## Air Slide Table

## Series MXJ


(1)Piping port
(2Axial piping plate
3Axial piping port
(4) Retraction end stroke adjuster
(5) Extension end stroke adjuster

6Switch rail
(7Vacuum port (clean specifications)


BAxial Piping


## Symmetric Style

Piping ports are provided both on the right and left sides. Switch rails and axial piping plates are interchangeable between the right and left side.


## Variations

| Model |  | $\begin{aligned} & \text { Bore size } \\ & (\mathrm{mm}) \end{aligned}$ | Standard stroke (mm) |  |  |  | Adjuster option |  |  | Piping option |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Standard type | Symmetric type |  | 5 | 10 | 15 | 20 | Extension end | Retraction end | Both ends | Axial piping type |
| MXJ4 | MXJ4L | 4.5 | - | - | - | - | - | - | - | - |
| MXJ6 | MXJ6L | 6 | - | - | - | - | - | - | - | - |
| MXJ8 | MXJ8L | 8 | - | $\bullet$ | - | - | - | - | - | - |

## Clean Specification

Clean specification products are available with no dimensional changes. The same options are available as for standard products.



* Operating pressure: 0.5 MPa when operating direction is OUT. OUT $\leftarrow \square \longrightarrow \mathbb{N}$


## Model Selection

## Procedure

Formula/Data
Selection Example

## Operating Conditions

Enumerate the operating conditions considering the mounting position and workpiece configuration.

- Model to be used
- Type of cushion
- Mounting orientation
- Average speed Va (mm/s)
- Load mass W (kg)
- Overhang (mm)

Load Mass

Find the collision speed $V(\mathrm{~mm} / \mathrm{S})$.

Confirm that the load mass W (kg) does not exceed the value in the graph.
$\mathbf{V}=\underset{*}{\mathbf{1 . 4}} \cdot \mathbf{V a} *$ Correction factor (Reference value)
Graph (1)
$V=1.4 \times 100=140$
Confirm that $\mathrm{V}=140$ and $\mathrm{W}=0.1$ do not exceed the values in Graph (1).

Applicable because it does not exceed the value in Graph (1).


## Load Factor

## 3-1 Load Factor of Static Moment

Find the static moment $\mathrm{M}(\mathrm{N} \cdot \mathrm{m})$.
Find the allowable static moment Ma ( $\mathrm{N} \cdot \mathrm{m}$ ).

Find the load factor of the static moment.
$M=W \times 9.8(\mathrm{Ln}+\mathrm{An}) / 1000$
Corrected value of moment center position
distance An: Table (1)
Pitch, Yaw moment: Graph (2)
Roll moment: Graph (3)
$\alpha_{1}=\mathrm{M} / \mathrm{Ma}$

3-2 Load Factor of Dynamic Moment

Find the dynamic moment Me ( $\mathrm{N} \cdot \mathrm{m}$ ).

Find the allowable dynamic moment Mea ( $\mathrm{N} \cdot \mathrm{m}$ ) from graph.

Find the load factor of the dynamic moment.

3-3 Sum of Load Factors

$$
M e=1 / 3 \cdot W e \times 9.8(L n+A n) / 1000
$$ mass equivalent to impact $\mathrm{We}=\delta \cdot \mathrm{W} \cdot \mathrm{V}$

$\delta$ : Bumper coefficient
Rubber stopper: 4/100
Metal stopper: 16/100
Corrected value of moment center position distance An: Table (1)

Pitch, Yaw moment: Graph (2)
$\alpha_{2}=\mathrm{Me} / \mathrm{Mea}$

Possible to use if the sum of the load factors does not

$$
\alpha_{1}+\alpha_{2}<1
$$

Examine Mr.
$\mathrm{Mr}=0.1 \times 9.8(40+3) / 1000=0.042$
A2 $=3$
Obtain Mar $=0.6$ from $\mathrm{Va}=100$ in Graph (3).

## Examine Mep.

Mep $=1 / 3 \times 0.56 \times 9.8 \times(40+3) / 1000=0.078$
$\mathrm{We}=4 / 100 \times 0.1 \times 140=0.56$
A3 $=3$
Obtain Meap $=1.1$ from $V=140$ in Graph (2).
$\alpha_{2}=0.078 / 1.1=0.07$


Examine Mey.
Mey $=1 / 3 \times 0.56 \times 9.8 \times(50+11) / 1000=0.116$
$W e=0.56$
A3 $=11$
Obtain Meay =1.1 from V=140 in Graph (2).
$\alpha_{2^{\prime}}=0.116 / 1.1=0.1$

$\alpha_{1}+\alpha_{2}+\alpha_{2}^{\prime}=$
Applicable because
$0.07+0.07+0.1=0.24<1$

## Series MXJ

Fig. (1) Overhang: Ln (mm), Correction Value of Moment Center Position Distance: An (mm)

|  | Pitch moment | Yaw moment | Roll moment |
| :---: | :---: | :---: | :---: |
|  |  |  |  |
|  |  |  | - |

Note) Static moment: Moment generated by gravity
Dynamic moment: Moment generated by impact when colliding with stopper


