

Wedge Cam Operation Slide Guide

Series *MHK2*

Air Gripper/2-Finger Type $\varnothing 12$, $\varnothing 16$, $\varnothing 20$, $\varnothing 25$



Load Resistant, Dust Cover for Adverse Environments

2 types of finger materials

Standard: Carbon steel
Option: Stainless steel

3 types of dust cover materials

Standard: Chloroprene rubber (CR) Black
Optional: Fluororubber (FKM) Black
Silicon rubber (Si) White

MHZ

MHF

MHL

MHR

MHK

MHS

MHC

MHT

MHY

MHW

-X□

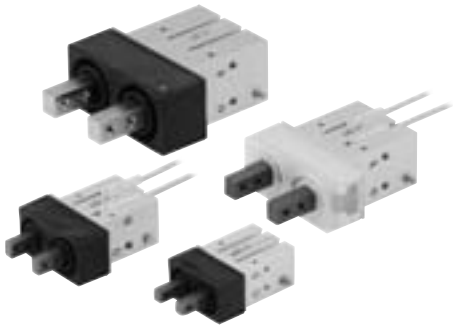
MRHQ

MA

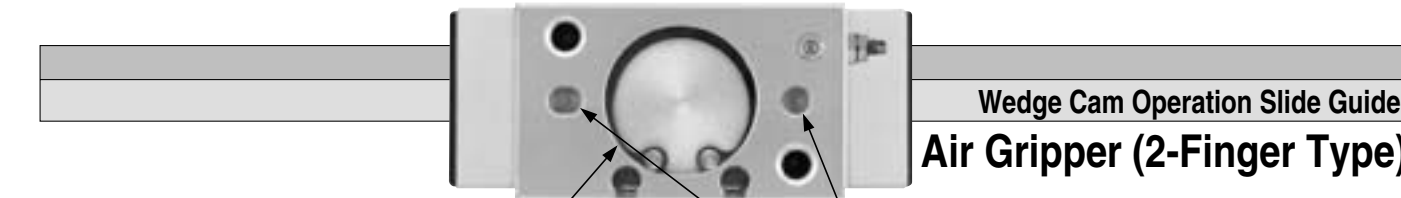
D-□

Wedge Cam Operation Provides Dust Cover for Adverse

High Precision and Rigidity. Environmental Conditions.



Series *MHK2*



Mounting repeatability

Centering accuracy ± 0.1 mm

Auto switch mountable

Grooves for auto switch are located on one side. Easy handling for adjustment and installation.

Pin hole for positioning on top side

Built-in adjustment needle for finger speed

Possible to adjust the speed for finger closing direction.

Wedge cam structure

The wedge structure allows no lateral vibration along stroke direction once work is held.

High rigidity

Slide type guide bearing enables highly rigid finger motion.

High precision repeatability: ± 0.01 mm

2 types of finger materials are available for different applications.

Standard: Carbon steel
Option: Stainless steel

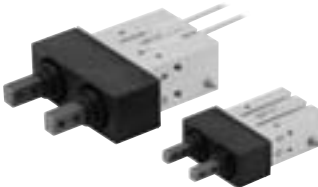
Improved performance

Incorporation of dust cover prevents dust, water, etc. from entering the body and avoids generating dust and releasing grease from air gripper.

3 types of dust covers are available for use in different environments.

Standard: Chloroprene rubber (CR) Black
Optional: Fluororubber (FKM) Black
Silicon rubber (Si) White

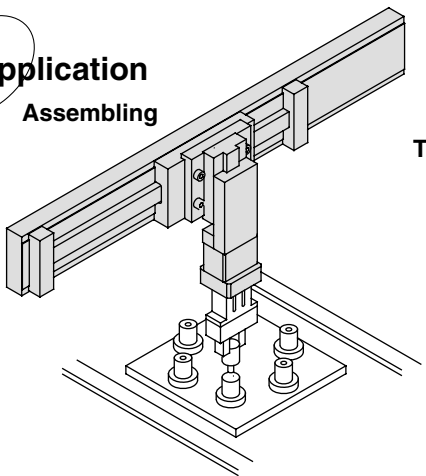
Longer strokes are now standard.



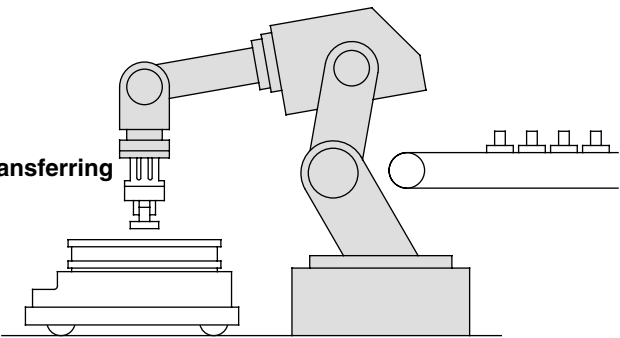
Bore size (mm)	Opening/Closing stroke (mm)	
	Long stroke	Standard stroke
12	11	4
16	14	6
20	18	10
25	22	14

Application

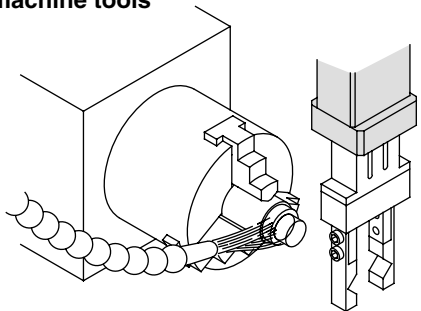
Assembling



Transferring

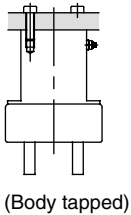


Loading/Unloading work into machine tools

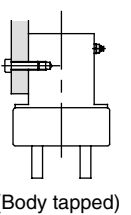


Universal mounting

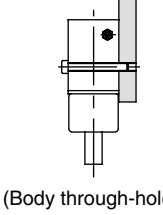
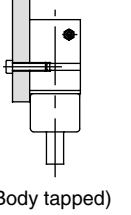
Axial mounting



Vertical mounting



Lateral mounting



Interchangeable with Series MHQG2

Series Variations

Series	Model	Bore size (mm)	Opening/Closing stroke (mm)	Option
Parallel opening/closing	Standard type Series MHK2	MHK2-12 □	12	4
		MHK2-16 □	16	6
		MHK2-20 □	20	10
		MHK2-25 □	25	14
	Long stroke type Series MHKL2	MHKL2-12 □	12	11
		MHKL2-16 □	16	14
		MHKL2-20 □	20	18
		MHKL2-25 □	25	22
				■ Finger option Carbon steel (Standard), Stainless steel
				■ Dust cover option Chloroprene rubber (Standard) Fluororubber Silicon rubber
				■ Auto switch Solid state switch D-M9N(V), D-M9P(V) D-M9B(V), Water resistant (2-color indication), D-M9□A(V)

Wedge Cam Operation Slide Guide

Air Gripper/2-Finger Type

Series *MHK2*

ø12, ø16, ø20, ø25

How to Order

Standard type	MHK 2 - 20 D 1 F - M9B		
Long stroke type	MHKL 2 - 20 D 1 F - M9B		

Number of fingers

2	2 fingers
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Bore size

12	12 mm
16	16 mm
20	20 mm
25	25 mm

Action

D	Double acting
S	Single acting (Normally open)
C	Single acting (Normally closed)

Finger material

Nil	Carbon steel
1	Stainless steel

Auto switch

Nil	Without auto switch (Built-in magnet)
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Dust cover material

Nil	Chloroprene rubber (CR)
F	Fluororubber (FKM)
S	Silicon rubber (Si)

Number of auto switches

Nil	2 pcs.
S	1 pc.

Made to Order
Refer to page 523 for details.

Applicable Auto Switch/Refer to pages 761 to 809 for further information on auto switches.

Type	Special function	Electrical entry	Indicator light	Wiring (Output)	Load voltage			Auto Switch model		Lead wire length (m)*				Pre-wired connector	Applicable load	
								Electrical entry direction		0.5 (Nil)	1 (M)	3 (L)	5 (Z)			
					DC	AC	Perpendicular	In-line								
Solid state switch	—	Grommet	Yes	3-wire (NPN)	24 V	5 V,	—	M9NV	M9N	●	●	●	○	○	IC circuit	Relay, PLC
				12 V		M9PV		M9P	●	●	●	○	○			
	2-wire			12 V		M9BV		M9B	●	●	●	○	○	—		
	3-wire (NPN)			5 V,		M9NAV		M9NA	○	○	●	○	○	IC circuit		
	3-wire (PNP)			12 V		M9PAV		M9PA	○	○	●	○	○			
	2-wire			12 V		M9BAV		M9BA	○	○	●	○	○	—		

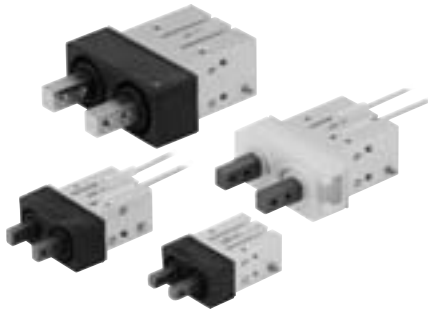
* Lead wire length symbols: 0.5 m Nil (Example) M9NW
 1 m M (Example) M9NWM
 3 m L (Example) M9NWL
 5 m Z (Example) M9NWZ

* Auto switches marked with a "○" symbol are produced upon receipt of order.

Note 1) Take note of hysteresis with 2-color indication type switches.
 Refer to "Auto Switch Hysteresis" on page 536.

Note 2) Refer to pages 761 to 809 for further information on auto switches.

Specifications



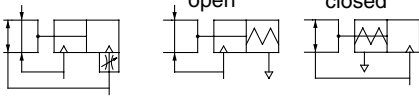
JIS Symbol

Double acting

Single acting

Normally open

Normally closed



Note) Refer to pages 761 to 809 for further information on auto switches.

