Electric Rotary Table

Step Motor (Servo/24 VDC)

New

CE c UL US

RoHS

Low profile

Space-saving

Basic type [mm]

Model	H
LER10	42
LER30	53
LER50	68

High precision type [mm]

Model	H
LERH10	49
LERH30	62
LERH50	78
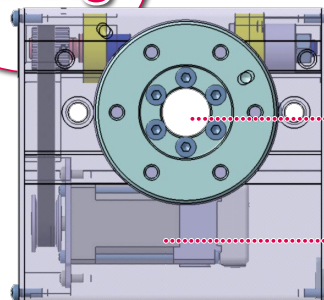
Hollow shaft axis
Accommodates wiring and piping of workpieces.

Motor built-in
Space-saving

● Shock-less/High speed actuation

Max. speed: 420°/sec (7.33 rad/sec)

Max. acceleration/deceleration: 3,000°/sec² (52.36 rad/sec²)

● Positioning repeatability: ±0.05°

Repeatability at the end: ±0.01° (Pushing control/With external stopper)

● Rotation angle

320° (310°), 180°, 90°

The value indicated in brackets shows the value for the LER10.

● Possible to set speed, acceleration/deceleration, and position. Max. 64 points

● Energy-saving product

Automatic 40% power reduction after the table has stopped.

Size	Rotating torque [N·m]		Max. speed [°/s]		Positioning repeatability [°]	
	Basic	High torque	Basic	High torque	Basic	High torque
10	0.2	0.3	420	280	±0.05 (End: ±0.01)*	
30	0.8	1.2				
50	6.6	10				

∗ Value when an external stopper is mounted.

Step Motor (Servo/24 VDC)

Controller/Driver

▶**Step data input type**
Series **LECP6**
• 64 points positioning
• Input using controller setting kit or teaching box

▶**Programless type**
Series **LECP1**
• 14 points positioning
• Control panel setting

▶**Pulse input type**
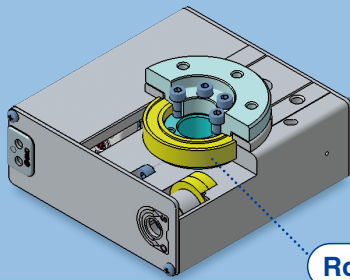Series **LECPA**

Series LER

SMC

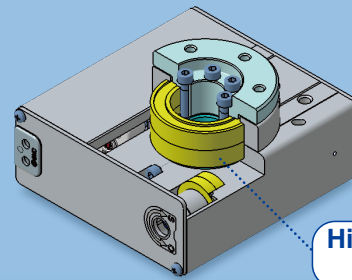CAT.ES100-94C

Electric Rotary Table

Basic and high precision types are available.

Basic type/LER

Rolling bearing

High precision type/LERH

High precision bearing

The movement in the table's radial thrust direction is reduced.

Rotation angle

320° (310°), 180°, 90°
The value indicated in brackets shows the value for the LER10.

Built-in step motor (Servo/24 VDC)

Space-saving

High torque

Output is **30** times with special worm gear. Special worm gear with reduced backlash is used.

Maximum rotation torque can be selected.

Belt deceleration ratio can be selected.

(N·m)

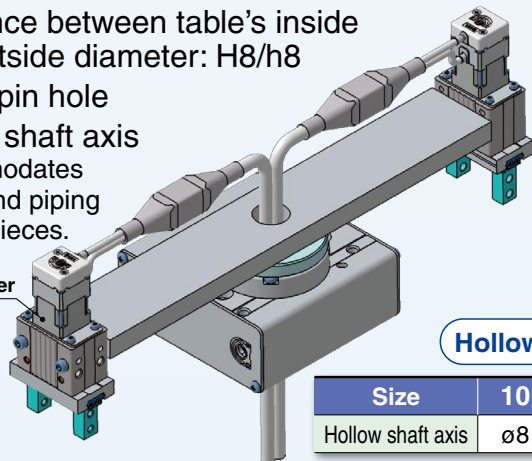| Model	Basic	High torque
LER10	0.2	0.3
LER30	0.8	1.2
LER50	6.6	10.0

Manual override screw (Both sides)

Possible to rotate the table with power OFF by manual override.

Easy Mounting of Workpieces

- Tolerance between table's inside and outside diameter: H8/h8
- Dowel pin hole
- Hollow shaft axis
  Accommodates wiring and piping of workpieces.

Electric gripper
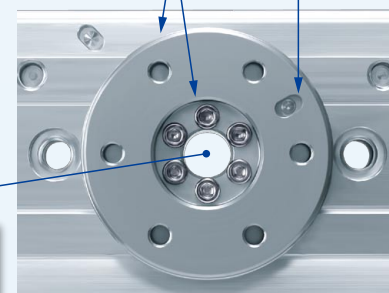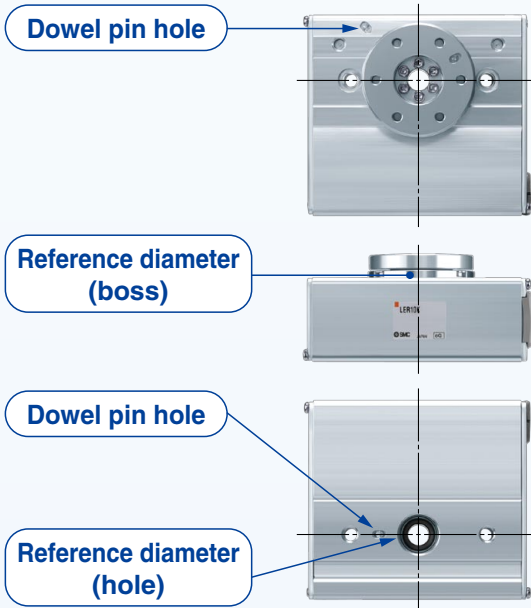**Series LEH**

For alignment of rotation center and workpiece

Dowel pin hole

Positioning of rotating direction

Hollow shaft axis

Size	10	30	50
Hollow shaft axis	ø8	ø17	ø20

SMC

Easy Mounting of the Main Body

Dowel pin hole

Reference diameter (boss)

Dowel pin hole

Reference diameter (hole)

Mounting Variations

■ Through-hole mounting

■ Body tapped mounting
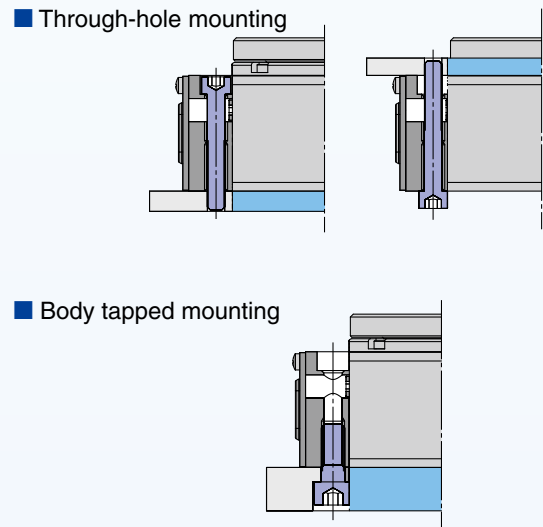
With External Stopper/Rotation Angle: 90°/180° Specification

Repeatability at the end: ±0.01°

90° specification

Adjuster bolt

Setting range ±2°

180° specification
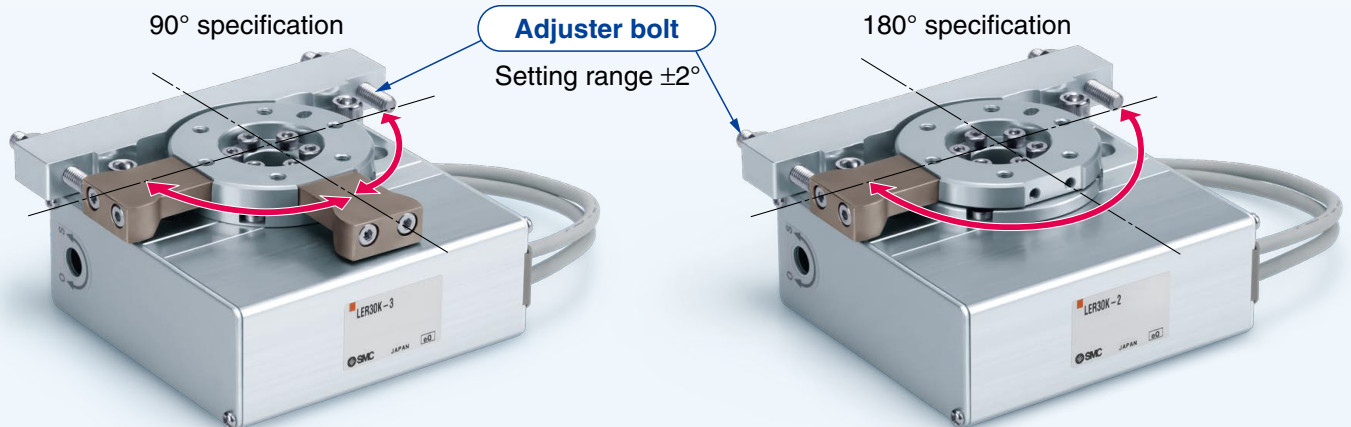
Application Examples

Electric gripper
Series LEH
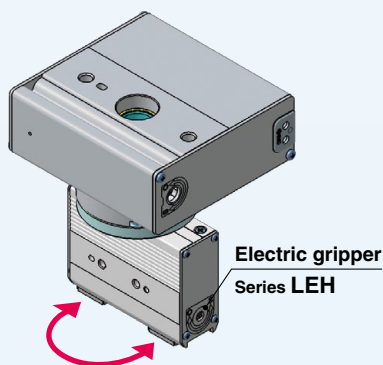
Rotation transfer after gripping in combination with a gripper
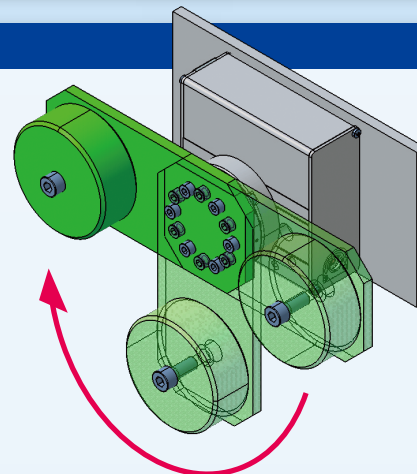
Vertical transfer: No change in speed due to load fluctuation

Simple Setting to Use Straight Away
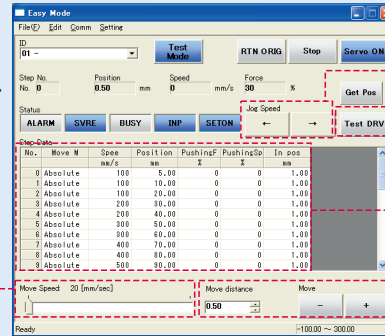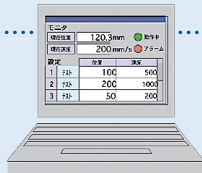## ◎Easy Mode for Simple Setting

Step motor
(Servo/24 VDC)
LECP6

If you want to use it right away, select "Easy Mode."

<When a PC is used>
Controller setting software

● Step data setting, test operation, move jog and move for the constant rate can be set and operated on one screen.

Setting of jog and speed of the constant rate
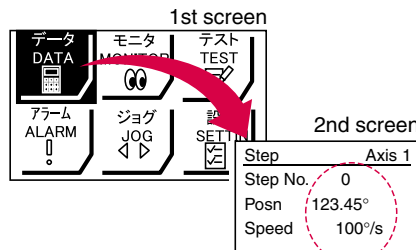
Move jog

Start testing

Step data setting

Move for the constant rate

<When a TB (teaching box) is used>

● Simple screen without scrolling promotes ease of setting and operating.
● Pick up an icon from the first screen to select a function.
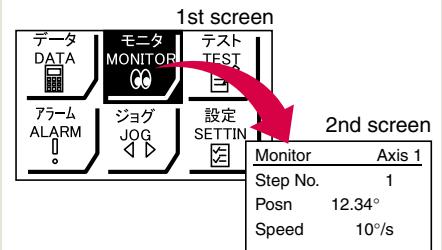● Set up the step data and check the monitor on the second screen.

Example of setting the step data

1st screen

データ DATA
モニタ MONITOR
テスト TEST
アラーム ALARM
ジョグ JOG
設定 SETTIN

2nd screen

Step	Axis 1
Step No.	0
Posn	123.45°
Speed	100°/s

It can be registered by "SET" after entering the values.

Example of checking the operation status

1st screen

データ DATA
モニタ MONITOR
テスト TEST
アラーム ALARM
ジョグ JOG
設定 SETTIN

2nd screen

Monitor	Axis 1
Step No.	1
Posn	12.34°
Speed	10°/s

Operation status can be checked.

Teaching box screen

● **Data can be set with position and speed.** (Other conditions are already set.)

Step	Axis 1
Step No.	0
Posn	50.00°
Speed	200°/s

Step	Axis 1
Step No.	1
Posn	80.00°
Speed	100°/s

Gateway Unit Series LEC-G

● Unit linking the LECP6 series and Fieldbus network
● Two methods of operation
 Step data input: Operate using preset step data in the controller.
 Numerical data input: The actuator operates using values such as position and speed from the PLC.

Fieldbus network

PLC

Serial communication RS485

Up to 12 controllers are connectable

Gateway (GW) unit

Compatible controllers Series LEC

Applicable Fieldbus protocols	CC-Link V2	DeviceNet	PROFIBUS	EtherNet/IP
Max. number of connectable controllers	12	8	5	12

Step motor controller (Servo/24 VDC) **Series LECP6**

Power supply

24 VDC for gateway unit

Compatible electric actuators

Electric gripper **Series LEH**

Electric slide table **Series LES**

Electric actuator/ Rod type **Series LEY**

Electric actuator/ Slider type **Series LEF**

Electric actuator/ Rotary table **Series LER**

Electric actuator/ Miniature type **Series LEP**

Electric actuator/ Guide rod slider **Series LEL**

Features 3

SMC

◎Normal Mode for Detailed Setting

Select normal mode when detailed setting is required.

● Step data can be set in detail.
● Signals and terminal status can be monitored.
● Parameters can be set.
● JOG and constant rate movement, return to origin, test operation and testing of forced output can be performed.

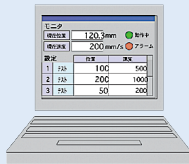### \<When a PC is used\>
Controller setting software

● Step data setting, parameter setting, monitor, teaching, etc., are indicated in different windows.

Step data setup window

Parameter setup window

Monitoring window

Teaching window

\<When a TB (teaching box) is used\>

● Multiple step data can be stored in the teaching box, and transferred to the controller.
● Continuous test operation by up to 5 step data.

Teaching box screen

● Each function (step data setting, test, monitor, etc.) can be selected from the main menu.

Menu   Axis 1
Step data
Parameter
Test

Main menu screen

Step   Axis 1
Step No.   ▲
                 0
Movement MOD   ▼

Step data setup screen

Test DRV   Axis 1
Step No.   1
Posn   123.45°
         Stop

Test screen

Out mon   Axis 1
BUSY[ ]   ▲
SVRE[●]
SETON[ ]   ▼

Monitoring screen

The actuator and controller are provided as a set. (They can be ordered separately.)

Confirm that the combination of the controller and the actuator is correct.
\<Check the following before use.\>
① Check the actuator label for model number. This matches the controller.
② Check Parallel I/O configuration matches (NPN or PNP).

Actuator

LER10K

① SMC JAPAN MS

Controller

LER10K

① NPN ②
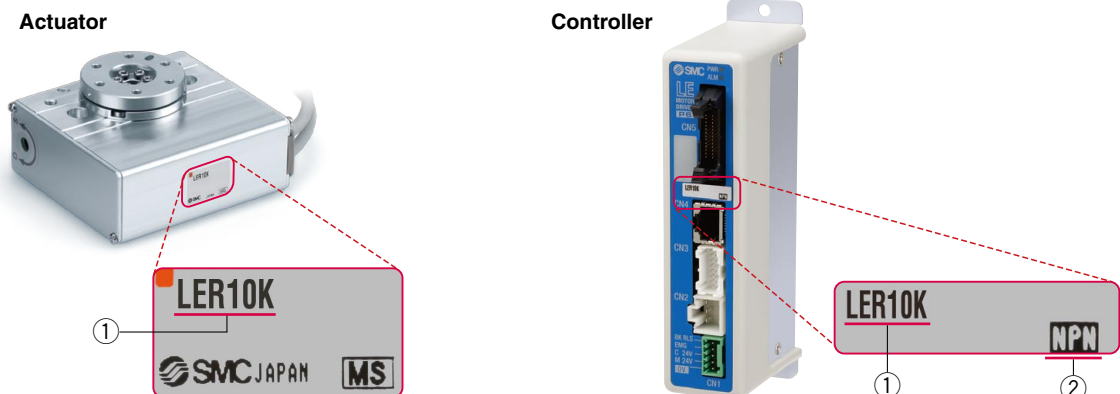
Programless Type Series LECP1

No programming

Capable of setting up an electric actuator operation without using a PC or teaching box

① Setting position number → **② Setting a stop position** → **③ Registration**

Setting a registered number
for the stop position
Maximum 14 points

Moving the actuator to a stop
position using FORWARD and
REVERSE buttons

Registering the stop
position using SET
button

Step motor
(Servo/24 VDC)
LECP1

**Position
number
display**

**Position
selecting
switch**

**FORWARD
and
REVERSE
buttons**

SET button
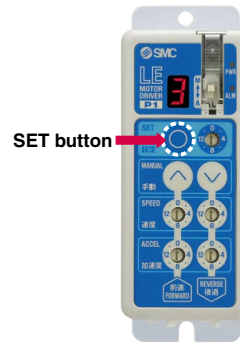
**Speed/Acceleration
16-level adjustment**

**Speed
adjustment
switches**

**Acceleration
adjustment
switches**
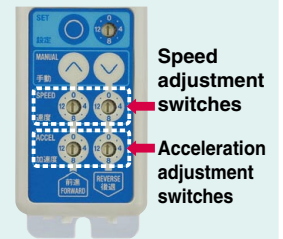
Pulse Input Type Series LECPA

● **A driver that uses pulse signals to allow positioning at any position.
The actuator can be controlled from the customers' positioning unit.**

Touch panel

Pulse signal

PLC
positioning
unit

**Step motor driver (Pulse input type)
Series LECPA**

Electric rotary table
Series LER
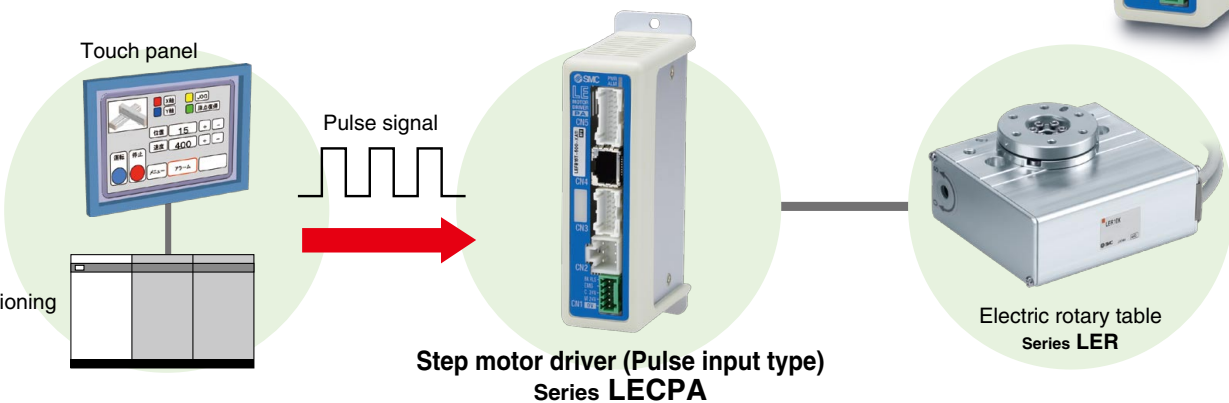
● **Return-to-origin command signal**
Enables automatic return-to-origin action.

● **With force limit function (Pushing force/Gripping force operation available)**
Pushing force/Positioning operation possible by switching signals.

SMC

Function

Item	Step data input type LECP6	Programless type LECP1	Pulse input type LECPA
Step data and parameter setting	• Input from controller setting software (PC) • Input from teaching box	• Select using controller operation buttons	• Input from controller setting software (PC) • Input from teaching box
Step data "position" setting	• Input the numerical value from controller setting software (PC) or teaching box • Input the numerical value • Direct teaching • JOG teaching	• Direct teaching • JOG teaching	• No "position" setting required Position and speed set by pulse signal
Number of step data	64 points	14 points	—
Operation command (I/O signal)	Step No. [IN*] input ⇒ [DRIVE] input	Step No. [IN*] input only	Pulse signal
Completion signal	[INP] output	[OUT*] output	[INP] output

Setting Items

TB: Teaching box PC: Controller setting software

Item		Contents	Easy mode TB	Easy mode PC	Normal mode TB/PC	Step data input type LECP6	Pulse input type LECPA	Programless type LECP1*
Step data setting (Excerpt)	**Movement MOD**	Selection of "absolute position" and "relative position"	△	●	●	Set at ABS/INC		Fixed value (ABS)
	Speed	**Transfer speed**	●	●	●	Set in units of 1°/s		Select from 16-level
	Position	[Position]: Target position [Pushing]: Pushing start position	●	●	●	Set in units of 0.01°	No setting required	Direct teaching JOG teaching
	Acceleration/Deceleration	Acceleration/deceleration during movement	●	●	●	Set in units of 1°/s²		Select from 16-level
	Pushing force	Rate of force during pushing operation	●	●	●	Set in units of 1%	Set in units of 1%	Select from 3-level (weak, medium, strong)
	Trigger LV	Target force during pushing operation	△	●	●	Set in units of 1%	Set in units of 1%	No setting required (same value as pushing force)
	Pushing speed	Speed during pushing operation	△	●	●	Set in units of 1°/s	Set in units of 1 mm/s	
	Moving force	Force during positioning operation	△	●	●	Set to 100%	Set to (Different values for each actuator)%	No setting required
	Area output	Conditions for area output signal to turn ON	△	●	●	Set in units of 0.01°	Set in units of 0.01 mm	
	In position	[Position]: Width to the target position [Pushing]: How much it moves during pushing	△	●	●	Set to 0.5° or more (Units: 0.01°)	Set to (Different values for each actuator) or more (Units: 0.01 mm)	
Parameter setting (Excerpt)	**Stroke (+)**	**+ side limit of position**	×	×	●	Set in units of 0.01°	Set in units of 0.01 mm	
	Stroke (−)	**− side limit of position**	×	×	●	Set in units of 0.01°	Set in units of 0.01 mm	
	ORIG direction	Direction of the return to origin can be set.	×	×	●	Compatible	Compatible	Compatible
	ORIG speed	Speed during return to origin position	×	×	●	Set in units of 1°/s	Set in units of 1 mm/s	No setting required
	ORIG ACC	Acceleration during return to origin position	×	×	●	Set in units of 1°/s²	Set in units of 1 mm/s	
Test	**JOG**		●	●	●	Continuous operation at the set speed can be tested while the switch is being pressed.	Continuous operation at the set speed can be tested while the switch is being pressed.	Hold down MANUAL button (△▽) for uniform sending (speed is specified value)
	MOVE		×	●	●	Operation at the set distance and speed from the current position can be tested.	Operation at the set distance and speed from the current position can be tested.	Press MANUAL button (△▽) once for sizing operation (speed, sizing amount are specified values)
	Return to ORIG		●	●	●	Compatible	Compatible	Compatible
	Test drive	**Operation of the specified step data**	●	●	● (Continuous operation)	Compatible	Not compatible	Compatible
	Forced output	ON/OFF of the output terminal can be tested.	×	×	●	Compatible	Compatible	
Monitor	**DRV mon**	**Current position, speed, force and the specified step data can be monitored.**	●	●	●	Compatible	Compatible	Not compatible
	In/Out mon	**Current ON/OFF status of the input and output terminal can be monitored.**	×	×	●	Compatible	Compatible	
ALM	**Status**	Alarm currently being generated can be confirmed.	●	●	●	Compatible	Compatible	Compatible (display alarm group)
	ALM Log record	Alarm generated in the past can be confirmed.	×	×	●	Compatible	Compatible	
File	**Save/Load**	**Step data and parameter can be saved, forwarded and deleted.**	×	×	●	Compatible	Compatible	Not compatible
Other	**Language**	Can be changed to Japanese or English.	●	●	●	Compatible	Compatible	

△: Can be set from TB Ver. 2.** (The version information is displayed on the initial screen)
* Programless type LECP1 cannot be used with the teaching box and controller setting kit.

System Construction/General Purpose I/O

●**Electric rotary table**

Provided by customer

PLC

Power supply for I/O signal
24 VDC Note)
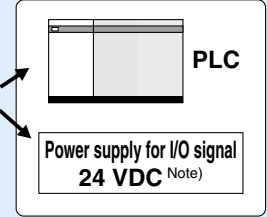
●**I/O cable** Pages 21, 33

Controller type	Part no.
LECP6	**LEC-CN5-□**
LECP1 (Programless)	**LEC-CK4-□**

●**Controller**∗ Page 14

To CN5

To CN4

To CN3

To CN2

To CN1
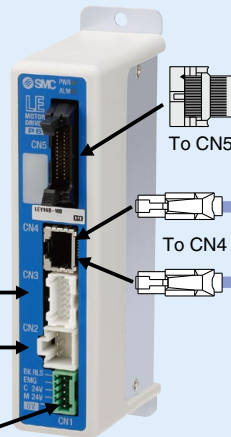
Provided by customer

Power supply for controller
24 VDC Note)

Note) When conformity to UL is required, the electric actuator and controller should be used with a UL1310 Class 2 power supply.

●**Power supply plug**
(Accessory)
<Applicable cable size>
AWG20 (0.5 mm²)

Step data input type
LECP6
Page 15

Programless type
LECP1
Page 28

Note) The teaching box, controller setting kit and Touch Operator Interface cannot be connected.

●**Touch Operator Interface (Provided by customer)**
GP4501T/GP3500T
Manufactured by Digital Electronics Corp.

Pro-face
for the best interface

Cockpit parts can be downloaded free via the Pro-face website. Using cockpit parts makes adjustment from the Touch Operator Interface possible.

●**Actuator cable**∗ Pages 21, 33

Controller type	Standard cable	Robotic cable
LECP6 (Step data input type)	**LE-CP-□-S**	**LE-CP-□**
LECP1 (Programless type)	**LE-CP-□-S**	**LE-CP-□**

The ∗ mark: Can be included in the "How to Order" for the actuator.