Note) Use the average speed when calculating static moment.
Use the collision speed when calualaing dyramic moment.refér to page 177. . Table (1) Correction Value of Moment Center Position Distance: An (mm)

| Model | Corrected value of moment center <br> position distance (Refer to Fig. 2.) |  |  |
| :---: | :---: | :---: | :---: |
|  | A1 | A2 | A3 |
| MXJ4 | 10 | 3 | 10 |
| MXJ6 | 10 | 3 | 11 |
| MXJ8 | 12 | 4 | 13 |

Graph (3) Allowable Moment Roll Moment: Mar


Table (2) Max. Allowable Load Mass: Wmax (kg)

| Model | Max. allowable load mass |  |
| :---: | :---: | :---: |
|  | Rubber stopper | Metal stopper |
| MXJ4 | 0.1 | 0.08 |
| MXJ6 | 0.2 | 0.14 |
| MXJ8 | 0.35 | 0.25 |

The above value represents the maximum value for each allowable load mass. For the maximum allowable load mass for each piston speed, please refer to Graph (1).

## Table (3) Maximum Allowable Moment: Mmax ( $\mathrm{N} \cdot \mathrm{m}$ )

| Model | Pitch/Yaw moment: Mpmax/Mymax | Roll moment: Mrmax |
| :---: | :---: | :---: |
| MXJ4 | 1.1 | 0.6 |
| MXJ6 | 1.1 | 0.6 |
| MXJ8 | 1.5 | 1.0 |

The above value represents the maximum value of allowable moment. For the maximum allowable moment for each piston speed, please refer to Graph (2) and (3).

## Symbol

| Symbol | Definition | Unit | Symbol | Definition | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: |
| An ( $\mathrm{n}=1$ to 3 ) | Corrected value of moment center position distance | mm | F | Allowable static load | N |
| $\mathbf{L n}(\mathrm{n}=1$ to 3) | Overhang | mm | V | Collision speed (Average speed $\times$ 1.4) | $\mathrm{mm} / \mathrm{s}$ |
| M (Mp, My, Mr) | Static moment (pitch, yaw, roll) | $\mathrm{N} \cdot \mathrm{m}$ | Va | Average speed | mm/s |
| Ma (Map, May, Mar) | Allowable static moment (pitch, yaw, roll) | $\mathrm{N} \cdot \mathrm{m}$ | w | Load mass | kg |
| Me (Mep, Mey) | Dynamic moment (pitch, yaw) | $\mathrm{N} \cdot \mathrm{m}$ | Wa | mass equivalent to impact | kg |
| Mea (Meap, Meay) | Allowable dynamic moment (pitch, yaw) | $\mathrm{N} \cdot \mathrm{m}$ | Wmax | Max. allowable load mass | kg |
| Mmax (Mpmax, Mymax, Mrmax) | Max. allowable moment (pitch, yaw, roll) | $\mathrm{N} \cdot \mathrm{m}$ | $\alpha$ | Load factor | - |

# Air Slide Table <br> Series MXJ <br> ø4, ø6, ø8 

How to Order


MXH

Applicable Auto Switches/Refer to pages 1719 through to 1827 for further information on auto switches.

| Type | Special function | Electrical entry |  | Wiring (Output) | Load voltage |  |  | Auto switch model Electrical entry direction |  | Lead wire length (m) |  |  |  | Pre-wired connector | Applicable load |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  | DC |  | AC |  |  | $\begin{gathered} 0.5 \\ \text { (Nil) } \end{gathered}$ | $\begin{gathered} \hline 1 \\ (\mathrm{M}) \end{gathered}$ | $\begin{gathered} 3 \\ \text { (L) } \end{gathered}$ | $\begin{gathered} 5 \\ (\mathrm{Z}) \end{gathered}$ |  |  |  |
|  |  | Grommet | Yes | 3-wire (NPN) | 24 V | $\begin{array}{r} 5 \mathrm{~V} \\ 12 \mathrm{~V} \end{array}$ | - | M9NV | M9N | $\bullet$ | $\bullet$ | $\bullet$ | $\bigcirc$ | $\bigcirc$ | IC circuit | Relay, PLC |
|  |  |  |  | 3-wire (PNP) |  |  |  | M9PV | M9P | $\bullet$ | $\bullet$ | - | $\bigcirc$ | $\bigcirc$ |  |  |
|  |  |  |  | 2-wire |  | 12 V |  | M9BV | M9B | $\bullet$ | $\bullet$ | $\bullet$ | $\bigcirc$ | $\bigcirc$ | - |  |
|  |  |  |  | 3-wire (NPN) |  | $\begin{array}{r} 5 \mathrm{~V} \\ 12 \mathrm{~V} \end{array}$ |  | F8N | - | $\bullet$ | - | $\bullet$ | $\bigcirc$ | - | IC circuit |  |
|  |  |  |  | 3-wire (PNP) |  |  |  | F8P |  | $\bullet$ | - | $\bullet$ | $\bigcirc$ |  |  |  |
|  |  |  |  | 2-wire |  | 12 V |  | F8B |  | $\bullet$ | - | $\bullet$ | $\bigcirc$ |  |  |  |
|  | Diagnostic |  |  | 3-wire (NPN) |  | $\begin{array}{r} 5 \mathrm{~V} \\ 12 \mathrm{~V} \end{array}$ |  | M9NWV | M9NW | $\bullet$ | $\bullet$ | - | $\bigcirc$ | $\bigcirc$ | IC circuit |  |
|  | indication (2-color |  |  | 3-wire (PNP) |  |  |  | M9PWV | M9PW | $\bullet$ | $\bullet$ | $\bullet$ | $\bigcirc$ | $\bigcirc$ |  |  |
|  | indication) |  |  | 2-wire |  | 12 V |  | M9BWV | M9BW | $\bullet$ | $\bullet$ | $\bullet$ | $\bigcirc$ | $\bigcirc$ | - |  |
|  | - | Grommet | Yes | 3-wire (NPN equivalent) | - | 5 V | - | A96V | A96 | - | - | $\bullet$ | - | - | $\begin{gathered} \text { ICC } \\ \text { circuit } \end{gathered}$ | - |
|  |  |  |  | 2-wire | 24 V | 12 V | 100 V | A93V | A93 | $\bullet$ | - | $\bullet$ | - | - | - | Relay, |
|  |  |  | - |  |  | $5 \mathrm{~V}, 12 \mathrm{~V}$ | 100 V or less | A90V | A90 | $\bullet$ | - | $\bullet$ | - | - | $\begin{gathered} \text { IC } \\ \text { circuit } \end{gathered}$ | PLC |