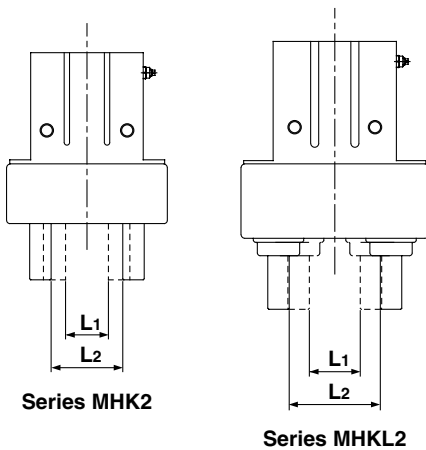
Option

Finger material	Carbon steel (Standard), Stainless steel
Dust cover material	Chloroprene rubber (CR) (Standard), Fluoro rubber (FKM), Silicon rubber (Si)

Model

Series MHK2/Standard Type

Action	Model	Bore size (mm)	Max. operating frequency (c.p.m)	Effective gripping force per finger (N) Note)	Opening/Closing stroke (mm) L2-L1	Width at closing (mm) L1	Width at opening (mm) L2	Mass (g)
Double acting	MHK2-12D	12	120	External grip: 15 Internal grip : 16	4	9	13	75
	MHK2-16D	16		External grip: 31 Internal grip : 36	6	14.6	20.6	113
	MHK2-20D	20		External grip: 46 Internal grip : 56	10	16	26	235
	MHK2-25D	25		External grip: 80 Internal grip : 86	14	19	33	440
Single acting	Normally open	MHK2-12S		9	4	9	13	76
		MHK2-16S		23	6	14.6	20.6	114
		MHK2-20S		34	10	16	26	237
		MHK2-25S		58	14	19	33	443
	Normally closed	MHK2-12C		12	4	9	13	76
		MHK2-16C		25	6	14.6	20.6	115
		MHK2-20C		44	10	16	26	237
		MHK2-25C		73	14	19	33	443



Made to Order

Refer to pages 683 to 713 for details.

Symbol	Specifications/Description
-X4	Heat resistance (100°C)
-X5	Fluororubber seal
-X7	Closing direction spring assist
-X12	Opening direction spring assist
-X39	With grease needle
-X41	Switch groove (Both-side type)
-X50	Without magnet
-X53	EPDM seal/Fluorine grease
-X63	Fluorine grease
-X64	Finger: Side tapped mounting
-X65	Finger: Through-hole mounting
-X77A	Dust cover adhesion
-X77B	Dust cover adhesion (Finger part only)
-X78A	Dust cover caulking
-X78B	Dust cover caulking (Finger part only)
-X79	Grease for food

Series MHKL2/Long Stroke Type

Action	Model	Bore size (mm)	Max. operating frequency (c.p.m)	Effective gripping force per finger (N) Note)	Opening/Closing stroke (mm) L2-L1	Width at closing (mm) L1	Width at opening (mm) L2	Mass (g)
Double acting	MHKL2-12D	12	90	External grip: 14 Internal grip : 16	11	9	20	104
	MHKL2-16D	16		External grip: 27 Internal grip : 30	14	14.6	28.6	164
	MHKL2-20D	20		External grip: 45 Internal grip : 53	18	16	34	312
	MHKL2-25D	25		External grip: 79 Internal grip : 90	22	19	41	562
Single acting	Normally open	MHKL2-12S		9	11	9	20	105
		MHKL2-16S		17	14	14.6	28.6	165
		MHKL2-20S		32	18	16	34	314
		MHKL2-25S		53	22	19	41	565
	Normally closed	MHKL2-12C		11	11	9	20	105
		MHKL2-16C		22	14	14.6	28.6	166
		MHKL2-20C		40	18	16	34	314
		MHKL2-25C		63	22	19	41	565



Note) At the pressure of 0.5 MPa, when gripping point L is 20 mm.

Single acting normally open: External holding force, Single acting normally closed:

Internal gripping force.

Refer to "Effective Gripping Force" for the gripping force at each gripping position on pages 525 to 529.

MHZ

MHF

MHL

MHR

MHK

MHS

MHC

MHT

MHY

MHW

-X□

MRHQ

MA

D-□

Model Selection Example

Procedure



Workpiece form:
Diameter x Length
ø28 x 35 mm round bar

Workpiece diameter: From dimensions of model that has opening width 28 mm or more.
MHK2-25D
MHKL2-16D
MHKL2-20D
MHKL2-25D

Work mass: 0.17 kg

Gripping method:
External gripping

Guidelines for the selection of the gripper with respect to component weight

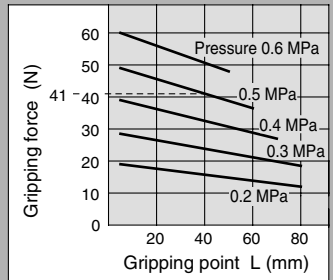
- Although conditions differ according to the workpiece shape and the coefficient of friction between the attachments and the workpiece, select a model that can provide a gripping force of 10 to 20 times the workpiece mass, or more.
- If high acceleration, deceleration or impact forces are encountered during motion, a further margin of safety should be considered.

Ex.) For setting the gripping force to be at least 20 times the workpiece mass:
Required gripping force = $0.17 \text{ kg} \times 20 \times 9.8 \text{ m/s}^2 \approx 33 \text{ N}$

Gripping point 40 mm

Operating pressure: 0.5 MPa

MHKL2-20D External Gripping Force

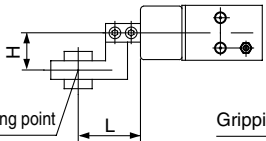
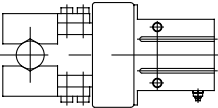


- When MHKL2-20D is selected, the gripping force is determined to be 41N according to the gripping point distance 40 mm and the pressure (0.5 MPa).
- The gripping force is 24.5 times the workpiece mass meeting the guideline that gripping force should be more than 20.

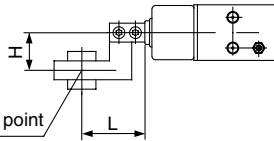
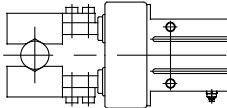
Gripping Point

External grip

Series MHK2

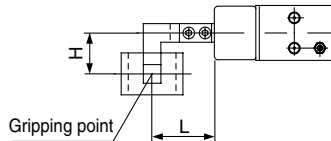
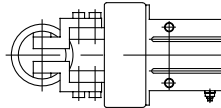


Series MHKL2

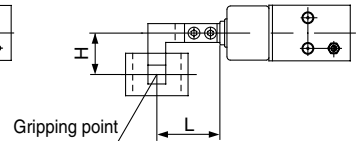
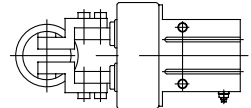


Internal grip

Series MHK2



Series MHKL2

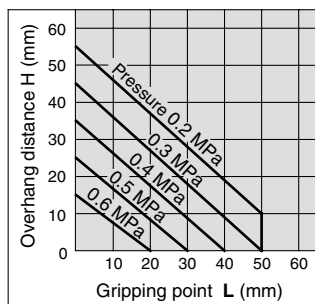


L: Gripping point distance
H: Overhang distance

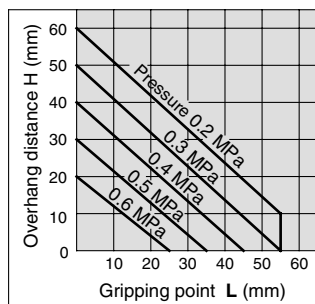
- Proper gripping points should be selected in accordance with the operating pressure. The distance to the gripping point L and the overhang distance H should be within the limited range given in the graphs below.
- When the gripping point distance becomes large, the finger attachment applies an excessively large load to the finger sliding section, causing excessive play of the fingers and possibly leading to premature failure.

Gripping Point Range Limit

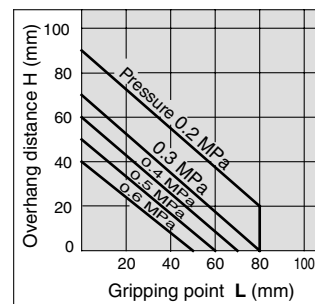
MHK2-12□
MHKL2-12□



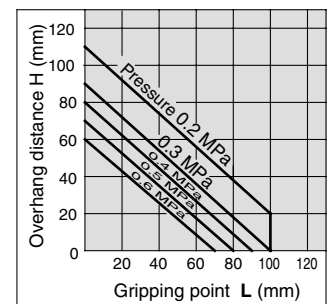
MHK2-16□
MHKL2-16□



MHK2-20□
MHKL2-20□



MHK2-25□
MHKL2-25□



Note) Distance to the gripping point L of single acting type is shortened by spring return.

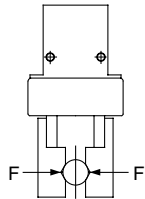
Use air gripper within gripping force line shown for each pressure in effective gripping force graph.

Series MHK2

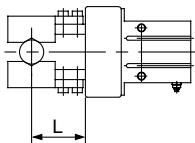
Effective Gripping Force: Series MHK2 Double Acting

- Indication of effective gripping force

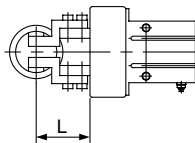
The effective gripping force shown in the graphs to the right is expressed as F , which is the thrust of one finger, when both fingers and attachments are in full contact with the work-piece as shown in the figure below.



