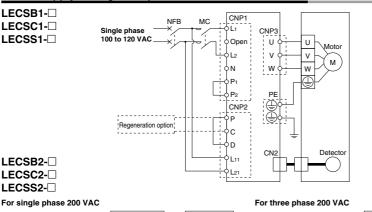
Terminal n	ame Function	Details
(1)	Protective earth (PE)	Should be grounded by connecting the servo motor's earth terminal and the control panel's protective earth (PE).
L ₁	Main circuit	Connect the main circuit power supply. LECSA1: Single phase 100 to 120 VAC, 50/60 Hz
L2	power supply	LECSA1: Single phase 100 to 120 VAC, 50/60 Hz LECSA2: Single phase 200 to 230 VAC, 50/60 Hz
Р	Degeneration ention	Terminal to connect regeneration option LECSA□-S1: Not connected at time of shipping. LECSA□-S3. S4: Connected at time of shipping.
С	Regeneration option	* If regeneration option is required for "Model Selection", connect to this terminal.
U	Servo motor power (U)	
V	Servo motor power (V)	Connect to motor cable (U, V, W).
W	Servo motor power (W)	

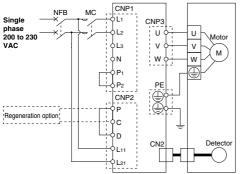
Control Circuit Power Supply Connector: CNP2 * Accessory

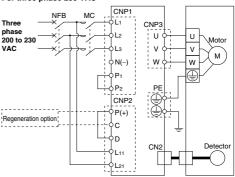
	,		
Terminal name	Function	Details	
24V	Control circuit power supply (24 V)	24 V side of the control circuit power supply (24 VDC) supplied to the driver	
0V	Control circuit power supply (0 V)	0 V side of the control circuit power supply (24 VDC) supplied to the driver	



Power Supply Wiring Example: LECSB, LECSC, LECSS







Note) For single phase 200 to 230 VAC, power supply should be connected to L1 and L2 terminals, with nothing connected to L3.

Main Circuit Power Supply Connector: CNP1 * Accessory

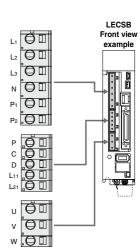
Terminal name	Function	Details		
L ₁	Main circuit power supply	Connect the main circuit power supply.		
L2		LECSB1/LECSC1/LECSS1: Single phase 100 to 120 VAC, 50/60 Hz Connection terminal: L1,L2 LECSB2/LECSC2/LECSS2: Single phase 200 to 230 VAC, 50/60 Hz Connection terminal: L1,L2		
Lз		Three phase 200 to 230 VAC, 50/60 Hz Connection terminal: L1,L2,L3		
N		Do not connect.		
P ₁		Connect between P1 and P2. (Connected at time of shipping.)		
Pa				

Control Circuit Power Supply Connector: CNP2 * Accessory

Terminal name	Function	Details
Р	Degeneration	Connect between P and D. (Connected at time of shipping.)
С	Regeneration option	* If regeneration option is required for "Model Selection", connect to this
D	орион	terminal.
L11	Control circuit	Connect the control circuit power supply. LECSB1/LECSC1/LECSS1: Single phase 100 to 120 VAC, 50/60 Hz Connection terminal: L11,L21
L21	power supply	LECSB2/LECSC2/LECSS2: Single phase 200 to 230 VAC, 50/60 Hz Connection terminal: L11,L21 Three phase 200 to 230 VAC, 50/60 Hz Connection terminal: L11,L21

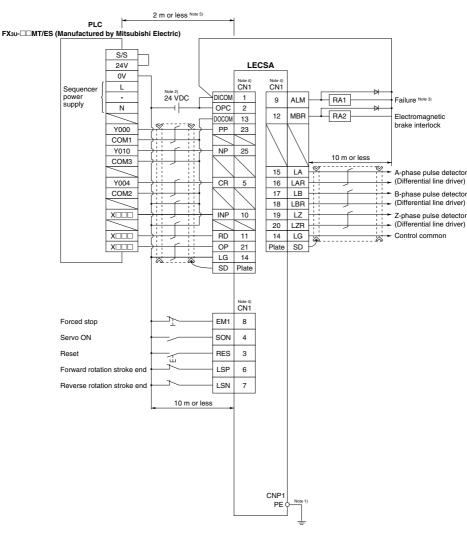
Motor Connector: CNP3 * Accessory

1	Terminal name	Function	Details
	U	Servo motor power (U)	
	V	Servo motor power (V)	Connect to motor cable (U, V, W).
	W	Servo motor power (W)	