* Lead wire length symbols: $0.5 \mathrm{~m} . . . . . . .$. Nil (Example) M9NW * Solid state auto switches marked with "O" are produced upon receipt of order.

| $1 \mathrm{~m} \cdots \ldots \ldots . . . . .$. | M |
| :--- | :--- | (Example) M9NWM

* Refer to page 185 for applicable auto switches in addition to those listed above.
* For details on auto switches with a pre-wired connector, refer to page 1784 and 1785.


## $\triangle$ Caution

When an auto switch is not mounted properly, it can cause a malfunction. Refer to page 185 "Auto Switch Mounting".

## Clean Series

## 11 - MXJ Standard model no. <br> Clean Series <br> 11: Vacuum type * External dimensions are identical to the standard model. <br> Model

| Model | Adjuster option | Grade | Intake flow <br> e/min (ANR)* |
| :---: | :--- | :--- | :---: |
| 11-MXJ4(L) | Without adjuster | Grade 3 (Class 100 or equivalent) |  |
|  | Metal stopper | Grade 4 (Class 1000 or equivalent) |  |
| 11-MXJ6(L) | Without adjuster | Grade 3 (Class 100 or equivalent) |  |
|  | Metal stopper | Grade 4 (Class 1000 or equivalent) |  |
| 11-MXJ8(L) | Without adjuster | Grade 3 (Class 100 or equivalent) |  |
|  | Metal stopper | Grade 4 (Class 1000 or equivalent) |  |



Intensive vacuum suction prevents the particles from discharging inside a clean room.

## Series MXJ

Specifications


| Model | MXJ4 | MXJ6 | MXJ8 |
| :---: | :---: | :---: | :---: |
| Bore size (mm) | 4.5 | 6 | 8 |
| Piping port size | M3 x 0.5 |  |  |
| Fluid | Air |  |  |
| Action | Double acting |  |  |
| Operating pressure | 0.15 to 0.7 MPa |  |  |
| Proof pressure | 1.05 MPa |  |  |
| Ambient and fluid temperature | -10 to $60^{\circ} \mathrm{C}$ |  |  |
| Operating speed range | 50 to $500 \mathrm{~mm} / \mathrm{s}$ <br> (Metal stopper: 50 to $200 \mathrm{~mm} / \mathrm{s}$ ) |  |  |
| Cushion | Rubber bumper (Metal stopper: Without cushion) |  |  |
| Lubrication | Non-lube |  |  |
| Stroke adjuster | Standard equipment |  |  |
| Stroke adjusting range (metal stopper) | Both ends each 0 to 5 mm |  |  |
| Auto switch | Reed auto switch (2-wire, 3-wire) Solid state auto switch (2-wire, 3-wire) 2-color indication solid state auto switch (2-wire, 3-wire) |  |  |
| Stroke length tolerance | ${ }_{0}^{+1} \mathrm{~mm}$ |  |  |

## Standard Stroke

| Model | Standard stroke (mm) |
| :--- | :--- |
| MXJ4 | 5,10 |
| MXJ6 | $5,10,15$ |
| MXJ8 | $5,10,15,20$ |

Option

| Adjuster option | Metal stopper | Extension end (CS) | Stroke adjustment range 0 to 5 mm |
| :---: | :---: | :---: | :---: |
|  |  | Retraction end (CT) |  |
|  |  | Both ends (C) |  |
| Functional option | Axial piping type (P) |  | Stroke adjuster is mountable on the axial piping. |