**External grip
Series MHK2**

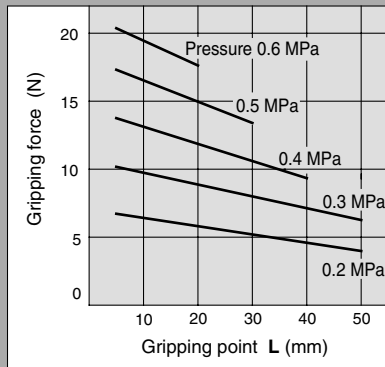


**Internal grip
Series MHK2**

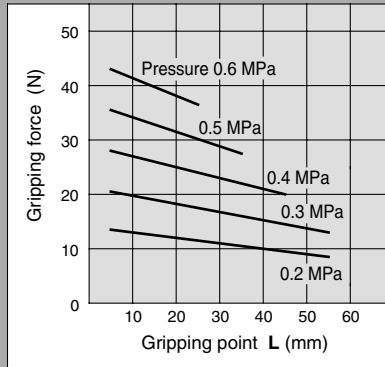


External Grip

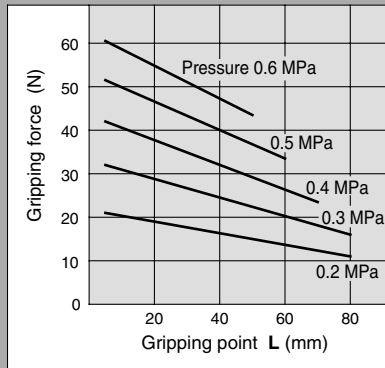
MHK2-12D



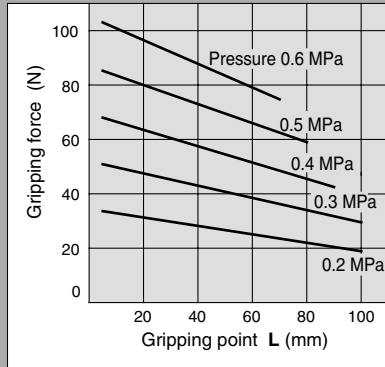
MHK2-16D



MHK2-20D

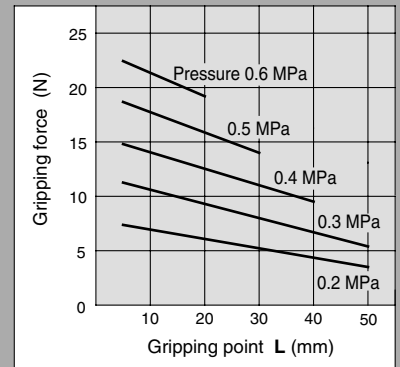


MHK2-25D

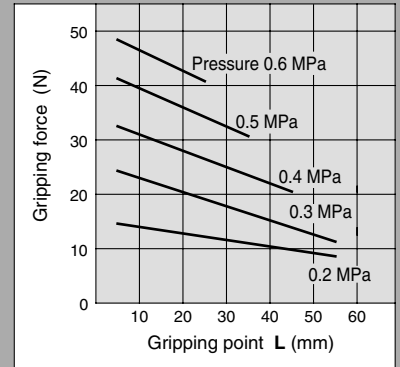


Internal Grip

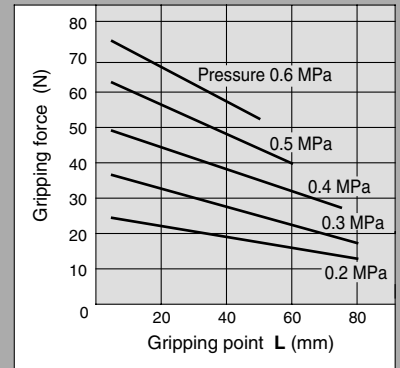
MHK2-12D



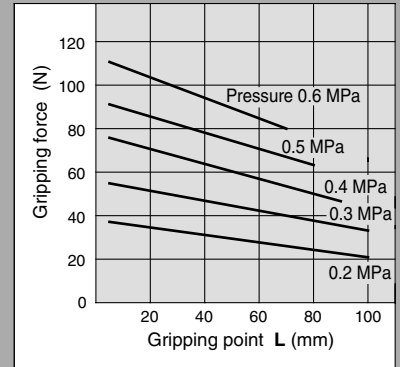
MHK2-16D



MHK2-20D



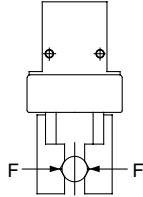
MHK2-25D



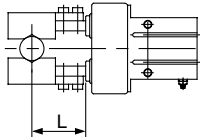
Effective Gripping Force: Series MHKL2 Double Acting

• Indication of effective gripping force

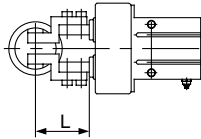
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External grip
Series MHKL2

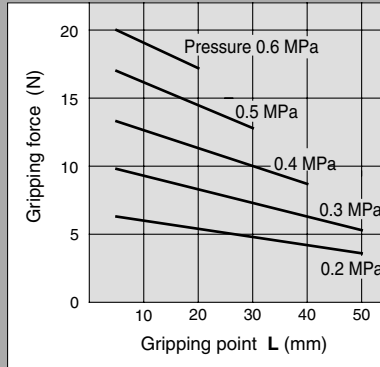


Internal grip
Series MHKL2

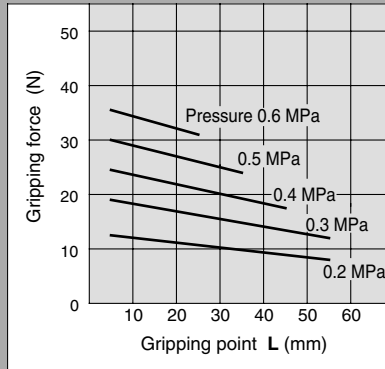


External Grip

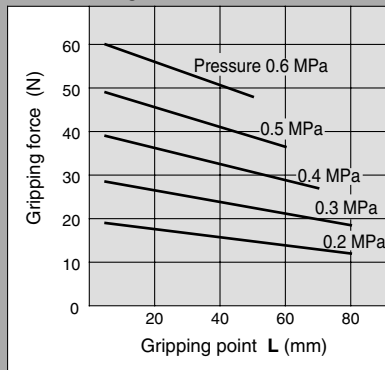
MHKL2-12D



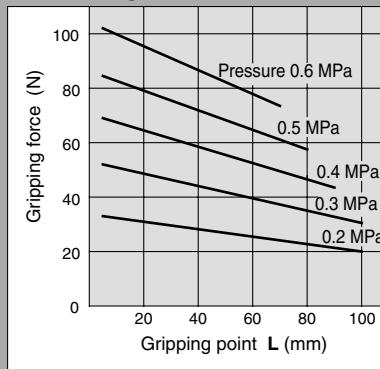
MHKL2-16D



MHKL2-20D

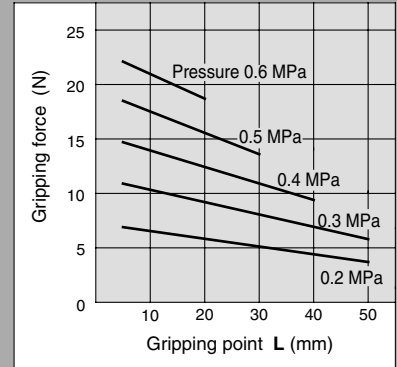


MHKL2-25D

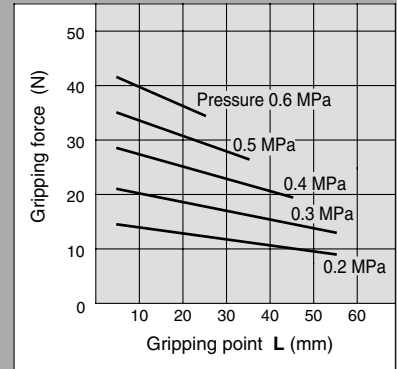


Internal Grip

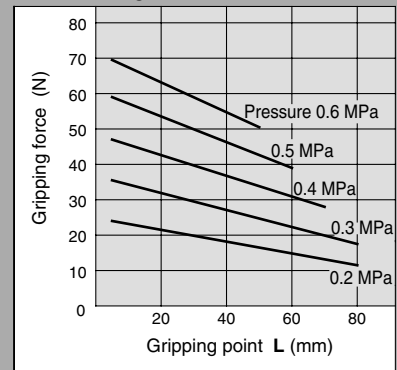
MHKL2-12D



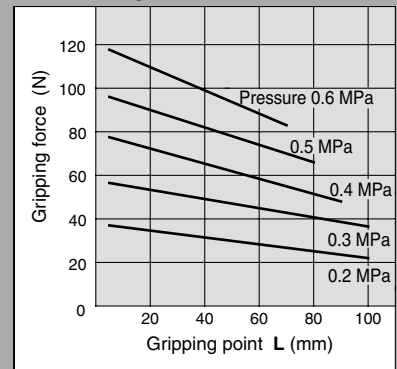
MHKL2-16D



MHKL2-20D



MHKL2-25D



MHZ

MHF

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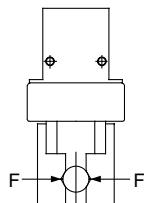
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Series MHK2

Effective Gripping Force: Series MHK2 Single Acting

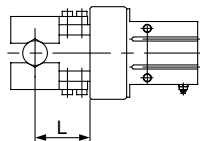
• Indication of effective gripping force

The effective gripping force shown in the graphs to the right is expressed as **F**, which is the thrust of one finger, when both fingers and attachments are in full contact with the work-piece as shown in the figure below.

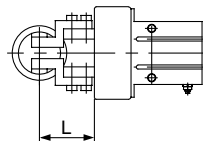


Note) In case of single acting type, the value is for stroke center.

External grip Series MHK2



Internal grip Series MHK2



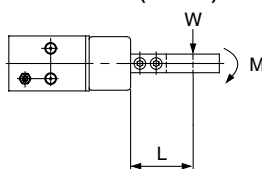
• Precautions when using the single acting type:

If a moment such as that illustrated below is applied to the finger, the finger might not be able to retract by the spring force alone. Therefore, make sure to use the air gripper within the allowable moment that is indicated in the table below.