Option

●**Teaching box** Page 23
(With 3 m cable)
Part no.: LEC-T1-3JG□

Or

●**Controller setting kit** Page 22
Controller setting kit
(Communication cable, conversion unit and USB cable are included.)
Part no.: LEC-W2

Communication cable●
(3 m)
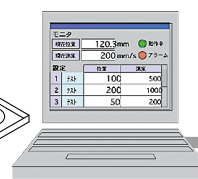
●**USB cable**
(A-miniB type)
(0.3 m)

PC

Note) Cannot be used with the programless type (LECP1).

SMC

System Construction/Pulse Signal

●Electric rotary table
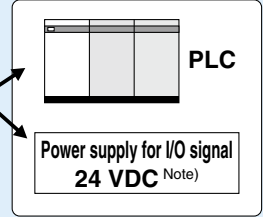
Provided by customer

PLC

Power supply for I/O signal 24 VDC Note)

Note) When conformity to UL is required, the electric actuator and driver should be used with a UL1310 Class 2 power supply.

●Driver * Page 34

To CN5

●I/O cable Page 40

Driver type	Part no.
LECPA	LEC-CL5-☐

To CN3

To CN4

To CN2

Provided by customer

Power supply for driver 24 VDC Note)

Note) When conformity to UL is required, the electric actuator and driver should be used with a UL1310 Class 2 power supply.

To CN1

●Power supply plug (Accessory)
<Applicable cable size>
AWG20 (0.5 mm²)

●Actuator cable * Page 39

Driver type	Standard cable	Robotic cable
LECPA (Pulse input type)	LE-CP-☐-S	LE-CP-☐

The * mark: Can be included in the "How to Order" for the actuator.

Option

●Teaching box Page 42
(With 3 m cable)
Part no.: LEC-T1-3JG☐

Or

●Controller setting software Page 41
Communication cable (With conversion unit) and USB cable are included.
Part no.: LEC-W2

Communication cable●

●USB cable
(A-miniB type)

**PC**

SMC
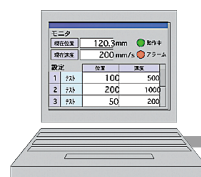
System Construction/Fieldbus Network

PLC
(Provided by customer)

Power supply for gateway unit 24 VDC Note 1)

Power supply

Fieldbus network

Gateway (GW) unit [Page 25]

Applicable Fieldbus protocols
CC-Link Ver. 2.0
DeviceNet™
PROFIBUS DP
EtherNet/IP™

● **Power supply connector**
(Accessory)   To CN4

● **Communication connector**
(Accessory)*   To CN3
* CC-Link Ver. 2.0
DeviceNet™ only

To CN2

To CN1

[Page 25]
● **Communication cable**
LEC-CG1-□

[Page 25]
● **Cable between branches**
LEC-CG2-□

● **Branch connector** [Page 25]
LEC-CGD

● **Terminating resistor connector 120Ω**
LEC-CGR

[Page 25]
● **Communication cable**
LEC-CG1-□

Option

● **Controller setting software** [Page 22]
(Communication cable and USB cable are included.)
Part no.: LEC-W2

● **Communication cable**

USB cable ●
(A-miniB type)

PC
(Provided by customer)

Or

● **Teaching box** [Page 23]
(With 3 m cable)
Part no.: LEC-T1-3JG□

● **Controller** [Page 15]   ● **Controller** [Page 15]

To CN4

● **Power supply connector**
(Accessory)   To CN1

Controller input power supply Note 1)

● **Power supply connector**
(Accessory)   To CN1

Controller input power supply Note 1)

Applicable Fieldbus protocols	Max. number of connectable controllers
CC-Link Ver. 2.0	12
DeviceNet™	8
PROFIBUS DP	5
EtherNet/IP™	12

Compatible controller

Step motor controller (Servo/24 VDC)	Series **LECP6**

Note 1) Connect the 0 V terminals for both the controller input power supply and gateway unit power supply.
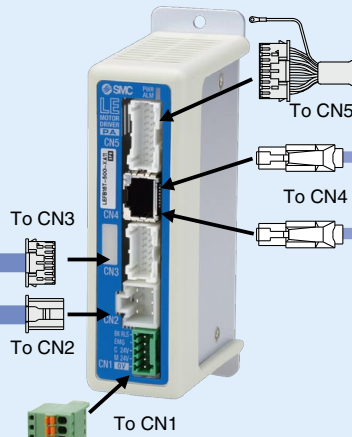When conformity to UL is required, the electric actuator and controller should be used with a UL1310 Class 2 power supply.

● **Electric rotary table**

Series LER

SMC

SMC Electric Actuators

Slider Type [Step Motor (Servo/24 VDC)] [Servo Motor (24 VDC)] [AC Servo Motor]

CAT.ES100-87

Ball screw drive
Series LEFS
Clean room compatible

Belt drive
Series LEFB

Ball screw drive
Series LEFS
Clean room compatible

Belt drive
Series LEFB

Series LEFS

Size	Max. work load (kg)	Stroke (mm)
16	10	Up to 400
25	20	Up to 600
32	45	Up to 800
40	60	Up to 1000

Series LEFB

Size	Max. work load (kg)	Stroke (mm)
16	1	Up to 1000
25	5	Up to 2000
32	14	Up to 2000

Series LEFS

Size	Max. work load (kg)	Stroke (mm)
25	20	Up to 600
32	45	Up to 800
40	60	Up to 1000
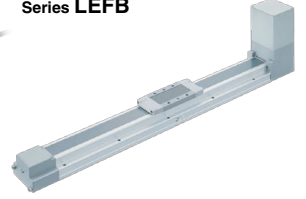
Series LEFB

Size	Max. work load (kg)	Stroke (mm)
25	5	Up to 2000
32	15	Up to 2500
40	25	Up to 3000

High Rigidity Slider Type [AC Servo Motor]

CAT.ES100-104

Ball screw drive
Series LEJS

Belt drive
Series LEJB
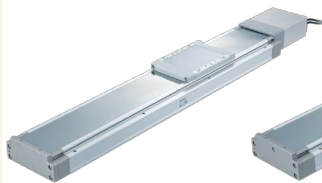
Series LEJS

Size	Max. work load (kg)	Stroke (mm)
40	55	200 to 1200
63	85	300 to 1500
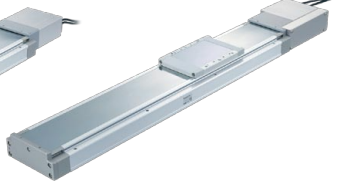
Series LEJB

Size	Max. work load (kg)	Stroke (mm)
40	20	200 to 2000
63	30	300 to 3000

Guide Rod Slider [Step Motor (Servo/24 VDC)]

CAT.ES100-101

Belt drive
Series LEL

Series LEL25M
Sliding bearing

Size	Max. work load (kg)	Stroke (mm)
25	3	Up to 1000

Series LEL25L
Ball bushing bearing

Size	Max. work load (kg)	Stroke (mm)
25	5	Up to 1000

Rod Type [Step Motor (Servo/24 VDC)] [Servo Motor (24 VDC)]

CAT.ES100-83

Basic type
Series LEY
Dust/Drip proof compatible

In-line motor type
Series LEY□D
Dust/Drip proof compatible

Guide rod type
Series LEYG

Guide rod type /In-line motor type
Series LEYG□D

Series LEY

Size	Pushing force (N)	Stroke (mm)
16	141	Up to 300
25	452	Up to 400
32	707	Up to 500
40	1058	Up to 500
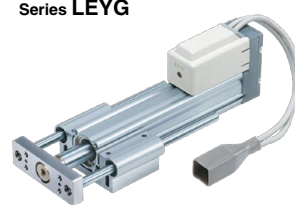
Series LEYG

Size	Pushing force (N)	Stroke (mm)
16	141	Up to 200
25	452	Up to 300
32	707	Up to 300
40	1058	Up to 300

[AC Servo Motor]

Basic type
Series LEY
Dust/Drip proof compatible

In-line motor type
Series LEY□D
Dust/Drip proof compatible

Guide rod type
Series LEYG

Guide rod type /In-line motor type
Series LEYG□D

Series LEY

Size	Pushing force (N)	Stroke (mm)
25	485	Up to 400
32	588	Up to 500

Series LEY

Size	Pushing force (N)	Stroke (mm)
25	485	Up to 400
32	736	Up to 500
63	1910	Up to 800
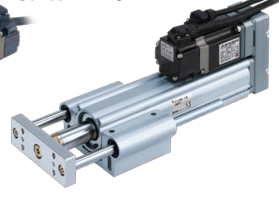
Series LEYG

Size	Pushing force (N)	Stroke (mm)
25	485	300
32	588	

Series LEYG

Size	Pushing force (N)	Stroke (mm)
25	485	300
32	736	

SMC

SMC Electric Actuators

Slide Table [Step Motor (Servo/24 VDC)] [Servo Motor (24 VDC)]

CAT.ES100-78

Compact type Series LES

Basic type/R type
Series LES□R

Symmetrical type/L type
Series LES□L

In-line motor type/D type
Series LES□D

Size	Max. work load (kg)	Stroke (mm)
8	1	30, 50, 75
16	3	30, 50 75, 100
25	5	30, 50, 75 100, 125, 150

High rigidity type Series LESH

Basic type/R type
Series LESH□R

Symmetrical type/L type
Series LESH□L

In-line motor type/D type
Series LESH□D

Size	Max. work load (kg)	Stroke (mm)
8	2	50, 75
16	6	50, 100
25	9	50, 100 150

Miniature [Step Motor (Servo/24 VDC)]

CAT.ES100-92

Rod type
Series LEPY

Slide table type
Series LEPS

Series LEPY

Size	Max. work load (kg)	Stroke (mm)
6	1	25, 50, 75
10	2	

Series LEPS

Size	Max. work load (kg)	Stroke (mm)
6	1	25
10	2	50

Rotary Table [Step Motor (Servo/24 VDC)]

CAT.ES100-94

Basic type
Series LER

High precision type
Series LERH

Series LER

Size	Rotating torque (N·m) Basic	Rotating torque (N·m) High torque	Max. speed (°/s) Basic	Max. speed (°/s) High torque
10	0.2	0.3	420	280
30	0.8	1.2		
50	6.6	10		

Gripper [Step Motor (Servo/24 VDC)]

CAT.ES100-77

2-finger type
Series LEHZ

2-finger type With dust cover
Series LEHZJ

2-finger type Long stroke
Series LEHF

3-finger type
Series LEHS

Series LEHZ

Size	Max. gripping force (N) Basic	Max. gripping force (N) Compact	Stroke/both sides (mm)
10	14	6	4
16		8	6
20	40	28	10
25			14
32	130	—	22
40	210	—	30

Series LEHZJ

Size	Max. gripping force (N) Basic	Max. gripping force (N) Compact	Stroke/both sides (mm)
10	14	6	4
16		8	6
20	40	28	10
25			14

Series LEHF

Size	Max. gripping force (N)	Stroke/both sides (mm)
10	7	16 (32)
20	28	24 (48)
32	120	32 (64)
40	180	40 (80)

Note) ( ): Long stroke

Series LEHS

Size	Max. gripping force (N) Basic	Max. gripping force (N) Compact	Stroke/both sides (mm)
10	5.5	3.5	4
20	22	17	6
32	90	—	8
40	130	—	12

SMC

Controller/Driver

Controller

Step data input type For step motor Series **LECP6**	Step data input type For servo motor Series **LECA6**	Programless type Series **LECP1**

Driver

Pulse input type Series LECPA

Control motor	Control motor	Control motor
Step motor (Servo/24 VDC)	Servo motor (24 VDC)	Step motor (Servo/24 VDC)

Control motor
Step motor (Servo/24 VDC)

Gateway Unit

Fieldbus-compatible gateway (GW) unit
Series **LEC-G**

Applicable Fieldbus protocols	CC-Link V2	DeviceNet	PROFIBUS	EtherNet/IP
Max. number of connectable controllers	12	8	5	12

Driver

AC Servo Motor Driver

Pulse input type/ Positioning type Series **LECSA** (Incremental type)	Pulse input type Series **LECSB** (Absolute type)	CC-Link direct input type Series **LECSC** (Absolute type)	SSCNET III type Series **LECSS** (Absolute type)

Control motor	Control motor	Control motor	Control motor
AC servo motor (100/200/400 W)	AC servo motor (100/200/400 W)	AC servo motor (100/200/400 W)	AC servo motor (100/200/400 W)

SMC

Electric Rotary Table *Series LER*

Type	Rotating torque [N·m]		Max. speed [°/s]		Positioning repeatability [°]		Controller /Driver series	Reference page
	Basic	High torque	Basic	High torque	Basic	High torque		
LER10	0.2	0.3	420	280	±0.05 (End: ±0.01)∗		Series LECP6 Series LECP1 Series LECPA	Page 1
LER30	0.8	1.2						
LER50	6.6	10						

∗ Value when an external stopper is mounted.

Controller/Driver *LEC*

LECP6   **LECP1**

LECPA

Type	Series	Compatible motor	Power supply voltage	Parallel I/O		Number of positioning pattern points	Reference page
				Input	Output		
Step data input type	LECP6	Step motor (Servo/24 VDC)	24 VDC ±10%	11 inputs (Photo-coupler isolation)	13 outputs (Photo-coupler isolation)	64	Page 15
Programless type	LECP1	Step motor (Servo/24 VDC)	24 VDC ±10%	6 inputs (Photo-coupler isolation)	6 outputs (Photo-coupler isolation)	14	Page 28
Pulse input type	LECPA	Step motor (Servo/24 VDC)	24 VDC ±10%	5 inputs (Photo-coupler isolation)	9 outputs (Photo-coupler isolation)	—	Page 34

SMC

Step Motor (Servo/24 VDC) Type

◎Electric Rotary Table Series LER

◎Step Motor (Servo/24 VDC) Controller/Driver

Step Motor (Servo/24 VDC)

LER

LECP6

LEC-G

LECP1

LECPA

Specific Product Precautions

Electric Rotary Table

Step Motor (Servo/24 VDC)

Series **LER**

Model Selection

Selection Precedure

Operating conditions

H
b
a

Electric rotary table: LER30J
Mounting position: Horizontal
Load type: Inertial load Ta
Configuration of load: 150 mm x 80 mm
(Rectangular plate)
Rotation angle θ: 180°

Angular acceleration/
angular deceleration $\dot{\omega}$: 1,000°/sec²
Angular speed ω: 420°/sec
Load mass (m): 2.0 kg
Distance between shaft and center
of gravity H: 40 mm

Step1 Moment of inertia—Angular acceleration/deceleration

① **Calculation of moment of inertia**

② **Moment of inertia—Check the angular acceleration/deceleration**
Select the target model based on the moment of inertia and angular acceleration and deceleration with reference to the (Moment of Inertia —Angular Acceleration/Deceleration graph).

Formula

$$I = m \times (a^2 + b^2)/12 + m \times H^2$$

Selection example

$$I = 2.0 \times (0.15^2 + 0.08^2)/12 + 2.0 \times 0.04^2$$
$$= 0.00802 \text{ kg·m}^2$$

LER30

LER□30K High torque
LER□30J Basic

Moment of inertia: I (kg·m²)
Angular acceleration/deceleration: $\dot{\omega}$ (°/s²)
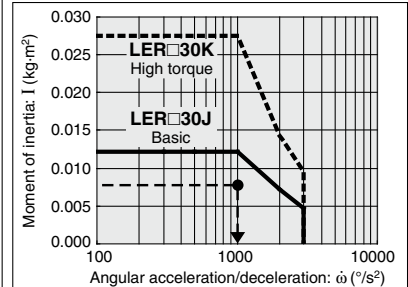
Step2 Necessary torque

① **Load type**
• Static load: Ts
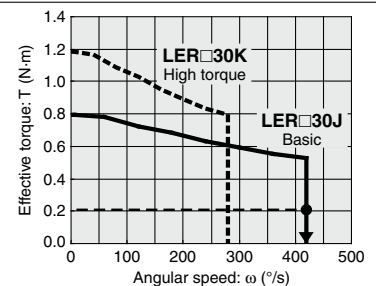• Resistance load: Tf
• Inertial load: Ta

② **Check the effective torque**
Confirm whether it is possible to control the speed based on the effective torque corresponding with the angular speed with reference to the (Effective Torque—Angular Speed graph).

Formula

Effective torque ≥ Ts
Effective torque ≥ Tf x 1.5
Effective torque ≥ Ta x 1.5

Selection example

Inertial load: Ta
Ta x 1.5 = I x $\dot{\omega}$ x 2 π/360 x 1.5
= 0.00802 x 1,000 x 0.0175 x 1.5
= 0.21 N·m

LER30

LER□30K High torque
LER□30J Basic

Effective torque: T (N·m)
Angular speed: ω (°/s)

Step3 Allowable load

① **Check the allowable load**
• Radial load
• Thrust load
• Moment

Formula

Allowable thrust load ≥ m x 9.8
Allowable moment ≥ m x 9.8 x H

Selection example

• Thrust load
2.0 x 9.8 = 19.6 N < Allowable load OK
• Allowable moment
2.0 x 9.8 x 0.04
= 0.784 N·m < Allowable moment OK

Step4 Rotation time

① **Calculation of cycle time (rotation time)**

θ
$\dot{\omega}1$
$\dot{\omega}2$
Speed: ω [°/sec]
Time [s]
T1 T2 T3 T4
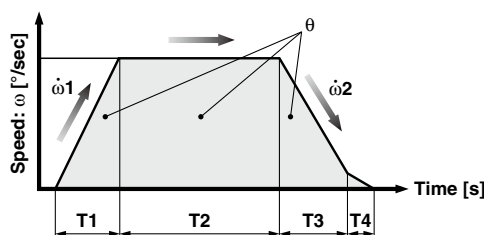
θ : **Rotation angle [°]**
ω : **Angular speed [°/sec]**
$\dot{\omega}1$: Angular acceleration [°/sec²]
$\dot{\omega}2$: Angular deceleration [°/sec²]

T1: **Acceleration time [s]** ··· Time until reaching the set speed
T2: **Constant speed time [s]** ··· Time while the actuator is operating at a constant speed
T3: **Deceleration time [s]** ··· Time from constant speed operation to stop
T4: **Settling time [s]** ··· Time until in position is completed

Formula

Angular acceleration time   T1 = ω/$\dot{\omega}1$
Angular deceleration time   T3 = ω/$\dot{\omega}2$
Constant speed time   T2 = {θ − 0.5 x ω x (T1 + T3)}/ω
Settling time   T4 = 0.2 (sec)
Cycle time   T = T1 + T2 + T3 + T4

Selection example

• Angular acceleration time   T1 = 420/1,000 = 0.42 sec
• Angular deceleration time   T3 = 420/1,000 = 0.42 sec
• Constant speed time
T2 = {180 − 0.5 x 420 x (0.42 + 0.42)}/420
= 0.009 sec
• Cycle time   T = T1 + T2 + T3 + T4
= 0.42 + 0.009 + 0.42 + 0.2
= 1.049 (sec)

SMC

Model Selection *Series LER*

Model Selection

Step Motor (Servo/24 VDC)

LER

LECP6

LEC-G

LECP1

LECPA

Specific Product Precautions

Formulas for Moment of Inertia (Calculation of moment of inertia I)

I: Moment of inertia (kg·m²)   m: Load mass (kg)

1. Thin bar
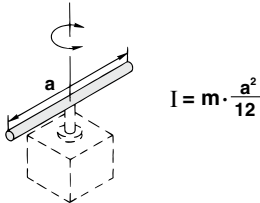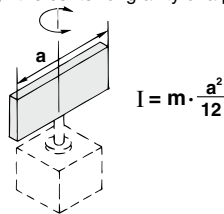Position of rotation shaft: Perpendicular to a bar through one end

$$I = m_1 \cdot \frac{a_1{}^2}{3} + m_2 \cdot \frac{a_2{}^2}{3}$$
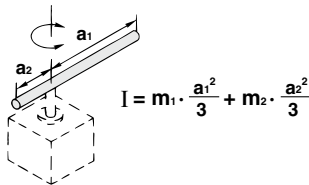
2. Thin bar
Position of rotation shaft: Passes through the center of gravity of the bar.

$$I = m \cdot \frac{a^2}{12}$$

3. Thin rectangular plate (cuboid)
Position of rotation shaft: Passes through the center of gravity of a plate.

$$I = m \cdot \frac{a^2}{12}$$

4. Thin rectangular plate (cuboid)
Position of rotation shaft: Perpendicular to the plate and passes through one end. (The same applies to thicker cuboids.)

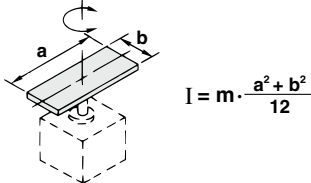$$I = m_1 \cdot \frac{4a_1{}^2 + b^2}{12} + m_2 \cdot \frac{4a_2{}^2 + b^2}{12}$$
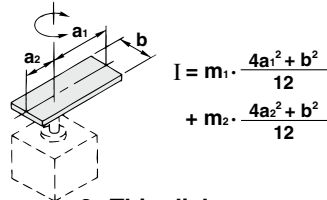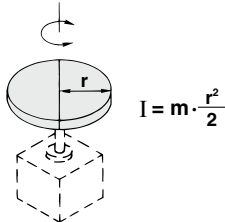
5. Thin rectangular plate (cuboid)
Position of the rotation shaft: Passes through the center of gravity of the plate and perpendicular to the plate. (The same applies to thicker cuboids.)
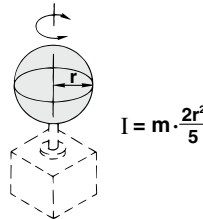
$$I = m \cdot \frac{a^2 + b^2}{12}$$

6. Cylindrical shape (including a thin disk)
Position of rotation shaft: Center axis

$$I = m \cdot \frac{r^2}{2}$$

7. Sphere
Position of rotation shaft: Diameter

$$I = m \cdot \frac{2r^2}{5}$$

8. Thin disk (mounted vertically)
Position of rotation shaft: Diameter

$$I = m \cdot \frac{r^2}{4}$$
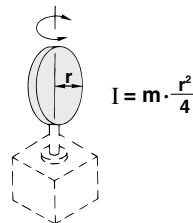
9. When a load is mounted on the end of the lever

$$I = m_1 \cdot \frac{a_1{}^2}{3} + m_2 \cdot a_2{}^2 + K$$

(Ex.) Refer to **7** when the shape of **m₂** is spherical.

$$K = m_2 \cdot \frac{2r^2}{5}$$

10. Gear transmission

Number of teeth = a
Number of teeth = b
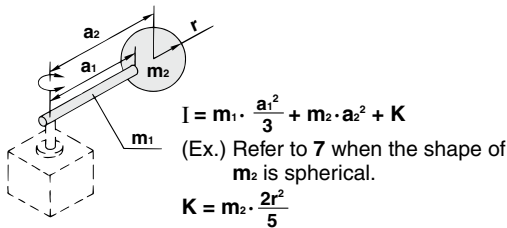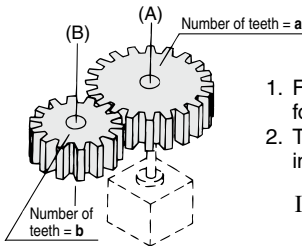
1. Find the moment of inertia I_B for the rotation of shaft (B).
2. Then, replace the moment of inertia I_B around the shaft (A) by I_A,

$$I_A = \left(\frac{a}{b}\right)^2 \cdot I_B$$

Load Type

Load type		
Static load: Ts	**Resistance load: Tf**	**Inertial load: Ta**
Only pressing force is necessary. (e.g. for clamping)	Gravity or friction force is applied to rotating direction.	Rotate the load with inertia.
	Gravity is applied. / Friction force is applied.	Center of rotation and center of gravity of the load are concentric. / Rotation shaft is vertical (up and down).
Ts = F·L **Ts:** Static load (N·m) **F :** Clamping force (N) **L :** Distance from the rotation center to the clamping position (m)	Gravity is applied to rotating direction. **Tf = m·g·L** Friction force is applied to rotating direction. **Tf = μ·m·g·L** **Tf:** Resistance load (N·m) **m :** Load mass (kg) **g :** Gravitational acceleration 9.8 (m/s²) **L :** Distance from the rotation center to the point of application of the gravity or friction force (m) **μ :** Friction coefficient	**Ta = I·ω̇·2 π/360** **(Ta = I·ω̇·0.0175)** **Ta:** Inertial load (N·m) **I :** Moment of inertia (kg·m²) **ω̇ :** Angular acceleration/deceleration (°/sec²) **ω :** Angular speed (°/sec)
Necessary torque: **T = Ts**	Necessary torque: **T = Tf x 1.5** [Note 1]	Necessary torque: **T = Ta x 1.5** [Note 1]

- **Resistance load: Gravity or friction force is applied to rotating direction.**
  Ex. 1) Rotation shaft is horizontal (lateral), and the rotation center and the center of gravity of the load are not concentric.
  Ex. 2) Load moves by sliding on the floor.
    ∗ The total of resistance load and inertial load is the necessary torque. **T = (Tf + Ta) x 1.5**

- **Not resistance load: Neither gravity or friction force is applied to rotating direction.**
  Ex. 1) Rotation shaft is vertical (up and down).
  Ex. 2) Rotation shaft is horizontal (lateral), and rotation center and the center of gravity of the load are concentric.
    ∗ Necessary torque is inertial load only. **T = Ta x 1.5**

  Note 1) To adjust the speed, margin is necessary for **Tf** and **Ta**.