## Theoretical Output

$\qquad$

| Model | Bore size (mm) | Rod size (mm) | Operating direction | Piston area ( $\mathrm{mm}^{2}$ ) | Operating pressure ( MPa ) |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  | 0.2 | 0.3 | 0.4 | 0.5 | 0.6 | 0.7 |
| MXJ4 | 4.5 | 2 | OUT | 16 | 3 | 5 | 6 | 8 | 10 | 11 |
|  |  |  | IN | 13 | 3 | 4 | 5 | 6 | 8 | 9 |
| MXJ6 | 6 | 3 | OUT | 28 | 6 | 8 | 11 | 14 | 17 | 20 |
|  |  |  | IN | 21 | 4 | 6 | 8 | 11 | 13 | 15 |
| MXJ8 | 8 | 4 | OUT | 50 | 10 | 15 | 20 | 25 | 30 | 35 |
|  |  |  | IN | 38 | 8 | 11 | 15 | 19 | 23 | 26 |

[^0]
## Mass

Basic Style (Without switch rail) MXJ $\square \square-\square \square{ }^{-1}$

| Model | Standard stroke (mm) |  |  | Additional mass of adjuster option |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 5 | 10 | 15 | 20 | Extension end | Retraction end |
| MXJ4 | 40 | 40 | - | - | 2 | 6 |
| MXJ6 | 50 | 50 | 55 | - | 2 | 8 |
| MXJ8 | 70 | 70 | 90 | 90 | 2 | 12 |

Axial Piping Type (Without switch rail) MXJロロ- $\square \square P \mathrm{PN}$

| Model | Standard stroke (mm) |  |  | Additional mass of adjuster option |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 5 | 10 | 15 | 20 | Extension end | Retraction end |
| MXJ4 | 50 | 50 | - | - | 2 |  |
| MXJ6 | 60 | 60 | 65 | - | 2 |  |
| MXJ8 | 85 | 85 | 110 | 110 | 2 |  |

## Additional Mass of Switch Rail

(g)

| Model | Standard stroke (mm) |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | 5 | 10 | 15 | 20 |
| MXJ4 | 5 | 5 | - | - |
| MXJ6 | 5 | 5 | 6 | - |
| MXJ8 | 5 | 5 | 7 | 7 |


| B side parallelism to A side | 0.03 |
| :--- | :---: |
| B side traveling parallelism to A side | 0.005 |
| C side perpendicularity to A side | 0.01 |
| M dimension tolerance | $\pm 0.05$ |
| Radial clearance ( $\mu \mathrm{m}$ ) | $0^{\text {Note) }}$ |
| Non-rotating table accuracy (deg) | $0^{\text {Note) }}$ |

Note) In theory, radial clearance and non-rotating table accuracy are zero by the preloaded specification. However, in some actual cases, a moment can be applied and can cause deflection in an individual part. Therefore, refer to the table displacement amount on page 176.


## Optional Specifications

Rail assembly for mounting auto switch
When auto switch is mounted on air slide table without rail (MXJ $\square-\square \mathrm{N}$ ),
this assembly is used.


Stepped positioning pin
MXJ-LP


Use the optional stepped positioning pin that is provided because the positioning pin hole for the table is a through hole.
Stepped Positioning Pin

| Part no. | Note |
| :---: | :---: |
| MXJ-LP | Common for all models |

## Series MXJ

## Table Deflection (Reference Values)

Table displacement due to pitch moment load
Table displacement when loads are applied to the section marked with the arrow at the full stroke.


## MXJ4



## MXJ6



## MXJ8



The graphs below show the table displacement when the static moment load is applied to the table. The graphs do not show the loadable mass. Refer to the Model Selection for the loadable mass.

## Table displacement due to yaw moment load

Table displacement when loads are applied to the section marked with the arrow at the full stroke.


MXJ4


## MXJ6



## MXJ8



## Table displacement due to roll moment load

Table displacement when loads are applied to the section marked with the arrow with the slide table retracted.


## MXJ4



## MXJ6



MXJ8


Dimensions

## Basic style (Without switch rail)

## MXJ4- $\square \square \mathrm{N}$

Vacuum port M3 $\times 0.5$ (Plugged when the product is a symmetric type.) (Not plugged in the case of the clean series)



Note 1) Use an optional stepped positioning pin. (See page 175.) Note 2) Since the body and table are constructed with a magnetic substance, it becomes magnetized when magnets, etc. are attached to them, and this may cause the auto switch malfunction.
Note 3) If workpiece holding bolts are used, they can touch the body and cause malfunctions, etc. Refer to the Specific Product Precautions.


## Series MXJ

## Dimensions

With stroke adjuster
With adjuster on both ends

## With adjuster on extension end MXJ4-■CSN



With adjuster on retraction end MXJ4-■CTN


Note) Use caution because the height of the end plate's top surface will be higher than the table's top surface.

Axial piping
MXJ4-■■PN


With switch rail MXJ4


Note) Use caution because the height of the end plate's top surface will be higher than the table's top surface.