Allowable Moment

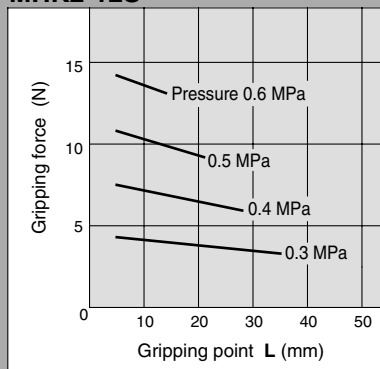
Model	Allowable moment (N·m)
MHK2-12S/C	0.05
MHK2-16S/C	0.12
MHK2-20S/C	0.25
MHK2-25S/C	0.49

M: Allowable moment
($M = WL$)



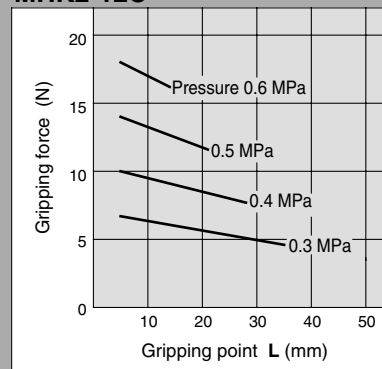
External Grip

MHK2-12S

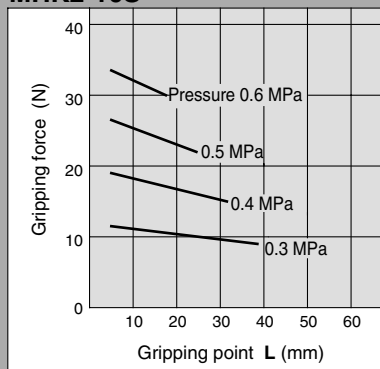


Internal Grip

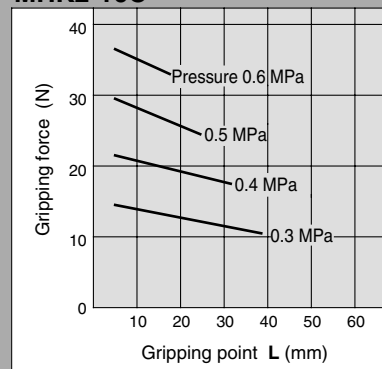
MHK2-12C



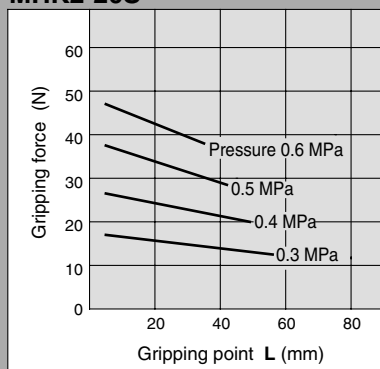
MHK2-16S



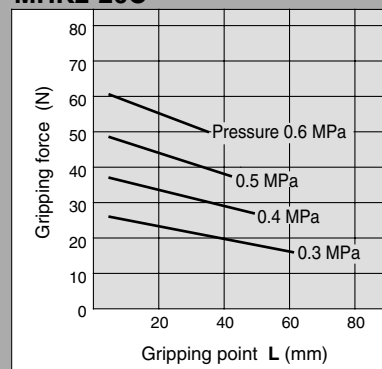
MHK2-16C



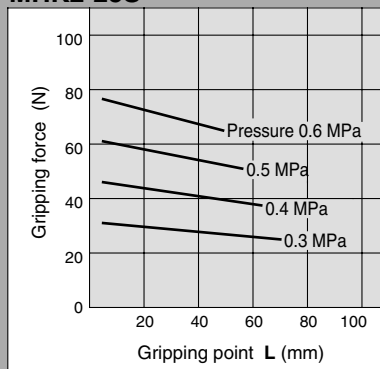
MHK2-20S



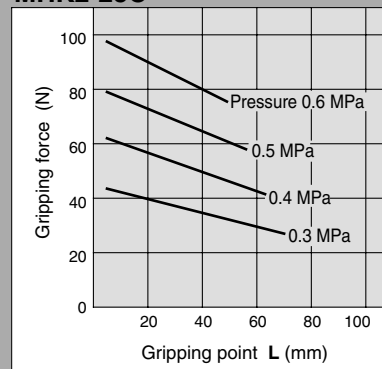
MHK2-20C



MHK2-25S



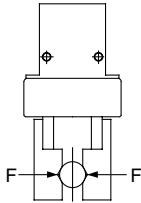
MHK2-25C



Effective Gripping Force: Series MHKL2 Single Acting

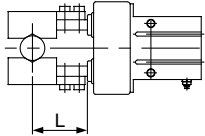
• Indication of effective gripping force

The effective gripping force shown in the graphs to the right is expressed as F , which is the thrust of one finger, when both fingers and attachments are in full contact with the work-piece as shown in the figure below.

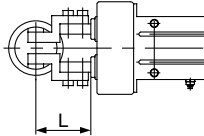


Note) In case of single acting type, the value is for stroke center.

External grip Series MHKL2



Internal grip Series MHKL2

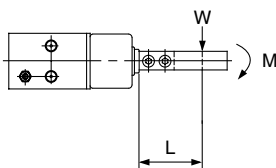


- Precautions when using the single acting type:
If a moment such as that illustrated below is applied to the finger, the finger might not be able to retract by the spring force alone. Therefore, make sure to use the air gripper within the allowable moment that is indicated in the table below.

Allowable Moment

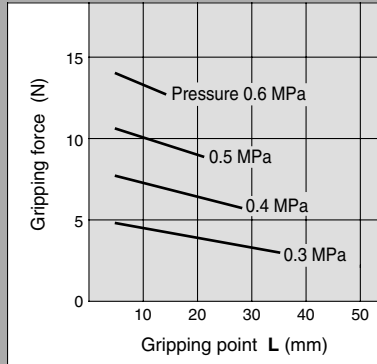
Model	Allowable moment (N·m)
MHKL2-12S/C	0.05
MHKL2-16S/C	0.12
MHKL2-20S/C	0.25
MHKL2-25S/C	0.49

M: Allowable moment
($M = WL$)