Moment of Inertia—Angular Acceleration/Deceleration

LER10

LER30

LER50

Effective Torque—Angular Speed

LER10

LER30

LER50

Model Selection *Series LER*

Model Selection

Step Motor (Servo/24 VDC)

LER

LECP6

LEC-G

LECP1

LECPA

Specific Product Precautions
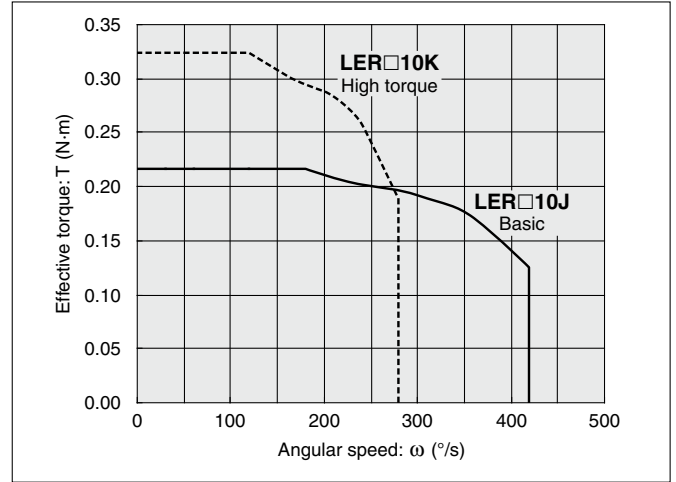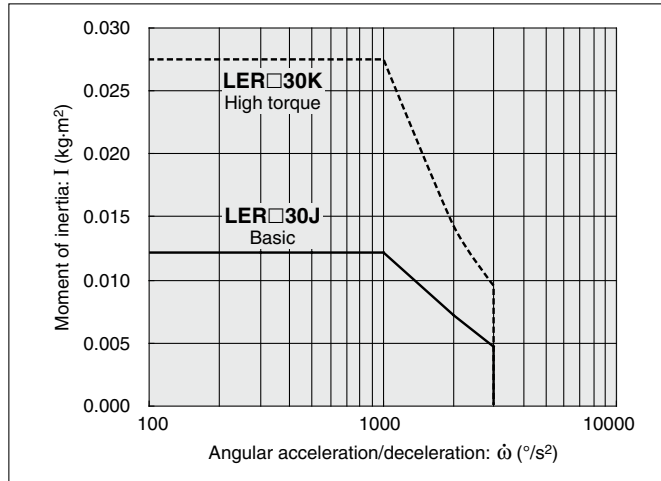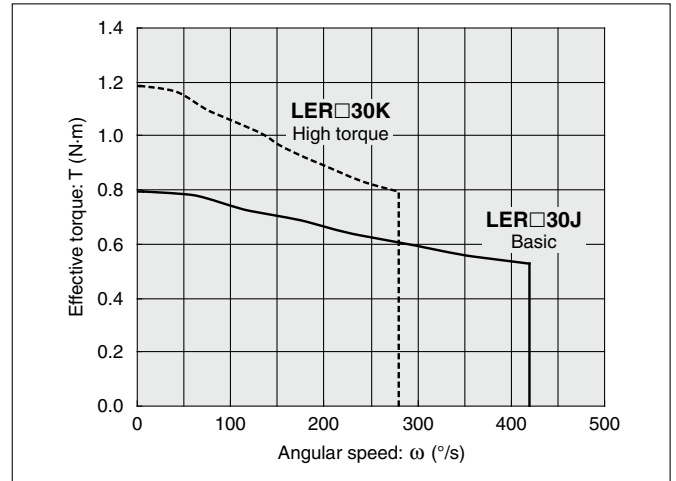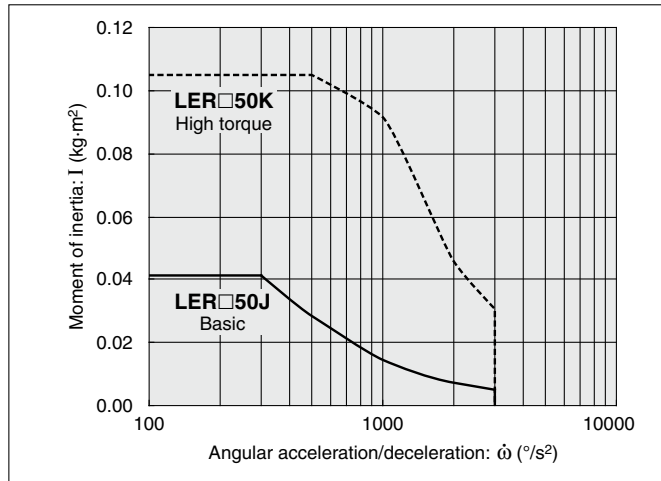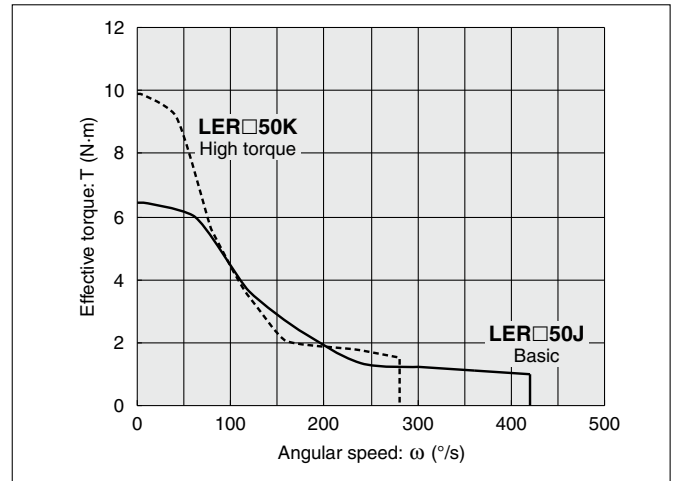
Allowable Load

Size	Allowable radial load (N)		Allowable thrust load (N)				Allowable moment (N·m)	
			(a)		(b)			
	Basic type	High precision type	Basic type	High precision type	Basic type	High precision type	Basic type	High precision type
10	78	86	74	78	107		2.4	2.9
30	196	233	197	363	398		5.3	6.4
50	314	378	296	398	517		9.7	12.0

Table Displacement (Reference Value)

• Displacement at point A when a load is applied to point A 100 mm away from the rotation center.
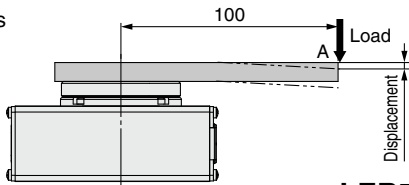
LER□10
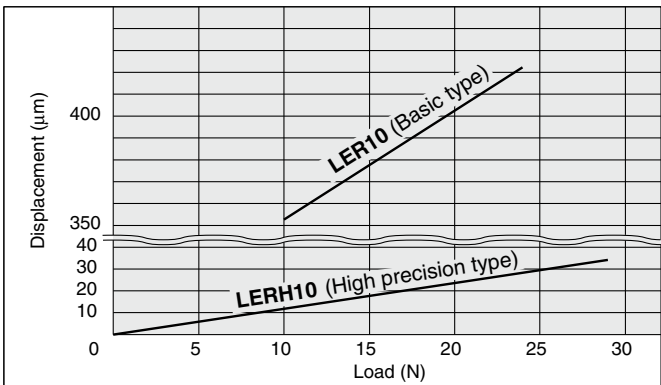
LER□50
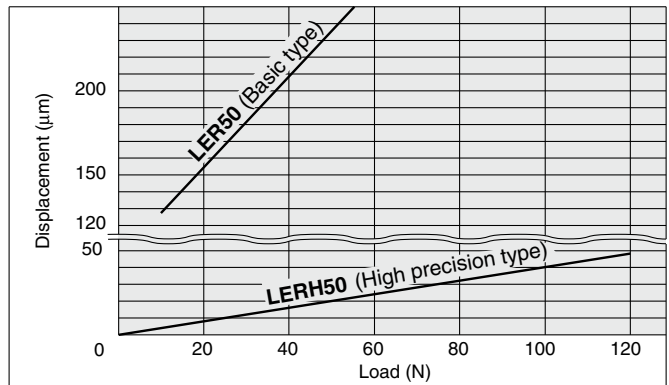
LER□30
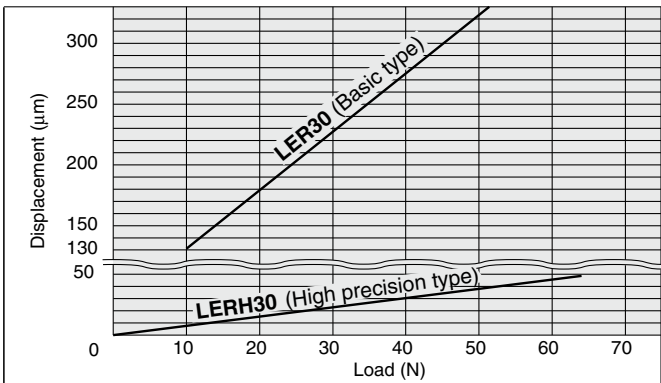
Deflection Accuracy: Displacement at 180° Rotation (Guide)

[mm]
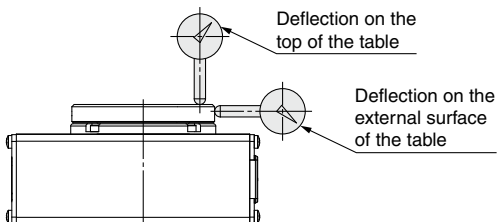
Measured part	**LER** (Basic type)	**LERH** (High precision type)
Deflection on the top of the table	0.1	0.03
Deflection on the external surface of the table	0.1	0.03

SMC

4

Electric Rotary Table

Step Motor (Servo/24 VDC)

Series LER

LER10, 30, 50

C € c**UL**us RoHS

How to Order

LER ☐ **10** **K** – ☐ ☐ – **S** **1** **6N** ☐

❶ ❷ ❸ ❹ ❺ ❻ ❼ ❽ ❾ ❿
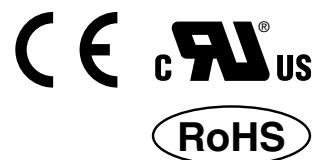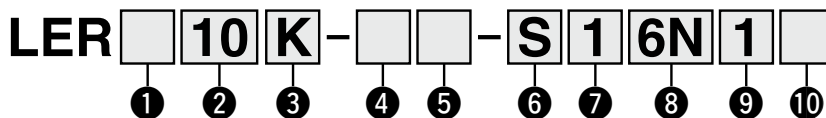
❶ Table accuracy

Nil	Basic type
H	High precision type

❷ Size

10
30
50

❸ Max. rotating torque [N·m]

Symbol	Type	LER10	LER30	LER50
K	High torque	0.3	1.2	10
J	Basic	0.2	0.8	6.6

❹ Rotation angle [°]

Symbol	LER10	LER30	LER50
Nil	310	320	
2	External stopper: 180		
3	External stopper: 90		

❺ Motor cable entry

Nil	Basic type (entry on the right side)
L	Entry on the left side
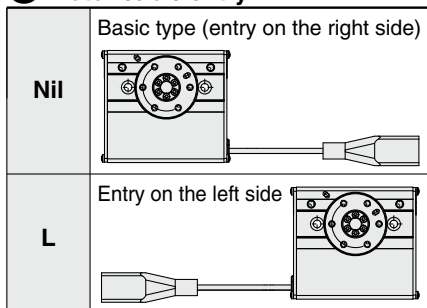
❻ Actuator cable type*

Nil	Without cable
S	Standard cable
R	Robotic cable (Flexible cable)

* The standard cable should be used on fixed parts. For using on moving parts, select the robotic cable.

❼ Actuator cable length [m]

Nil	Without cable	8	8*
1	1.5	A	10*
3	3	B	15*
5	5	C	20*

* Produced upon receipt of order (Robotic cable only) Refer to the specifications Note 3) on page 6.

❽ Controller/Driver type*1

Nil	Without controller/driver	
6N	LECP6	NPN
6P	(Step data input type)	PNP
1N	LECP1	NPN
1P	(Programless type)	PNP
AN	LECPA	NPN
AP	(Pulse input type)	PNP

*1 For details about controllers/driver and compatible motors, refer to the compatible controllers/driver below.

❾ I/O cable length [m]*1

Nil	Without cable
1	1.5
3	3*2
5	5*2

*1 When "Without controller/driver" is selected for controller/driver types, I/O cable cannot be selected. Refer to page 21 (For LECP6), page 33 (For LECP1) or page 40 (For LECPA) if I/O cable is required.
*2 When "Pulse input type" is selected for controller/driver types, pulse input usable only with differential. Only 1.5 m cables usable with open collector.

❿ Controller/Driver mounting

Nil	Screw mounting
D	DIN rail mounting*

* DIN rail is not included. Order it separately. (Refer to page 16.)

⚠ Caution

[CE-compliant products]
EMC compliance was tested by combining the electric actuator LER series and the controller LEC series.
The EMC depends on the configuration of the customer's control panel and the relationship with other electrical equipment and wiring. Therefore conformity to the EMC directive cannot be certified for SMC components incorporated into the customer's equipment under actual operating conditions. As a result it is necessary for the customer to verify conformity to the EMC directive for the machinery and equipment as a whole.

[UL-compliant products]
When conformity to UL is required, the electric actuator and controller/driver should be used with a UL1310 Class 2 power supply.

The actuator and controller/driver are sold as a package.

Confirm that the combination of the controller/driver and the actuator is correct.

<Check the following before use.>
① Check the actuator label for model number.
   This matches the controller/driver.
② Check Parallel I/O configuration matches (NPN or PNP).
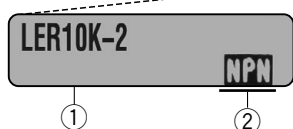
LER10K–2   NPN
   ①   ②

* Refer to the operation manual for using the products.
Please download it via our website, http://www.smcworld.com

Compatible Controllers/Driver

Type	Step data input type	Programless type	Pulse input type
Series	LECP6	LECP1	LECPA
Features	Value (Step data) input Standard controller	Capable of setting up operation (step data) without using a PC or teaching box	Operation by pulse signals
Compatible motor	Step motor (Servo/24 VDC)	Step motor (Servo/24 VDC)	
Maximum number of step data	64 points	14 points	—
Power supply voltage	24 VDC		
Reference page	Page 15	Page 28	Page 34

SMC

Specifications

Step Motor (Servo/24 VDC)

	Model		LER□10K	LER□10J	LER□30K	LER□30J	LER□50K	LER□50J
Actuator specifications	**Basic type**	**Rotation angle [°]**	310		320			
		Max. rotating torque [N·m]	0.3	0.2	1.2	0.8	10	6.6
		Max. pushing torque [N·m] Note 1) 3)	0.15	0.1	0.6	0.4	5	3.3
		Max. moment of inertia [kg·m²] Note 2)	0.0040	0.0018	0.027	0.012	0.10	0.04
		Angular speed [°/sec] Note 2) 3)	20 to 280	30 to 420	20 to 280	30 to 420	20 to 280	30 to 420
		Pushing speed [°/sec]	20	30	20	30	20	30
	Max. angular acceleration/deceleration [°/sec²] Note 2)		3,000					
	Backlash [°]		±0.5					
	Positioning repeatability [°]		±0.05					
	Impact/Vibration resistance [m/s²] Note 4)		150/30					
	Actuation type		Special worm gear + Belt drive					
	Max. operating frequency [c.p.m]		60					
	Operating temp. range [°C]		5 to 40					
	Operating humidity range [%RH]		90 or less (No condensation)					
	Weight [kg]	**Basic type**	0.49		1.1		2.2	
		High precision type	0.52		1.2		2.4	
External stopper type	**Rotation angle [°]**	**-2/ arm (1 pc.)**	180					
		-3/ arm (2 pcs.)	90					
	Repeatability at the end [°]/ with external stopper		±0.01					
	External stopper setting range [°]		±2					
	Weight [kg]	**-2/external arm (1 pc.)** **Basic type**	0.55		1.2		2.5	
		High precision type	0.61		1.4		2.7	
		-3/external arm (1 pc.) **Basic type**	0.57		1.2		2.6	
		High precision type	0.63		1.4		2.8	
Electric specifications	**Motor size**		□20		□28		□42	
	Motor type		Step motor (Servo/24 VDC)					
	Encoder		Incremental A/B phase (800 pulse/rotation)					
	Power supply [V]		24 VDC ±10%					
	Power consumption [W] Note 5)		11		22		34	
	Standby power consumption when operating [W] Note 6)		7		12		13	
	Max. instantaneous power consumption [W] Note 7)		14		42		57	

Note 1) Pushing force accuracy is LER10: ±30% (F.S.), LER30: ±25% (F.S.), LER50: ±20% (F.S.).
Note 2) The angular acceleration, angular deceleration and angular speed may fluctuate due to variations in the inertia moment.
Refer to page 3 "Moment of Inertia—Angular Acceleration/Deceleration, Effective Torque—Angular Speed" graphs for confirmation.
Note 3) The speed and force may change depending on the cable length, load and mounting conditions. Furthermore, if the cable length exceeds 5 m, then it will decrease by up to 10% for each 5 m. (At 15 m: Reduced by up to 20%)
Note 4) Impact resistance: No malfunction occurred when the slide table was tested with a drop tester in both an axial direction and a perpendicular direction to the lead screw. (Test was performed with the actuator in the initial state.)
Vibration resistance: No malfunction occurred in a test ranging between 45 to 2000 Hz. Test was performed in both an axial direction and a perpendicular direction to the lead screw. (Test was performed with the actuator in the initial state.)
Note 5) The power consumption (including the controller) is for when the actuator is operating.
Note 6) The standby power consumption when operating (including the controller) is for when the actuator is stopped in the set position during operation.
Note 7) The maximum instantaneous power consumption (including the controller) is for when the actuator is operating. This value can be used for the selection of the power supply.

Table Rotation Angle Range

Home position mark
Stroke end (Home position) Note 3)
Home position mark
Dowel pin hole
Home position (Stroke end)
Note 2)
LER10/310°
LER30, 50/320°
Table operating range Note 1)

External stopper: 180°

Adjuster bolt adjustment range   Adjuster bolt adjustment range
±2°   ±2°
180°

External stopper: 90°
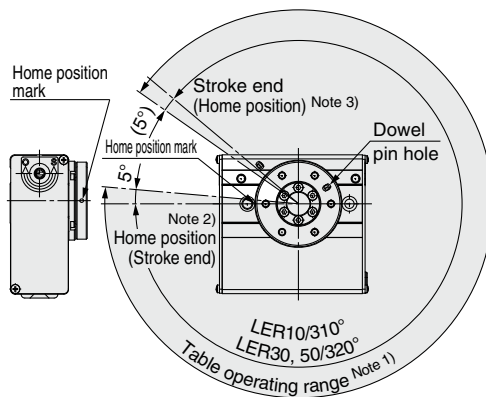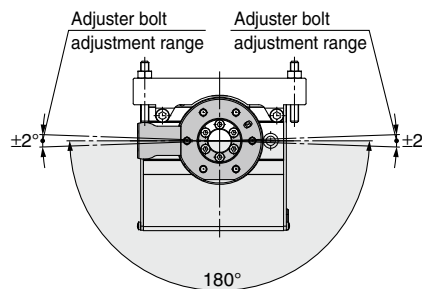
Adjuster bolt adjustment range   Adjuster bolt adjustment range
±2°   ±2°
90°   90°
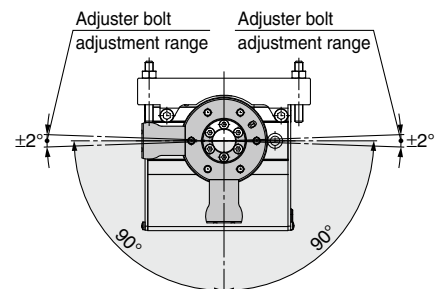
∗ The figures show the origin position for each actuator.

Note 1) Range within which the table can move when it returns to origin.
Make sure a workpiece mounted on the table does not interfere with the workpieces and facilities around the table.
Note 2) Position after return to origin.
Note 3) The number in brackets indicates when the direction of return to origin has changed.

Series *LER*

Construction
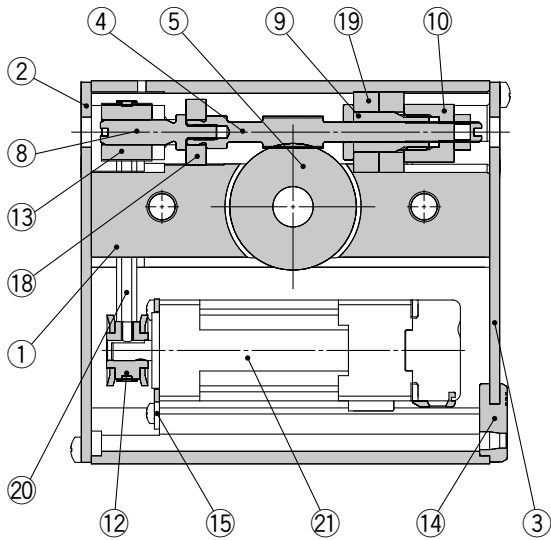
External stopper type
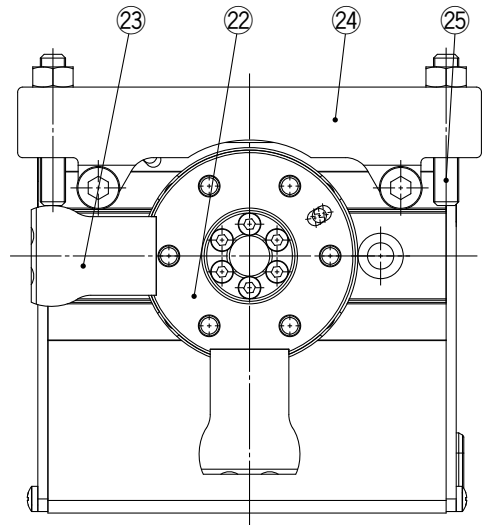
Basic type
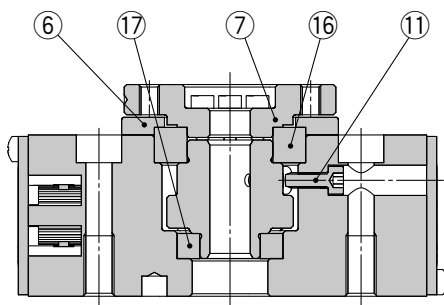
High precision type
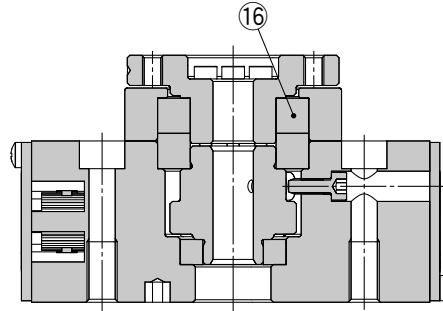
Component Parts

No.	Description	Material	Note
1	**Body**	Aluminum alloy	Anodized
2	**Side plate A**	Aluminum alloy	Anodized
3	**Side plate B**	Aluminum alloy	Anodized
4	**Worm screw**	Stainless steel	Heat treated, specially treated
5	**Worm wheel**	Stainless steel	Heat treated, specially treated
6	**Bearing cover**	Aluminum alloy	Anodized
7	**Table**	Aluminum alloy	
8	**Joint**	Stainless steel	
9	**Bearing holder**	Aluminum alloy	
10	**Bearing retainer**	Aluminum alloy	
11	**Home position bolt**	Carbon steel	
12	**Pulley A**	Aluminum alloy	
13	**Pulley B**	Aluminum alloy	
14	**Grommet**	NBR	
15	**Motor plate**	Carbon steel	
16	**Basic type** — Deep groove ball bearing / **High precision type** — Special ball bearing	—	
17	**Deep groove ball bearing**	—	
18	**Deep groove ball bearing**	—	
19	**Deep groove ball bearing**	—	
20	**Belt**	—	
21	**Step motor (Servo/24 VDC)**	—	

Component Parts

No.	Description	Material	Note
22	**Table**	Aluminum alloy	Anodized
23	**Arm**	Carbon steel	Heat treated, electroless nickel treated
24	**Holder**	Aluminum alloy	Anodized
25	**Adjuster bolt**	Carbon steel	Heat treated, chromate treated

SMC

Model Selection

Step Motor (Servo/24 VDC)

LER

LECP6

LEC-G

LECP1

LECPA

Specific Product Precautions

Dimensions

LER□10□ (Rotation angle: 310°)

3H8 (⁺⁰·⁰¹⁴ ₀) depth 3.8

3H8 (⁺⁰·⁰¹⁴ ₀) depth 4

6 x M4 x 0.7 x 6

45°

15 2 41

30°

51

2 27

52 32

2 x ø9 depth of counterbore
5.5 depth

2 x ø5.2 (through)

Home position mark

Manual override screw
(Both sides)

6

H1

16

0.2

H2

32

0.2

65.8

76

Effective length of accuracy = 2

Effective length of accuracy = 7

ø43h8 (₀ ₋₀.₀₃₉)

ø42h8 (₀ ₋₀.₀₃₉)

ø18H8 (⁺⁰·⁰²⁷ ₀)

ø8 (through)

2 x ø5

20

ø15H8 (⁺⁰·⁰²⁷ ₀)

2.1 83 2.1

≈ 240 (Motor cable entry: Entry on the left side)

≈ 300 (Motor cable entry: Basic type)

20

3H8 (⁺⁰·⁰¹⁴ ₀) depth 4

2 x M6 x 1.0 x 12

2 14

Dimensions [mm]

Model	H1	H2
LER10	10	3.5
LERH10	17	10.5

LER□10-2 (Rotation angle: 180°)
LER□10-3 (Rotation angle: 90°)

3H8 (⁺⁰·⁰¹⁴ ₀) depth 4

92

4

2 x M5 x 0.8 (Adjuster bolt)

6 x M4 x 0.7 x 6

15 2 41 5

4

14

30°

33.5

ø88.5 (Arm operating range)

≈ 93 (at max. adjuster bolt length)

51

15.6

20

52

Note) Not applicable to 180° specification (LER□10-2)

2 x ø9 depth of counterbore
5.5 depth

2 x ø5.2 (through)

32

Manual override screw
(Both sides)

4.8

H3

0.5

6

H1

16

0.2 8.5

H2

32

0.2

65.8

76

Effective length of accuracy = 2

Effective length of accuracy = 7

ø43h8 (₀ ₋₀.₀₃₉)

ø42h8 (₀ ₋₀.₀₃₉)

ø18H8 (⁺⁰·⁰²⁷ ₀)

ø8 (through)

2 x ø5

20

ø15H8 (⁺⁰·⁰²⁷ ₀)

2.1 83 2.1

≈ 240 (Motor cable entry: Entry on the left side)

≈ 300 (Motor cable entry: Basic type)

20

3H8 (⁺⁰·⁰¹⁴ ₀) depth 4

2 x M6 x 1.0 x 12

2 14

Dimensions [mm]

Model	H1	H2	H3
LER10	10	3.5	9
LERH10	17	10.5	16

SMC

8

Series *LER*

Dimensions

LER□30□ (Rotation angle: 320°)

4H8 ($^{+0.018}_{0}$) depth 4.8
4H8 ($^{0}_{-0.018}$) depth 5
6 x M5 x 0.8 x 8
45°
30°
23
2
49
2
39
66
2 x ø6.8 (through)
2 x ø11 depth of counterbore
6.5 depth
75
48

Home position mark
Manual override screw (Both sides)
8
H1
0.2
H2
20
40
0.2
88.2
102

ø64h8 ($^{0}_{-0.046}$)
ø63h8 ($^{0}_{-0.046}$)
ø32H8 ($^{+0.039}_{0}$)
ø17 (through)
2 x ø5
Effective length of accuracy = 8
Effective length of accuracy = 2
20
ø22H8 ($^{+0.033}_{0}$)
2.4
107
2.4

≈ 250 (Motor cable entry: Entry on the left side)
≈ 250 (Motor cable entry: Basic type)
20

4H8 ($^{+0.018}_{0}$) depth 5
2 x M8 x 1.25 x 16
2
25

Dimensions [mm]

Model	H1	H2
LER30	13	4.5
LERH30	22	13.5

LER□30-2 (Rotation angle: 180°)
LER□30-3 (Rotation angle: 90°)

127
5.5
6 x M5 x 0.8 x 8
2 x M6 x 1.0 (Adjuster bolt)
14.5
5.2
23
2
49
19.5
46
66
30°
4H8 ($^{+0.018}_{0}$) depth 5
126 (at max. adjuster bolt length)
ø123.2 (Arm operating range)
Note) Not applicable to 180° specification (LER□30-2)
75
48
2 x ø11 depth of counterbore
6.5 depth
2 x ø6.8 (through)