When all the available options are mounted (switch rail, stroke adjuster, with axial piping).

## Standard type <br> MXJ4- $\square$ CP



Symmetric type
MXJ4L- $\square$ CP


## Dimensions

Basic style (Without switch rail)

## MXJ6- $\square \square \mathbf{N}$

Vacuum port M3 $\times 0.5$ (Plugged when the product is a symmetric type.)
(Not plugged in the case of the clean series)



Note 1) Use an optional stepped positioning pin. (See page 175. ) Note 2) Since the body and table are constructed with a magnetic substance, it becomes magnetized when magnets, etc. are attached to them, and this may cause the auto switch malfunction.
Note 3) If workpiece holding bolts are used, they can touch the body and cause malfunctions, etc. Refer to the Specific Product Precautions.

Vacuum port M3 x 0.5 (Plugged when the product is not symmetric type.) (Not plugged in the case of the clean series)


A-A

## Series MXJ

Dimensions
With stroke adjuster
With adjuster on both ends
MXJ6- $\square \mathbf{C} \square \mathbf{N}$

## With adjuster on extension end MXJ6- $\square$ CS $\square$ N



With adjuster on retraction end MXJ6- $\square \square$ CTN


Note) Use caution because the height of the end plate's top surface will be higher than the table's top surface.

## Axial piping <br> MXJ6- $\square \square$ PN



With switch rail MXJ6


Note) Use caution because the height of the end plate's top surface will be higher than the table's top surface.

When all the available options are mounted (switch rail, stroke adjuster, with axial piping)

## Standard type MXJ6- $\square$ CP



Symmetric type
MXJ6L- $\square$ CP


## Dimensions

Basic style (Without switch rail)

## MXJ8- $\square \square \square$

Vacuum port M3 $\times 0.5$ (Plugged when the product is a symmetric type.) (Not plugged in the case of the clean series)


Note 1) Use an optional stepped positioning pin (See page 175.)
Note 2) Since the body and table are constructed with a magnetic substance, it becomes magnetized when magnets, etc. are attached to them, and this may cause the auto switch malfunction.
Note 3) If workpiece holding bolts are used, they can touch the body and cause
malfunctions, etc.
Refer to the Specific Product Precautions.


| Model | G | GA | H | I | J | K | M | Z | ZZ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| MXJ8-5 | 12 | 18 | 17 | 6 | 17 | 28.5 | 44.5 | 38 | 45 |
| MXJ8-10 | 12 | 18 | 17 | 6 | 17 | 28.5 | 44.5 | 38 | 45 |
| MXJ8-15 | 19 | 28 | 20 | 8 | 25 | 39.5 | 54.5 | 48 | 55 |
| MXJ8-20 | 19 | 28 | 20 | 8 | 25 | 39.5 | 54.5 | 48 | 55 |



A-A

## Series MXJ

## Dimensions

With stroke adjuster
With adjuster on both ends MXJ8- $\square \mathbf{C} \square \mathbf{N}$
 $\div 1$


With adjuster on extension end MXJ8- $\square$ CS $\square$ N


With adjuster on retraction end MXJ8-■CTN


## Axial piping <br> MXJ8-■■PN



With switch rail MXJ8

it is located on the opposite surface.


When all the available options are mounted (switch rail, stroke adjuster, with axial piping)

Standard type
MXJ8- $\square$ CP


Symmetric type
MXJ8L- $\square$ CP



## Component Parts

| No. | Description | Material | Note |
| :---: | :--- | :---: | :---: |
| $\mathbf{1}$ | Body | Martensitic stainless steel | Heat treated |
| $\mathbf{2}$ | Table | Martensitic stainless steel | Heat treated |
| $\mathbf{3}$ | Rod | Stainless steel |  |
| $\mathbf{4}$ | Piston | Brass | Electroless nickel plated |
| $\mathbf{5}$ | Rod cover | Resin |  |
| $\mathbf{6}$ | Head cap | Resin |  |
| $\mathbf{7}$ | Floating bushing A | Stainless steel |  |
| $\mathbf{8}$ | Floating bushing B | Stainless steel |  |
| 9 | Roller stopper A | Stainless steel |  |
| $\mathbf{1 0}$ | Roller stopper B | Stainless steel |  |
| $\mathbf{1 1}$ | Rod bumper | Polyurethane |  |
| $\mathbf{1 2}$ | Plate | Stainless steel |  |
| $\mathbf{1 3}$ | Plug | Steel + Fluorine | Nickel plated |
| $\mathbf{1 4}$ | Piston seal | NBR |  |
| $\mathbf{1 5}$ | Rod seal | NBR |  |
| $\mathbf{1 6}$ | O-ring | NBR |  |
| $\mathbf{1 7}$ | Steel balls | High carbon chrome bearing steel |  |

Note) Use caution because the martensitic stainless steel is inferior in corrosiveness when compaed with austenitic stainless steel.