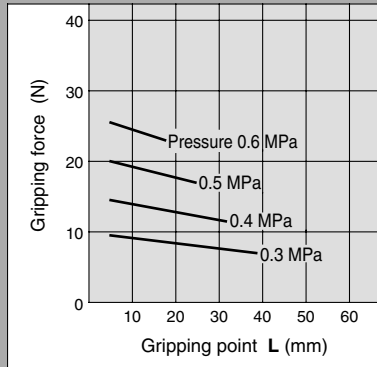


External Grip

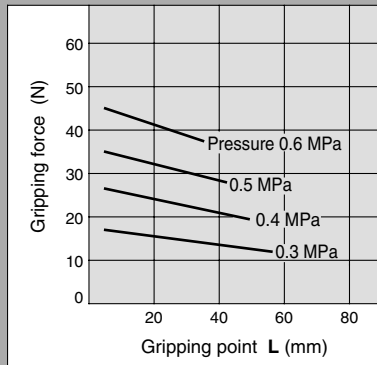
MHKL2-12S



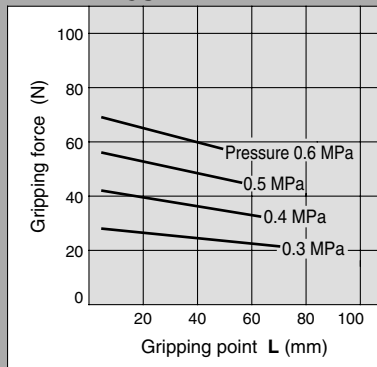
MHKL2-16S



MHKL2-20S

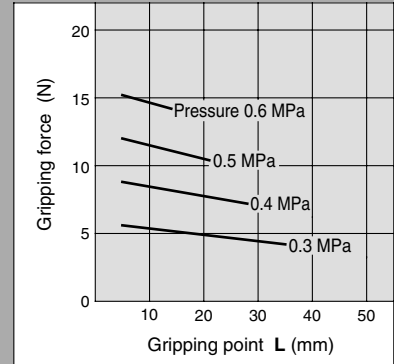


MHKL2-25S

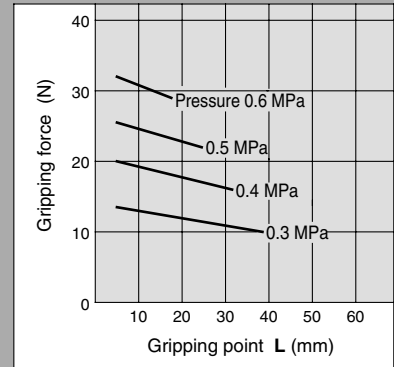


Internal Grip

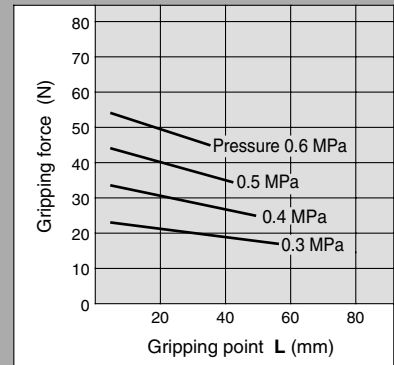
MHKL2-12C



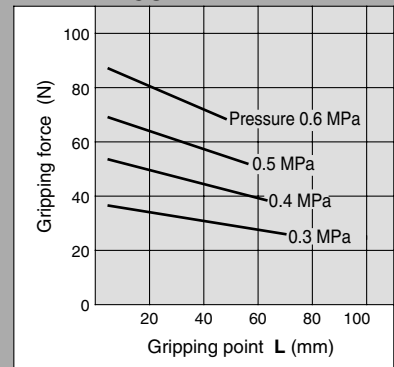
MHKL2-16C



MHKL2-20C



MHKL2-25C



MHZ

MHF

MHL

MHR

MHK

MHS

MHC

MHT

MHY

MHW

-X□

MRHQ

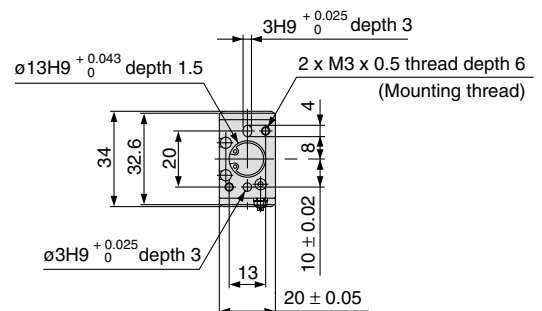
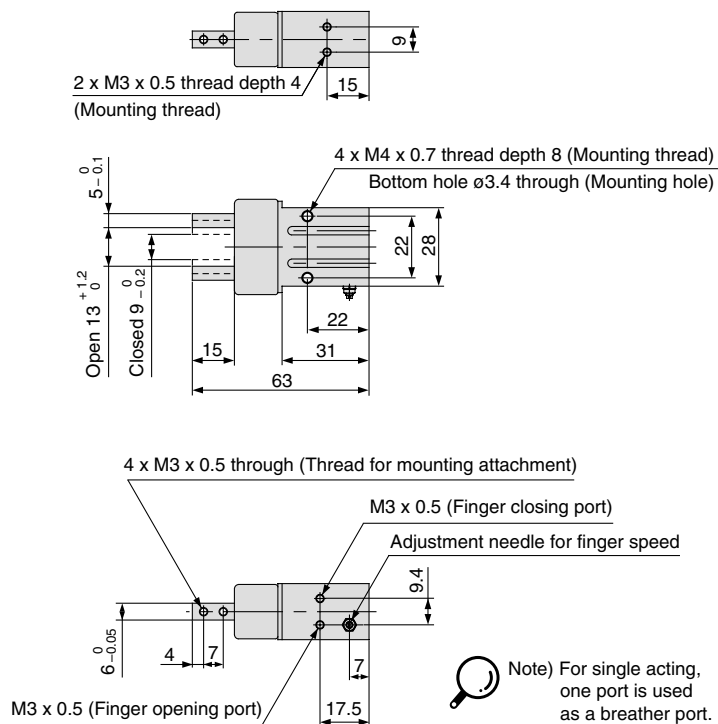
MA

D-□

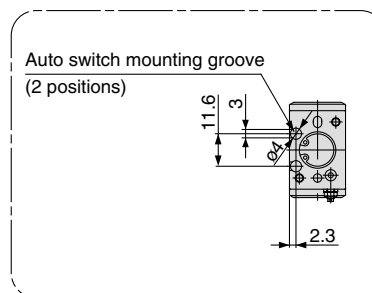
Series MHK2

Dimensions

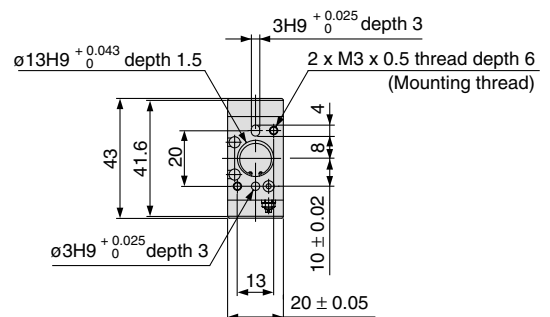
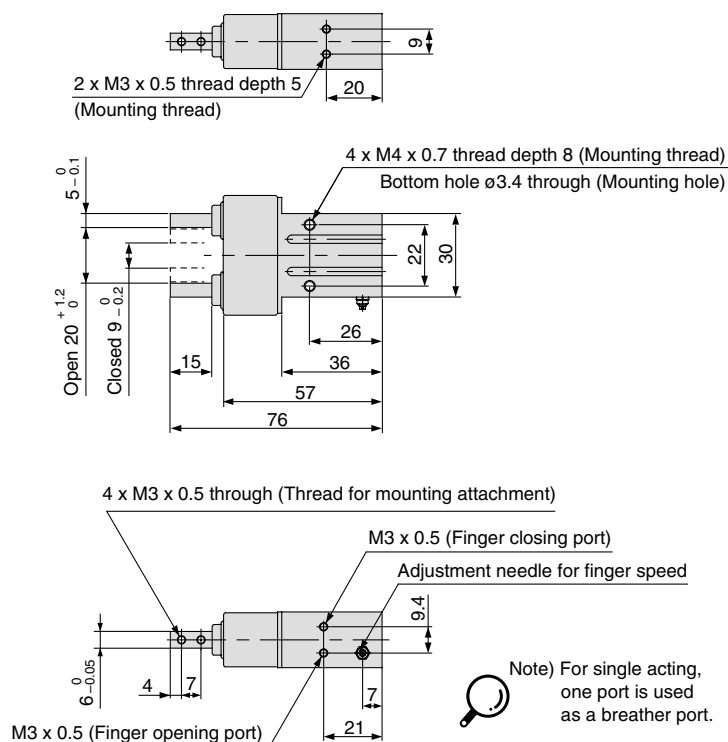
MHK2-12□: Standard type