ø64h8 ($^{0}_{-0.046}$)
ø63h8 ($^{0}_{-0.046}$)
ø32H8 ($^{+0.039}_{0}$)
ø17 (through)
2 x ø5
Effective length of accuracy = 8
Effective length of accuracy = 2
20
ø22H8 ($^{+0.033}_{0}$)
2.4
107
2.4

Manual override screw (Both sides)
6
H3
0.5
8
H1
0.2
11.5
H2
20
40
0.2
88.2
102

≈ 250 (Motor cable entry: Entry on the left side)
≈ 250 (Motor cable entry: Basic type)
20

4H8 ($^{+0.018}_{0}$) depth 5
2 x M8 x 1.25 x 16
2
25

Dimensions [mm]

Model	H1	H2	H3
LER30	13	4.5	12.5
LERH30	22	13.5	21.5

9

SMC

Electric Rotary Table *Series LER*

Model Selection

Step Motor (Servo/24 VDC)

LER

LECP6

LEC-G

LECP1

LECPA

Specific Product Precautions

Dimensions

LER□50□ (Rotation angle: 320°)

6 x M6 x 1.0 x 10

5H8 ($^{+0.018}_{0}$) depth 5.3

5H8 ($^{+0.018}_{0}$) depth 5.5

45°

26.5   2   57

30°

85

2

45

2 x ø8.5 (through)

90

55

ø14 depth of counterbore
8.5 depth

Home position mark

Manual override screw
(Both sides)

10   **H1**

H2   52

0.2

26

0.2

114.2

133

ø76h8 ($^{0}_{-0.046}$)

ø74h8 ($^{0}_{-0.046}$)

ø35H8 ($^{+0.039}_{0}$)

ø20 (through)

Effective length of accuracy = 11

Effective length of accuracy = 2

2 x ø5

20

ø26H8 ($^{+0.033}_{0}$)

3   127   3

≈ 230 (Motor cable entry: Entry on the left side)

≈ 240 (Motor cable entry: Basic type)

20

5H8 ($^{+0.018}_{0}$) depth 5.5

2 x M10 x 1.5 x 20

2   30

Dimensions [mm]

Model	H1	H2
LER50	16	5.5
LERH50	26	15.5

LER□50-2 (Rotation angle: 180°)
LER□50-3 (Rotation angle: 90°)

6 x M6 x 1.0 x 10

6

152

2 x M8 x 1.25 (Adjuster bolt)

5H8 ($^{+0.018}_{0}$) depth 5.5

6.8

19

22

26.5   2   57

30°

56

85

≈ 158 (at max. adjuster bolt length)

ø146 (Arm operating range)
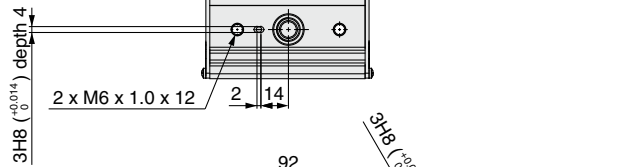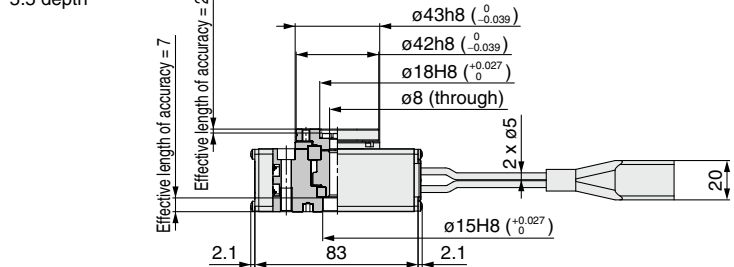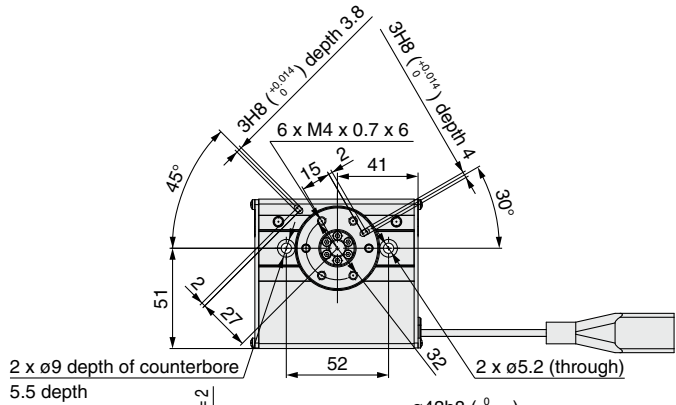
Note) Not applicable to 180° specification (LER□50-2)

90

55

2 x ø14 depth of counterbore
8.5 depth

2 x ø8.5 (through)

Manual override screw
(Both sides)

7.5

0.5   10

H1

H3

14.5

H2   52

0.2

26

0.2

114.2

133

ø76h8 ($^{0}_{-0.046}$)

ø74h8 ($^{0}_{-0.046}$)

ø35H8 ($^{+0.039}_{0}$)

ø20 (through)

Effective length of accuracy = 11

Effective length of accuracy = 2

2 x ø5

20

ø26H8 ($^{+0.033}_{0}$)

3   127   3

≈ 230 (Motor cable entry: Entry on the left side)

≈ 240 (Motor cable entry: Basic type)

20

5H8 ($^{+0.018}_{0}$) depth 5.5

2 x M10 x 1.5 x 20

2   30

Dimensions [mm]

Model	H1	H2	H3
LER50	16	5.5	15.5
LERH50	26	15.5	25.5
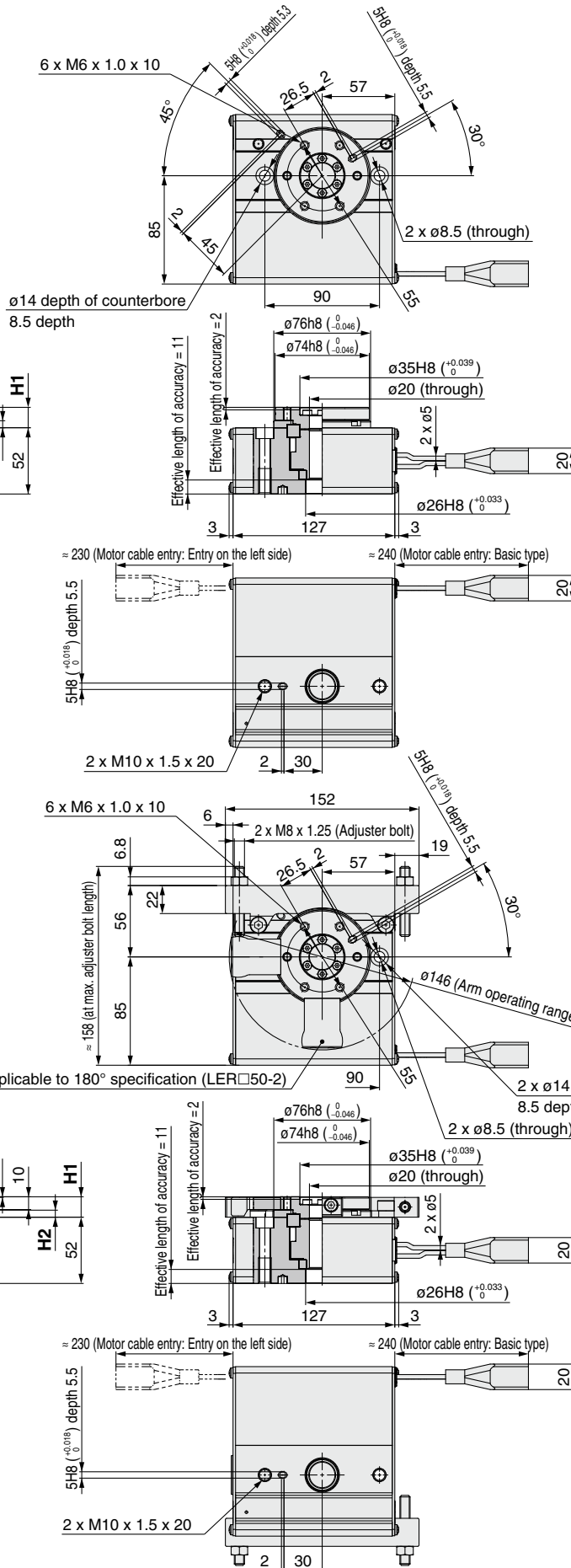
Electric Rotary Table/
Specific Product Precautions 1

Be sure to read before handling. Refer to back cover for Safety Instructions and the Operation Manual for Electric Actuator Precautions.
Please download it via our website, http://www.smcworld.com

Design/Selection

⚠Warning

1. If the operating conditions involve load fluctuations, ascending/descending movements, or changes in the frictional resistance, ensure that safety measures are in place to prevent injury to the operator or damage to the equipment.
Failure to provide such measures could accelerate the operation speed, which may be hazardous to humans, machinery, and other equipment.

2. Power failure may result in a decrease in the pushing force; ensure that safety measures are in place to prevent injury to the operator or damage to the equipment.
When the product is used for clamping, the clamping force could be decreased due to power failure, potentially creating a hazardous situation in which the workpiece is released.

⚠Caution

1. If the operating speed is set too fast and the moment of inertia is too large, the product could be damaged.
Set appropriate product operating conditions in accordance with the model selection procedure.

2. If more precise repeatability of the rotation angle is required, use the product with an external stopper, with repeatability of ±0.01° (180° and 90° with adjustment of ±2°) or by directly stopping the workpiece using an external object utilizing the pushing operation.
When using angle adjustment, the initially set rotation angle may change.

3. When using the electric rotary table with an external stopper, or by directly stopping the load externally, ensure that the [Pushing operation] is utilized.
Also, ensure that the workpiece is not impacted externally during the positioning operation or in the range of positioning operation.

Mounting

⚠Warning

1. Do not drop or hit the electric rotary table to avoid scratching and denting the mounting surfaces.
Even slight deformation can cause the deterioration of accuracy and operation failure.

2. Tighten the load mounting screws to the specified torque.
Tightening to a torque greater than the specified range may cause malfunction, and insufficient tightening may cause displacement.

Mounting the workpiece to the electric rotary table

The load should be mounted with the torque specified in the following table by screwing the bolt into the mounting female thread.

Model	Bolt	Max. tightening torque [N·m]
LER☐10	M4 x 0.7	1.4
LER☐30	M5 x 0.8	3.0
LER☐50	M6 x 1	5.0

Mounting

⚠Warning

3. When mounting the electric rotary table, use screws with adequate length and tighten them with adequate torque within the specified torque range.
Tightening the screws with a higher torque than recommended may cause malfunction, whilst the tightening with a lower torque can cause the displacement of the mounting position or in extreme conditions the actuator could become detached from its mounting position.

Through-hole mounting
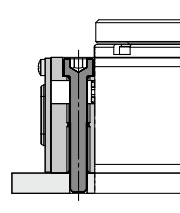
Body mounting/bottom   **Body mounting/top**
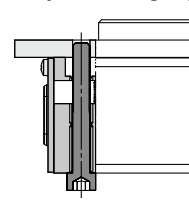
Model	Bolt	Max. tightening torque [N·m]
LER☐10	M5 x 0.8	3.0
LER☐30	M6 x 1	5.0
LER☐50	M8 x 1.25	12.0

Body tapped mounting

Body mounting/bottom
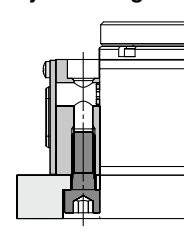
Model	Bolt	Max. tightening torque [N·m]	Max. screw-in depth [mm]
LER☐10	M6 x 1	5.0	12
LER☐30	M8 x 1.25	12.0	16
LER☐50	M10 x 1.5	25.0	20

4. The mounting face has holes and slots for positioning. Use them for accurate positioning of the electric rotary table if required.

5. If it is necessary to operate the electric rotary table when it is not energized, use the manual override screws.
When the product is operated with the manual override screws, check the position of the manual override screws of the product, and leave necessary space. Do not apply excessive torque to the manual override screws that could lead to damage and malfunction of the product.

SMC

Model Selection

Step Motor (Servo/24 VDC)

LER

LECP6

LEC-G

LECP1

LECPA

Specific Product Precautions

Series LER
Electric Rotary Table/
Specific Product Precautions 2

Be sure to read before handling. Refer to back cover for Safety Instructions and the Operation Manual for Electric Actuator Precautions.
Please download it via our website, http://www.smcworld.com

Handling

⚠Caution

1. When an external guide is used, connect it in such a way that no impact or load is applied to it.
Use a free moving connector (such as a coupling).

2. INP output signal
1) Positioning operation
When the product comes within the set range by step data [In position], the INP output signal will turn on.
Initial value: Set to [0.50] or higher.
2) Pushing operation
When the effective force exceeds the [Trigger LV] value (including thrust during operation), the INP output signal will turn on.
The [Trigger LV] should be set between 40% and [Pushing force].
a) To ensure that the clamping and external stop is achieved by [Pushing force], it is recommended that the [Trigger LV] be set to the same value as the [Pushing force].
b) When the [Pushing force] and [Trigger LV] are set less than the specified range, the INP output signal will turn on from the pushing start position.

3. When the workpiece is to be stopped by the electric rotary actuator with an external stopper or directly by an external object, utilize the "pushing operation". Do not stop the table with an external stopper or external object by using in the range of the "positioning operation mode".
If the product is used in the positioning operation mode, there may be galling or other problems when the product/workpiece comes into contact with the external stopper or external object.

4. When the table is stopped by the pushing operation mode (stopping/clamping), set the product to a position of at least 1° away from the workpiece. (This position is referred to as the pushing start position.)
If the pushing operations start position (stopping or clamping) is set to the same position as the external stop position, the following alarms may be generated and operation may become unstable.
a. "Posn failed" alarm is generated.
It is not possible to reach the pushing operation start position within the target time.
b. "Pushing ALM" alarm is generated.
The product is pushed back from a pushing start position after starting to push.
c. "Deviation over flow" alarm is generated.
Displacement exceeding the specified value is generated at the pushing start position.

5. There is no backlash effect when the product is stopped externally by pushing operation.
For the return to origin, the origin position is set by the pushing operation.

6. For the specification with an external stopper, an angle adjustment bolt is provided as standard.
The rotation angle adjustment range is ±2° from the angle rotation end.
If the angle adjustment range is exceeded, the rotation angle may change due to insufficient strength of the external stopper.
One revolution of the adjustment bolt is approximately equal to 1° of rotation.

7. When mounting the product, keep a 40 mm or longer diameter for bends in the cable.

Maintenance

⚠Danger

1. The high precision type bearing is assembled by pressing into position. It is not possible to disassemble it.

SMC

12

Controller/Driver

Step Motor (Servo/24 VDC)
Series *LECP6*

Series *LEC-G*

Step Motor (Servo/24 VDC)
Series *LECP1*

Step Motor (Servo/24 VDC)
Series *LECPA*

Model Selection

Step Motor (Servo/24 VDC)

LER

LECP6

LEC-G

LECP1

LECPA

Specific Product Precautions

Controller (Step Data Input Type)
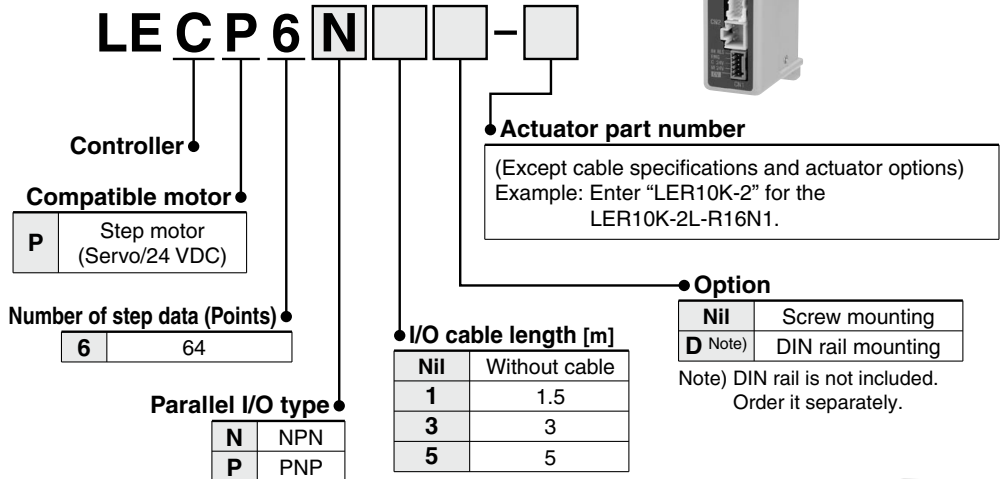## Step Motor (Servo/24 VDC)
Series *LECP6*

C€ ℃ ⓊⓁ US RoHS

How to Order

LE [C] [P] [6] [N] [ ] [ ] – [ ]

Controller

Compatible motor

P	Step motor (Servo/24 VDC)

Number of step data (Points)

6	64

Parallel I/O type

N	NPN
P	PNP

I/O cable length [m]

Nil	Without cable
1	1.5
3	3
5	5

Actuator part number

(Except cable specifications and actuator options)
Example: Enter "LER10K-2" for the
LER10K-2L-R16N1.

Option

Nil	Screw mounting
D Note)	DIN rail mounting

Note) DIN rail is not included.
Order it separately.

∗ When controller equipped type is selected when ordering the LE series,
you do not need to order this controller.

The controller is sold as single unit after the compatible actuator is set.

Confirm that the combination of the controller and the actuator is correct.

<Check the following before use.>
① Check that actuator label for model number. This matches the controller.
② Check Parallel I/O configuration matches (NPN or PNP).

LER10K–2   NPN
①   ②

∗ Refer to the operation manual for using the products. Please download it via our website, http://www.smcworld.com

Specifications

Basic Specifications

Item	Specifications
Compatible motor	Step motor (Servo/24 VDC)
Power supply Note 1)	Power voltage: 24 VDC±10% Current consumption: 3 A (Peak 5 A) Note 2) [Including motor drive power, control power, stop, lock release]
Parallel input	11 inputs (Photo-coupler isolation)
Parallel output	13 outputs (Photo-coupler isolation)
Compatible encoder	Incremental A/B phase (800 pulse/rotation)
Serial communication	RS485 (Modbus protocol compliant)
Memory	EEPROM
LED indicator	LED (Green/Red) one of each
Lock control	Forced-lock release terminal Note 3)
Cable length [m]	I/O cable: 5 or less Actuator cable: 20 or less
Cooling system	Natural air cooling
Operating temperature range [°C]	0 to 40 (No freezing)
Operating humidity range [%RH]	90 or less (No condensation)
Storage temperature range [°C]	−10 to 60 (No freezing)
Storage humidity range [%RH]	90 or less (No condensation)
Insulation resistance [MΩ]	Between the housing and SG terminal 50 (500 VDC)
Weight [g]	150 (Screw mounting) 170 (DIN rail mounting)

Note 1) Do not use the power supply of "inrush current prevention type" for the controller power supply. When conformity to UL is required, the electric actuator and controller should be used with a UL1310 Class 2 power supply.
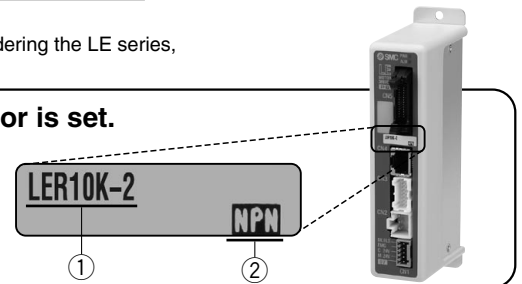Note 2) The power consumption changes depending on the actuator model. Refer to the specifications of actuator for more details.
Note 3) Applicable to non-magnetizing lock.

SMC

Model Selection

Step Motor (Servo/24 VDC)

LER

LECP6

LEC-G

LECP1

LECPA

Specific Product Precautions

How to Mount

a) Screw mounting (LECP6□□-□)
(Installation with two M4 screws)

Ground wire

Mounting direction

Mounting direction
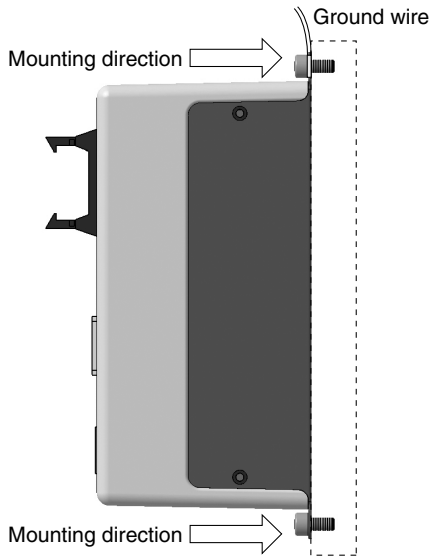
b) DIN rail mounting (LECP6□□D-□)
(Installation with the DIN rail)

DIN rail is locked.

Ground wire

Ground wire

DIN rail

A

DIN rail mounting adapter
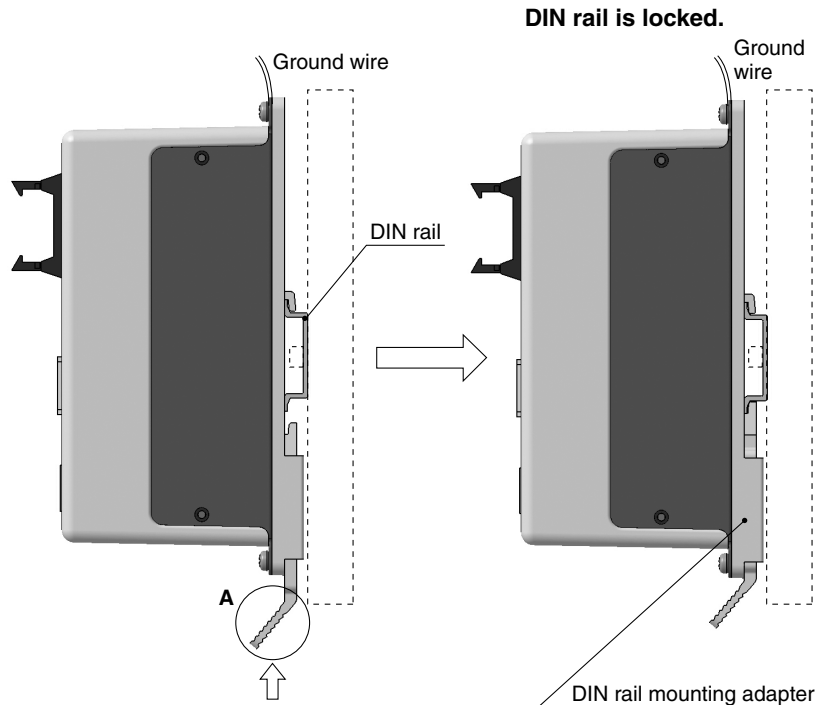
Hook the controller on the DIN rail and press the lever of section **A** in the arrow direction to lock it.

Note) When sizes 30 or 50 of the LER series are used, the space between the controllers should be 10 mm or more.

DIN rail
AXT100-DR-□

∗ For □, enter a number from the "No." line in the table below.
Refer to the dimensions on page 17 for the mounting dimensions.

L

12.5 (Pitch) 5.25 7.5

(35) (25)

5.5 1.25

L Dimension [mm]

No.	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20
L	23	35.5	48	60.5	73	85.5	98	110.5	123	135.5	148	160.5	173	185.5	198	210.5	223	235.5	248	260.5

No.	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40
L	273	285.5	298	310.5	323	335.5	348	360.5	373	385.5	398	410.5	423	435.5	448	460.5	473	485.5	498	510.5

DIN rail mounting adapter
LEC-D0 (with 2 mounting screws)

This should be used when the DIN rail mounting adapter is mounted onto the screw mounting type controller afterwards.

Series *LECP6*

Dimensions

a) Screw mounting (LECP6□□-□)

Power supply LED (Green)
(ON: Power supply is ON.)

Power supply LED (Red)
(ON: Alarm is ON.)