Control Signal Wiring Example: LECSA

This wiring example shows connection with a PLC (FX3U-\\D\T/ES) manufactured by Mitsubishi Electric as when used in position control mode. Refer to the LECSA operation manual and any technical literature or operation manuals for your PLC and positioning unit before connecting to another PLC or positioning unit.



Note 1) For preventing electric shock, be sure to connect the driver circuit power supply connector (CNP1)'s protective earth (PE) terminal to the control panel's protective earth (PE).

Note 2) For interface use, supply 24 VDC ±10% 200 mA using an external source. 200 mA is the value when all I/O command signals are used and reducing the number of inputs/outputs can decrease current capacity. Refer to "Operation Manual" for required current for interface.

Note 3) The failure (ALM) is ON during normal conditions. When it is OFF (alarm occurs), stop the sequencer signal using the sequence program.

Note 4) The same name signals are connected inside the driver.

Note 5) For command pulse input with an open collector method. When a positioning unit loaded with a differential line driver method is used, it is 10 m or

Ë

LEJ

펄

<u>"</u>

~

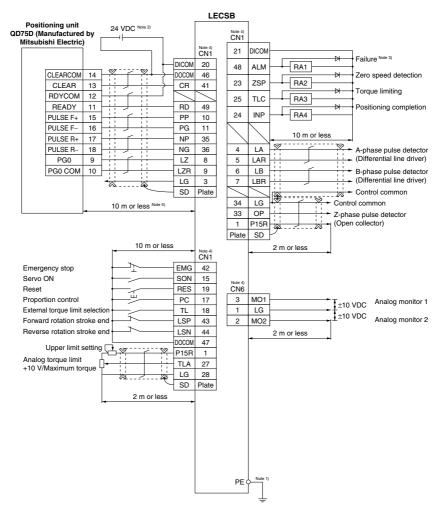
CA6 LEH

LECS□ LECPA LECP1 LEC-G LECA6



Control Signal Wiring Example: LECSB

This wiring example shows connection with a positioning unit (QD75D) manufactured by Mitsubishi Electric as when used in position control mode. Refer to the LECSB operation manual and any technical literature or operation manuals for your PLC and positioning unit before connecting to another PLC or positioning unit.



Note 1) For preventing electric shock, be sure to connect the driver circuit power supply connector (CNP1)'s protective earth (PE) terminal to the control panel's protective earth (PE).

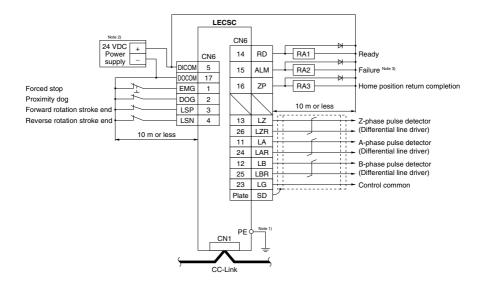
Note 2) For interface use, supply 24 VDC ±10% 300 mA using an external source.

Note 3) The failure (ALM) is ON during normal conditions. When it is OFF (alarm occurs), stop the sequencer signal using the sequence program.

Note 4) The same name signals are connected inside the driver.

Note 5) For command pulse input with a differential line driver method. For open collector method, it is 2 m or less.

Control Signal Wiring Example: LECSC



Note 1) For preventing electric shock, be sure to connect the driver's protective earth (PE) terminal (marked \circ) to the control panel's protective earth (PE). Note 2) For interface use, supply 24 VDC ±10% 150 mA using an external source.

Note 3) The failure (ALM) is ON during normal conditions. When it is OFF (alarm occurs), stop the sequencer signal using the sequence program.