With Magnet, Rail

| No. | Description | Material | Note |
| :---: | :--- | :---: | :---: |
| $\mathbf{1 8}$ | Switch rail | Aluminum alloy | Hard anodized |
| $\mathbf{1 9}$ | Magnet | - |  |
| $\mathbf{2 0}$ | Magnet holder | Stainless steel |  |

With Stroke Adjuster

| No. | Description | Material | Note |
| :---: | :--- | :---: | :---: |
| $\mathbf{2 1}$ | End plate | Stainless steel |  |
| $\mathbf{2 2}$ | Stopper pin | Steel | Heat treated, Trivalent chromated |
| $\mathbf{2 3}$ | Adjustment bolt | Steel | Heat treated Note), Nickel plated |
| $\mathbf{2 4}$ | Adjustment nut | Steel | Nickel plated |
| Note) Only the MXJ8 series is heat treated |  |  |  |

## Axial Piping Type

| No. | Description | Material | Note |
| :---: | :--- | :---: | :---: |
| $\mathbf{2 5}$ | Axial piping plate | Aluminum alloy | Hard anodized |
| $\mathbf{2 6}$ | Stud | Brass | Electroless nickel plated |
| $\mathbf{2 7}$ | Gasket | Stainless steel + NBR |  |
| $\mathbf{2 8}$ | O-ring | NBR |  |

D- $\square$
$-\mathrm{X} \square$
Individual

- X $\square$


## Series MXJ

## Auto Switch Proper Mounting Position (Detection at Stroke End)

## Reed auto switch

 D-A9 $\square$Solid state auto switch
D-M9 $\square$
D-M9 $\square$ W


* Figures in the table above are used as a reference when mounting the auto switches for stroke end detection. In the case of actually setting the auto switches, adjust them after confirming their operation.

Reed Auto Switch: D-A9 $\square$
(mm)

| Model | A |  |  |  | B |  |  |  | C |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Stroke |  |  |  | Stroke |  |  |  | Stroke |  |  |  |
|  | 5 | 10 | 15 | 20 | 5 | 10 | 15 | 20 | 5 | 10 | 15 | 20 |
| MXJ4 | 9 | 4 | - | - | 14 | 14 | - | - | 0.5 | 0.5 | - | - |
| MXJ6 | 9 | 4 | 3 | - | 14 | 14 | 18 | - | 0.5 | 0.5 | -0.5 | - |
| MXJ8 | 9 | 4 | 10 | 5 | 14 | 14 | 25 | 25 | -0.5 | -0.5 | 0.5 | 0.5 |

Solid State Auto Switch, 2-Color Indication Solid State Auto Switch: D-M9 $\square$, D-M9 $\square$ W

| Model | A |  |  |  | B |  |  |  | C |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Stroke |  |  |  | Stroke |  |  |  | Stroke |  |  |  |
|  | 5 | 10 | 15 | 20 | 5 | 10 | 15 | 20 | 5 | 10 | 15 | 20 |
| MXJ4 | 13 | 8 | - | - | 18 | 18 | - | - | 4.5 | 4.5 | - | - |
| MXJ6 | 13 | 8 | 7 | - | 18 | 18 | 22 | - | 4.5 | 4.5 | 3.5 | - |
| MXJ8 | 13 | 8 | 14 | 9 | 18 | 18 | 29 | 29 | 3.5 | 3.5 | 4.5 | 4.5 |

## Reed auto switch D-A9■V <br> Solid state auto switch <br> D-M9 $\square V$ <br> D-M9■WV <br> D-F8■



* Figures in the table above are used as a reference when mounting the auto Lead wire, perpendicular entry switches for stroke end detection. In the case of actually setting the auto switches, adjust them after confirming their operation.

Reed Auto Switch: D-A9 $\square$ V

| Model | A |  |  |  | D |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Stroke |  |  |  | Stroke |  |  |  |
|  | 5 | 10 | 15 | 20 | 5 | 10 | 15 | 20 |
| MXJ4 | 9 | 4 | - | - | 1.5 | 1.5 | - | - |
| MXJ6 | 9 | 4 | 3 | - | 1.5 | 1.5 | 2.5 | - |
| MXJ8 | 9 | 4 | 10 | 5 | 2.5 | 2.5 | 1.5 | 1.5 |

Solid State Auto Switch, 2-Color Indication Solid State Auto Switch: D-M9■V, D-M9■WV (mm)

| Model | A |  |  |  | D |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Stroke |  |  |  | Stroke |  |  |  |  |
|  | 5 | 10 | 15 | 20 | 5 | 10 | 15 | 20 |  |
| MXJ4 | 13 | 8 | - | - | 5.5 | 5.5 | - | - |  |
| MXJ6 | 13 | 8 | 7 | - | 5.5 | 5.5 | 6.5 | - |  |
| MXJ8 | 13 | 8 | 14 | 9 | 6.5 | 6.5 | 5.5 | 5.5 |  |

Solid State Auto Switch: D-F8 $\square$

| Model | A |  |  |  | D |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | Stroke |  |  |  | Stroke |  |  |  |
|  | 5 | 10 | 15 | 20 | 5 | 10 | 15 | 20 |
| MXJ4 | 11 | 6 | - | - | 3.5 | 3.5 | - | - |
| MXJ6 | 11 | 6 | 5 | - | 3.5 | 3.5 | 4.5 | - |
| MXJ8 | 11 | 6 | 12 | 7 | 4.5 | 4.5 | 3.5 | 3.5 |