CN5 parallel I/O connector

CN4 serial I/O connector

CN3 encoder connector

CN2 motor power connector

CN1 power supply connector

ø4.5
for body
mounting

35
31
150
132
141

(81.7)
66
1

4.6
for body
mounting
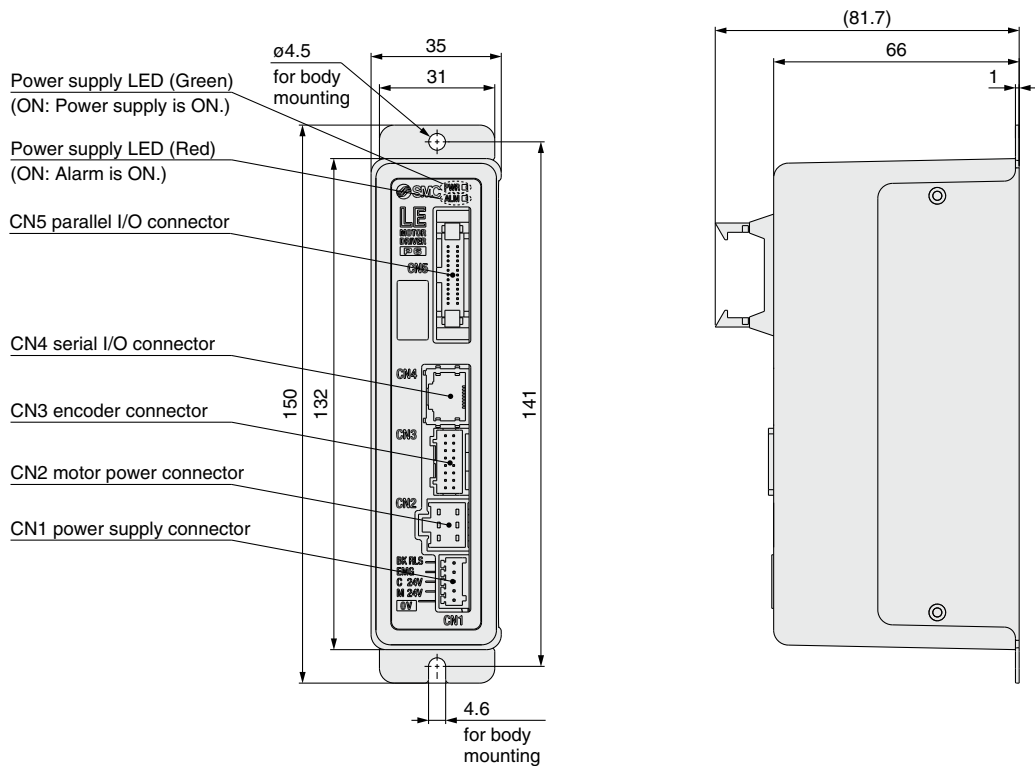
b) DIN rail mounting (LECP6□□D-□)

Refer to page 16 for L dimension and
part number of DIN rail.
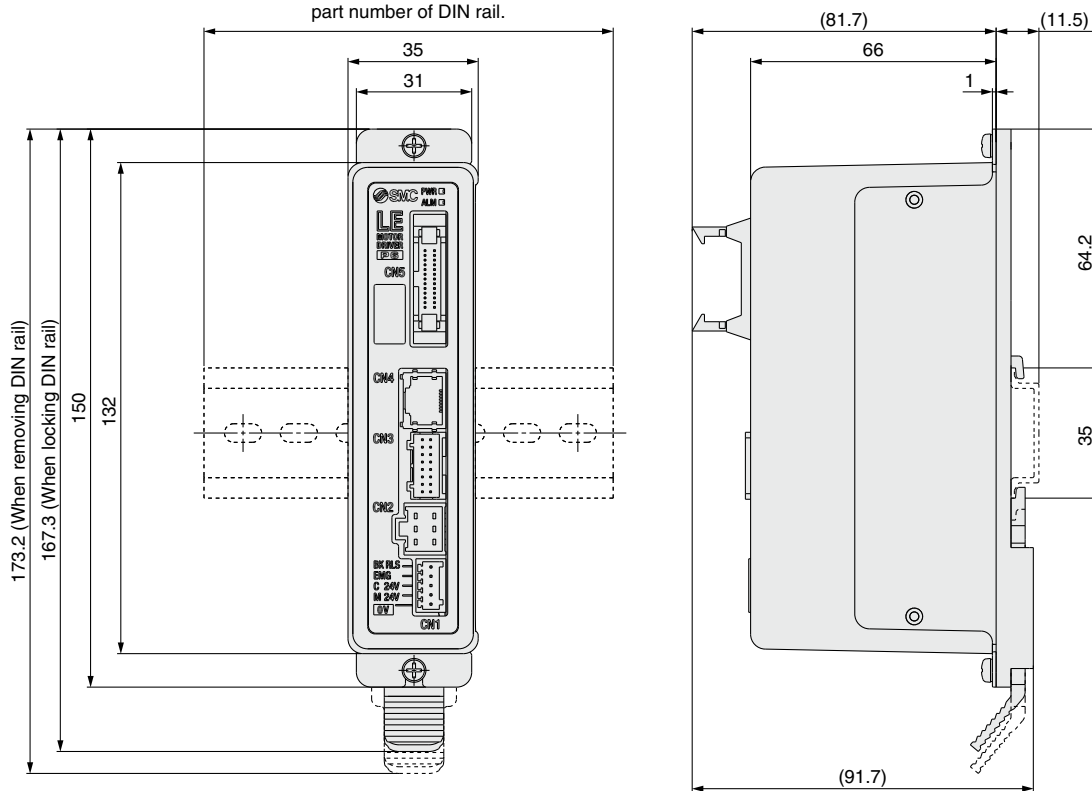
35
31
132
150
173.2 (When removing DIN rail)
167.3 (When locking DIN rail)

(81.7)
66
1
(11.5)
64.2
35
(91.7)

SMC

Model Selection

Step Motor (Selection) (Servo/24 VDC)

LER

LECP6

LEC-G

LECP1

LECPA

Specific Product Precautions

Wiring Example 1

| Power Supply Connector: CN1 | * Power supply plug is an accessory. |

Power supply plug for LECP6

CN1 Power Supply Connector Terminal for LECP6 (PHOENIX CONTACT FK-MC0.5/5-ST-2.5)

Terminal name	Function	Details
0V	Common supply (−)	M24V terminal/C24V terminal/EMG terminal/BK RLS terminal are common (−).
M24V	Motor power supply (+)	Motor power supply (+) supplied to the controller
C24V	Control power supply (+)	Control power supply (+) supplied to the controller
EMG	Stop (+)	Input (+) for releasing the stop
BK RLS	Lock release (+)	Input (+) for releasing the lock

0V
M24V
C24V
EMG
BK RLS

Wiring Example 2

| Parallel I/O Connector: CN5 | * When you connect a PLC, etc., to the CN5 parallel I/O connector, please use the I/O cable (LEC-CN5-□). * The wiring should be changed depending on the type of the parallel I/O (NPN or PNP). |

Wiring diagram
LECP6N□□-□ (NPN)
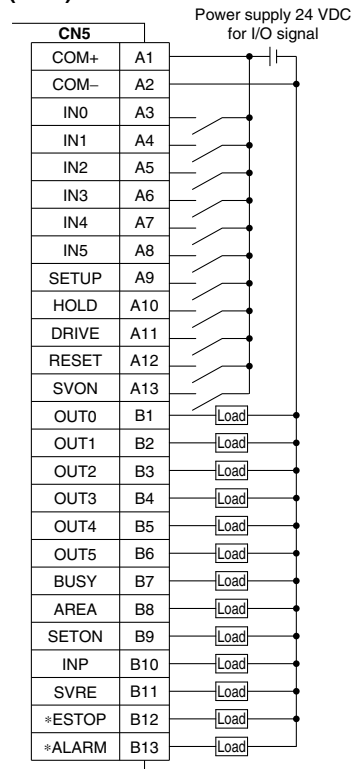
Power supply 24 VDC for I/O signal

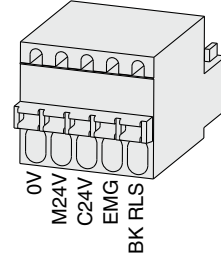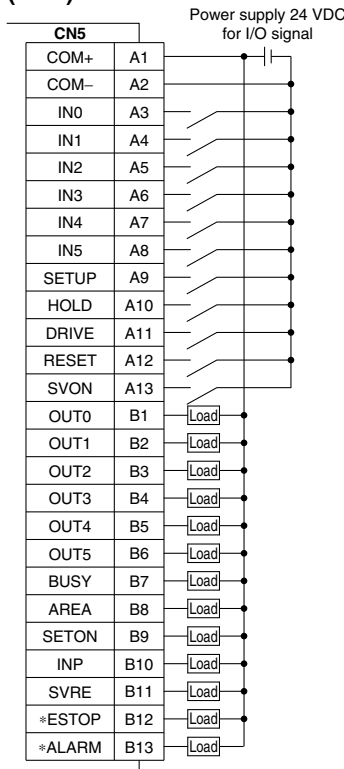| CN5	
COM+	A1
COM−	A2
IN0	A3
IN1	A4
IN2	A5
IN3	A6
IN4	A7
IN5	A8
SETUP	A9
HOLD	A10
DRIVE	A11
RESET	A12
SVON	A13
OUT0	B1
OUT1	B2
OUT2	B3
OUT3	B4
OUT4	B5
OUT5	B6
BUSY	B7
AREA	B8
SETON	B9
INP	B10
SVRE	B11
*ESTOP	B12
*ALARM	B13

LECP6P□□-□ (PNP)

Power supply 24 VDC for I/O signal

CN5	
COM+	A1
COM−	A2
IN0	A3
IN1	A4
IN2	A5
IN3	A6
IN4	A7
IN5	A8
SETUP	A9
HOLD	A10
DRIVE	A11
RESET	A12
SVON	A13
OUT0	B1
OUT1	B2
OUT2	B3
OUT3	B4
OUT4	B5
OUT5	B6
BUSY	B7
AREA	B8
SETON	B9
INP	B10
SVRE	B11
*ESTOP	B12
*ALARM	B13

Input Signal

Name	Details
COM+	Connects the power supply 24 V for input/output signal
COM−	Connects the power supply 0 V for input/output signal
IN0 to IN5	Step data specified Bit No. (Input is instructed in the combination of IN0 to 5.)
SETUP	Instruction to return to origin
HOLD	Operation is temporarily stopped
DRIVE	Instruction to drive
RESET	Alarm reset and operation interruption
SVON	Servo ON instruction

Output Signal

Name	Details
OUT0 to OUT5	Outputs the step data no. during operation
BUSY	Outputs when the actuator is moving
AREA	Outputs within the step data area output setting range
SETON	Outputs when returning to origin
INP	Outputs when target position or target force is reached (Turns on when the positioning or pushing is completed.)
SVRE	Outputs when servo is on
*ESTOP Note)	Not output when EMG stop is instructed
*ALARM Note)	Not output when alarm is generated

Note) Signal of negative-logic circuit ON (N.C.)

Step Data Setting

1. Step data setting for positioning

In this setting, the actuator moves toward and stops at the target position.
The following diagram shows the setting items and operation. The setting items and set values for this operation are stated below.

2. Step data setting for pushing

The actuator moves toward the pushing start position, and when it reaches that position, it starts pushing with the set force or less.
The following diagram shows the setting items and operation. The setting items and set values for this operation are stated below.
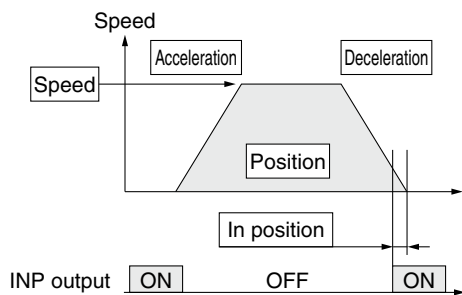
◎ : Need to be set.
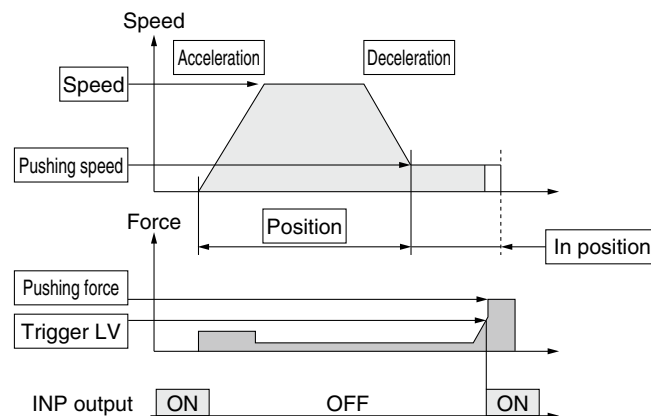○ : Need to be adjusted as required.
— : Setting is not required.

Step Data (Positioning)

Necessity	Item	Details
◎	Movement MOD	When the absolute position is required, set Absolute. When the relative position is required, set Relative.
◎	Speed	Transfer speed to the target position
◎	Position	Target position
○	Acceleration	Parameter which defines how rapidly the actuator reaches the speed set. The higher the set value, the faster it reaches the speed set.
○	Deceleration	Parameter which defines how rapidly the actuator comes to stop. The higher the set value, the quicker it stops.
◎	Pushing force	Set 0. (If values 1 to 100 are set, the operation will be changed to the pushing operation.)
—	Trigger LV	Setting is not required.
—	Pushing speed	Setting is not required.
○	Moving force	Max. torque during the positioning operation (No specific change is required.)
○	Area 1, Area 2	Condition that turns on the AREA output signal.
○	In position	Condition that turns on the INP output signal. When the actuator enters the range of [in position], the INP output signal turns on. (It is unnecessary to change this from the initial value.) When it is necessary to output the arrival signal before the operation is completed, make the value larger.

◎ : Need to be set.
○ : Need to be adjusted as required.

Step Data (Pushing)

Necessity	Item	Details
◎	Movement MOD	When the absolute position is required, set Absolute. When the relative position is required, set Relative.
◎	Speed	Transfer speed to the pushing start position
◎	Position	Pushing start position
○	Acceleration	Parameter which defines how rapidly the actuator reaches the speed set. The higher the set value, the faster it reaches the speed set.
○	Deceleration	Parameter which defines how rapidly the actuator comes to stop. The higher the set value, the quicker it stops.
◎	Pushing force	Pushing force ratio is defined. The setting range differs depending on the electric actuator type. Refer to the operation manual for the electric actuator.
◎	Trigger LV	Condition that turns on the INP output signal. The INP output signal turns on when the generated force exceeds the value. Trigger level should be the pushing force or less.
○	Pushing speed	Pushing speed during pushing. When the speed is set fast, the electric actuator and workpieces might be damaged due to the impact when they hit the end, so this set value should be smaller. Refer to the operation manual for the electric actuator.
○	Moving force	Max. torque during the positioning operation (No specific change is required.)
○	Area 1, Area 2	Condition that turns on the AREA output signal.
◎	In position	Transfer distance during pushing. If the transferred distance exceeds the setting, it stops even if it is not pushing. If the transfer distance is exceeded, the INP output signal will not turn on.

SMC
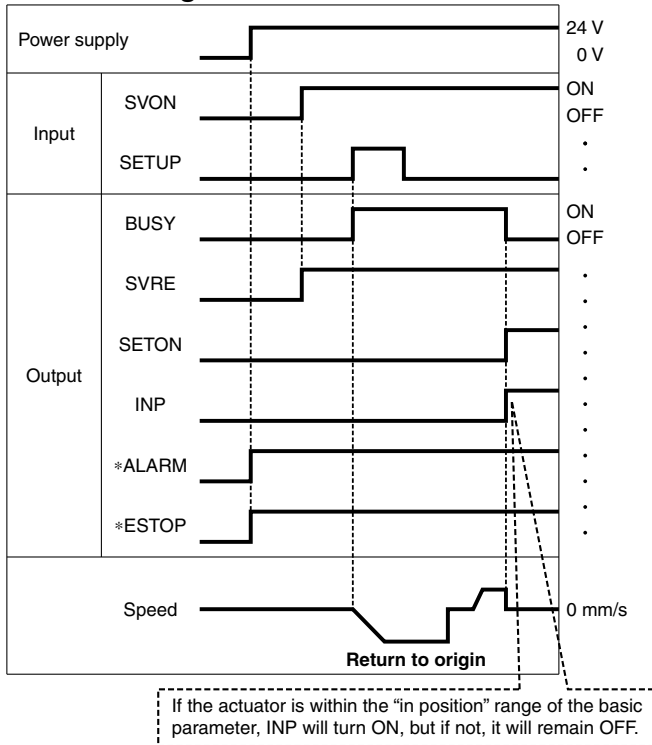
Step Motor (Servo/24 VDC)

LER

LECP6

LEC-G

LECP1

LECPA

Specific Product Precautions

Signal Timing

Return to Origin

If the actuator is within the "in position" range of the basic parameter, INP will turn ON, but if not, it will remain OFF.

∗ "∗ALARM" and "∗ESTOP" are expressed as negative-logic circuit.

Positioning Operation

Scan the step data no.

Output the step data no.

Positioning operation

If the actuator is within the "in position" range of the step data, INP will turn ON, but if not, it will remain OFF.
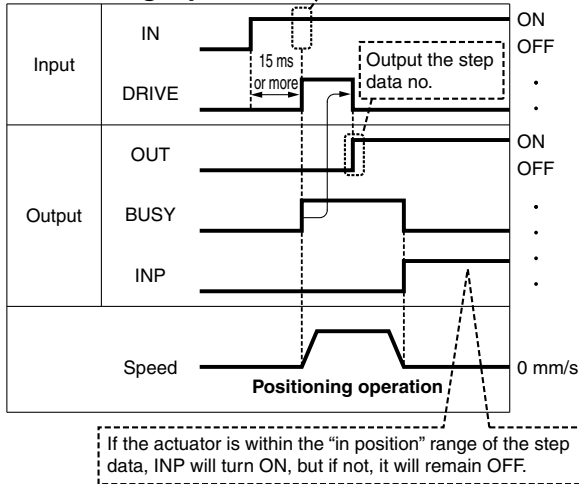
∗ "OUT" is output when "DRIVE" is changed from ON to OFF.
(When power supply is applied, "DRIVE" or "RESET" is turned ON or "∗ESTOP" is turned OFF, all of the "OUT" outputs are OFF.)

Pushing Operation

Scan the step data no.

Output the step data no.

Pushing operation

If the current pushing force exceeds the "trigger LV" value of the step data, the INP signal will turn ON.

HOLD

Slow-down starting point

HOLD during the operation
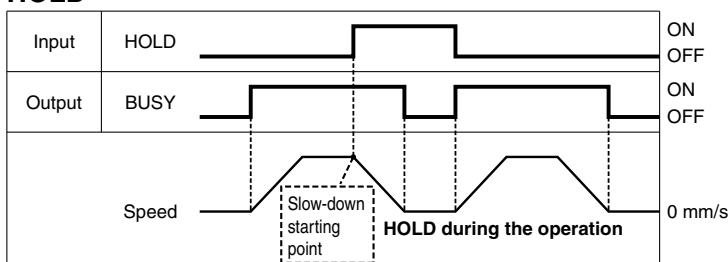
∗ When the actuator is in the positioning range in the pushing operation, it does not stop even if HOLD signal is input.

Reset

Alarm reset

Alarm out

It is possible to identify the alarm group by the combination of OUT signals when the alarm is generated.

∗ "∗ALARM" is expressed as negative-logic circuit.

20
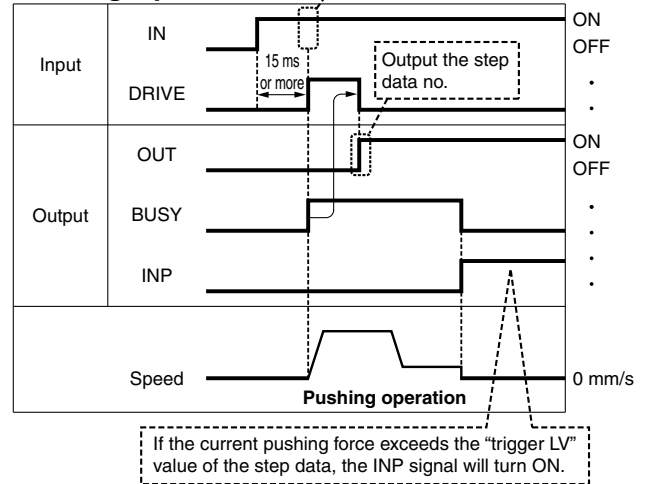
Series *LECP6*

Options: Actuator Cable, I/O Cable

Actuator cable
[Robotic cable, standard cable for step motor (Servo/24 VDC)]

LE－CP－1－☐

Cable length (L) [m]

1	1.5
3	3
5	5
8	8*
A	10*
B	15*
C	20*

∗ Produced upon receipt of order
(Robotic cable only)

Cable type

Nil	Robotic cable (Flexible cable)
S	Standard cable

LE-CP-⅓/Cable length: 1.5 m, 3 m, 5 m

LE-CP-⅜ᴮ/Cable length: 8 m, 10 m, 15 m, 20 m
(∗ Produced upon receipt of order)

Signal	Connector A terminal no.	Cable color	Connector C terminal no.
A	B-1	Brown	2
Ā	A-1	Red	1
B	B-2	Orange	6
B̄	A-2	Yellow	5
COM-A/COM	B-3	Green	3
COM-B/—	A-3	Blue	4

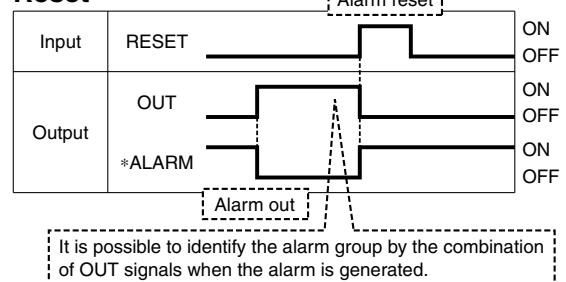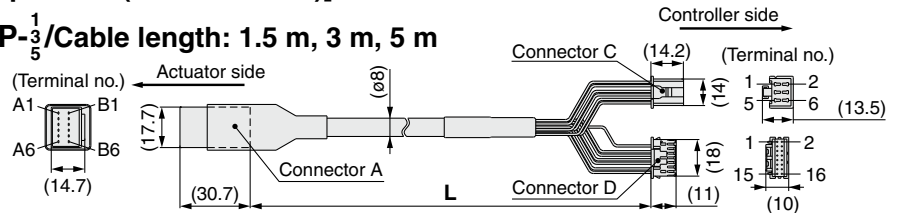| Signal	Connector A terminal no.	Cable color	Connector D terminal no.
Vcc	B-4	Brown	12
GND	A-4	Black	13
Ā	B-5	Red	7
A	A-5	Black	6
B̄	B-6	Orange	9
B	A-6	Black	8
		—	3

I/O cable

LEC－CN5－1

Cable length (L) [m]

1	1.5
3	3
5	5

∗ Conductor size: AWG28
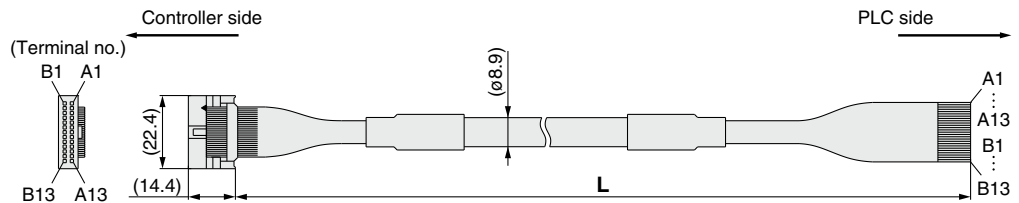
Connector pin no.	Insulation color	Dot mark	Dot color
A1	Light brown	■	Black
A2	Light brown	■	Red
A3	Yellow	■	Black
A4	Yellow	■	Red
A5	Light green	■	Black
A6	Light green	■	Red
A7	Gray	■	Black
A8	Gray	■	Red
A9	White	■	Black
A10	White	■	Red
A11	Light brown	■ ■	Black
A12	Light brown	■ ■	Red
A13	Yellow	■ ■	Black

Connector pin no.	Insulation color	Dot mark	Dot color
B1	Yellow	■ ■	Red
B2	Light green	■ ■	Black
B3	Light green	■ ■	Red
B4	Gray	■ ■	Black
B5	Gray	■ ■	Red
B6	White	■ ■	Black
B7	White	■ ■	Red
B8	Light brown	■ ■ ■	Black
B9	Light brown	■ ■ ■	Red
B10	Yellow	■ ■ ■	Black
B11	Yellow	■ ■ ■	Red
B12	Light green	■ ■ ■	Black
B13	Light green	■ ■ ■	Red
—	Shield		

SMC

Model Selection

Step Motor (Servo/24 VDC)

LER

LECP6

LEC-G

LECP1

LECPA

Specific Product Precautions

Series *LEC*

Controller Setting Kit/LEC-W2

① Controller setting software

② Communication cable

③ USB cable (A-miniB type)

PC

How to Order

LEC－W2

Controller setting kit

(Japanese and English are available.)

Contents

① **Controller setting software (CD-ROM)**

② **Communication cable (With conversion unit)**

③ **USB cable**
   (Cable between the PC and the conversion unit)

Compatible Controller/Driver

Step motor controller (Servo/24 VDC)   **Series LECP6**

Step motor driver (Pulse input type)   **Series LECPA**

Hardware Requirements
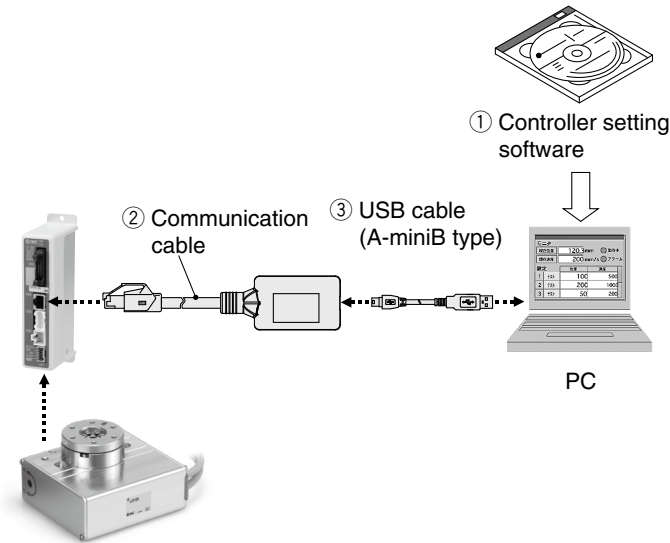
OS	IBM PC/AT compatible machine running Windows®XP (32-bit), Windows®7 (32-bit and 64-bit).
Communication interface	USB 1.1 or USB 2.0 ports
Display	XGA (1024 x 768) or more

∗ Windows® and Windows®7 are registered trademarks of Microsoft Corporation in the United States.
∗ Refer to SMC website for version update information, http://www.smcworld.com

Screen Example

Easy mode screen example

Normal mode screen example

Easy operation and simple setting
● Allowing to set and display actuator step data such as position, speed, force, etc.
● Setting of step data and testing of the drive can be performed on the same page.
● Can be used to jog and move at a constant rate.

Detailed setting
● Step data can be set in detail.
● Signals and terminal status can be monitored.
● Parameters can be set.
● JOG and constant rate movement, return to origin, test operation and testing of forced output can be performed.

SMC

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Teaching Box/LEC-T1

C E   c U L us

RoHS

How to Order

LEC-T1-3 J G ☐

Teaching box ●

Cable length [m] ●

3	3

Initial language ●

J	Japanese
E	English

∗ The displayed language can be changed to English or Japanese.

● Enable switch

Nil	None
S	Equipped with enable switch

∗ Interlock switch for jog and test function

● Stop switch

G	Equipped with stop switch

Enable switch
(Option)

Stop switch

Standard functions
• **Chinese character display**
• **Stop switch is provided.**

Option
• **Enable switch is provided.**

Specifications

Item	Description
Switch	Stop switch, Enable switch (Option)
Cable length [m]	3
Enclosure	IP64 (Except connector)
Operating temperature range [°C]	5 to 50
Operating humidity range [%RH]	90 or less (No condensation)
Weight [g]	350 (Except cable)

[CE-compliant products]
The EMC compliance of the teaching box was tested with the LECP6 series step motor controller (servo/24 VDC) and an applicable actuator.
[UL-compliant products]
When conformity to UL is required, the electric actuator and controller should be used with a UL1310 Class 2 power supply.

Easy Mode

Function	Details
Step data	• Setting of step data
Jog	• Jog operation • Return to origin
Test	• 1 step operation • Return to origin
Monitor	• Display of axis and step data no. • Display of two items selected from Position, Speed, Force.
ALM	• Active alarm display • Alarm reset
TB setting	• Reconnection of axis • Setting of easy/normal mode • Setting step data and selection of items from easy mode monitor

Menu Operations Flowchart

Menu
Data
Monitor
Jog
Test
ALM
TB setting

Data
Step data no. Setting of two items selected below (Position, Speed, Force, Acceleration, Deceleration)

Monitor
Display of step no. Display of two items selected below (Position, Speed, Force)

Jog
Return to origin Jog operation

Test
1 step operation

ALM
Active alarm display Alarm reset

TB setting
Reconnect Easy/Normal Set item

SMC

Normal Mode

Function	Details
Step data	• Step data setting
Parameter	• Parameters setting

Test	• Jog operation/Constant rate movement
	• Return to origin
	• Test drive
	  (Specify a maximum of 5 step data and operate.)
	• Forced output
	  (Forced signal output, Forced terminal output)

Monitor	• Drive monitor • Output signal monitor • Input signal monitor • Output terminal monitor • Input terminal monitor
ALM	• Active alarm display (Alarm reset) • Alarm log record display

File	• Data saving
	  Save the step data and parameters of the controller which is being used for communication (it is possible to save four files, with one set of step data and parameters defined as one file).
	• Load to controller
	  Loads the data which is saved in the teaching box to the controller which is being used for communication.
	• Delete the saved data.