EF

LEJ

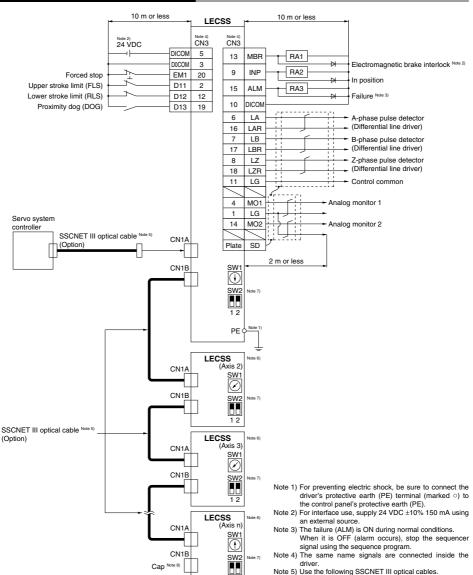
핔

<u>۳</u>

Ē



Control Signal Wiring Example: LECSS



Note 6) Connections from Axis 2 onward are omitted.

Refer to "SSCNET III optical cable" on page 425 for

SSCNET III optical cable LE-CSS- 0.15 m to 3 m

Cable model

Cable length

Note 7) Up to 16 axes can be set.

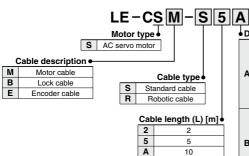
cable models

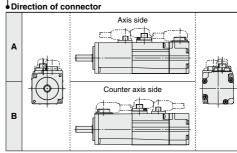
Note 8) Be sure to place a cap on unused CN1A/CN1B.

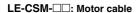
12

Options

Motor cable, Lock cable, Encoder cable (LECS□ common)









LE-CSB-□□: Lock cable



LE-CSE-□□: Encoder cable



* LE-CSM-SDD is MR-PWS1CBLDM-AD-L manufactured by Mitsubishi Electric. LE-CSB-S□□ is MR-BKS1CBL□M-A□-L manufactured by Mitsubishi Electric. LE-CSE-S□□ is MR-J3ENCBL□M-A□-L manufactured by Mitsubishi Electric. LE-CSM-R□□ is MR-PWS1CBL□M-A□-H manufactured by Mitsubishi Electric. LE-CSB-R□□ is MR-BKS1CBL□M-A□-H manufactured by Mitsubishi Electric. LE-CSE-R□□ is MR-J3ENCBL□M-A□-H manufactured by Mitsubishi Electric.

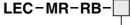
S AC servo motor 0.15 m Cable description K 0.3 m S SSCNET III optical cable J 0.5 m 1 1 m * LE-CSS-□ is MR-J3BUS□M 3 3 m manufactured by Mitsubishi Electric.

LE-CSS-1

Cable length

SSCNET III optical cable

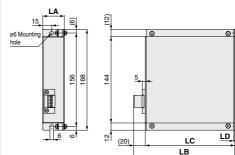
Regeneration option (LECS□ common)



Regeneration option type

032	Allowable regenerative power 30 W	
12	Allowable regenerative power 100 W	
Confirm regeneration option to be used		

in "Model Selection".



Dimensions [mm]

Model	LA	LB	LC	LD
LEC-MR-RB-032	30	119	99	1.6
LEC-MR-RB-12	40	169	149	2

* MR-RB- manufactured by Mitsubishi Electric.

I/O connector

LE-CSNA Driver type LECSA□. LECSC□ Α

В **LECSB**□ s **LECSS**

LE-CSNA

LE-CSNB

LE-CSNS







- * LE-CSNA: 10126-3000PE (connector)/10326-52F0-008 (shell kit) manufactured by 3M or equivalent item.
- LE-CSNB: 10150-3000PE (connector)/10350-52F0-008 (shell kit) manufactured by 3M or equivalent item.
- LE-CSNS: 10120-3000PE (connector)/10320-52F0-008 (shell kit) manufactured by 3M or equivalent item.

삨

굨

핔

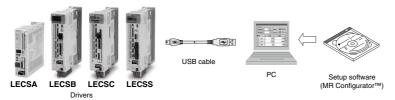
EB

핔

LEC-G

LECS | LECPA | LECP1

Options



Setup software (MR Configurator™) (LECSA, LECSB, LECSC, LECSS common)



Display language

Nil	Japanese version
Е	English version

* MRZJW3-SETUP221 manufactured by Mitsubishi Electric.