## Operating Range

| (mm) |  |  |  |  |
| :--- | :---: | :---: | :---: | :---: |
| Auto switch model |  | Applicable bore size $(\mathrm{mm})$ |  |  |
|  | $\varnothing 4$ | $\varnothing 6$ | $\varnothing 8$ |  |
| D-A9 $\square /$ A9 $\square \mathbf{V}$ | 4 | 4 | 4 |  |
| D-F8 $\square$ | 2 | 2 | 2 |  |
| D-M9 $\square /$ M9 $\square \mathbf{V}$ <br> D-M9W $\square /$ M9W $\square \mathbf{V}$ | 2 | 2.5 | 2.5 |  |

* Since the operating range is provided as a guideline including hysteresis, it cannot be guaranteed (assuming approximately $\pm 30 \%$ dispersion). It may vary substantially depending on an ambient environment.


## Auto Switch Mounting

## $\triangle$ Caution

## Auto Switch Mounting Tool

- When tightening the auto switch mounting screw (included with auto switch), use a watchmaker's screwdriver with a handle about 5 to 6 mm in diameter.


## Tightening Torque

Tightening Torque of Auto Switch

| Mounting Screw | (N.m) |
| :--- | :---: |
| Auto switch model | Tightening torque |
| D-F8 $\square$ <br> D-A9 $\square(V)$ | 0.10 to 0.20 |
| D-M9 $\square(V)$ <br> D-M9 $\square \mathbf{W}(V)$ | 0.05 to 0.15 |



## Caution on handling symmetric type

## $\triangle$ Caution

1. Maintain a minimum space if standard type and symmetric type are used side by side.

If the space is insufficient, it may cause auto switches to malfunction.

$L$ Dimension

| Without shielding plate | 8 mm |
| :--- | :---: |
| With shielding plate | 3 mm |

Placing in the shield plate ( 0.2 to 0.3 mm iron plate) between the products allows the distance to be smaller.

[^1]
## D-

Be sure to read before handling. Refer to front matters 42 and 43 for Safety Instructions and pages 3 to 11 for Actuator and Auto Switch Precautions.

## Selection <br> © Caution

1. Operate loads within the range of the operating limits.
Select the model considering maximum loading mass and allowable moment. For details, refer to "Model Selection" on pages 171 and 172. When actuator is used outside of operating limits, eccentric loads on guide will be in excess of this causing vibration on guide, inaccuracy, and shortened life.
2. If intermediate stops by external stopper is done, avoid ejection.
If lurching occurs, damage can result. When making an inermediate stop with an external stopper to be followed by continued forward movement, first supply pressure to momentarily reverse the table, then retract the intermediate stopper, and finally apply pressure to the opposite port to operate the table again.
3. Do not use it in such a way that excessive external force or impact force could work on it.
This could result in damage.

## Mounting <br> $\triangle$ Caution

1. Do not scratch or dent on the mounting side of body, table and end plate.
The damage will result in a decrease in parallelism, vibration of guide and an increase in moving part resistance.
2. Do not scratch or dent on the forward side of the rail or guide.
This could result in looseness and increased operating resistance, etc.


## Mounting

## © Caution

3. Do not apply excessive power and load when work is mounted.
If the external force more than the allowable moment were applied, looseness of the guide unit or increased operating resistance could take place.
4. Flatness of mounting surface should be 0.02 mm or less.
Poor parallelism of the workpiece mounted on the body, the base, and other parts can cause vibration in the guide unit and increased operating resistance, etc.
5. Select the proper connection with the load which has external support and/or guide mechanism on the outside, and align it properly.
6. Avoid contact with the body during operation.
Hands, etc. may get caught in the stroke adjuster. Install a cover as a safety measure if there are instances to be near the slide table during operation.
7. Keep away from objects which are influenced by magnets.
Since a body has magnets built-in, do not allow close contact with magnetic disks, magnetic cards or magnetic tapes. Data may be erased.

8. Do not attach magnets to the body and table section.
Since the body and table are constructed with a magnetic substance, it becomes magnetized when magnets, etc.
are attached to them, and this may cause malfunction of auto switches, etc.
9. When mounting the body, use appropriate length of screws and do no exceed the maximum tightening torque.
Tightening with a torque above the limit could malfunction. Whereas tightening insufficiently could result in misalignment or come to a drop.

10. Use the below speed controllers and fittings.
If other speed controllers and fittings are used, they can interfere with the mounting surface.

| Model | Side piping port | Axial piping port | Vacuum port |
| :---: | :---: | :---: | :---: |
| MXJ4 | AS1200-M3 | AS1200-M3 <br> AS1201F-M3 <br> AS1301F-M3 | Miniature fittings M3 series |
| MXJ6 | AS1200-M3 |  |  |
| MXJ8 | AS1201F-M3 |  |  |



Be sure to read before handling. Refer to front matters 42 and 43 for Safety Instructions and pages 3 to 11 for Actuator and Auto Switch Precautions.