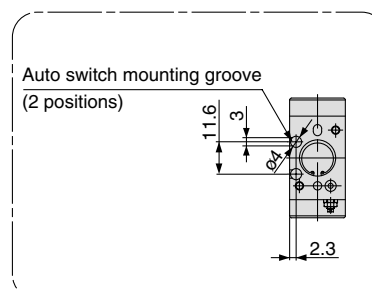
Auto Switch Mounting Groove Dimensions



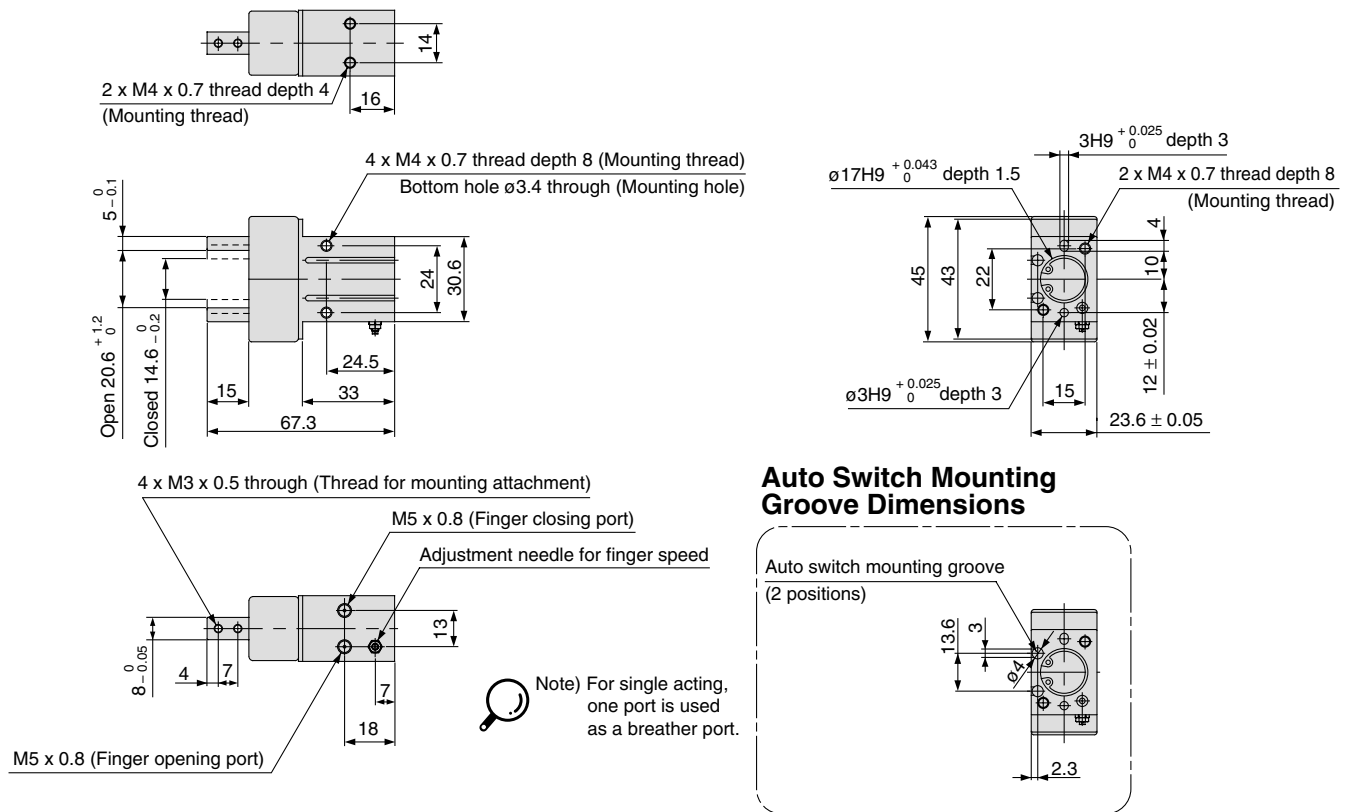
MHKL2-12□: Long stroke type



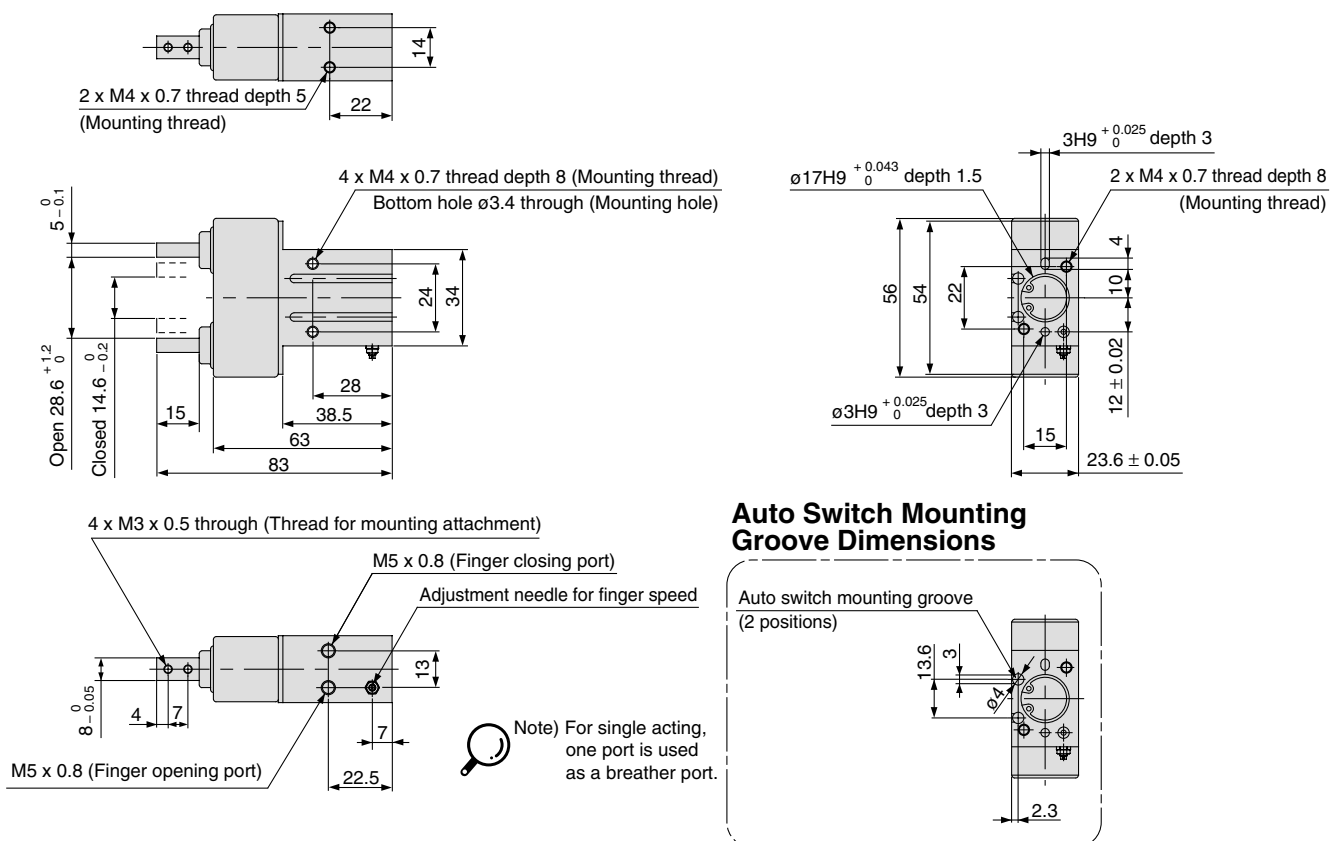
Auto Switch Mounting Groove Dimensions



MHK2-16□: Standard type



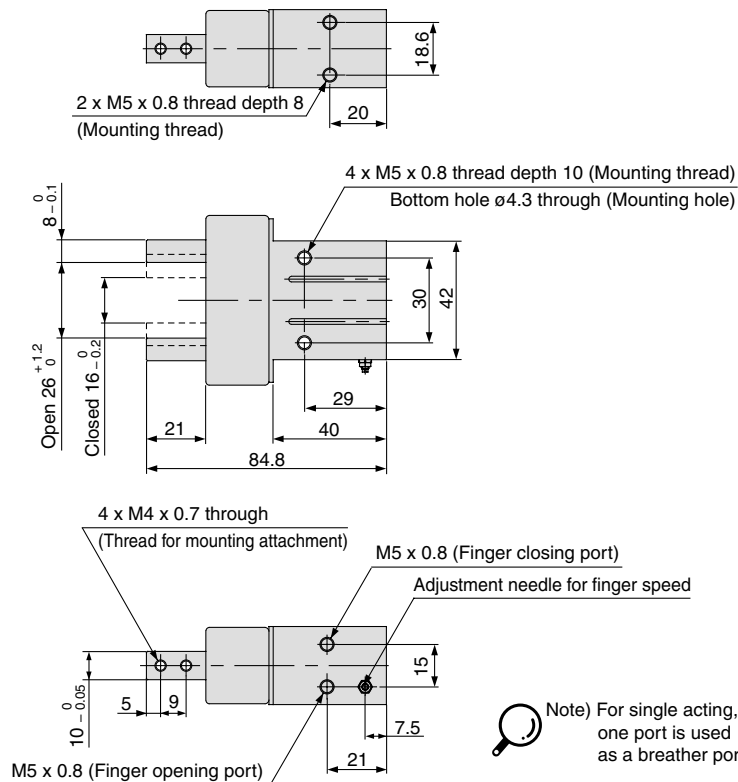
MHKL2-16□: Long stroke type



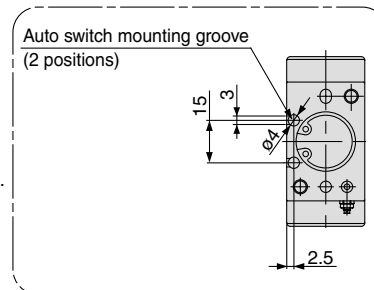
Series MHK2

Dimensions

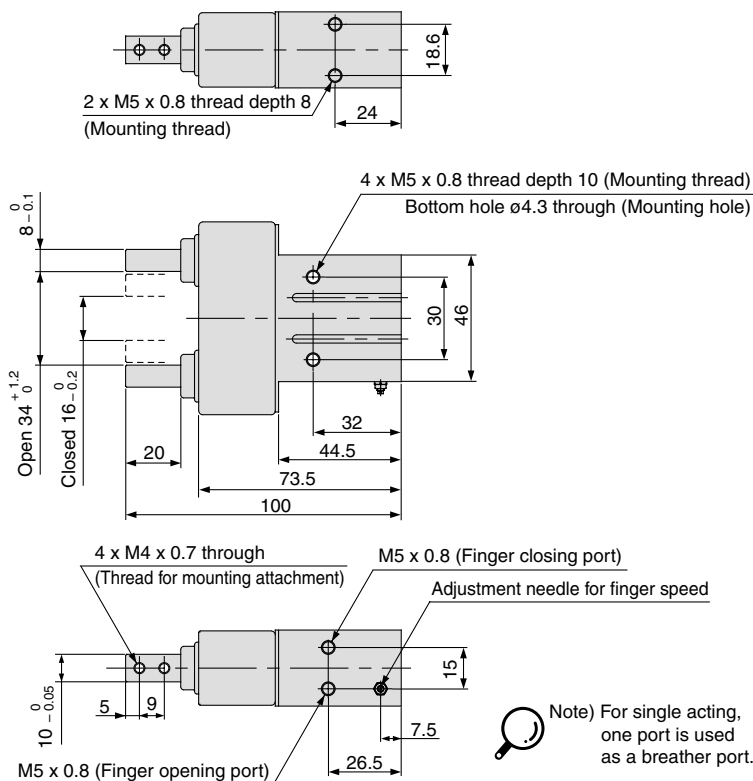
MHK2-20□: Standard type



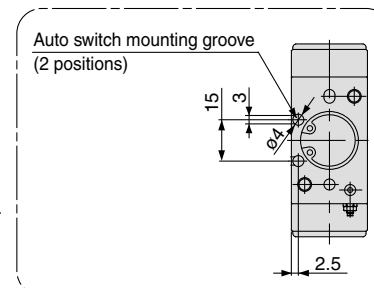
Auto Switch Mounting Groove Dimensions



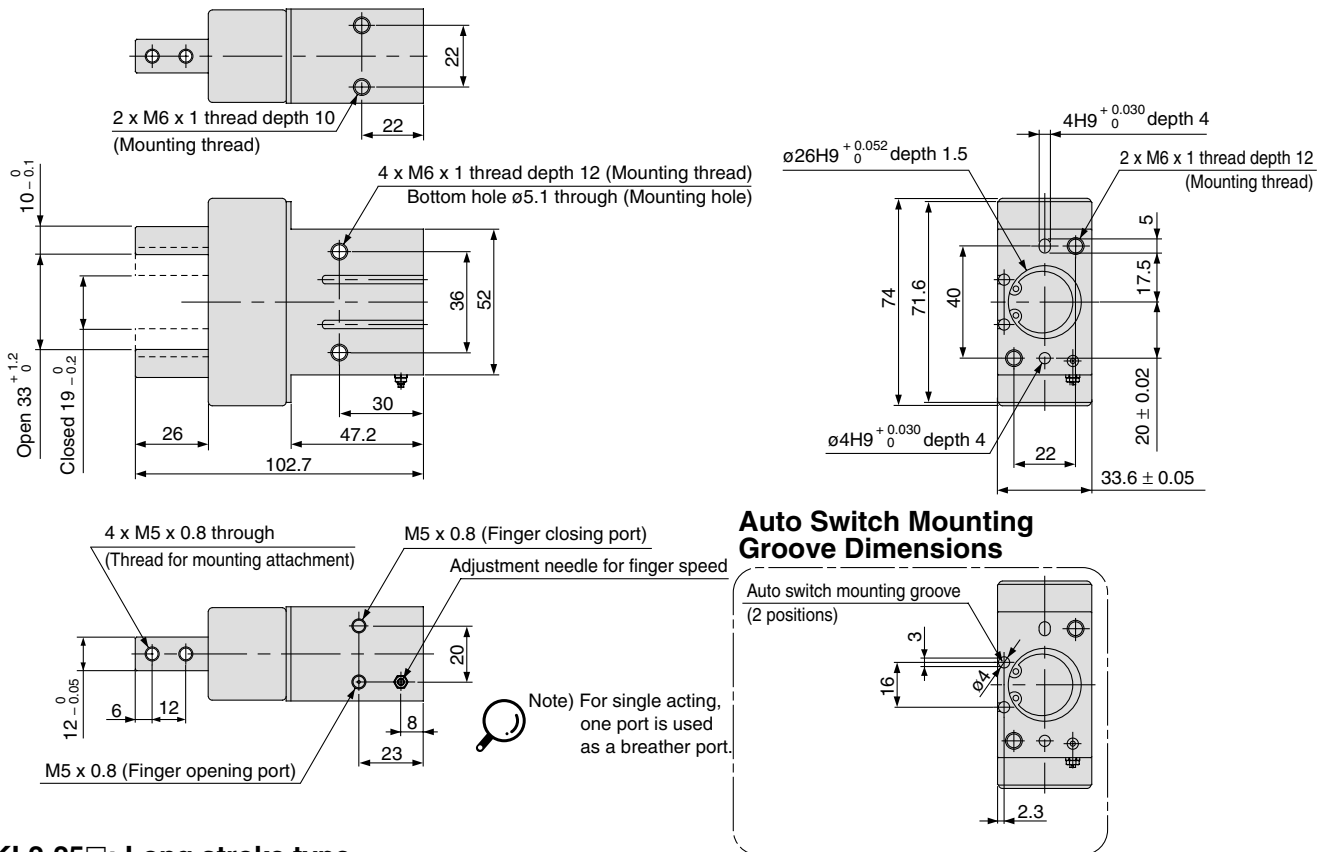
MHKL2-20□: Long stroke type



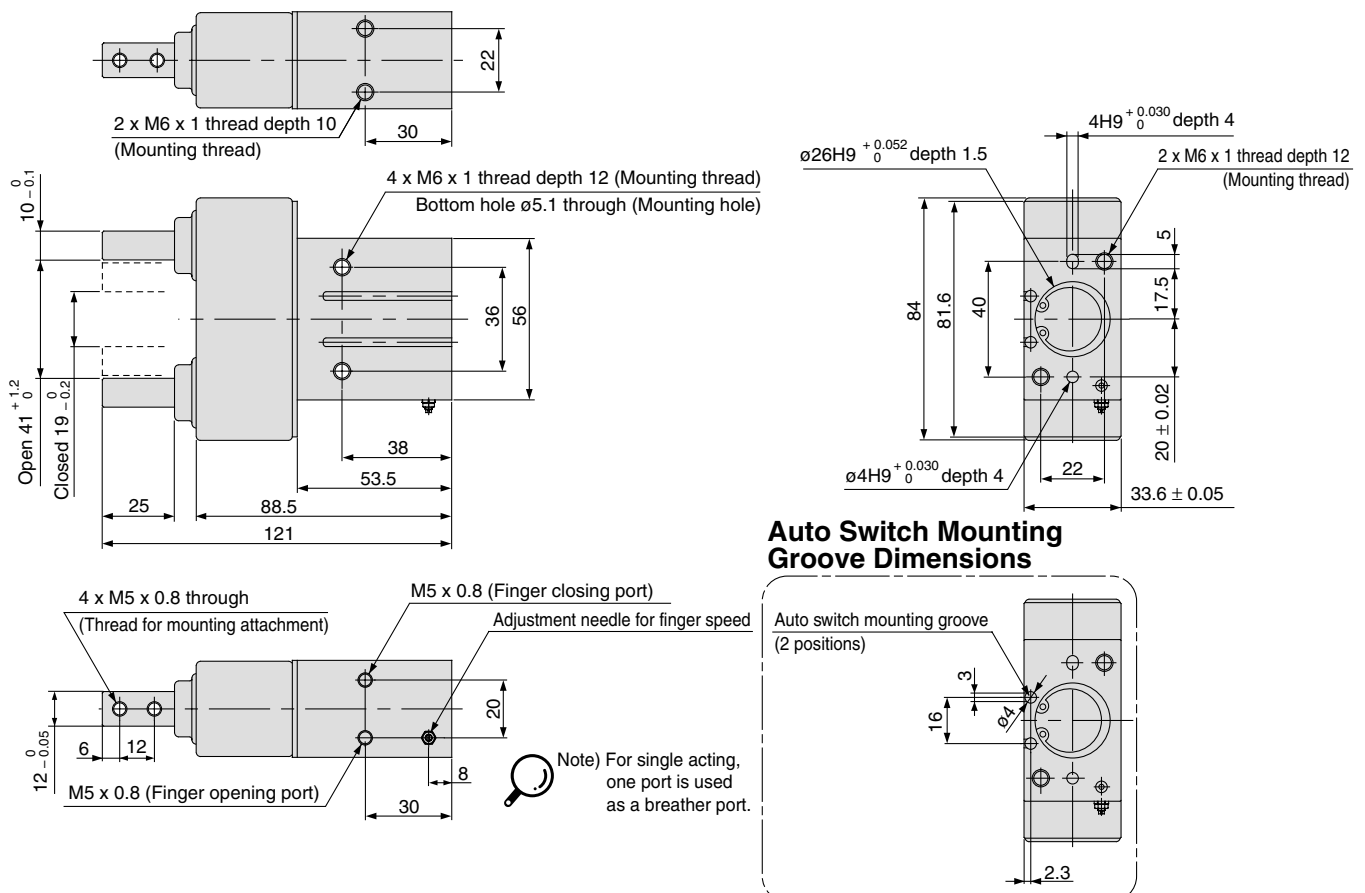
Auto Switch Mounting Groove Dimensions



MHK2-25□: Standard type



MHKL2-25□: Long stroke type

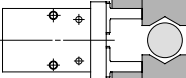
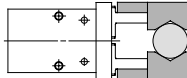
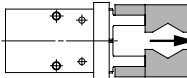
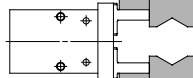
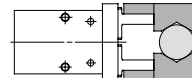
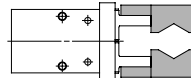
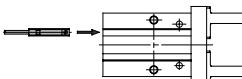
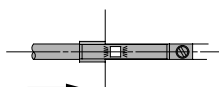
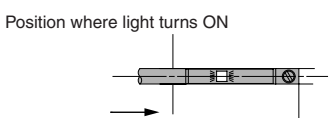
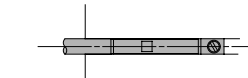
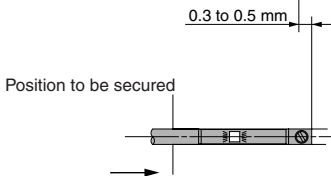
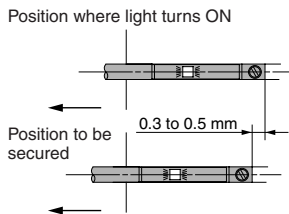


Series **MHK2/MHKL2**

Auto Switch Installation Examples and Mounting Positions

Various auto switch applications are possible through different combinations of auto switch quantities and detecting positions.

1) Detection when Gripping Exterior of Workpiece

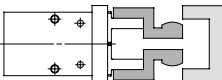
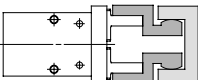
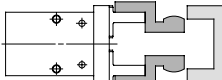
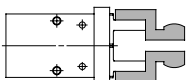
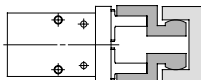
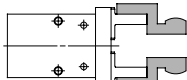
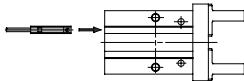
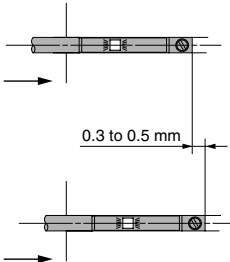
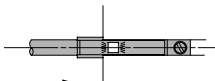
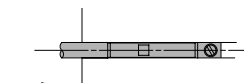
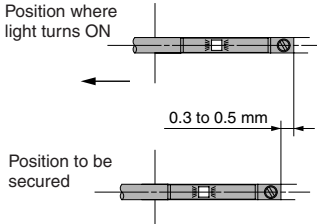
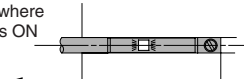
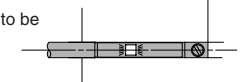