Refer to Mitsubishi Electric's website for operating environment and version update information. MR Configurator™ is a registered trademark or trademark of Mitsubishi Electric.

Adjustment, waveform display, diagnostics, parameter read/write, and test operation can be performed upon a PC. Compatible PC

When using setup software (MR Configurator™), use an IBM PC/AT compatible PC that meets the following operating conditions.

Hardware Requirements

Equipment		Setup software (MR Configurator™) LEC-MR-SETUP221 □	
Note 1) Note 2) Note 3)	os	Windows®98, Windows®Me, Windows®2000 Professional, Windows®XP Professional / Home Edition, Windows Vista® Home Basic / Home Premium / Business / Ultimate / Enterprise Windows®7 Starter / Home Premium / Professional / Ultimate / Enterprise	
	Available HD space	130 MB or more	
	Communication interface	Use USB port	
Display		Resolution 1024 x 768 or more Must be capable of high color (16-bit) display. The connectable with the above PC	
Keyboard Mouse		The connectable with the above PC	
		The connectable with the above PC	
Printer		The connectable with the above PC	
USB cable		LEC-MR-J3USB Note 4, 5)	

Note 1) Before using a PC for setting LECSA point table method/program method or LECSC point table No. input, upgrade to version C5 (Japanese version) /version C4 (English version). Refer to Mitsubishi Electric's website for version upgrade information.

USB cable (3 m)

LEC-MR-J3USB

* MR-J3USB manufactured by Mitsubishi Electric.

Cable for connecting PC and driver when using the setup software (MR Configurator™).

Do not use any cable other than this cable.

Battery (only for LECSB, LECSC or LECSS)

LEC-MR-J3BAT

* MR-J3BAT manufactured by Mitsubishi Electric.

Battery for replacement.

Absolute position data is maintained by installing the battery to the driver.



Note 2) Windows, Windows Vista, Windows 7 are registered trademarks of Microsoft Corporation in the United States and/or other countries.

Note 3) This software may not run correctly depending on the PC that you are using.

Note 4) Not compatible with 64-bit Windows® XP and 64-bit Windows Vista®.

Note 5) Order USB cable separately.



Series LECS□ Specific Product Precautions 1

Be sure to read before handling. Refer to page 459 for Safety Instructions and the Operation Manual for Electric Actuator Precautions.

Please download it via our website, http://www.smcworld.com

Design/Selection

.Marning

1. Use the specified voltage.

If the applied voltage is higher than the specified voltage, malfunction and damage to the driver may result. If the applied voltage is lower than the specified voltage, there is a possibility that the load cannot be moved due to internal voltage drop. Check the operating voltage prior to start. Also, confirm that the operating voltage does not drop below the specified voltage during operation.

2. Do not use the products outside the specifications.

Otherwise, fire, malfunction or damage to the driver/actuator can result. Check the specifications prior to use.

3. Install an emergency stop circuit.

Install an emergency stop outside the enclosure in easy reach to the operator so that the operator can stop the system operation immediately and intercept the power supply.

- 4. To prevent danger and damage due to a breakdown or malfunction of these products, which may occur at a certain probability, a backup system should be arranged in advance by using a multiple-layered structure or by making a fail-safe equipment design, etc.
- 5. If there is a risk of fire or personal injury due to abnormal heat generation, sparking, smoke generated by the product, etc., cut off the power supply from this product and the system immediately.

Handling

 Never touch the inside of the driver and its peripheral devices.

Otherwise, electric shock or failure can result

- 2. Do not operate or set up this equipment with wet hands. Otherwise, electric shock can result.
- Do not use a product that is damaged or missing any components.

Electric shock, fire or injury can result.

Use only the specified combination between the electric actuator and driver.

Otherwise, it may cause damage to the driver or to the other equipment.

Be careful not to touch, get caught or hit by the workpiece while the actuator is moving.

An injury can result.

Do not connect the power supply or power up the product until it is confirmed that the workpiece can be moved safely within the area that can be reached by the workpiece.

Otherwise, the movement of the workpiece may cause an accident.

Do not touch the product when it is energized and for some time after the power has been disconnected, as it is very hot.

Otherwise, it may cause burns due to the high temperature.

 Check the voltage using a tester at least 5 minutes after power-off when performing installation, wiring and maintenance.