TB setting	• Display setting
	  (Easy/Normal mode)
	• Language setting
	  (Japanese/English)
	• Backlight setting
	• LCD contrast setting
	• Beep sound setting
	• Max. connection axis
	• Distance unit (mm/inch)

Reconnect	• Reconnection of axis

Menu Operations Flowchart

Menu
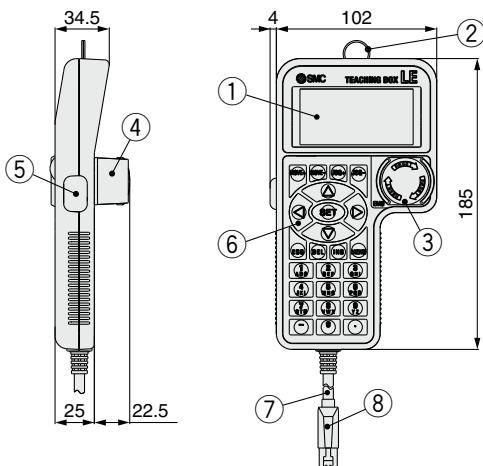Step data
Parameter
Monitor
Test
ALM
File
TB setting
Reconnect

Step data
Step data no.
Movement MOD
Speed
Position
Acceleration
Deceleration
Pushing force
Trigger LV
Pushing speed
Moving force
Area 1, 2
In position

Parameter
Basic
ORIG

Basic setting

ORIG setting

Monitor
Drive
Output signal
Input signal
Output terminal
Input terminal

DRV monitor
Position, Speed, Torque
Step no.
Last step no.

Output signal monitor

Input signal monitor

Output terminal monitor

Input terminal monitor

Test
JOG/MOVE
Return to ORIG
Test drive
Forced output

ALM
Status
ALM Log record

Status
Active alarm display
Alarm reset

ALM Log record display
Log entry display

File
Data saving
Load to controller
File deletion

TB setting
Easy/Normal
Language
Backlight
LCD contrast
Beep
Max. connection axis
Password
Distance unit

Reconnect

Side tabs: Model Selection | Step Motor (Servo/24 VDC) **LER** | **LECP6** | LEC-G | LECP1 | LECPA | Specific Product Precautions

Dimensions

No.	Description	Function
1	**LCD**	A screen of liquid crystal display (with backlight)
2	**Ring**	A ring for hanging the teaching box
3	**Stop switch**	When switch is pushed in, the switch locks and stops. The lock is released when it is turned to the right.
4	**Stop switch guard**	A guard for the stop switch
5	**Enable switch (Option)**	Prevents unintentional operation (unexpected operation) of the jog test function. Other functions such as data change are not covered.
6	**Key switch**	Switch for each input
7	**Cable**	Length: 3 meters
8	**Connector**	A connector connected to CN4 of the controller

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Gateway Unit
Series LEC-G CE c(UL)us RoHS

How to Order

⚠Caution
[CE-compliant products]
EMC compliance was tested by combining the electric actuator LER series and the controller LEC series.
The EMC depends on the configuration of the customer's control panel and the relationship with other electrical equipment and wiring. Therefore conformity to the EMC directive cannot be certified for SMC components incorporated into the customer's equipment under actual operating conditions. As a result it is necessary for the customer to verify conformity to the EMC directive for the machinery and equipment as a whole.

[UL-compliant products]
When conformity to UL is required, the electric actuator and controller should be used with a UL1310 Class 2 power supply.

Gateway unit LEC‑G MJ2 □

Applicable Fieldbus protocols

MJ2	CC-Link Ver. 2.0
DN1	DeviceNet™
PR1	PROFIBUS DP
EN1	EtherNet/IP™

Mounting

| Nil | Screw mounting |
| D Note) | DIN rail mounting |

Note) DIN rail is not included.
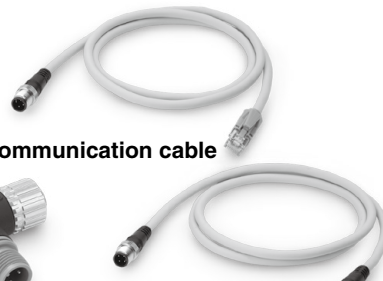Order it separately.

Cable LEC‑CG 1 ‑ L

Cable type

| 1 | Communication cable |
| 2 | Cable between branches |

Cable length

K	0.3 m
L	0.5 m
1	1 m

Communication cable

Cable between branches

Branch connector LEC‑CGD

Branch connector

Terminating resistor LEC‑CGR

Specifications

Model			LEC-GMJ2□		LEC-GDN1□	LEC-GPR1□	LEC-GEN1□
Communication specifications	Applicable system	Fieldbus	CC-Link		DeviceNet™	PROFIBUS DP	EtherNet/IP™
		Version Note 1)	Ver. 2.0		Release 2.0	V1	Release 1.0
	Communication speed [bps]		156 k/625 k/2.5 M/ 5 M/10 M		125 k/250 k/500 k	9.6 k/19.2 k/45.45 k/ 93.75 k/187.5 k/500 k/ 1.5 M/3 M/6 M/12 M	10 M/100 M
	Configuration file Note 2)		—		EDS file	GSD file	EDS file
	I/O occupation area		4 stations occupied (8 times setting)	Input 896 points 108 words Output 896 points 108 words	Input 200 bytes Output 200 bytes	Input 57 words Output 57 words	Input 256 bytes Output 256 bytes
	Power supply for communication	Power supply voltage [V] Note 6)	—		11 to 25 VDC	—	—
		Internal current consumption [mA]	—		100	—	—
	Communication connector specifications		Connector (Accessory)		Connector (Accessory)	D-sub	RJ45
	Terminating resistor		Not included		Not included	Not included	Not included
Power supply voltage [V] Note 6)			24 VDC±10%				
Current consumption [mA]	Not connected to teaching box		200				
	Connected to teaching box		300				
EMG output terminal			30 VDC 1A				
Controller specifications	Applicable controllers		Series LECP6, Series LECA6				
	Communication speed [bps] Note 3)		115.2 k/230.4 k				
	Max. number of connectable controllers Note 4)		12		8 Note 5)	5	12
Accessories			Power supply connector, communication connector			Power supply connector	
Operating temperature range [°C]			0 to 40 (No freezing)				
Operating humidity range [%RH]			90 or less (No condensation)				
Storage temperature range [°C]			−10 to 60 (No freezing)				
Storage humidity range [%RH]			90 or less (No condensation)				
Weight [g]			200 (Screw mounting), 220 (DIN rail mounting)				

Note 1) Please note that the version is subject to change.
Note 2) Each file can be downloaded from the SMC website, http://www.smcworld.com
Note 3) When using a teaching box (LEC-T1-□), set the communication speed to 115.2 kbps.
Note 4) A communication response time for 1 controller is approximately 30 ms.
　　　 Refer to "Communication Response Time Guideline" for response times when several controllers are connected.
Note 5) For step data input, up to 12 controllers connectable.
Note 6) When conformity to UL is required, the electric actuator and controller should be used with a UL1310 Class 2 power supply.

SMC

Gateway Unit *Series LEC-G*

Model Selection

Step Motor (Servo/24 VDC)

LER

LECP6

LEC-G

LECP1

LECPA

Specific Product Precautions

Communication Response Time Guideline

Response time between gateway unit and controllers depends on the number of controllers connected to the gateway unit.
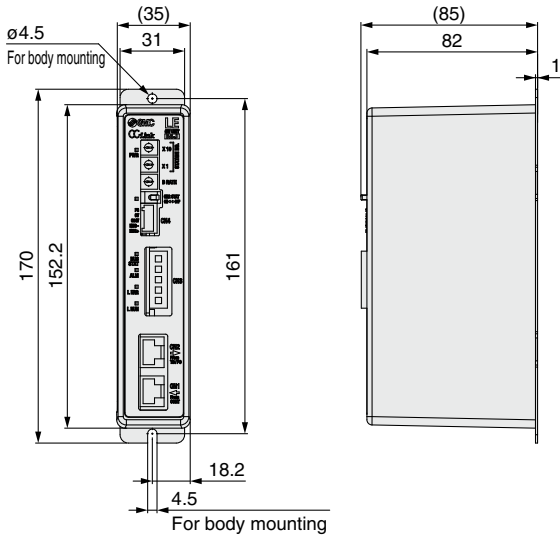For response time, refer to the graph below.

Number of connectable controllers (unit)
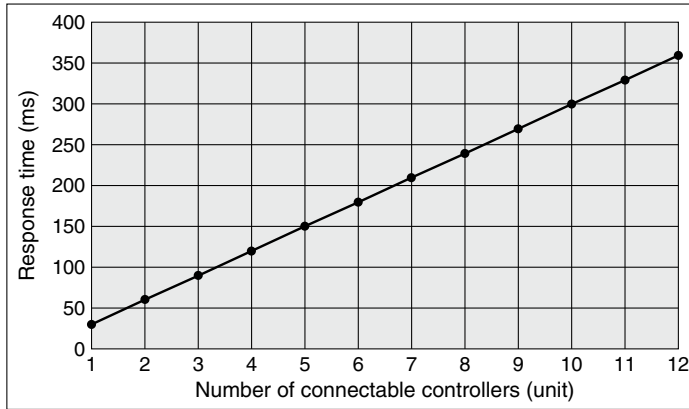
* This graph shows delay times between gateway unit and controllers.
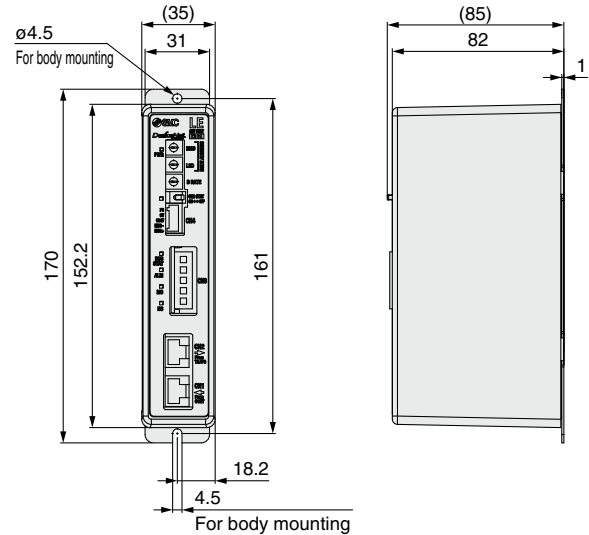Fieldbus network delay time is not included.

Dimensions
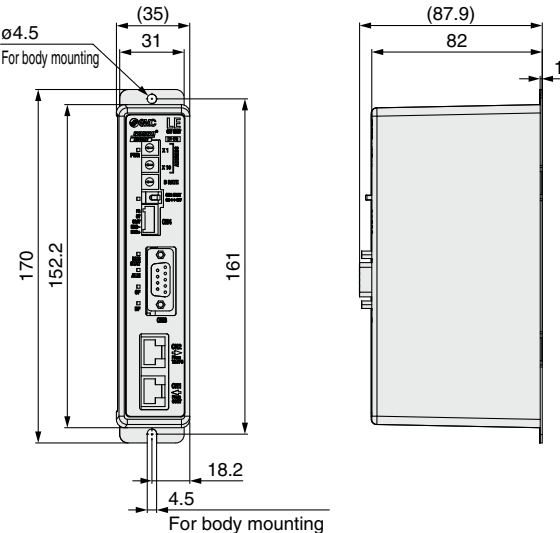
Screw mounting (LEC-G□□□)

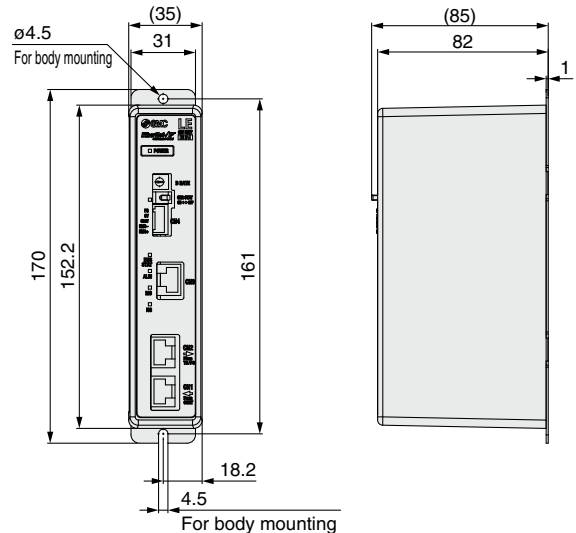**Applicable Fieldbus protocol: CC-Link Ver. 2.0**

Applicable Fieldbus protocol: DeviceNet™

Applicable Fieldbus protocol: PROFIBUS DP
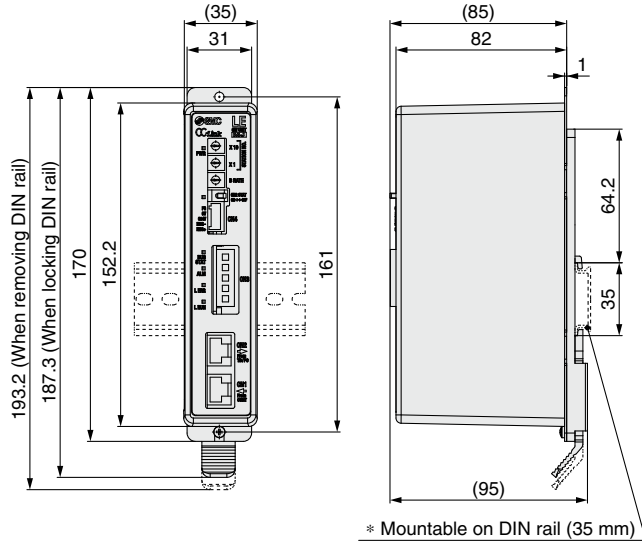

Applicable Fieldbus protocol: EtherNet/IP™

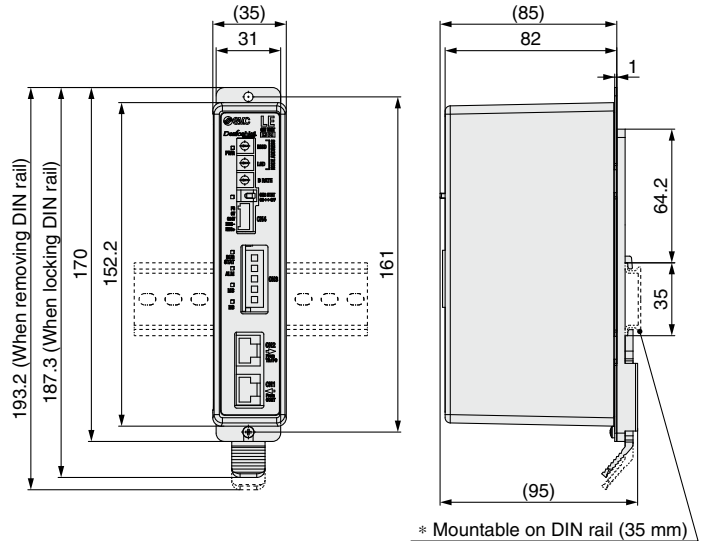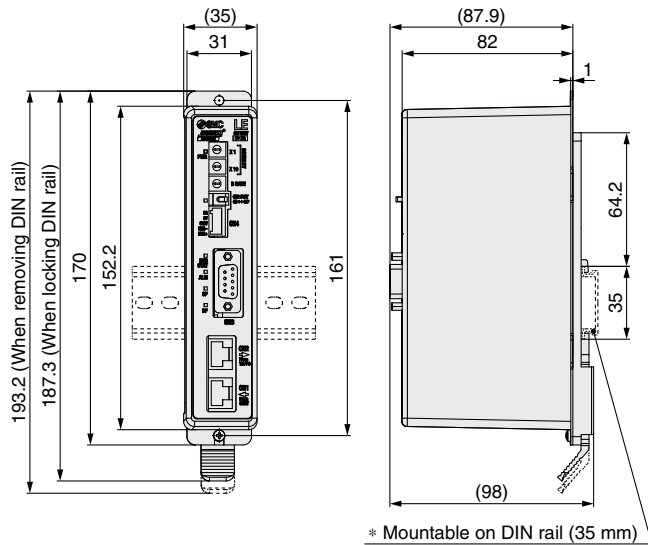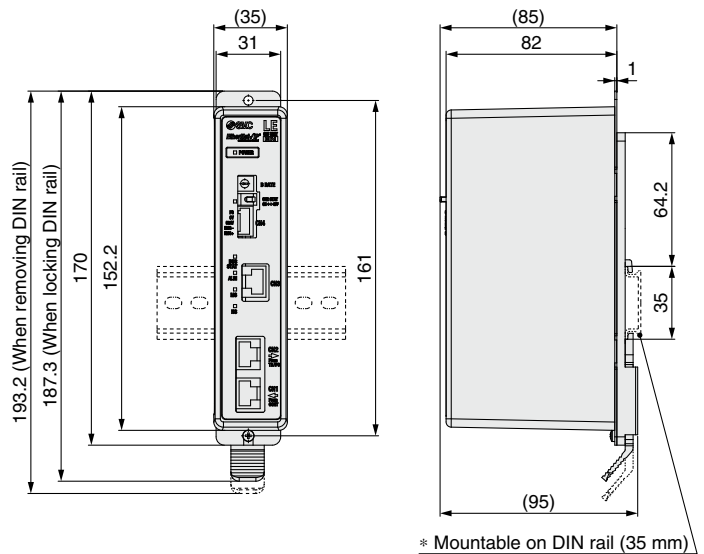■**Trademark** DeviceNet™ is a trademark of ODVA.   EtherNet/IP™ is a trademark of ODVA.

SMC

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Series *LEC-G*

Dimensions

DIN rail mounting (LEC-G□□□D)

Applicable Fieldbus protocol: CC-Link Ver. 2.0

∗ Mountable on DIN rail (35 mm)

Applicable Fieldbus protocol: DeviceNet™

∗ Mountable on DIN rail (35 mm)

Applicable Fieldbus protocol: PROFIBUS DP

∗ Mountable on DIN rail (35 mm)

Applicable Fieldbus protocol: EtherNet/IP™

∗ Mountable on DIN rail (35 mm)

DIN rail
AXT100-DR-□

∗ For □, enter a number from the "No." line in the table below.
Refer to the dimensions above for the mounting dimensions.

L Dimension [mm]

No.	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20
L	23	35.5	48	60.5	73	85.5	98	110.5	123	135.5	148	160.5	173	185.5	198	210.5	223	235.5	248	260.5

No.	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40
L	273	285.5	298	310.5	323	335.5	348	360.5	373	385.5	398	410.5	423	435.5	448	460.5	473	485.5	498	510.5

■**Trademark** DeviceNet™ is a trademark of ODVA. EtherNet/IP™ is a trademark of ODVA.

SMC

Model Selection

Step Motor (Servo/24 VDC)

LER

LECP6

LEC-G

LECP1

LECPA

Specific Product Precautions

Programless Controller
Series *LECP1*

CE c(UL)US

RoHS

How to Order

| LE C P 1 | N | 1 | | – | LER10K-2 |

Controller

Compatible motor

| P | Step motor (Servo/24 VDC) |

Number of step data (Points)

| 1 | 14 (Programless) |

Parallel I/O type

| N | NPN |
| P | PNP |

Option

| Nil | Screw mounting |
| D Note) | DIN rail mounting |

Note) DIN rail is not included.
Order it separately.

I/O cable length [m]

Nil	Without cable
1	1.5
3	3
5	5

Actuator part number

(Except cable specifications and actuator options)
Example: Enter "LER10K-2" for the
LER10K-2L-R11N1.

∗ **When controller equipped type is selected when ordering the LE series, you do not need to order this controller.**

⚠Caution

[CE-compliant products]
EMC compliance was tested by combining the electric actuator LER series and the controller LEC series.
The EMC depends on the configuration of the customer's control panel and the relationship with other electrical equipment and wiring. Therefore conformity to the EMC directive cannot be certified for SMC components incorporated into the customer's equipment under actual operating conditions. As a result it is necessary for the customer to verify conformity to the EMC directive for the machinery and equipment as a whole.

[UL-compliant products]
When conformity to UL is required, the electric actuator and controller should be used with a UL1310 Class 2 power supply.

The controller is sold as single unit after the compatible actuator is set.
Confirm that the combination of the controller and the actuator is correct.

∗ Refer to the operation manual for using the products. Please download it via our website, http://www.smcworld.com

Specifications

Basic Specifications

Item	LECP1
Compatible motor	Step motor (Servo/24 VDC)
Power supply Note 1)	Power supply voltage: 24 VDC ±10%, Max. current consumption: 3A (Peak 5A) Note 2) [Including the motor drive power, control power supply, stop, lock release]
Parallel input	6 inputs (Photo-coupler isolation)
Parallel output	6 outputs (Photo-coupler isolation)
Stop points	14 points (Position number 1 to 14(E))
Compatible encoder	Incremental A/B phase (800 pulse/rotation)
Serial communication	RS485 (Modbus protocol compliant)
Memory	EEPROM
LED indicator	LED (Green/Red) one of each
7-segment LED display Note 3)	1 digit, 7-segment display (Red) Figures are expressed in hexadecimal ("10" to "15" in decimal number are expressed as "A" to "F")
Lock control	Forced-lock release terminal Note 4)
Cable length [m]	I/O cable: 5 or less, Actuator cable: 20 or less
Cooling system	Natural air cooling
Operating temperature range [°C]	0 to 40 (No freezing)
Operating humidity range [%RH]	90 or less (No condensation)
Storage temperature range [°C]	−10 to 60 (No freezing)
Storage humidity range [%RH]	90 or less (No condensation)
Insulation resistance [MΩ]	Between the housing and SG terminal: 50 (500 VDC)
Weight [g]	130 (Screw mounting), 150 (DIN rail mounting)

Note 1) Do not use the power supply of "inrush current prevention type" for the controller input power supply. When conformity to UL is required, the electric actuator and controller should be used with a UL1310 Class 2 power supply.
Note 2) The power consumption changes depending on the actuator model. Refer to the each actuator's operation manual etc. for details.
Note 3) "10" to "15" in decimal number are displayed as follows in the 7-segment LED.
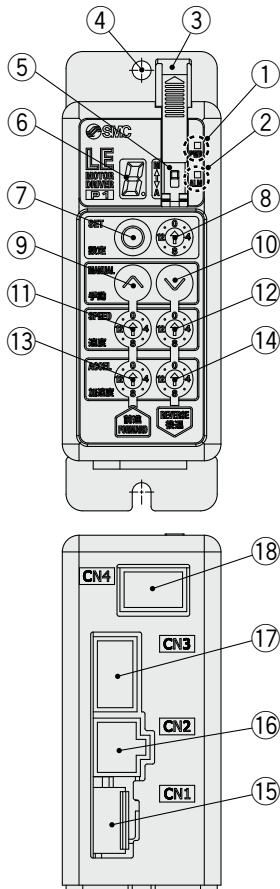
Decimal display	10	11	12	13	14	15
Hexadecimal display	A	b	c	d	E	F

Note 4) Applicable to non-magnetizing lock.

SMC

Series *LECP1*

Controller Details

No.	Display	Description	Details
①	**PWR**	Power supply LED	Power supply ON/Servo ON : Green turns on Power supply ON/Servo OFF: Green flashes
②	**ALM**	Alarm LED	With alarm : Red turns on Parameter setting : Red flashes
③	—	Cover	Change and protection of the mode switch (Close the cover after changing switch)
④	—	FG	Frame ground (Tighten the bolt with the nut when mounting the controller. Connect the ground wire.)
⑤	—	Mode switch	Switch the mode between manual and auto.
⑥	—	7-segment LED	Stop position, the value set by ⑧ and alarm information are displayed.
⑦	**SET**	Set button	Decide the settings or drive operation in Manual mode.
⑧	—	Position selecting switch	Assign the position to drive (1 to 14), and the origin position (15).
⑨	**MANUAL**	Manual forward button	Perform forward jog and inching.
⑩		Manual reverse button	Perform reverse jog and inching.
⑪	**SPEED**	Forward speed switch	16 forward speeds are available.
⑫		Reverse speed switch	16 reverse speeds are available.
⑬	**ACCEL**	Forward acceleration switch	16 forward acceleration steps are available.
⑭		Reverse acceleration switch	16 reverse acceleration steps are available.
⑮	**CN1**	Power supply connector	Connect the power supply cable.
⑯	**CN2**	Motor connector	Connect the motor connector.
⑰	**CN3**	Encoder connector	Connect the encoder connector.
⑱	**CN4**	I/O connector	Connect I/O cable.

How to Mount

Controller mounting shown below.

1. Mounting screw (LECP1□□-□)
(Installation with two M4 screws)

Ground wire

Mounting direction

Mounting direction
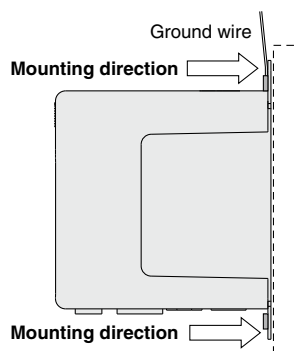
2. Grounding
Tighten the bolt with the nut when mounting the ground wire as shown below.
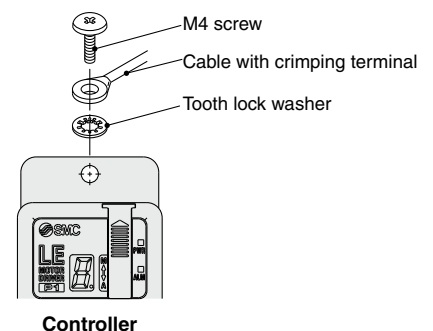
M4 screw

Cable with crimping terminal

Tooth lock washer

Controller

Note) When sizes 30 or 50 of the LER series are used, the space between the controllers should be 10 mm or more.

⚠ Caution

- M4 screws, cable with crimping terminal and tooth lock washer are not included.
  Be sure to carry out grounding earth in order to ensure the noise tolerance.

- Use a watchmaker's screwdriver of the size shown below when changing position switch ⑧ and the set value of the speed/acceleration switch ⑪ to ⑭.