Detection example			1. Confirmation of fingers in reset position	2. Confirmation of workpiece held	3. Confirmation of workpiece released	
Position to be detected			Position of fingers fully opened 	Position when gripping a workpiece 	Position of fingers fully closed 	
Operation of auto switch			Auto switch turned ON when fingers return. (Light ON)	Auto switch turned ON when gripping a workpiece. (Light ON)	When a workpiece is not held (Abnormal operation): Auto switch to turn ON (Light illuminating)	
Detection combinations	One auto switch * One position, any of ①, ②, and ③, can be detected.		●	●	●	
	Two auto switches * Two positions of ①, ②, and ③ can be detected.	Pattern	A	●	—	
			B	—	●	
			C	●	●	
How to determine auto switch installation position			Step 1) Fully open the fingers. 	Step 1) Position fingers for gripping a workpiece. 	Step 1) Fully close the fingers. 	
At no pressure or low pressure, connect the auto switch to a power supply, and follow the directions.			Step 2) Insert the auto switch into the auto switch installation groove in the direction shown in the following drawing. 			
			Step 3) Slide the auto switch in the direction of the arrow until the indicator light illuminates. 		Step 3) Slide the auto switch in the direction of the arrow until the light illuminates and fasten it at a position 0.3 to 0.5 mm in the direction of the arrow beyond the position where the indicator light illuminates. 	
			Step 4) Slide the auto switch further in the direction of the arrow until the indicator light goes out. 		Position where light turns ON  Position to be secured	
			Step 5) Move the auto switch in the opposite direction and fasten it at a position 0.3 to 0.5 mm beyond the position where the indicator light illuminates. 			

Note 1) It is recommended that gripping of a workpiece be performed close to the center of the finger stroke.

Note 2) When holding a workpiece close at the end of open/close stroke of fingers, detecting performance of the combinations listed in the above table may be limited, depending on the hysteresis of an auto switch, etc.