Otherwise, electric shock, fire or injury can result.

Handling

⚠ Warning

Static electricity may cause a malfunction or damage the driver. Do not touch the driver while power is supplied to it.

Take sufficient safety measures to eliminate static electricity when it is necessary to touch the driver for maintenance.

- Do not use the products in an area where they could be exposed to dust, metallic powder, machining chips or splashes of water, oil or chemicals.
 - Otherwise, a failure or malfunction can result.
- Do not use the products in a magnetic field.
 Otherwise, a malfunction or failure can result.
- Do not use the products in an environment where flammable, explosive or corrosive gases, liquids or other substances are present.

Otherwise, fire, explosion or corrosion can result.

13. Avoid heat radiation from strong heat sources, such as direct sunlight or a hot furnace.

Otherwise, it will cause a failure to the driver or its peripheral devices.

14. Do not use the products in an environment with cyclic temperature changes.

Otherwise, it will cause a failure to the driver or its peripheral devices.

Do not use the products in an environment where surges are generated.

Devices (solenoid type lifters, high frequency induction furnaces, motors, etc.) that generate a large amount of surge around the product may lead to deterioration or damage to the internal circuits of the products. Avoid supplies of surge generation and crossed lines

16. Do not install these products in a place subject to vibration and impact.

Otherwise, a malfunction or failure can result.

 When a surge generating load such as a relay or solenoid valve is directly driven, use a product that incorporates a surge absorption element.

Mounting

⚠ Warning

 Install the driver and its peripheral devices on fireproof material.

Direct installation on or near flammable material may cause fire.

Do not install these products in a place subject to vibration and impact.

Otherwise, a malfunction or failure can result.

The driver should be mounted on a vertical wall in a vertical direction.

Also, do not cover the driver's suction/exhaust ports.

 Install the driver and its peripheral devices on a flat surface.

If the mounting surface is not flat or uneven, excessive force may be applied to the housing and other parts resulting in a malfunction.



LESH

삨

괵

핔

PS

E

Ē

A6 L

רבכ-פ ר

LECS LECPA LECP1





Specific Product Precautions 2

Be sure to read before handling. Refer to page 459 for Safety Instructions and the Operation Manual for Electric Actuator Precautions.

Please download it via our website, http://www.smcworld.com

Power Supply

⚠ Caution

1. Use a power supply with low noise between lines and between power and ground.

In cases where noise is high, use an isolation transformer.

2. Take appropriate measures to prevent surges from lightning. Ground the surge absorber for lightning separately from the grounding of the driver and its peripheral devices.

Wiring

⚠ Warning

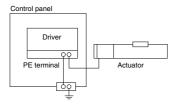
- 1. The driver will be damaged if a commercial power supply (100V/200V) is added to the driver's servo motor power (U. V. W). Be sure to check wiring such as wiring mistakes when the power supply is turned on.
- 2. Connect the ends of the U, V, W wires from the motor cable correctly to the phases (U, V, W) of the servo motor power. If these wires do not match up, it is unable to control the servo motor.

Grounding

∧ Warning

1. For grounding actuator, connect the copper wire of the actuator to the driver's protective earth (PE) terminal and connect the copper wire of the driver to the earth via the control panel's protective earth (PE) terminal.

Do not connect them directly to the control panel's protective earth (PE) terminal.



2. In the unlikely event that malfunction is caused by the ground, it may be disconnected.

Maintenance

⚠ Warning

- 1. Perform maintenance checks periodically.
 - Confirm wiring and screws are not loose.
 - Loose screws or wires may cause unexpected malfunction.
- 2. Conduct an appropriate functional inspection and test after completed maintenance.
 - In case of any abnormalities (if the actuator does not move or the equipment does not operate properly, etc.), stop the operation of the system.
 - Otherwise unexpected malfunction may occur and safety cannot be assured.
 - Conduct a test of the emergency stop to confirm the safety of the equipment
- 3. Do not disassemble, modify or repair the driver or its peripheral devices.
- 4. Do not put anything conductive or flammable inside the driver.
 - Otherwise, fire can result.
- 5. Do not conduct an insulation resistance test or insulation withstand voltage test.
- 6. Reserve sufficient space for maintenance.
 - Design the system so that it allows required space for maintenance.