Size
End width **L**: 2.0 to 2.4 [mm]
End thickness **W**: 0.5 to 0.6 [mm]
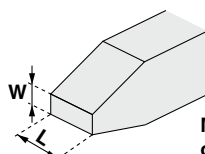
Magnified view of the end of the screwdriver
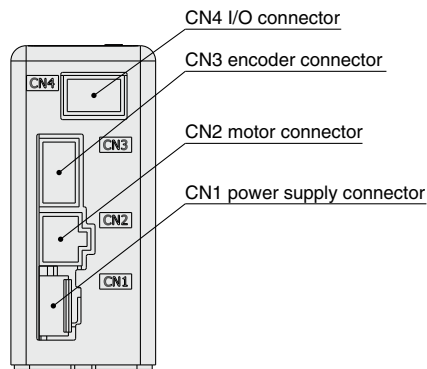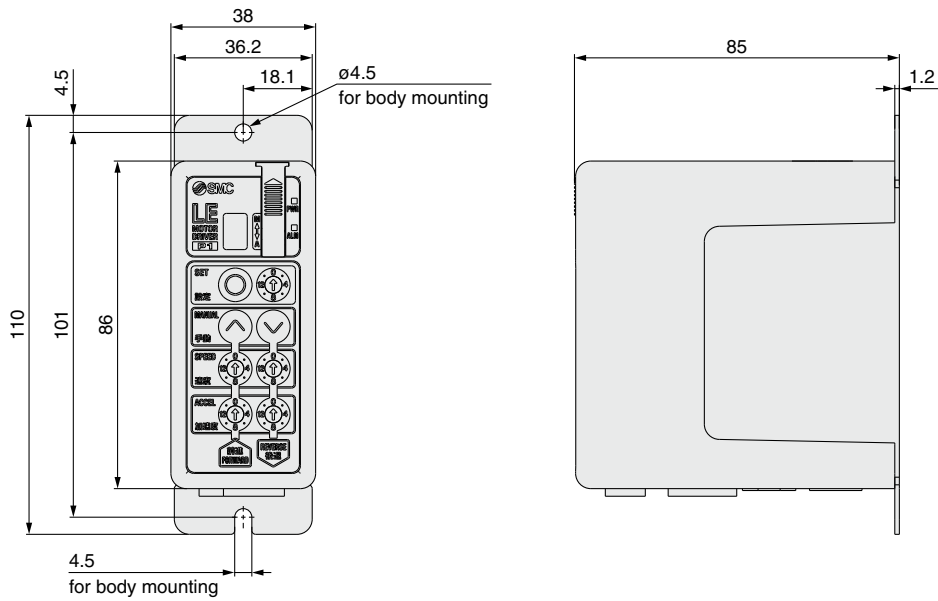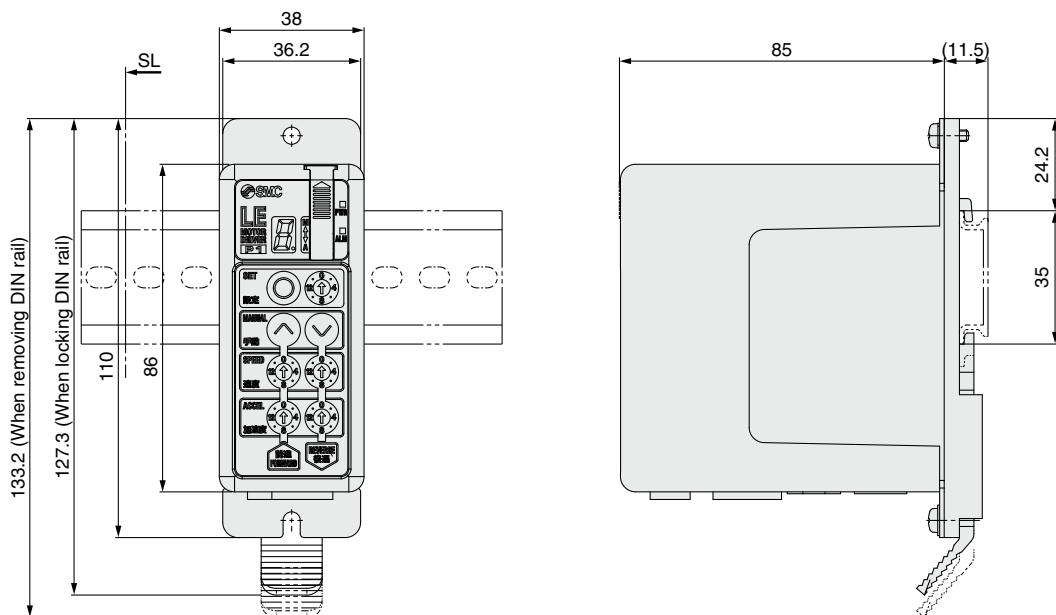
SMC

Model Selection

Step Motor (Servo/24 VDC)

LER

LECP6

LEC-G

LECP1

LECPA

Specific Product Precautions

Dimensions

Screw mounting (LEC☐1☐☐-☐)

38
36.2
18.1
ø4.5
for body mounting
4.5
110
101
86
4.5
for body mounting

85
1.2

CN4 I/O connector
CN3 encoder connector
CN2 motor connector
CN1 power supply connector

CN4
CN3
CN2
CN1

DIN rail mounting (LEC☐1☐☐D-☐)

SL
38
36.2
133.2 (When removing DIN rail)
127.3 (When locking DIN rail)
110
86

85
(11.5)
24.2
35

Series *LECP1*

Wiring Example 1

Power Supply Connector: CN1

∗ When you connect a CN1 power supply connector, please use the power supply cable (LEC-CK1-1).
∗ Power supply cable (LEC-CK1-1) is an accessory.

CN1 Power Supply Connector Terminal for LECP1

Terminal name	Cable color	Function	Details
0V	Blue	Common supply (−)	M24V terminal/C24V terminal/BK RLS terminal are common (−).
M24V	White	Motor power supply (+)	Motor power supply (+) supplied to the controller
C24V	Brown	Control power supply (+)	Control power supply (+) supplied to the controller
BK RLS	Black	Lock release (+)	Input (+) for releasing the lock

Power supply cable for LECP1 (LEC-CK1-1)

Wiring Example 2

Parallel I/O Connector: CN4

∗ When you connect a PLC, etc., to the CN4 parallel I/O connector, please use the I/O cable (LEC-CK4-□).
∗ The wiring should be changed depending on the type of the parallel I/O (NPN or PNP).

■NPN

■PNP

Input Signal

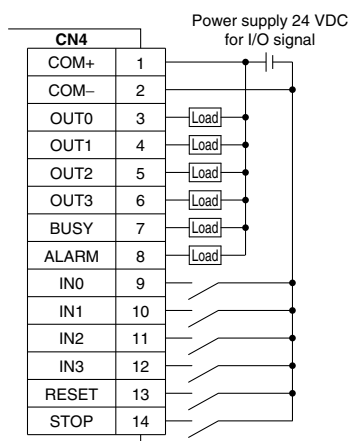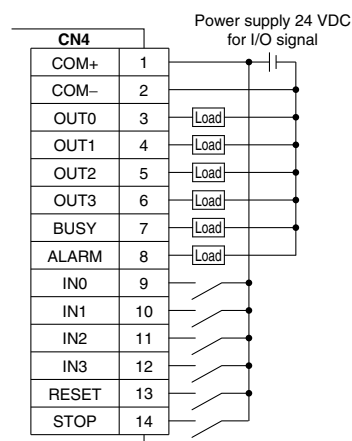| Name	Details
COM+	Connects the power supply 24 V for input/output signal
COM−	Connects the power supply 0 V for input/output signal
IN0 to IN3	• Instruction to drive (input as a combination of IN0 to IN3) • Instruction to return to origin (IN0 to IN3 all ON simultaneously) Example - (instruction to drive for position no. 5) <table><tr><td>IN3</td><td>IN2</td><td>IN1</td><td>IN0</td></tr><tr><td>OFF</td><td>ON</td><td>OFF</td><td>ON</td></tr></table>
RESET	Alarm reset and operation interruption During operation: deceleration stop from position at which signal is input (servo ON maintained) While alarm is active: alarm reset
STOP	Instruction to stop (after maximum deceleration stop, servo OFF)

Output Signal

Name	Details
OUT0 to OUT3	Turns on when the positioning or pushing is completed. (Output is instructed in the combination of OUT0 to 3.) Example - (operation complete for position no. 3) <table><tr><td>OUT3</td><td>OUT2</td><td>OUT1</td><td>OUT0</td></tr><tr><td>OFF</td><td>OFF</td><td>ON</td><td>ON</td></tr></table>
BUSY	Outputs when the actuator is moving
∗ALARM Note)	Not output when alarm is active or servo OFF

Note) Signal of negative-logic circuit (N.C.)

Input Signal [IN0 - IN3] Position Number Chart   ○: OFF ●: ON

Position number	IN3	IN2	IN1	IN0
1	○	○	○	●
2	○	○	●	○
3	○	○	●	●
4	○	●	○	○
5	○	●	○	●
6	○	●	●	○
7	○	●	●	●
8	●	○	○	○
9	●	○	○	●
10 (A)	●	○	●	○
11 (B)	●	○	●	●
12 (C)	●	●	○	○
13 (D)	●	●	○	●
14 (E)	●	●	●	○
Retun to origin	●	●	●	●

Output Signal [OUT0 - OUT3] Position Number Chart   ○: OFF ●: ON

Position number	OUT3	OUT2	OUT1	OUT0
1	○	○	○	●
2	○	○	●	○
3	○	○	●	●
4	○	●	○	○
5	○	●	○	●
6	○	●	●	○
7	○	●	●	●
8	●	○	○	○
9	●	○	○	●
10 (A)	●	○	●	○
11 (B)	●	○	●	●
12 (C)	●	●	○	○
13 (D)	●	●	○	●
14 (E)	●	●	●	○
Retun to origin	●	●	●	●

SMC

Signal Timing

(1) Return to Origin

IN0-3 all ON

ON after controller system initialization

Return to origin

Output signals for OUT0, OUT1, OUT2, OUT3 are ON when return to origin is completed.
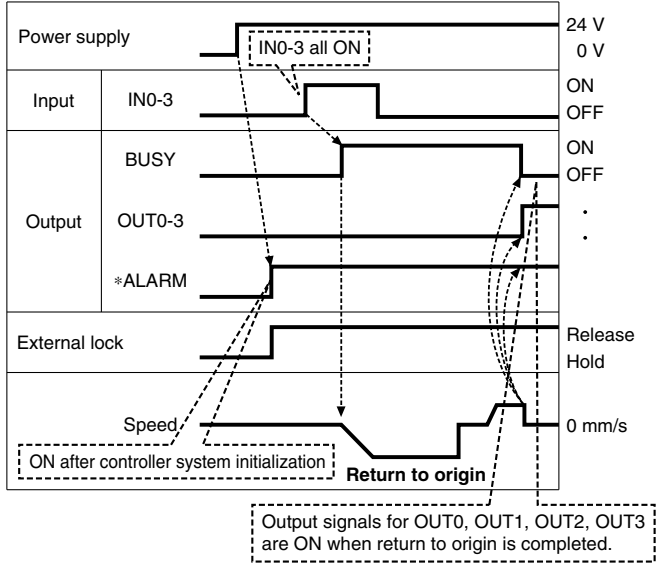
∗ "∗ALARM" is expressed as negative-logic circuit.

(2) Positioning Operation

Positioning operation

OUT0-3 output signals are ON in the same state as the input IN0-3 when positioning is completed.

(3) Cut-off Stop (Reset Stop)

Cut-off stop during positioning operation

(4) Stop by the STOP Signal

Stop by the STOP signal during positioning operation

(5) Alarm Reset

Alarm reset

Alarm out

"∗ALARM" is expressed as negative-logic circuit.

Model Selection

Step Motor (Servo/24 VDC)

LER

LECP6

LEC-G

LECP1

LECPA

Specific Product Precautions

Options: Actuator Cable

[Robotic cable, standard cable for step motor (Servo/24 VDC)]

LE−CP−1−□

Cable length (L) [m]

1	1.5
3	3
5	5
8	8*
A	10*
B	15*
C	20*

* Produced upon receipt of order (Robotic cable only)

Cable type

Nil	Robotic cable (Flexible cable)
S	Standard cable

LE-CP-$\frac{1}{3}$/Cable length: 1.5 m, 3 m, 5 m

LE-CP-$\frac{8 \, B}{A \, C}$/Cable length: 8 m, 10 m, 15 m, 20 m
(* Produced upon receipt of order)

Signal	Connector A terminal no.		Cable color	Connector C terminal no.
A	B-1		Brown	2
Ā	A-1		Red	1
B	B-2		Orange	6
B̄	A-2		Yellow	5
COM-A/COM	B-3		Green	3
COM-B/—	A-3		Blue	4

Signal	Connector A terminal no.		Cable color	Connector D terminal no.
Vcc	B-4	Shield	Brown	12
GND	A-4		Black	13
Ā	B-5		Red	7
A	A-5		Black	6
B̄	B-6		Orange	9
B	A-6		Black	8
			—	3

Options

[Power supply cable]

LEC−CK1−1

Terminal name	Covered color	Function
0V	Blue	Common supply (−)
M24V	White	Motor power supply (+)
C24V	Brown	Control power supply (+)
BK RLS	Black	Lock release (+)
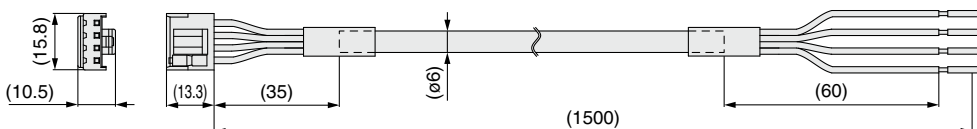
* Conductor size: AWG20

[I/O cable]

LEC−CK4−□

Cable length (L) [m]

1	1.5
3	3
5	5
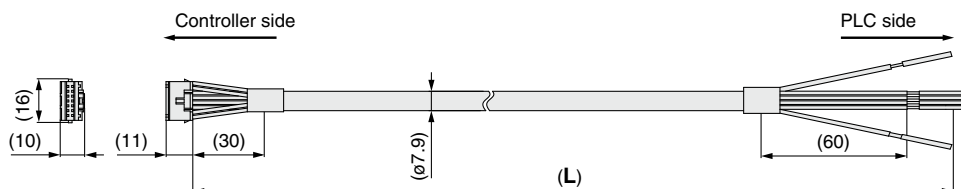
* Conductor size: AWG26

Terminal no.	Insulation color	Dot mark	Dot color	Function
1	Light brown	■	Black	COM+
2	Light brown	■	Red	COM−
3	Yellow	■	Black	OUT0
4	Yellow	■	Red	OUT1
5	Light green	■	Black	OUT2
6	Light green	■	Red	OUT3
7	Gray	■	Black	BUSY

Terminal no.	Insulation color	Dot mark	Dot color	Function
8	Gray	■	Red	ALARM
9	White	■	Black	IN0
10	White	■	Red	IN1
11	Light brown	■ ■	Black	IN2
12	Light brown	■ ■	Red	IN3
13	Yellow	■ ■	Black	RESET
14	Yellow	■ ■	Red	STOP

* Parallel I/O signal is valid in auto mode. While the test function operates at manual mode, only the output is valid.

SMC

Model Selection

Step Motor (Servo/24 VDC)

LER

LECP6

LEC-G

LECP1

LECPA

Specific Product Precautions

Step Motor Driver
Series *LECPA*

CE c**UL**us RoHS

How to Order

⚠️Caution

[CE-compliant products]

① EMC compliance was tested by combining the electric actuator LER series and the LECPA series. The EMC depends on the configuration of the customer's control panel and the relationship with other electrical equipment and wiring. Therefore conformity to the EMC directive cannot be certified for SMC components incorporated into the customer's equipment under actual operating conditions. As a result it is necessary for the customer to verify conformity to the EMC directive for the machinery and equipment as a whole.

② For the LECPA series (step motor driver), EMC compliance was tested by installing a noise filter set (LEC-NFA).
Refer to page 40 for the noise filter set. Refer to the LECPA Operation Manual for installation.

[UL-compliant products]

When conformity to UL is required, the electric actuator and driver should be used with a UL1310 Class 2 power supply.

LECP | AN | 1 | □ | – | LER10K-2

Driver type

AN	Pulse input type (NPN)
AP	Pulse input type (PNP)

Driver mounting

Nil	Screw mounting
D Note)	DIN rail mounting

Note) DIN rail is not included.
Order it separately.

I/O cable length [m]

Nil	None
1	1.5
3	3*
5	5*

* Pulse input usable only with differential. Only 1.5 m cables usable with open collector.

Actuator part number

(Except cable specifications and actuator options)
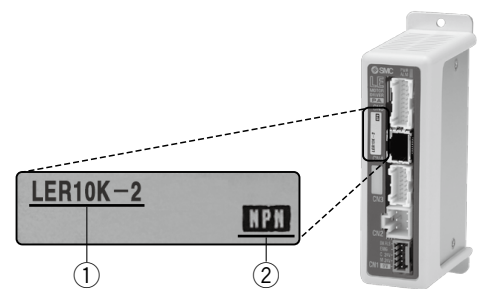Example: Enter "LER10K-2" for the LER10K-2L-R1AN1.

* When controller equipped type is selected when ordering the LE series, you do not need to order this driver.

The driver is sold as single unit after the compatible actuator is set.

Confirm that the combination of the driver and the actuator is correct.

<Check the following before use.>

① Check the actuator label for model number. This matches the driver.

② Check Parallel I/O configuration matches (NPN or PNP).

LER10K−2   NPN

① ②

* Refer to the operation manual for using the products. Please download it via our website, http://www.smcworld.com

Specifications

Item	LECPA
Compatible motor	Step motor (Servo/24 VDC)
Power supply Note 1)	Power voltage: 24 VDC ±10% Maximum current consumption: 3 A (Peak 5 A) Note 2) [Including motor drive power, control power, stop, lock release]
Parallel input	5 inputs (Except photo-coupler isolation, pulse input terminal, COM terminal)
Parallel output	9 outputs (Photo-coupler isolation)
Pulse signal input	Maximum frequency: 60 kpps (Open collector), 200 kpps (Differential) Input method: 1 pulse mode (Pulse input in direction), 2 pulse mode (Pulse input in differing directions)
Compatible encoder	Incremental A/B phase (Encoder resolution: 800 pulse/rotation)
Serial communication	RS485 (Modbus protocol compliant)
Memory	EEPROM
LED indicator	LED (Green/Red) one of each
Lock control	Forced-lock release terminal Note 3)
Cable length [m]	I/O cable: 1.5 or less (Open collector), 5 or less (Differential) Actuator cable: 20 or less
Cooling system	Natural air cooling
Operating temperature range [°C]	0 to 40 (No freezing)
Operating humidity range [%RH]	90 or less (No condensation)
Storage temperature range [°C]	−10 to 60 (No freezing)
Storage humidity range [%RH]	90 or less (No condensation)
Insulation resistance [MΩ]	Between the housing and SG terminal: 50 (500 VDC)
Weight [g]	120 (Screw mounting), 140 (DIN rail mounting)

Note 1) Do not use the power supply of "inrush current prevention type" for the driver power supply. When conformity to UL is required, the electric actuator and driver should be used with a UL1310 Class 2 power supply.

Note 2) The power consumption changes depending on the actuator model. Refer to the specifications of actuator for more details.

Note 3) Applicable to non-magnetizing lock.

SMC

Series *LECPA*

How to Mount

a) Screw mounting (LECPA☐☐-☐) (Installation with two M4 screws)

Ground wire

Mounting direction ☐ ➔

Mounting direction ☐ ➔
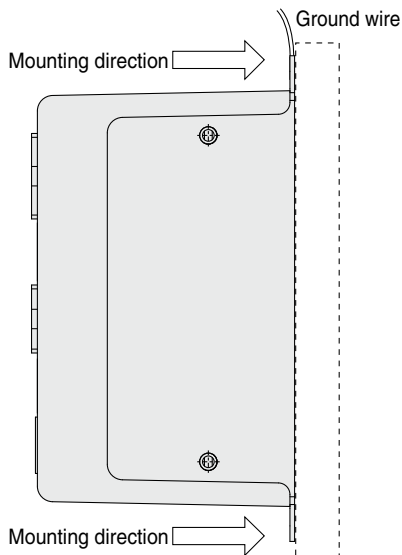
b) DIN rail mounting (LECPA☐☐D-☐) (Installation with the DIN rail)

DIN rail is locked.

Ground wire

DIN rail

Ground wire

DIN rail

A

A

DIN rail mounting adapter
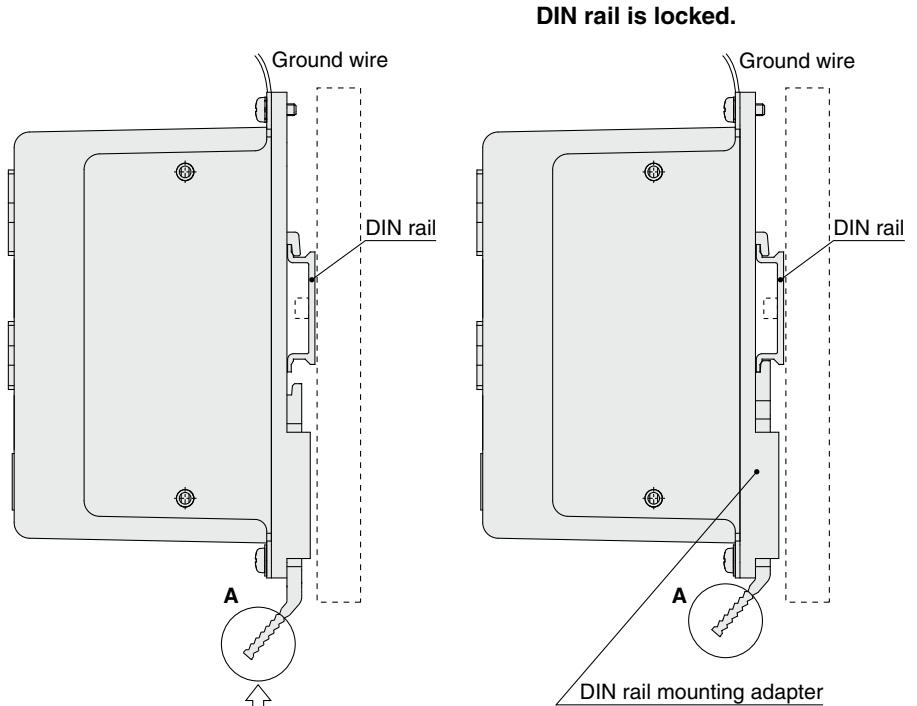
Hook the driver on the DIN rail and press the lever of section **A** in the arrow direction to lock it.

Note) The space between the drivers should be 10 mm or more.

DIN rail
AXT100-DR-☐

∗ For ☐, enter a number from the "No." line in the table below.
  Refer to the dimensions on page 36 for the mounting dimensions.

L

12.5
(Pitch)

5.25

7.5

(35)
(25)

5.5

1.25

L Dimension [mm]

No.	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20
L	23	35.5	48	60.5	73	85.5	98	110.5	123	135.5	148	160.5	173	185.5	198	210.5	223	235.5	248	260.5

No.	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40
L	273	285.5	298	310.5	323	335.5	348	360.5	373	385.5	398	410.5	423	435.5	448	460.5	473	485.5	498	510.5

DIN rail mounting adapter
LEC-2-D0 (with 2 mounting screws)

This should be used when the DIN rail mounting adapter is mounted onto the screw mounting type driver afterwards.

SMC

Model Selection

Step Motor (Servo/24 VDC)

LER

LECP6

LEC-G

LECP1

LECPA

Specific Product Precautions

Dimensions

a) Screw mounting (LECPA□□-□)

Power supply LED (Green)
(ON: Power supply is ON.)

35

ø4.5
for body mounting
(Screw mounting type)

66

1.2

Power supply LED (Red)
(ON: Alarm is ON.)

CN5 parallel I/O connector

CN4 serial I/O connector

CN3 encoder connector

CN2 motor power connector

CN1 power supply connector

125

116

109

4.5
for body mounting
(Screw mounting type)

b) DIN rail mounting (LECPA□□D-□)

35

76

148.2 (When removing DIN rail)

142.3 (When locking DIN rail)

109

39.2

35

142.3 (When locking DIN rail)

148.2 (When removing DIN rail)

∗ Mountable on DIN rail (35 mm)

Wiring Example 1

Power Supply Connector: CN1 ∗ Power supply plug is an accessory.

Power supply plug for LECPA

CN1 Power Supply Connector Terminal for LECPA (PHOENIX CONTACT FK-MC0.5/5-ST-2.5)

Terminal name	Function	Details
0V	Common supply (−)	M24V terminal/C24V terminal/EMG terminal/BK RLS terminal are common (−).
M24V	Motor power supply (+)	Motor power supply (+) supplied to the driver
C24V	Control power supply (+)	Control power supply (+) supplied to the driver
EMG	Stop (+)	Input (+) for releasing the stop
BK RLS	Lock release (+)	Input (+) for releasing the lock

0V
M24V
C24V
EMG
BK RLS

SMC
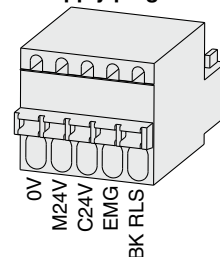
Wiring Example 2

Parallel I/O Connector: CN5 ∗ When you connect a PLC, etc., to the CN5 parallel I/O connector, please use the I/O cable (LEC-CL5-☐).
∗ The wiring should be changed depending on the type of the parallel I/O (NPN or PNP).

LECPAN☐☐-☐ (NPN)

CN5			
Terminal name	Function	Pin no.	
COM+	24 V	1	
COM−	0 V	2	
NP+	Pulse signal	3	
NP−	Pulse signal	4	Note 1)
PP+	Pulse signal	5	
PP−	Pulse signal	6	
SETUP	Input	7	
RESET	Input	8	
SVON	Input	9	
CLR	Input	10	
TL	Input	11	
TLOUT	Output	12	Load
WAREA	Output	13	Load
BUSY	Output	14	Load
SETON	Output	15	Load
INP	Output	16	Load
SVRE	Output	17	Load
∗ESTOP Note 2)	Output	18	Load
∗ALARM Note 2)	Output	19	Load
AREA	Output	20	Load
FG		Round terminal 0.5-5	

Power supply 24 VDC ±10% for I/O signal
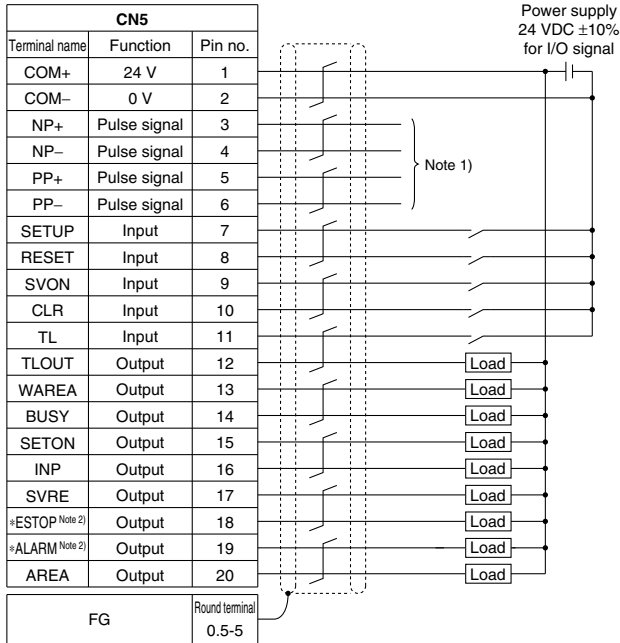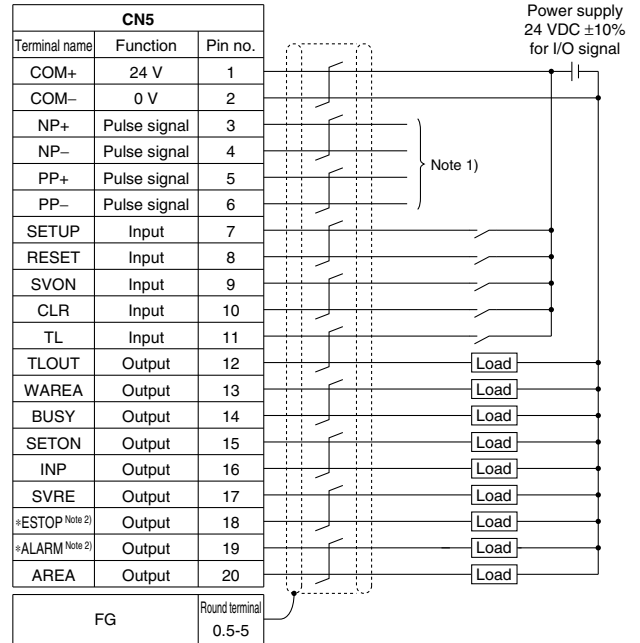
Note 1) For pulse signal wiring method, refer to "Pulse Signal Wiring Details".
Note 2) Output when the power supply of the driver is ON. (N.C.)