Various auto switch applications are possible through different combinations of auto switch quantities and detecting positions.

2) Detection when Gripping Interior of Workpiece

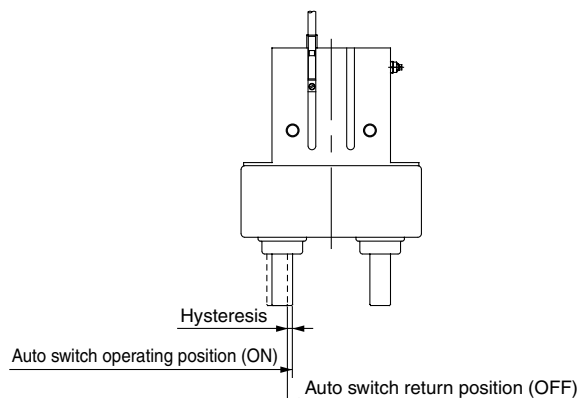
Detection example			1. Confirmation of fingers in reset position	2. Confirmation of workpiece held	3. Confirmation of workpiece released	
Position to be detected			Position of fingers fully closed 	Position when gripping a workpiece 	Position of fingers fully opened 	
Operation of auto switch			Auto switch turned ON when fingers return. (Light ON)	Auto switch turned ON when gripping a workpiece. (Light ON)	When a workpiece is not held (Abnormal operation): Auto switch to turn ON (Light illuminating)	
Detection combinations	One auto switch * One position, any of ①, ②, and ③, can be detected.		●	●	●	
	Two auto switches * Two positions of ①, ②, and ③ can be detected.	Pattern	A	●	—	
			B	—	●	
			C	●	●	
How to determine auto switch installation position			Step 1) Fully close the fingers. 	Step 1) Position fingers for gripping a workpiece. 	Step 1) Fully open the fingers. 	
At no pressure or low pressure, connect the auto switch to a power supply, and follow the directions.			Step 2) Insert the auto switch into the auto switch installation groove in the direction shown in the following drawing. 			
			Step 3) Move the auto switch in the direction of the arrow and fasten it at a position 0.3 to 0.5 mm beyond the position where the indicator light illuminates. 		Step 3) Slide the auto switch in the direction of the arrow until the indicator light illuminates. 	
					Step 4) Slide the auto switch further in the direction of the arrow until the indicator light goes out. 	
					Step 5) Move the auto switch in the opposite direction 0.3 to 0.5 mm in the direction indicated by the arrow from its location when the indicator light comes on again. 	
					Position where light turns ON  0.3 to 0.5 mm Position to be secured 	

Note 1) It is recommended that gripping of a workpiece be performed close to the center of the finger stroke.
Note 2) When holding a workpiece close at the end of open/close stroke of fingers, detecting performance of the combinations listed in the above table may be limited, depending on the hysteresis of an auto switch, etc.

Series MHK2

Auto Switch Hysteresis

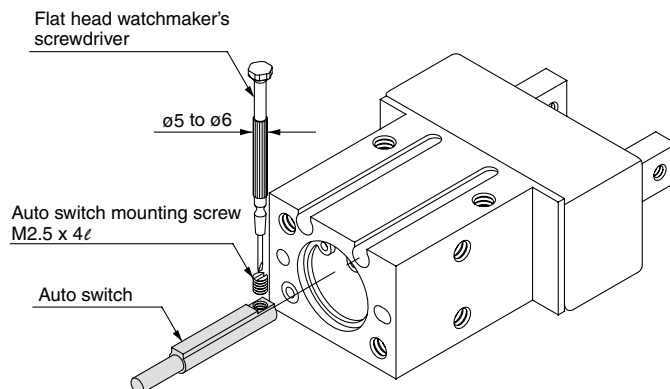
Auto switches have hysteresis similar to micro switches. Use the table below as a guide when adjusting auto switch positions, etc.



Auto switch Model	Max. hysteresis (mm)		
	D-M9□(V)	D-M9□A(V)L, M9□W(V)	
		Setting of ON position when red light is on.	Setting of ON position when green light is on.
MHK□2-12	0.1	0.1	0.3
MHK□2-16	0.1	0.1	0.3
MHK□2-20	0.3	0.3	0.8
MHK□2-25	0.2	0.2	0.6

Auto Switch Mounting

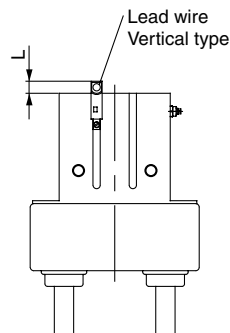
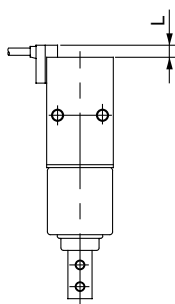
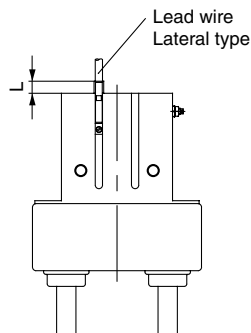
To set the auto switch, insert the auto switch into the installation groove of the gripper from the direction indicated in the following drawing. After setting the position, tighten the attached auto switch mounting set screw with a flat head watchmaker's screwdriver.



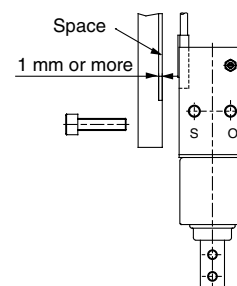
Note) Use a watchmaker's screwdriver with a grip diameter of 5 to 6 mm to tighten the auto switch mounting screw. The tightening torque should be about 0.05 to 0.15 N·m.

Protrusion of Auto Switch from Edge of Body

- The amount of auto switch protrusion from the body's end surface is as shown in the table below.
- Use the table as a guideline for mounting.



When auto switch for MHK2, MHKL2 is set on mounting side as figure below, allow for at least 1 mm on mounting plate since the auto switch is protruded from edge of gripper.



(mm)

Air gripper model	Auto switch model Finger position	In-line electrical entry type		Perpendicular electrical entry type	
		Lead wire type		Lead wire type	
		D-M9□ D-M9□W	D-M9□AL	D-M9□V D-M9□WV	D-M9□AVL
MHK2-12□	Open	—	—	—	—
	Closed	3	5	—	3
MHK2-16□	Open	—	—	—	—
	Closed	3	5	1	3
MHK2-20□	Open	—	—	—	—
	Closed	1	3	—	1
MHK2-25□	Open	—	—	—	—
	Closed	2	4	—	2
MHKL2-12□	Open	—	—	—	—
	Closed	3	5	—	3
MHKL2-16□	Open	—	—	—	—
	Closed	3	5	1	3
MHKL2-20□	Open	—	—	—	—
	Closed	1	3	—	1
MHKL2-25□	Open	—	—	—	—
	Closed	1	3	—	1

Note) There is no protrusion if no values are entered in the table.



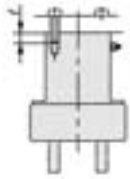
Series **MHK2** Specific Product Precautions

Be sure to read before handling.

Mounting Air Grippers/Series MHK2

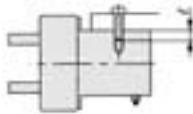
Possible to mount from 3 directions.

Axial Mounting (Body tapped)



Model	Applicable bolts	Max. tightening torque N·m	Max. screw-in depth ℓ mm
MHK2 -12□ MHKL2-12□	M3 x 0.5	0.88	6
MHK2 -16□ MHKL2-16□	M4 x 0.7	2.1	8
MHK2 -20□ MHKL2-20□	M5 x 0.8	4.3	10
MHK2 -25□ MHKL2-25□	M6 x 1	7.3	12

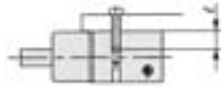
Vertical Mounting (Body tapped)



Model	Applicable bolts	Max. tightening torque N·m	Max. screw-in depth ℓ mm
MHK2 -12□ MHKL2-12□	M3 x 0.5	0.59	4
MHK2 -16□ MHKL2-16□	M4 x 0.7	0.88	4
MHK2 -20□ MHKL2-20□	M5 x 0.8	3.3	8
MHK2 -25□ MHKL2-25□	M6 x 1	5.9	10

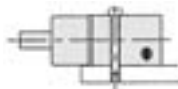
Lateral mounting (Body tapped and through-hole)

Body tapped



Model	Applicable bolts	Max. tightening torque N·m	Max. screw-in depth ℓ mm
MHK2 -12□ MHKL2-12□	M4 x 0.7	2.1	8
MHK2 -16□ MHKL2-16□	M5 x 0.8	4.3	10
MHK2 -25□ MHKL2-25□	M6 x 1	7.3	12

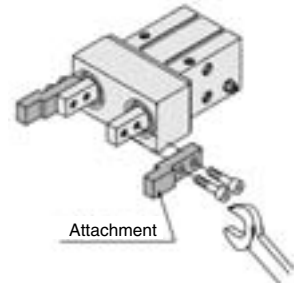
●Body through-hole



Model	Applicable bolts	Max. tightening torque N·m
MHK2 -12□ MHKL2-12□	M3 x 0.5	0.88
MHK2 -16□ MHKL2-16□	M4 x 0.7	2.1
MHK2 -25□ MHKL2-25□	M5 x 0.8	4.3

How to Mount the Attachment to the Finger

- To mount the attachment to the finger, make sure to use a wrench to support the attachment so as not to apply undue strain on the finger.
- Refer to the table below for the proper tightening torque on the bolt used for securing the attachment to the finger.



Model	Applicable bolts	Max. tightening torque N·m
MHK2 -12□ MHKL2-12□	M3 x 0.5	0.59
MHK2 -16□ MHKL2-16□	M4 x 0.7	1.4
MHK2 -25□ MHKL2-25□	M5 x 0.8	2.8

MHZ

MHF

MHL

MHR

MHK

MHS

MHC

MHT

MHY

MHW

-X□

MRHQ

MA

D-□