## Mounting

## $\triangle$ Caution


$\triangle$ Caution To prevent the workpiece holding bolts from touching the guide block, use bolts that are at least shorter than the maximum screwin depth. If longer bolts are used, they can touch the guide and cause a malfunction.

| Model | Bolt | Maximum <br> tightening torque <br> $(\mathrm{N} \cdot \mathrm{m})$ | Maximum <br> screw-in <br> depth $\ell(\mathrm{mm})$ |
| :---: | :---: | :---: | :---: |
| MXJ4 | $\mathrm{M} 3 \times 0.5$ | 1.14 | 3.5 |
| MXJ6 | $\mathrm{M} 3 \times 0.5$ | 1.14 | 3.5 |
| MXJ8 | $\mathrm{M} 3 \times 0.5$ | 1.14 | 3.5 |

2. Top mounting


| @ CautionTo prevent the workpiece holding <br> bolts from touching the guide <br> block, use bolts that are at least <br> shorter than the maximum screw- <br> in depth. If longer bolts are used, <br> they can touch the guide and <br> cause a malfunction. |  |  |  |
| :---: | :---: | :---: | :---: |
| Model | Bolt | Maximum <br> tightening torque <br> (N.m) | Maximum <br> screw-in <br> depth $(\mathrm{mm})$ |
| MXJ4 | M3 $\times 0.5$ | 1.14 | 4 |
| MXJ6 | M3 $\times 0.5$ | 1.14 | 4 |
| MXJ8 | M3 $\times 0.5$ | 1.14 | 5.5 |

1. Use a stepped positioning pin that is provided optionally because the positioning pin hole for the table is through.
(Refer to page 175.)

## Operating Environment

## © Caution

1. Do not use in an environment, where the product could be exposed to liquids such as cutting oil, etc.
Using in an environment where the product could be exposed to cutting oil, coolant, oil, etc. could result in looseness, increased operating resistance, air leakage, etc.
2. Do not use in an environment, where the product could be exposed directly to foreign materials such as powder dust, blown dust, cutting chips, spatter, etc.
This could result in looseness, increased operating resistance, air leakage, etc.
Contact us regarding use in this kind of environment.
3. Do not use in direct sunlight.
4. When there are heat sources in the surrounding area, block off them off.
When there are heat sources in the surrounding area, radiated heat may cause the product's temperature to rise and exceed the operating temperature range. Block off the heat with a cover, etc.
5. Do not subject it to excessive vibration and/or impact.
Contact us regarding use in this kind of environment, since this can cause damage or a malfunction.
6. Be careful about the corrosion resistance of the linear guide.
Be careful that the body and table use martensitic stainless steel, which is inerior to austenitic stainless steel in terms of corrosion resistance. Rust may result especially in an environment that allows water drops from condensation to stay on the surface.

## Caution on Adjuster Option

Stroke Adjuster

## Caution

MXH

1. Refer to the below table for lock nut tightening torque.
Insufficient torque will cause a decrease in the positioning accuracy.

| Model | Thread size | Tightening torque (N•m) |
| :---: | :---: | :---: |
| MXJ4 | $\mathrm{M} 2.5 \times 0.45$ | 0.36 |
| MXJ6 | $\mathrm{M} 2.5 \times 0.45$ | 0.36 |
| MXJ8 | $\mathrm{M} 3 \times 0.5$ | 0.63 |

2. When sroke adjuster is adjusted, do not hit the table with a wrench, etc.
This could result in looseness.
MXJ

## Series MXJ Specific Product Precautions 3

Be sure to read before handling. Refer to front matters 42 and 43 for Safety Instructions and pages 3 to 11 for Actuator and Auto Switch Precautions.

Caution on replacing standard type to symmetric type, and vice versa

## $\triangle$ Caution

Switch rail, axial piping plate and port location can be changed symmetrically. In the event of replacing them, secure with the tightening torque below.

| Thread | Thread size | Tightening torque (N.m) |
| :---: | :---: | :---: |
| Cross-recessed head machine screw | $\mathrm{M} 1.7 \times 0.35$ | 0.1 |
| Stud | $\mathrm{M} 3 \times 0.5$ | 0.3 |
| Dedicated plug | $\mathrm{M} 3 \times 0.5$ | 0.3 |
| Hexagon socket set screw | $\mathrm{M} 3 \times 0.5$ | 0.3 |

* No need to applying sealant to the dedicated plug, and stud when exchanging.



[^0]:    Note) Theoretical output $(\mathrm{N})=$ Pressure $(\mathrm{MPa}) \times$ Piston area $\left(\mathrm{mm}^{2}\right)$

[^1]:    Other than the applicable auto switches listed in "How to Order", the following auto switches can be mounted.

    * Normally closed (NC = b contact) solid state auto switches (D-F9G/F9H types) and a solid state auto switch (D-F8) are also available. Refer to pages 1745 and 1746 for details.