Input Signal

Name	Details
COM+	Connects the power supply 24 V for input/output signal
COM−	Connects the power supply 0 V for input/output signal
SETUP	Instruction to return to origin
RESET	Alarm reset
SVON	Servo ON instruction
CLR	Deviation reset
TL	Instruction to pushing operation

LECPAP☐☐-☐ (PNP)

CN5			
Terminal name	Function	Pin no.	
COM+	24 V	1	
COM−	0 V	2	
NP+	Pulse signal	3	
NP−	Pulse signal	4	Note 1)
PP+	Pulse signal	5	
PP−	Pulse signal	6	
SETUP	Input	7	
RESET	Input	8	
SVON	Input	9	
CLR	Input	10	
TL	Input	11	
TLOUT	Output	12	Load
WAREA	Output	13	Load
BUSY	Output	14	Load
SETON	Output	15	Load
INP	Output	16	Load
SVRE	Output	17	Load
∗ESTOP Note 2)	Output	18	Load
∗ALARM Note 2)	Output	19	Load
AREA	Output	20	Load
FG		Round terminal 0.5-5	

Power supply 24 VDC ±10% for I/O signal

Output Signal

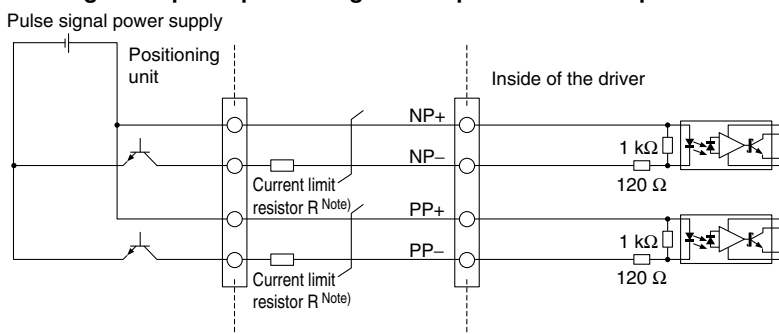| Name	Details
BUSY	Outputs when the actuator is operating
SETON	Outputs when returning to origin
INP	Outputs when target position is reached
SVRE	Outputs when servo is on
∗ESTOP Note 3)	Not output when EMG stop is instructed
∗ALARM Note 3)	Not output when alarm is generated
AREA	Outputs within the area output setting range
WAREA	Outputs within W-AREA output setting range
TLOUT	Outputs during pushing operation

Note 3) Signal of negative-logic circuit ON (N.C.)

Pulse Signal Wiring Details

• **Pulse signal output of positioning unit is differential output**

Positioning unit   Inside of the driver

NP+
NP− 1 kΩ 120 Ω
PP+
PP− 1 kΩ 120 Ω
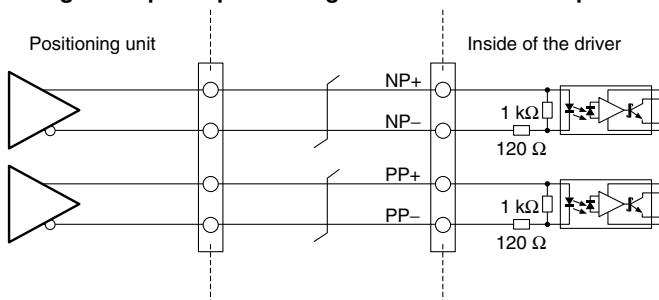
• **Pulse signal output of positioning unit is open collector output**

Pulse signal power supply

Positioning unit   Inside of the driver

NP+
NP− 1 kΩ 120 Ω
Current limit resistor R Note)
PP+
PP− 1 kΩ 120 Ω
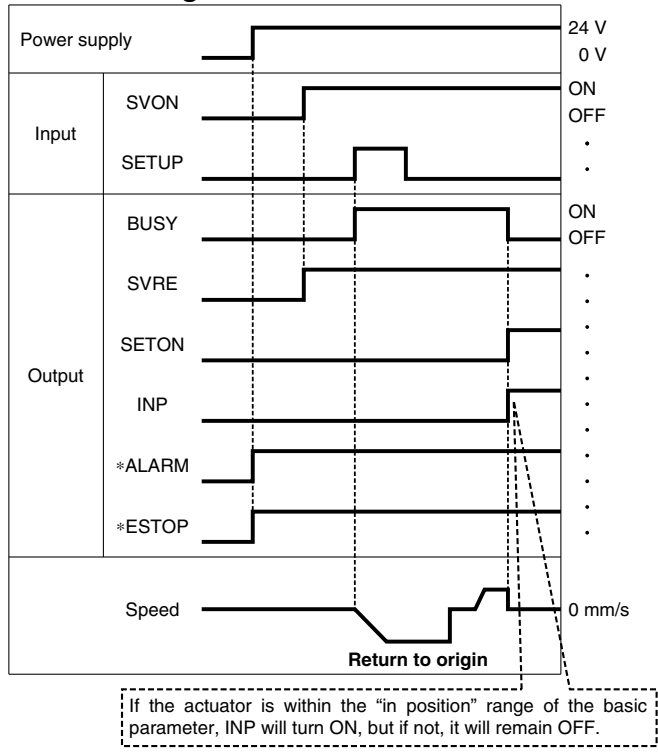Current limit resistor R Note)

Note) Connect the current limit resistor R in series to correspond to the pulse signal voltage.

Pulse signal power supply voltage	Current limit resistor R specifications
24 VDC ±10%	3.3 kΩ ±5% (0.5 W or more)
5 VDC ±5%	390 Ω ±5% (0.1 W or more)

SMC

Model Selection

Step Motor (Servo/24 VDC)

LER

LECP6

LEC-G

LECP1

LECPA

Specific Product Precautions

Signal Timing

Return to Origin

If the actuator is within the "in position" range of the basic parameter, INP will turn ON, but if not, it will remain OFF.

∗ "∗ALARM" and "∗ESTOP" are expressed as negative-logic circuit.

Positioning Operation

If the actuator is within the "in position" range of the step data, INP will turn ON, but if not, it will remain OFF.

Pushing Operation

If the current pushing force exceeds the "trigger LV" value of the step data, INP signal will turn ON.
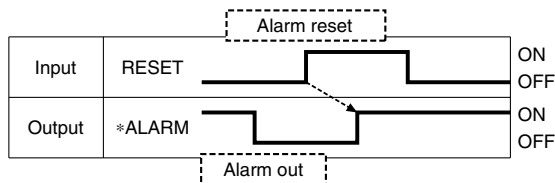
Note) If pushing operation is stopped when there is no pulse deviation, the moving part of the actuator may pulsate.

Alarm Reset

"∗ALARM" is expressed as negative-logic circuit.

Options: Actuator Cable

[Robotic cable, standard cable for step motor (Servo/24 VDC)]

LE‒CP‒1‒☐

Cable length (L) [m]

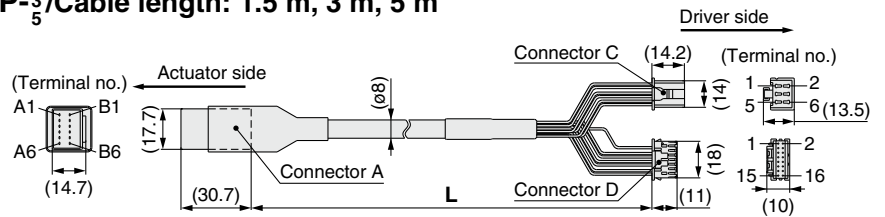| 1	1.5
3	3
5	5
8	8*
A	10*
B	15*
C	20*

* Produced upon receipt of order (Robotic cable only)

Cable type

Nil	Robotic cable (Flexible cable)
S	Standard cable

LE-CP-$\frac{1}{3}$/Cable length: 1.5 m, 3 m, 5 m

LE-CP-$\frac{8}{A}\frac{B}{C}$/Cable length: 8 m, 10 m, 15 m, 20 m
(* Produced upon receipt of order)

Signal	Connector A terminal no.		Cable color	Connector C terminal no.
A	B-1		Brown	2
$\overline{A}$	A-1		Red	1
B	B-2		Orange	6
$\overline{B}$	A-2		Yellow	5
COM-A/COM	B-3		Green	3
COM-B/—	A-3		Blue	4

Signal	Connector A terminal no.		Cable color	Connector D terminal no.
Vcc	B-4		Brown	12
GND	A-4		Black	13
$\overline{A}$	B-5		Red	7
A	A-5		Black	6
$\overline{B}$	B-6		Orange	9
B	A-6		Black	8
			—	3

Shield

SMC

Step Motor Driver *Series LECPA*

Model Selection

Step Motor (Servo/24 VDC)

LER

LECP6

LEC-G

LECP1

LECPA

Specific Product Precautions

Options

[I/O cable]

LEC‑C L5‑1

I/O cable type	
L5	For LECPA

I/O cable length (L)

1	1.5 m
3	3 m*
5	5 m*

∗ Pulse input usable only with differential. Only 1.5 m cables usable with open collector.
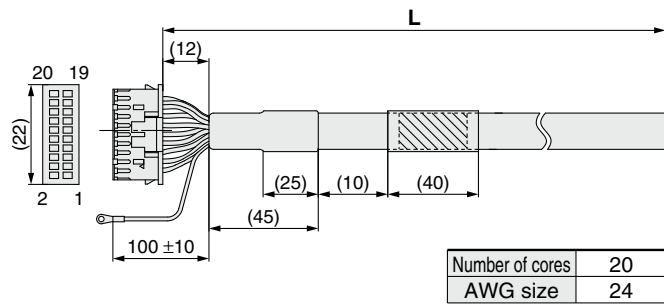
Pin no.	Insulation color	Dot mark	Dot color
1	Light brown	■	Black
2	Light brown	■	Red
3	Yellow	■	Black
4	Yellow	■	Red
5	Light green	■	Black
6	Light green	■	Red
7	Gray	■	Black
8	Gray	■	Red
9	White	■	Black
10	White	■	Red
11	Light brown	■ ■	Black

Pin no.	Insulation color	Dot mark	Dot color
12	Light brown	■ ■	Red
13	Yellow	■ ■	Black
14	Yellow	■ ■	Red
15	Light green	■ ■	Black
16	Light green	■ ■	Red
17	Gray	■ ■	Black
18	Gray	■ ■	Red
19	White	■ ■	Black
20	White	■ ■	Red
Round terminal 0.5-5	Green		

Number of cores	20
AWG size	24

(12)
20 19
(22)
2 1
100 ±10
(45)
(25) (10) (40)
L

[Noise filter set]
Step Motor Driver (Pulse Input Type)

LEC‑NFA

Contents of the set: 2 noise filters
(Manufactured by WURTH ELEKTRONIK: 74271222)

(33.5)
(42.2)
(28.8)
(12.5)
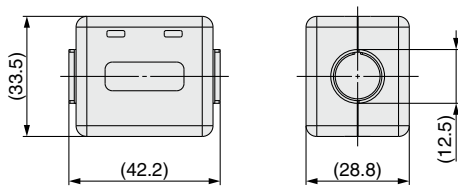
∗ Refer to the LECPA series Operation Manual for installation.

Controller Setting Kit/LEC-W2

① Controller setting software

② Communication cable ③ USB cable (A-miniB type)

PC

How to Order

LEC–W2

Controller setting kit
(Japanese and English are available.)
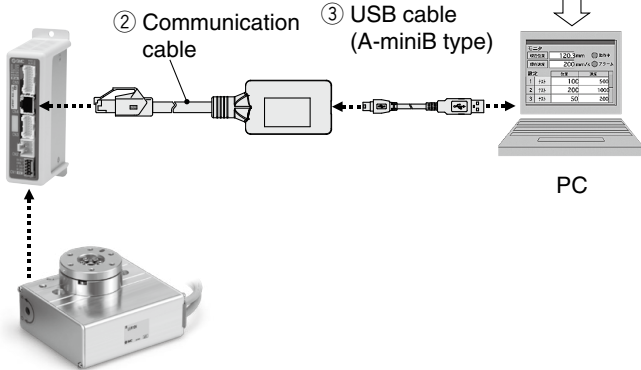
Contents

① **Controller setting software (CD-ROM)**

② **Communication cable**

③ **USB cable**
(Cable between the PC and the conversion unit)

Compatible Controllers/Driver

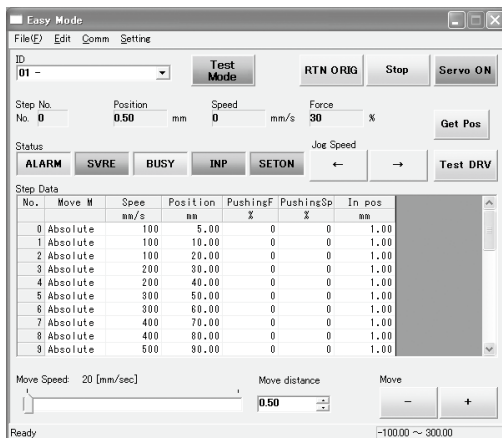|	
Step motor controller (Servo/24 VDC)	**Series LECP6**
Servo motor controller (24 VDC)	**Series LECA6**
Step motor driver (Pulse input type)	**Series LECPA**

Hardware Requirements

OS	IBM PC/AT compatible machine running Windows®XP (32-bit), Windows®7 (32-bit and 64-bit).
Communication interface	USB 1.1 or USB 2.0 ports
Display	XGA (1024 x 768) or more

∗ Windows® and Windows®7 are registered trademarks of Microsoft Corporation in the United States.
∗ Refer to SMC website for version update information, http://www.smcworld.com

Screen Example

Easy mode screen example

Normal mode screen example

Easy operation and simple setting
● Allowing to set and display actuator step data such as position, speed, force, etc.
● Setting of step data and testing of the drive can be performed on the same page.
● Can be used to jog and move at a constant rate.

Detailed setting
● Step data can be set in detail.
● Signals and terminal status can be monitored.
● Parameters can be set.
● JOG and constant rate movement, return to origin, test operation and testing of forced output can be performed.

SMC

Model Selection

Step Motor (Servo/24 VDC) LER

LECP6

LEC-G

LECP1

LECPA

Specific Product Precautions

Series *LEC*
Teaching Box/LEC-T1

C E c UL us

RoHS

How to Order

LEC-T1-3 J G ☐

Teaching box

Cable length [m]

3	3

Initial language

J	Japanese
E	English

∗ The displayed language can be changed to English or Japanese.

Enable switch

Nil	None
S	Equipped with enable switch

∗ Interlock switch for jog and test function

Stop switch

G	Equipped with stop switch

Enable switch
(Option)

Stop switch

Standard functions
- **Chinese character display**
- **Stop switch is provided.**

Option
- **Enable switch is provided.**

Specifications

Item	Description
Switch	Stop switch, Enable switch (Option)
Cable length [m]	3
Enclosure	IP64 (Except connector)
Operating temperature range [°C]	5 to 50
Operating humidity range [%RH]	90 or less (No condensation)
Weight [g]	350 (Except cable)

[CE-compliant products]
The EMC compliance of the teaching box was tested with the LECP6 series step motor controller (servo/24 VDC) and an applicable actuator.
[UL-compliant products]
When conformity to UL is required, the electric actuator and driver should be used with a UL1310 Class 2 power supply.

Easy Mode

Function	Details
Step data	• Setting of step data
Jog	• Jog operation • Return to origin
Test	• 1 step operation Note 1) • Return to origin
Monitor	• Display of axis and step data no. • Display of two items selected from Position, Speed, Force.
ALM	• Active alarm display • Alarm reset
TB setting	• Reconnection of axis (Ver. 1.∗∗) • Displayed language setting (Ver. 2.∗∗) • Setting of easy/normal mode • Setting step data and selection of items from easy mode monitor

Menu Operations Flowchart

Menu
Data
Monitor
Jog
Test
ALM
TB setting

Data
Step data no.
Setting of two items selected below
Ver. 1.∗∗:
Position, Speed, Force, Acceleration, Deceleration
Ver. 2.∗∗:
Position, Speed, Pushing force, Acceleration, Deceleration, Movement MOD, Trigger LV, Pushing speed, Moving force, Area 1, Area 2, In position

Monitor
Display of step no.
Display of two items selected below
(Position, Speed, Force)

Jog
Return to origin
Jog operation

Test Note 1)
1 step operation

ALM
Active alarm display
Alarm reset

TB setting
Reconnection of axis (Ver. 1.∗∗)
Japanese/English (Ver. 2.∗∗)
Easy/Normal
Set item

Note 1) Not compatible with the LECPA.

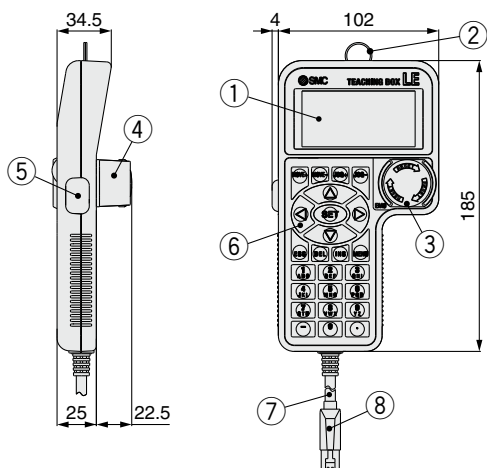SMC

Series *LEC*

Normal Mode

Function	Details
Step data	• Step data setting
Parameter	• Parameters setting

Test	• Jog operation/Constant rate movement
	• Return to origin
	• Test drive Note 1)
	  (Specify a maximum of 5 step data and operate.)
	• Forced output
	  (Forced signal output, Forced terminal output) Note 2)

Monitor	• Drive monitor • Output signal monitor Note 2) • Input signal monitor Note 2) • Output terminal monitor • Input terminal monitor
ALM	• Active alarm display (Alarm reset) • Alarm log record display

File	• Data saving
	  Save the step data and parameters of the driver which is being used for communication (it is possible to save four files, with one set of step data and parameters defined as one file).
	• Load to driver
	  Loads the data which is saved in the teaching box to the driver which is being used for communication.
	• Delete the saved data.
	• File protection (Ver. 2.∗∗)

TB setting	• Display setting
	  (Easy/Normal mode)
	• Language setting
	  (Japanese/English)
	• Backlight setting
	• LCD contrast setting
	• Beep sound setting
	• Max. connection axis
	• Distance unit (mm/inch)

Reconnect	• Reconnection of axis

Menu Operations Flowchart

Menu
Step data
Parameter
Monitor
Test
ALM
File
TB setting
Reconnect

Step data
Step data no.
Movement MOD
Speed
Position
Acceleration
Deceleration
Pushing force
Trigger LV
Pushing speed
Moving force
Area 1, 2
In position

Parameter
Basic
ORIG

→ **Basic setting**
→ **ORIG setting**

Monitor
Drive
Output signal Note 2)
Input signal Note 2)
Output terminal
Input terminal

DRV monitor
Position, Speed, Torque
Step no.
Last step no.

Output signal monitor
Input signal monitor
Output terminal monitor
Input terminal monitor

Test
JOG/MOVE
Return to ORIG
Test drive Note 1)
Forced output Note 2)

ALM
Status
ALM Log record

Status
Active alarm display
Alarm reset

ALM Log record display
Log entry display

File
Data saving
Load to driver
File deletion
File protection (Ver. 2.∗∗)

TB setting
Easy/Normal
Language
Backlight
LCD contrast
Beep
Max. connection axis
Password
Distance unit

Reconnect

Note 1) Not compatible with the LECPA.
Note 2) The following signals are not compatible with the LECPA.
Input: CLR, TL
Output: TLOUT

Dimensions

34.5   4   102   185   25   22.5

No.	Description	Function
1	**LCD**	A screen of liquid crystal display (with backlight)
2	**Ring**	A ring for hanging the teaching box
3	**Stop switch**	When switch is pushed in, the switch locks and stops. The lock is released when it is turned to the right.
4	**Stop switch guard**	A guard for the stop switch
5	**Enable switch (Option)**	Prevents unintentional operation (unexpected operation) of the jog test function. Other functions such as data change are not covered.
6	**Key switch**	Switch for each input
7	**Cable**	Length: 3 meters
8	**Connector**	A connector connected to CN4 of the driver

SMC

⚠ Safety Instructions

These safety instructions are intended to prevent hazardous situations and/or equipment damage. These instructions indicate the level of potential hazard with the labels of **"Caution," "Warning"** or **"Danger."** They are all important notes for safety and must be followed in addition to International Standards (ISO/IEC)[*1], and other safety regulations.

⚠ **Caution:** **Caution** indicates a hazard with a low level of risk which, if not avoided, could result in minor or moderate injury.

⚠ **Warning:** **Warning** indicates a hazard with a medium level of risk which, if not avoided, could result in death or serious injury.

⚠ **Danger :** **Danger** indicates a hazard with a high level of risk which, if not avoided, will result in death or serious injury.

[*1] ISO 4414: Pneumatic fluid power – General rules relating to systems.
ISO 4413: Hydraulic fluid power – General rules relating to systems.
IEC 60204-1: Safety of machinery – Electrical equipment of machines.
　　　　　　 (Part 1: General requirements)
ISO 10218-1: Manipulating industrial robots – Safety.
etc.

⚠Warning

1. **The compatibility of the product is the responsibility of the person who designs the equipment or decides its specifications.**
Since the product specified here is used under various operating conditions, its compatibility with specific equipment must be decided by the person who designs the equipment or decides its specifications based on necessary analysis and test results. The expected performance and safety assurance of the equipment will be the responsibility of the person who has determined its compatibility with the product. This person should also continuously review all specifications of the product referring to its latest catalog information, with a view to giving due consideration to any possibility of equipment failure when configuring the equipment.

2. **Only personnel with appropriate training should operate machinery and equipment.**
The product specified here may become unsafe if handled incorrectly. The assembly, operation and maintenance of machines or equipment including our products must be performed by an operator who is appropriately trained and experienced.

3. **Do not service or attempt to remove product and machinery/equipment until safety is confirmed.**
　1. The inspection and maintenance of machinery/equipment should only be performed after measures to prevent falling or runaway of the driven objects have been confirmed.
　2. When the product is to be removed, confirm that the safety measures as mentioned above are implemented and the power from any appropriate source is cut, and read and understand the specific product precautions of all relevant products carefully.
　3. Before machinery/equipment is restarted, take measures to prevent unexpected operation and malfunction.

4. **Contact SMC beforehand and take special consideration of safety measures if the product is to be used in any of the following conditions.**
　1. Conditions and environments outside of the given specifications, or use outdoors or in a place exposed to direct sunlight.
　2. Installation on equipment in conjunction with atomic energy, railways, air navigation, space, shipping, vehicles, military, medical treatment, combustion and recreation, or equipment in contact with food and beverages, emergency stop circuits, clutch and brake circuits in press applications, safety equipment or other applications unsuitable for the standard specifications described in the product catalog.
　3. An application which could have negative effects on people, property, or animals requiring special safety analysis.
　4. Use in an interlock circuit, which requires the provision of double interlock for possible failure by using a mechanical protective function, and periodical checks to confirm proper operation.

⚠Caution

1. **The product is provided for use in manufacturing industries.**
The product herein described is basically provided for peaceful use in manufacturing industries.
If considering using the product in other industries, consult SMC beforehand and exchange specifications or a contract if necessary.
If anything is unclear, contact your nearest sales branch.

Limited warranty and Disclaimer/ Compliance Requirements

The product used is subject to the following "Limited warranty and Disclaimer" and "Compliance Requirements".
Read and accept them before using the product.

Limited warranty and Disclaimer

1. The warranty period of the product is 1 year in service or 1.5 years after the product is delivered, whichever is first.[*2]
Also, the product may have specified durability, running distance or replacement parts. Please consult your nearest sales branch.

2. For any failure or damage reported within the warranty period which is clearly our responsibility, a replacement product or necessary parts will be provided.
This limited warranty applies only to our product independently, and not to any other damage incurred due to the failure of the product.

3. Prior to using SMC products, please read and understand the warranty terms and disclaimers noted in the specified catalog for the particular products.

　[*2] Vacuum pads are excluded from this 1 year warranty.
　A vacuum pad is a consumable part, so it is warranted for a year after it is delivered.
　Also, even within the warranty period, the wear of a product due to the use of the vacuum pad or failure due to the deterioration of rubber material are not covered by the limited warranty.

Compliance Requirements

1. The use of SMC products with production equipment for the manufacture of weapons of mass destruction (WMD) or any other weapon is strictly prohibited.

2. The exports of SMC products or technology from one country to another are governed by the relevant security laws and regulations of the countries involved in the transaction. Prior to the shipment of a SMC product to another country, assure that all local rules governing that export are known and followed.

Revision history
Edition B * Addition of programless controller, LECP1 series
* Number of pages from 32 to 44　　　　　　　　　　　　　　　PY
Edition C * Addition of step motor driver, LECPA series
* Addition of gateway unit, LEC-G series
* Number of pages from 44 to 60　　　　　　　　　　　　　　　RQ

⚠ **Safety Instructions** | Be sure to read "Handling Precautions for SMC Products" (M-E03-3) before using.

SMC Corporation

Akihabara UDX 15F,
4-14-1, Sotokanda, Chiyoda-ku, Tokyo 101-0021, JAPAN
Phone: 03-5207-8249　Fax: 03-5298-5362
http://www.smcworld.com
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Specifications are subject to change without prior notice and any obligation on the part of the manufacturer.

D-G

1st printing PP printing RQ 8150DN Printed in Japan.